

# DHRUV SHAH

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## RESEARCH INTERESTS

I am fascinated by problems at the intersection of geometrical and learning-based methods in perception, localization, mapping and control for robotics. I am also interested in computational photography & imaging, graphics, compressive sensing, statistical learning and information-theoretic approaches to vision.

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## EDUCATION

### Indian Institute of Technology, Bombay

Bachelor of Technology, *Department of Electrical Engineering*

June '15 – Present

- **Major CGPA:** 9.51/10
- Awarded the **Institute Academic Prize** 2017-18 (ranked 1<sup>st</sup>/137)
- Pursuing a **Minor Degree** in *Computer Science & Engineering*

### City International School Pune, India

High School

April 2015

- **Overall Performance:** 96.80%

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## PUBLICATIONS

- **Dhruv Shah** and Leena Vachhani, *Swarm Aggregation without Communication and Global Positioning*. (Submitted to the [IEEE Robotics & Automation Letters](#))
- **Dhruv Shah**<sup>†</sup>, Alankar Kotwal<sup>†</sup> and Ajit Rajwade, *Designing Constrained Projections for Compressed Sensing: Mean Errors and Anomalies with Coherence*. (To be presented at [IEEE GlobalSIP 2018](#)) 🔗
- Weikun Zhen<sup>†</sup>, **Dhruv Shah**<sup>†</sup>, Michael Lee, Matthew Hanczor and Sebastian Scherer, *Combining 3D Mapping and Radiation Source Localization in Nuclear Sites*. (Submitted to the [Journal of Field Robotics](#))
- **Dhruv Shah** and Sebastian Scherer, *Robust Localization of an Arbitrary Distribution of Radioactive Sources for Aerial Inspection*. (Proceedings of the [WM2018 Conference](#), Phoenix, Arizona) 🔗

(<sup>†</sup> equal contribution)

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## RESEARCH INTERNSHIPS & PROJECTS

### Visual Servoing for Aerial Manipulation

*Prof. Stefan Leutenegger, Department of Computing*

May '18 – Present

**Imperial College London**

- Developed a 3D Position-Based Visual Servoing (PBVS) system for the joint manipulation of a drone and onboard delta arm along intricate trajectories for writing or additive building manufacturing (ABM).
- Working on the development of a realtime full-state non-linear Model Predictive Controller (MPC).

### Aerial Inspection of Nuclear Facilities

*Dr. Sebastian Scherer, Robotics Institute*

Summer 2017

**Carnegie Mellon University**

- Proposed a novel scalable algorithm for the robust *localization* of an arbitrary distribution of radiation sources, for *inspection by UAVs* in a confined environment using *sequential Monte Carlo methods & filtering*.
- Demonstrated significant improvements over the state-of-the-art, in terms of F1-scores and localization error, while allowing better scalability to higher dimensional parameter spaces.
- The proposed method was coupled with a novel Error State Kalman Filter based SLAM algorithm for rotating LiDARs on aerial & ground for extensive field experiments.

### Optimizing Projections for Compressed Sensing

*Prof. Ajit Rajwade, Department of Computer Science & Engineering*

Jan. '18 – Present

**IIT Bombay**

- Proposed a novel algorithm for the design of sensing matrices for the compressive imaging of natural scenes, using statistical priors and optical constraints on the imaging system.
- Demonstrated improvements over existing methods in projection design, imposing optical constraints.

## Multi-agent Control without Communication

*Prof. Leena Vachhani, School of Systems and Control Engineering*

July '17 – Present

IIT Bombay

- Developed a decentralized controller for the aggregation of a robotic swarm in the absence of global positioning and inter-agent communication.
- Demonstrated stability of the algorithm with convergence guarantees in the presence of static obstacles, further validated by extensive simulations and real-world experiments.

## The IITB Mars Rover Project

*Mars Society India*

Sep. '15 – Jan. '18

- Served as the head of the *Computer Vision & Navigation* subsystem; responsible for the autonomous navigation & path planning algorithms for field operations of the rover.
- Active contributor to the GUI subsystem to ensure accurate simulation and interfacing of the sensors and vehicle model using ROS and Gazebo.
- The team will be participating in the [University Rover Challenge 2018](#) (Utah, USA) [\[Media Coverage\]](#)

## MISCELLANEOUS PROJECTS

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### Digitally Programmable Analog Computer (DPAC)

*EE344: Electronics Design Laboratory*

Spring 2018

IIT Bombay

Designed and developed a standalone digitally programmable analog computer, capable of solving linear dynamical systems upto the fifth order, demonstrating *hardware-in-loop* capabilities. [\[Project Page\]](#)

### Vector-Valued Image Regularization with PDEs

*CS663: Digital Image Processing*

Fall 2017

IIT Bombay

Implemented a generic PDE-based regularization framework using variational calculus and demonstrated exciting results in image restoration, inpainting, text removal, flow visualization etc. [\[Project Page\]](#)

### Pipelined Reduced Instruction Set Computer (IITB-RISC)

*EE309: Microprocessors*

Fall 2017

IIT Bombay

Designed and demonstrated a 6-stage pipelined 16-bit computer system from scratch, using VHDL. The architecture was optimized for performance, with hazard mitigation techniques, including data forwarding.

