

Digital Signal Processing

Tutorial 2

ENG421

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1 Overview

The primary objective of this laboratory is to establish a connection between musical notes, their frequencies and sinusoids. Firstly, synthesised waveforms composed of sums of sinusoids, will be sampled to create discrete time waveforms. Secondly, discrete time waveforms will be passed to a Digital to Analogue converter which will output the signal as sound. Finally, the first and second parts of the lab will be combined to create a synthesised version of Beethoven's *Fur Elise*.

2 Background and Results

The laboratory session was broken down into three principal components: sampling, digital to analogue conversion, and finally the synthesis of music. Further, additional tweaks were made to MATLAB code, such as the implementation of an Attack, Decay, Sustain, and Release envelope, and the inclusion of second and third order harmonics. This final step was undertaken to improve the quality of the sound.

2.1 Theory of Sampling

Analogue signals are ubiquitous in the real world. By definition, we consider these signals to be continuous in both time, and in their actual signal value. A problem arises when we want to capture these real signals for analysis on a computer. Given the uncountable set of numbers representing the real valued signal, we would need an infinite number of states to represent the signal. Unfortunately, computer memory is finite. As a compromise, we can agree to sample the real signal at periodic intervals. The sampling process can be seen in Figure 1. The figure shows that a continuous time input, $x(t)$, is sampled by the continuous-to-discrete converter to produce a sequence of numbers, $x[n]$, which represents the discrete time signal.

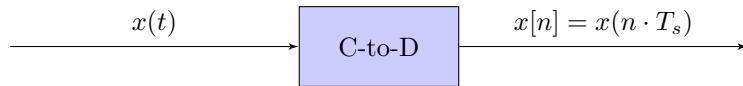


Figure 1: Sampling of a continuous time signal

We note that $n \in \mathbb{N}$ and T_s is the time interval in between samples. The parameter T_s is derived from the sampling frequency f_s . Shannon's Sampling Theorem (McClellan, Schafer & Yoder, 2015) states that in order to obtain a full reconstruction of a bandlimited continuous signal with maximum frequency f_{max} , we need to ensure that our sampling frequency, f_s , is greater than twice our f_{max} . That is:

$$f_s > 2 \cdot f_{max} \quad (1)$$

The sampling frequency condition shown in (1) is a theoretical boundary and as such is the smallest sampling frequency needed to be able to reconstruct the original signal. In practice, however, sampling at this rate can sometimes not produce a faithful reconstruction of the original signal. Best practice often sees the sampling frequency set 5 times f_{max} to achieve signal fidelity in the reconstruction (DeBoer, 2017). A MATLAB script, shown in Appendix A, demonstrates analogue to digital conversion using a sampling frequency of 8000Hz. The script constructs of two discrete time signals:

- (i) A sinusoid with frequency 1100Hz and no phase shift;
- (ii) A sinusoid with frequency 1650Hz and a phase shift of $\frac{\pi}{3}$ rad

After signal sampling and construction, the discrete time waveforms are passed through a digital to analogue converter in order to play the reconstructed signal back. We expect that the second signal will have a higher pitch than the first signal, due to a higher frequency. Further, the phase in the second signal should not have any impact on our perception of the sound of the signal, since it is simply a time delay. The discrete time signals were passed to the D-to-A converter - the process was implemented using the MATLAB script shown in Appendix A. When the signals were played next to each other the second signal sounded higher than the first.

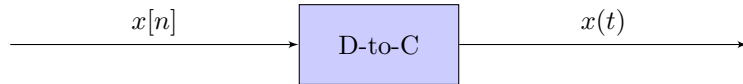


Figure 2: Reconstruction of continuous time signal from discrete time signal

According to McClellan, Schafer & Yoder (2015) the digital to analogue conversion process, shown in Figure 2, is the hardware implementation of the following equation:

$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \cdot p(t - nT_s) \quad (2)$$

The function $p(t)$ is the characteristic pulse shape of the converter, and dictates the type of interpolation employed - normally this is either constant, linear, or cubic-spline. An important point to note in equation (2) is the dependency on sampling period T_s . To understand how this dependency on T_s works, consider a discrete time signal with sampling frequency f_s which is passed through the D-to-A converter. If the D-to-A converter is told that the sampling frequency is twice the actual sampling frequency, that is $2 \cdot f_s$, then the D-to-A uses a sampling period which is half of the actual sampling period. This would have the effect of shortening the duration of the reconstructed signal by half, and increasing the pitch on playback. The script in Appendix A demonstrates this. The discrete time signal with sampling frequency 8000Hz is passed to the D-to-A converter using both 8000Hz and 16000Hz frequencies. The signal reconstruction at 16000Hz shows a shorter duration and higher pitch for both sinusoidal signals.

