

The testbench failed to compile. Please fix the module. The output of iverilog is as follows:

error: 'rxBusy' has already been declared in this scope.

It was declared here as a net.

error: 'txBusy' has already been declared in this scope.

It was declared here as a net.

The error message indicates that `rxBusy` and `txBusy` are already declared in the scope. This typically happens when you have both a `reg` and a `wire` declaration for the same name. In your module, you have declared `rxBusy` and `txBusy` as `reg` inside the `always` blocks, but you also have them as output ports declared as `wire`.

To fix this issue, you should ensure that each signal is declared only once. Since `rxBusy` and `txBusy` are output ports, they should be declared as `wire` outside the module. However, you also need internal `reg` variables to drive these outputs. Here's how you can modify your module:

```
module Uart8 #(
    parameter CLOCK_RATE = 100000000,
    parameter BAUD_RATE = 9600,
    parameter TURBO_FRAMES = 0
)()
    input wire clk,

    input wire rxEn,
    input wire rx,
    output wire rxBusy,
    output wire rxDone,
    output wire rxErr,
    output wire [7:0] out,

    input wire txEn,
    input wire txStart,
    input wire [7:0] in,
    output wire txBusy,
    output wire txDone,
    output wire tx
);

// UART Receiver Module
reg [7:0] rxReg;
reg [3:0] rxCnt;
reg [3:0] rxSampleCnt;
reg rxFrameErr;
reg rxOverRun;
```

```

reg rxEmpty;
reg rxD1;
reg rxD2;
reg _rxBusy; // Internal reg for rxBusy
reg _rxDone; // Internal reg for rxDone
reg _rxErr; // Internal reg for rxErr

assign rxBusy = _rxBusy; // Assign internal reg to output wire
assign rxDone = _rxDone;
assign rxErr = _rxErr;

always @(posedge clk or negedge rxEn) begin
    if (!rxEn) begin
        rxReg <= 0;
        rxCnt <= 0;
        rxSampleCnt <= 0;
        rxFrameErr <= 0;
        rxOverRun <= 0;
        rxEmpty <= 1;
        rxD1 <= 1;
        rxD2 <= 1;
        _rxBusy <= 0;
        _rxDone <= 0;
        _rxErr <= 0;
    end else if (rxEn) begin
        // Synchronize the asynchronous signal
        rxD1 <= rx;
        rxD2 <= rxD1;

        // Receive data only when rx is enabled
        if (!_rxBusy && !rxD2) begin
            _rxBusy <= 1;
            rxCnt <= 0;
        end else if (_rxBusy && (rxCnt == 8)) begin
            // Check for stop bit
            if (rxD2) begin
                rxReg <= rxReg;
                rxFrameErr <= 0;
            end else begin
                rxFrameErr <= 1;
            end
            _rxBusy <= 0;
            _rxDone <= 1;
            out <= rxReg;
            rxEmpty <= 0;
        end else if (_rxBusy) begin
            // Shift in data bits
            rxReg <= {rxD2, rxReg[7:1]};
            rxCnt <= rxCnt + 1;
        end
    end
end

// UART Transmitter Module
reg [7:0] txReg;
reg [3:0] txCnt;

```

```

reg txEmpty;
reg txOverRun;
reg _txBusy; // Internal reg for txBusy
reg _txDone; // Internal reg for txDone

assign txBusy = _txBusy; // Assign internal reg to output wire
assign txDone = _txDone;

always @(posedge clk) begin
    if (txStart) begin
        txReg <= in;
        txCnt <= 0;
        _txBusy <= 1;
    end else if (_txBusy) begin
        if (txCnt == 9) begin
            _txBusy <= 0;
            _txDone <= 1;
        end else if (txCnt == 8) begin
            // Send stop bit
            tx <= 1;
            txCnt <= txCnt + 1;
        end else if (txCnt > 0) begin
            // Send data bits
            tx <= txReg[7:0];
            txReg <= {1'b0, txReg[7:1]};
            txCnt <= txCnt + 1;
        end else if (txCnt == 0) begin
            // Send start bit
            tx <= 0;
            txCnt <= txCnt + 1;
        end
    end else begin
        tx <= 1; // Idle state
    end
end

// Baud Rate Generator
reg [23:0] baudCnt;
always @(posedge clk) begin
    if (baudCnt == (CLOCK_RATE / BAUD_RATE - 1)) begin
        baudCnt <= 0;
    end else begin
        baudCnt <= baudCnt + 1;
    end
end

endmodule

```

Explanation:

- **Internal Registers:** I've introduced internal registers (`_rxBusy`, `_txBusy`, `_rxDone`, `_txDone`, `_rxErr`) to hold the state of the UART. These are then assigned to the output wires (`rxBusy`, `txBusy`, `rxDone`, `txDone`, `rxErr`).

- **Assign Statements:** I've used continuous assignment statements to connect the internal registers to the output wires. This ensures that the outputs are driven by the internal logic without causing conflicts due to multiple declarations.

This approach should resolve the compilation errors related to multiple declarations of the same signal name.

**