### Modeling Noisy Channels

*EE702: Information Theory & Coding*

Spring 2017

IIT Bombay

Implemented various encoder-decoder pairs, including a typical decoder (asymptotic) to achieve channel capacity with negligible BER, demonstrating channel coding.

### An Information Theoretic Approach to Understanding Scenes

*EE325: Probability & Random Processes*

Fall 2017

IIT Bombay

Survey and analysis of information theoretic measures, theories and principles in the domain of computer vision. Implemented algorithms for feature point identification, tracking, clustering, etc. [\[Project Page\]](#)

### Statistical Signal Processing (Jupyter Notebooks)

*The Web and Coding Club*

Summer 2016

IIT Bombay

Built Jupyter notebooks implementing iconic algorithms and applications in statistical signal processing, including ICA (FOBI and fastICA backends) to solve the *Cocktail Party Problem* and the Poisson Solver (Jacobi and Gauss-Siedel backends) for *seamless image cloning*. [\[Tutorial\]](#).

## TECHNICAL SKILLS

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- ▷ **Experienced:** Python, C/C++, ROS, MATLAB/Octave, Git, Mathematica, Spice, VHDL & Verilog
- ▷ **Familiar:** Gazebo, TensorFlow, Keras, Java, Bash, OpenCV, AVR, JavaScript, BoneScript, Wireshark

## RELEVANT COURSEWORK

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- ▷ **Electrical Engineering:** Information Theory & Universal Schemes, Estimation & Identification<sup>†</sup>, Digital Signal Processing, Digital & Analog Comm., Control Systems, Network Theory, Microprocessors
- ▷ **Computer Science & Engineering:** Machine Learning, Computer Vision, Graphics<sup>†</sup>, Intelligent Agents<sup>†</sup>, Advanced Image Processing, Data Structures & Alg., Operating Systems, Computer Networks
- ▷ **Inter-Disciplinary:** Optimization<sup>†</sup>, Calculus, Linear Algebra, Advanced Probability, Complex Analysis, Economics, Game Theory, Ordinary & Partial Differential Equations, Quantum Physics, Linguistics  
(<sup>†</sup> courses to be completed by the end of Fall 2018)

## SCHOLASTIC ACHIEVEMENTS

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- Awarded the **Institute Academic Prize** 2017-18 for outstanding academic performance (ranked 1<sup>st</sup>/137)
- **Gold Medal and Certificate of Merit** in *Indian National Chemistry Olympiad*, 2015 for being among national top 35 out of  $\approx 10000$  students
- **Silver Medal** in the Medical Imaging Challenge at the 6<sup>th</sup> Inter IIT Technical Meet, 2018.
- **All India Rank 111** in *JEE Advanced* 2015, among 125,000 participants for entrance to the IITs
- Placed 21<sup>st</sup> at **Online Physics Brawl 2016** ( $\approx 250$  teams across major universities around the world)
- Attended the **Orientation-cum-Selection Camp** for the 46<sup>th</sup> *International Chemistry Olympiad 2015*
- **Certificate of Merit** in *National Standard Examination in Physics*, 2014 and 2015 for being among top 1% of the participants
- Scored **414/450** in *BITSAT* examination 2015, for admission to the BITS Institutes. (99.9 percentile)
- Awarded **AP grade** (given to top 1%) for *exceptional performance* in Engineering Graphics & Drawing
- Recipient of the *National Talent Search Examination (NTSE) Scholarship* awarded by the National Council for Educational Research and Training since **2011**

## MENTORING EXPERIENCE

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### Teaching Assistant

MA207 (Differential Equations II)  
CS101 (Computer Programming & Utilization)

Prof. Swapneel Mahajan  
Prof. D.B.Phatak

Fall 2018  
Summer 2016

**Convener, Maths and Physics Club**

2016-17

## REFERENCES

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**Prof. Stefan Leutenegger**  
Department of Computing  
Imperial College London

**Dr. Sebastian Scherer**  
Robotics Institute  
Carnegie Mellon University

**Prof. Leena Vachhani**  
School of Systems & Control  
Indian Institute of Technology, Bombay

**Prof. Ajit Rajwade**  
Dept. of Computer Science & Engineering  
Indian Institute of Technology, Bombay