Systems Modelling and Control: Tutorial 3

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Frequency Response

QUESTION A

A linear time-invariant continuous-time system has some frequency function $H(\omega)$. Some input x(t), which is composed of a DC component and 2 sinusoids with distinct multiples of some fundamental frequency, w_0 , is given as:

$$x(t) = 1 + 4\cos(2\pi t) + 8\sin(3\pi t - \pi/2)$$
$$= 1 + 4\cos(2\pi t) + 8\cos(3\pi t - \pi)$$

The fundamental frequency of the sinusoids, w_0 , is the lowest common divisor of 2π and 3π . Hence, the fundamental frequency is given by:

$$w_0 = \pi$$

The output to the system, y(t), is given by:

$$y(t) = 2 - 2\sin(2\pi t)$$

$$= 2 + 2\sin(-2\pi t)$$

$$= 2 + 2\cos(-2\pi t - \pi/2)$$

$$= 2 + 2\cos(-(2\pi t + \pi/2))$$

$$= 2 + 2\cos(2\pi t + \pi/2)$$

Now, the above input signal, x(t), is periodic and as such has the complex Fourier series representation:

$$x(t) = \sum_{k=-\infty}^{\infty} c_k^x e^{jk\omega_0 t}$$

A single instance, k, of this infinite series is given by:

$$x_k(t) = c_k^x e^{jk\omega_0 t}$$

Because the system is linear, we can apply the transfer function to each instance of complex Fourier series representation of x(t), and rely on superposition to obtain the output, y(t). This is represented as:

$$y(t) = \sum_{k=-\infty}^{\infty} H(\omega_0 k) c_k^x e^{jk\omega_0 t}$$

A single instance, k, of the infinite Fourier series representing y(t) can be written as:

$$y_k(t) = c_k^y e^{jk\omega_0 t} = H(\omega_0 k) c_k^x e^{jk\omega_0 t}$$

Hence, we can see that:

$$c_k^y = H(\omega_0 k) c_k^x$$

Which allows us to write an expression for the transfer function, $H(\omega)$, in terms of c_k^x and c_k^y :

$$H(\omega) = H(k\omega_0) = \frac{c_k^y}{c_k^x}, \quad \omega = k\omega_0$$

Hence, $\exists H(\omega) \ \forall \ c_k^x \neq 0$. That is to say, we can find $H(\omega)$ for k = 0, 2, 3.

QUESTION 2

 $H(\omega) = H(k\omega_0)$ can be found for k = 0, 2, 3. We first note that:

$$\begin{split} c_0^x &= 1 \\ c_2^x &= \frac{1}{2} \cdot 4 = 2 \\ c_3^x &= \frac{1}{2} \cdot 8 \cdot e^{-j\pi} = 4 \cdot e^{-j\pi} \end{split}$$

Further, we can see that:

$$\begin{aligned} c_0^y &= 2 \\ c_2^y &= \frac{1}{2} \cdot 2 \cdot e^{j \cdot \pi/2} = e^{j \cdot \pi/2} \\ c_3^y &= 0 \end{aligned}$$

Hence, we get that:

$$H(0 \cdot \pi) = \frac{c_0^y}{c_0^x} = \frac{2}{1} = 2$$

$$H(2 \cdot \pi) = \frac{c_2^y}{c_2^x} = \frac{e^{j \cdot \pi/2}}{2} = \frac{1}{2} \cdot e^{j \cdot \pi/2}$$

$$H(3 \cdot \pi) = \frac{c_3^y}{c_3^x} = \frac{0}{4 \cdot e^{-j\pi}} = 0$$

Filtering of sound

Suppose a continuous-time signal, x(t), is given by the following:

$$x(t) = \cos(440 \cdot 2\pi \cdot t) + \cos(554 \cdot 2\pi \cdot t) + \cos(659 \cdot 2\pi \cdot t)$$

To play the sound of this signal for 2 seconds, the following Matlab code was implemented:

```
% Script plays audio of signal x(t)
dur = 2.0;
fs = 44100;
t = 0:(1/fs):dur;

% Complex representation of the signal
xe1 = 0.5*(exp(1i*440*2*pi*t) + exp(-1i*440*2*pi*t));
xe2 = 0.5*(exp(1i*554*2*pi*t) + exp(-1i*554*2*pi*t));
xe3 = 0.5*(exp(1i*659*2*pi*t) + exp(-1i*659*2*pi*t));
x = xe1 + xe2 + xe3;
sound(x,fs)
```

Problem 3

Filtering of sound

Suppose a continuous-time signal, x(t), is given by the following:

$$x(t) = \cos(440 \cdot 2\pi \cdot t) + \cos(554 \cdot 2\pi \cdot t) + \cos(659 \cdot 2\pi \cdot t)$$

The representation of a periodic signal as a complex Fourier series can be written as follows:

$$x(t) = \sum_{k=-\infty}^{\infty} c_k^x e^{jk\omega_0 t}$$

The complex coefficients, c_k^x , can be written as:

$$c_k^x = \frac{1}{2} \cdot A_k \cdot e^{j\theta_k}$$

It must be noted that $|c_k^x| = |c_{-k}^x| = \frac{A_k}{2} \ \forall \ k \in \mathbb{Z}^+$, however, the same is not true for $\angle c_k^x$. In fact, $\angle c_k^x = -\angle c_{-k}^x \ \forall \ k \in \mathbb{Z}^+$.

