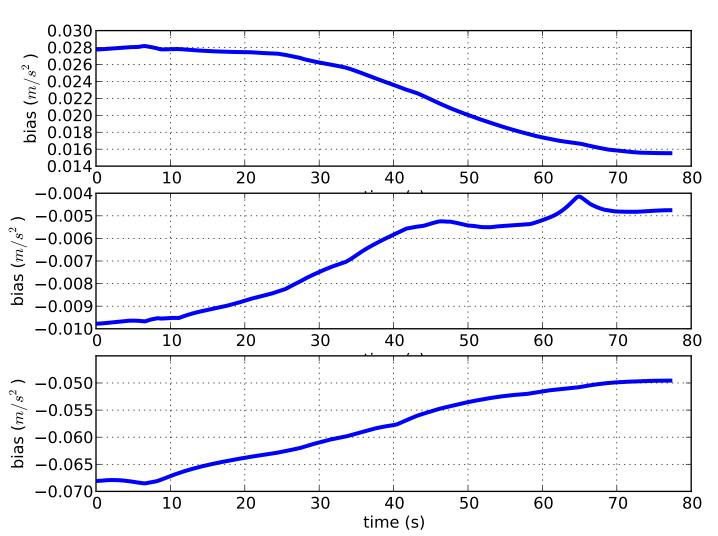
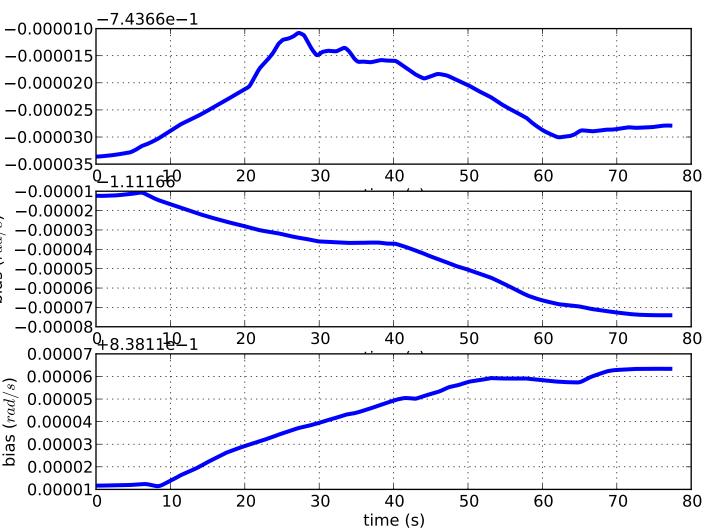


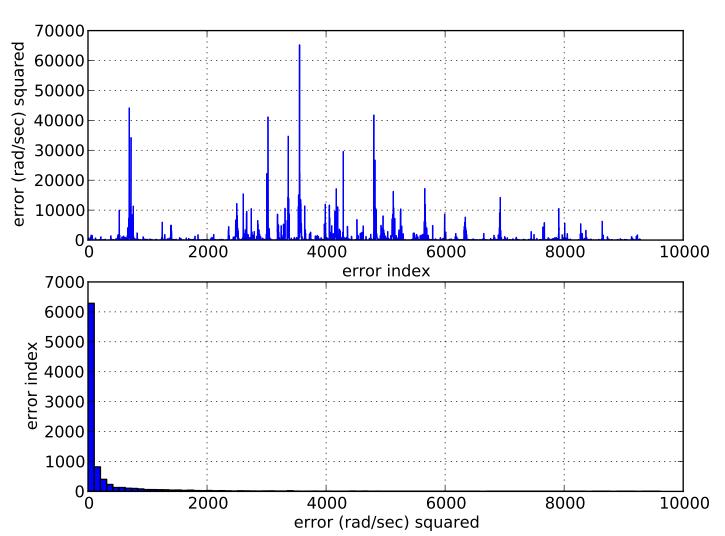
imu0: estimated accelerometer bias (imu frame)



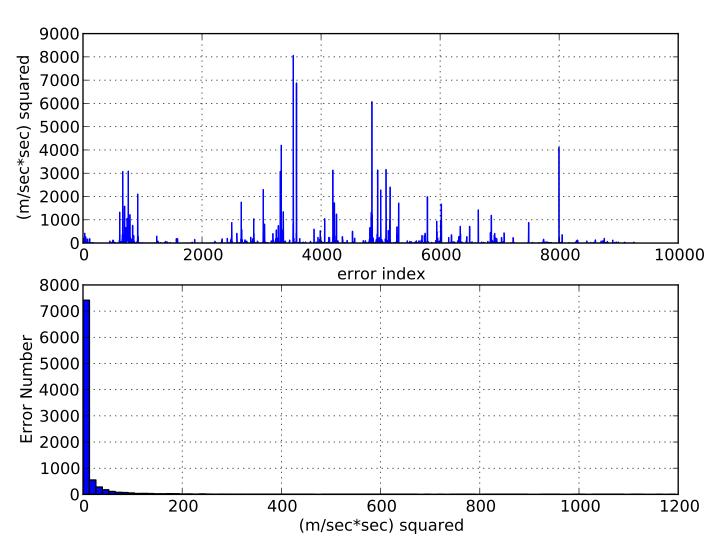
imu0: estimated gyro bias (imu frame)



imu0: angular velocities error



imu0: acceleration error



cam0: reprojection errors