2.2 Piano Keyboard

Figure 3 shows a piano keyboard with numbered keys. This topology is used in order to create a set of synthesised notes corresponding to the integer numbers, n , on each key such that n is in the set $\{k \in \mathbb{N} \mid 28 \leq k \leq 63\}$. Importantly, we note that each frequency ratio between the keys is constant at $2^{\frac{1}{12}}$. Given this, by using a known frequency of a reference note we can determine the frequency of any note on the board. The chosen reference note for this exercise is the A_4 key at 440Hz. The MATLAB script in Appendix B shows the synthesis of a discrete time sinusoid for the A_4 key using a sampling frequency of 8000Hz. The synthesised waveform was played through the D-to-A converter. A temporal plot of the A_4 signal can be seen in Figure 4.

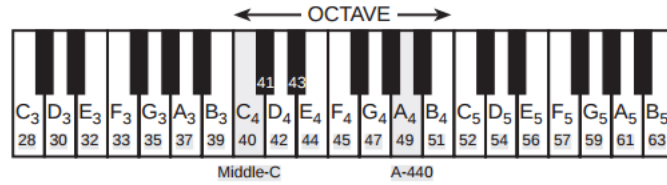


Figure 3: Piano keyboard with integer key numbers and reference key A_4 . Note that not all of the keys are pictured here

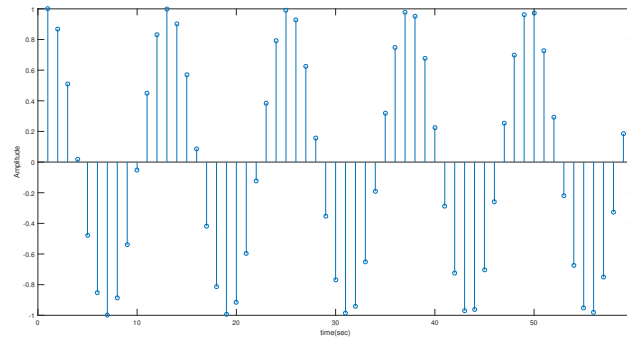


Figure 4: A temporal plot of the synthesised A_4 key

In order to play notes on the keyboard a MATLAB function was built, which can be seen in Appendix C. The function takes an argument, **keynum**, which specifies the number of the key that we want to play on the keyboard. The function takes a second argument, **dur**, which specifies the how long the note will be played. A MATLAB script, seen in Appendix D, was written to test the function. The script played a simple scale. It must be noted that the sampling frequency used in this section of the lab was 11025Hz, recommended by the laboratory instructions.

2.3 Synthesis of *Fur Elise*

Fur Elise is a piece of music composed by Ludwig Van Beethoven which has been synthesised in this laboratory. The implementation of the synthesis, seen in Appendix E, was written in MATLAB and makes use of the previously written note playing function seen in Appendix C. The note sequence and duration for both treble and bass were imported from the file `fenotes.m`. The sampling frequency used for this synthesis is 11025Hz.

2.4 Musical Tweaks

To improve the quality of the synthesised *Fur Elise* two techniques were employed: modulation using an Attack, Decay, Sustain & Release (ADSR) envelope; and implementing second and third order harmonics.