For the signal in this problem we note that $w_0 = 2\pi$, which greatly simplifies the complex Fourier series representation since there are only three terms in the sequence whose amplitudes are non-zero: k = 440, k = 554, and k = 659. Further, we see that $A_{440} = A_{554} = A_{659} = 1$, and that $\theta_{440} = \theta_{554} = \theta_{659} = 0$. Hence, the complex exponential Fourier series representation of x(t) is as follows:

$$x(t) = \frac{1}{2} \cdot \left[(e^{j \cdot 440 \cdot 2\pi \cdot t} + e^{-j \cdot 440 \cdot 2\pi \cdot t}) + (e^{j \cdot 554 \cdot 2\pi \cdot t} + e^{-j \cdot 554 \cdot 2\pi \cdot t}) + (e^{j \cdot 659 \cdot 2\pi \cdot t} + e^{-j \cdot 659 \cdot 2\pi \cdot t}) \right]$$

The following Matlab code was run to plot the magnitudes, $|c_k^x|$, versus k:

```
% Script simply plots k vs ck for a signal composed of a finite number
% of cosine functions
% Determine size of plot
n = 1000;
% Create values for k
k = -n:n;
% Create storage vector for |ck|
pos_ck = zeros(1,n);
% Insert ck amplitude into storage vector
A = [440 554 659];
pos_ck(A) = 0.5;
% Compose |ck|
ck = [fliplr(pos_ck) 0 pos_ck];
stem(k,ck,'marker','.')
title('Magnitude of Complex Exponetials')
xlabel('Frequency')
ylabel('Amplitude |ck|')
axis([-1000 1000 0 1]);
```

The plot can be seen in Figure 1.

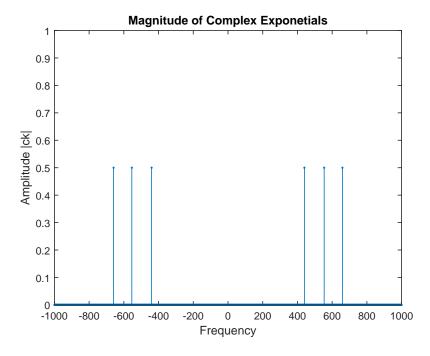


Figure 1: Magnitude of Complex Exponetials

A Matlab function was written to apply an ideal low pass filter to the signal. The Matlab code can be seen below:

```
function ck_out = low_pass_filter(k,ck,w0,B)

% Function has one output ck_out which is the output
% of the input signal with the filter applied to it.
% The inputs for the function are the fundamental
% frequency (w0), the input signal complex coefficients (ck),
% the bandwidth of the filter (B)

filter = abs(-k:k) < (B/w0);
ck_out = ck.*filter;</pre>
```

A Matlab script, implementing the above function, was written to plot the signal output for filters of bandwidth varying from 0 to 5000 rad/s. The script can be seen below:

```
% Script simply plots k vs ck for a signal composed of a finite number
% of cosine functions
% Determine size of plot
n = 1000;
w0 = 2*pi;
% Create values for k
k = -n:n;
% Create storage vector for |ck|
pos\_ck = zeros(1,n);
% Insert ck amplitude into storage vector
A = [440 554 659];
pos_ck(A) = 0.5;
% Compose |ck|
ck = [fliplr(pos_ck) 0 pos_ck];
ck_out = zeros(1,6);
for i = 0:5
    % Run filter over input signal
    ck_out = low_pass_filter(n,ck,w0,1000*i);
    % Create subplot template
    subplot(3,2,i+1)
    % Plot individual stem plots for each B
    stem(k,ck_out,'marker','.')
    title(sprintf('B: %d', 1000*i))
    xlabel('Frequency')
    ylabel('Amplitude |ck|')
    axis([-1000 1000 0 1]);
end
```

The plot can be seen in Figure 2.

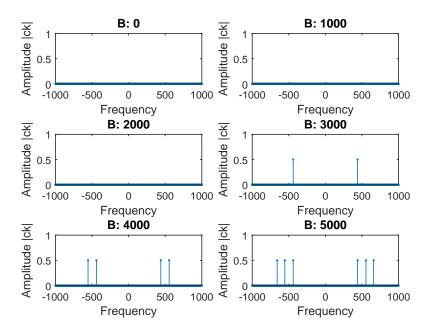


Figure 2: Magnitude of Complex Exponetials

Finally, the script from problem 4 was modified so that the filtered signal would play after each iteration of filtering. The code can be seen below:

```
% Script simply plots k vs ck for a signal composed of a finite number
% of cosine functions
% Determine size of plot
n = 1000;
w0 = 2*pi;
% Create values for k
k_{pos} = 1:n;
k = -n:n;
% Create storage vector for |ck|
pos_ck = zeros(1,n);
% Insert ck amplitude into storage vector
A = [440 554 659];
pos_ck(A) = 0.5;
% Compose |ck|
ck = [fliplr(pos_ck) 0 pos_ck];
ck_out = zeros(1,6);
% Set up sampling frequency and time duration to play back filtered signal
dur = 2.0;
fs = 44100;
t = 0: (1/fs):dur;
for i = 0:5
    \ensuremath{\text{\%}} Plot individual stem plots for each B
    ck_out = low_pass_filter(n,ck,w0,1000*i);
    subplot(3,2,i+1)
    stem(k,ck_out,'marker','.')
   title(sprintf('B: %d', 1000*i))
   xlabel('Frequency')
    ylabel('Amplitude | ck | ')
    axis([-1000 1000 0 1]);
    for j = 1:length(k_pos)
        % Check for magnitudes at frequency
        if ck_out(j) \sim 0
            % Convert back to time series
            x = ck_out(j)*(exp(li*k(j)*w0*t) + exp(-li*k(j)*w0*t));
            % Exclude any complex exponentials
            real_x = real(x);
            sound(x, fs)
            pause (3)
        end
    end
end
```