

Agenda for August 6th Meeting (12-3 p.m. TRL Makelt)

Convert `robby_with_class.py` to an obstacle avoiding robot `autorobot.py`

Material Required:

Servo Motor

Ultrasonic Sensor HCSR04

9 volt battery

3D printed attachment for the servo motor and ultrasonic sensor will be provided

Lesson:

How to calibrate a servo motor

How to set up the ultrasonic sensor as a distance sensor