2.4.1 ADSR Envelope

Modulating the signal by some function $E(t)$ is one way in which the sound quality can be improved. Modulating the signal with $E(t)$ means our continuous time output signal is of the form:

$$x(t) = E(t) \cdot \cos(2\pi f_0 t + \phi) \quad (3)$$

The recommended choice for the modulation function $E(t)$ was ADSR, the profile of which can be seen in Figure 5. This was implemented using a MATLAB function `adsr_env` which can be seen in Appendix

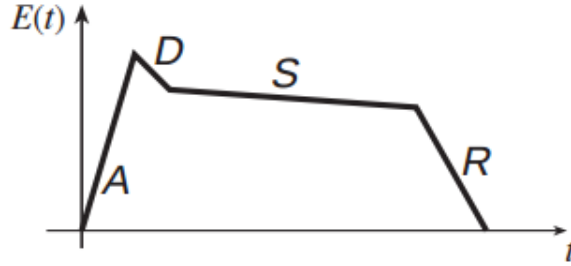


Figure 5: ADSR profile for an envelope function $E(t)$

2.4.2 Second and Third Order Harmonics

According to McClellan, Schafer & Yoder (2015), sums of sinusoids used to synthesise periodic signals and that each one of these sinusoids have harmonically related frequencies. That is to say that each sinusoid has some frequency f_k which is multiple of the fundamental frequency F_0 , for some signal synthesised as:

$$x(t) = A_0 + \sum_{k=1}^N A_k \cos(2\pi k F_0 t + \phi_k) \quad (4)$$

Put simply, we have harmonic frequencies which are integer multiples of the :

$$f_k = k F_0 \quad (5)$$

To improve the sound quality of the synthesised notes that individually make up our synthesised *Fur Elise*, it was recommended that the second and third harmonics be introduced. A MATLAB function, making adjustments to the `note` function, implementing the use of harmonics can be seen in Appendix G.

3 Improvements

The theory underlying the task was relatively straight forward and implementation was easy using MATLAB. There were some issues with the amplitude being set to 100 in some of the tasks - this may have been due to some saturation effect on the machine used to conduct the practical. Changing the amplitudes to 1 or lower ensure that lab results fell in line with expectation.

4 References

McClellan, J., Schafer, R., & Yoder, M. (2015). *DSP First* (Global Edition). Harlow, England: Pearson Education Limited.

5 Appendices

5.1 Appendix A

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% 2.2 Theory of Sampling %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Clear stored variables and the workspace
clear; clc;

% Specify the parameters for the task
A = 100;
w0_1 = 2*pi*1100;
ph_1 = 0;

% Specify the sampling rate and the sampling period
fs = 8000;
Ts = 1/fs;

% Specify the time vector for the signal duration
tt = (0:Ts:2);

% The discrete time sample of the analog signal A*cos(w0*t + ph)
x1 = A*cos(w0_1*tt + ph_1);

% Listen to the sound of the discrete time sampled x1
sound(x1,fs)
pause(3);

% The discrete time sample of the analog signal with a phase shift of
% pi/3 and a different angular frequency
w0_2 = 2*pi*1650;
ph_2 = pi/3;

x2 = A*cos(w0_2*tt + ph_2);

% Combining x1 and x2 to listen to them side by side
xx = [x1 zeros(1,2000) x2];
sound(xx,fs)
pause(5)

% Sending the vector xx through the D-A at double the sampling rate
sound(xx,2*fs)
```

5.2 Appendix B

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% 2.3 Piano Keyboard a %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Clear any stored variables and clear the workspace
clear; clc;

% Initialise the parameters to be used for the script
A = 100;
f440 = 440;

% Specify the sampling frequency and sampling period
fs = 8000;
Ts = 1/fs;

% Generate the time vector for the discrete points at which the
% discrete sample will be generated.
tt = (0:Ts:2);

% Generate the discrete sample of the note
n = 7;
fe5 = f440*2^(7/12);
xx = A*cos(2*pi*fe5*tt);

% Send the note to the D-A converter
sound(xx,fs)
```


5.3 Appendix C

```
function tone = note_adv(keynum,dur)
% NOTE Produce a sinusoidal waveform corresponding to a given
% piano key number

% usage: tone = note(keynum, dur)

% tone = the output sinusoidal waveform
% keynum = the piano keyboard number of the desired note
% dur = the duration (in seconds) of the output note

    % Amplitude of the fundamental frequency
    A0 = 0.5;

    fs = 11025;
    tt = 0:(1/fs):dur;

    if (keynum == 0)
        tone = 0*tt;
    else
        freq0 = 440*2^((keynum-49)/12);
        freq1 = 2*freq0;
        freq2 = 3*freq0;

        tone = A0*cos(2*pi*freq0*tt) ...
            + 0.75*A0*cos(2*pi*freq1*tt) ...
            + 0.5*A0*cos(2*pi*freq2*tt);
    end
end
```

5.4 Appendix D

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% 2.3 Piano Keyboard %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%--- play_scale.m
clear; clc;
%---
keys = [40 42 44 45 47 49 51 52];
%--- NOTES: C D E F G A B C
% key #40 is middle-C
%
dur = 0.25*ones(1,length(keys));
fs = 11025;
xx = zeros(1,sum(dur)*fs+1);

n1 = 1;

for kk = 1:length(keys)
    keynum = keys(kk);

    tone = note(keynum,0.25);

    n2 = n1 + length(tone) - 1;
    xx(n1:n2) = xx(n1:n2) + tone;
    n1 = n2;
end

sound(xx,fs)
```

5.5 Appendix E

```
##### 3.2 Fur Elise #####

% Clear the workspace and any stored variables
clear; clc;

% Load the notes and durations for Treble and Bass for Fur Elise
% from a pre-existing description.
FENOTES;

% Halve the duration of the notes, because I got sick of listening
% to this in its original timing
tdur = tdur/2;
bdur = bdur/2;

% Specify the sampling frequency used for the D-to-A system
fs = 11025;
Ts = 1/fs;

% Synthesize the treble waveform as a combination of sinusoids
xxt = zeros(1,sum(tdur)*fs+1);

n1 = 1;

for kk = 1:length(t)

    tone_t = note_adv(t(kk),tdur(kk));
    E = adsr_env(tone_t);
    tone_t = E.*tone_t;

    n2 = n1 + length(tone_t) - 1;
    xxt(n1:n2) = xxt(n1:n2) + tone_t;
    n1 = n2;
end

% Synthesize the bass waveform as a combination of sinusoids
xxb = zeros(1,sum(bdur)*fs+1);

n1 = 1;

for kk = 1:length(b)

    tone_b = note_adv(b(kk),bdur(kk));
    E = adsr_env(tone_b);
    tone_b = E.*tone_b;

    n2 = n1 + length(tone_b) - 1;
    xxb(n1:n2) = xxb(n1:n2) + tone_b;
    n1 = n2;
end

% Create the overall waveform
xx = xxt + xxb;

sound(xx,fs)
```

5.6 Appendix F

```
function E = adsr.env(tone)
% Function produces an Attack, Decay, Sustain, Release envelope
% which we modulate with our signal to provide better sounding tones

    A = linspace(0, 0.6, (length(tone)*0.2)); %rise 20% of signal
    D = linspace(0.6, 0.5, (length(tone)*0.05)); %drop of 5% of signal
    S = linspace(0.5, 0.5, (length(tone)*0.4)); %delay of 40% of signal
    R = linspace(0.5, 0, (length(tone)*0.35)); %drop of 35% of signal

    ADSR = [A D S R] ; %make a matrix

    len = length(tone) - length(ADSR); %find out the difference

    %concatenates a horrizontal (2) ADSR + the difference of ADSR
    % and the signal
    E = cat(2, ADSR, zeros(1,len));
end
```

5.7 Appendix G

```
function tone = note_adv(keynum,dur)
% NOTE Produce a sinusoidal waveform corresponding to a given
% piano key number

% usage: tone = note(keynum, dur)

% tone = the output sinusoidal waveform
% keynum = the piano keyboard number of the desired note
% dur = the duration (in seconds) of the output note

    % Amplitude of the fundamental frequency
    A0 = 0.5;

    fs = 11025;
    tt = 0:(1/fs):dur;

    if (keynum == 0)
        tone = 0*tt;
    else
        freq0 = 440*2^((keynum-49)/12);
        freq1 = 2*freq0;
        freq2 = 3*freq0;

        tone = A0*cos(2*pi*freq0*tt) ...
            + 0.75*A0*cos(2*pi*freq1*tt) ...
            + 0.5*A0*cos(2*pi*freq2*tt);
    end
end
```