

## 10: Second Derivative Test

Critical point:

$f(x, y)$ : where  $f_x = 0, f_y = 0$

Decide between  $\rightarrow$  {  
 local max  
 local min  
 saddle }  
 Global Max/min?  
 (critical point / boundary)

Consider  $w = ax^2 + bxy + cy^2$

$$\text{Example: } w = x^2 + 2xy + 3y^2 = (x+y)^2 + 2y^2$$

$$\text{If } a \neq 0 \rightarrow w = a\left(x^2 + \frac{b}{a}xy\right) + cy^2 = a\left(x + \frac{b}{2a}y\right)^2 + \left(c - \frac{b^2}{4a}\right)y^2$$

$$w = \frac{1}{4a} \left(4a^2\left(x + \frac{b}{2a}y\right)^2 + (4ac - b^2)y^2\right)$$

3 cases: 1)  $4ac - b^2 < 0 \Rightarrow -\infty, -\infty$

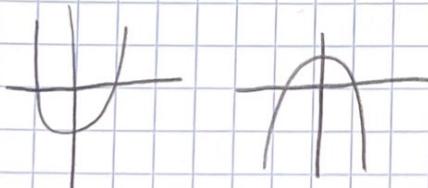
2)  $4ac - b^2 = 0$

3)  $4ac - b^2 > 0 \Rightarrow w = \frac{1}{4a} (+ \dots)^2 + (- \dots)^2$

if  $a > 0$ , minimum

if  $a < 0$ , maximum

$$w = ax^2 + bxy + cy^2 = y^2 \left(a\left(\frac{x}{y}\right)^2 + b\left(\frac{x}{y}\right) + c\right)$$



$w$  takes positive and negative values  $\Rightarrow$  saddle

## 10: second derivative test

$$\frac{\partial^2 f}{\partial x^2} = f_{xx}, \quad \frac{\partial^2 f}{\partial x \partial y} = f_{xy}$$

$$\frac{\partial^2 f}{\partial y \partial x} = f_{yx} = f_{xy}, \quad \frac{\partial^2 f}{\partial y^2} = f_{yy}$$

At a critical point  $(x_0, y_0)$  of  $f$

$$A \equiv f_{xx}(x_0, y_0), \quad B \equiv f_{xy}(x_0, y_0), \quad C \equiv f_{yy}(x_0, y_0)$$

$$AC - B^2 > 0 \begin{cases} \text{local minimum, } A > 0 \\ \text{local maximum, } A < 0 \end{cases}$$

$AC - B^2 < 0 \Rightarrow$  saddle point

$AC - B^2 = 0 \Rightarrow$  inconclusive

$$W = ax^2 + bxy + cy^2$$

$$f_{xx} = \frac{\partial W}{\partial x} (2ax + by) = 2a$$

$$f_{xy} = \frac{\partial W}{\partial y} (2ax + by) = b$$

$$f_{yy} = \frac{\partial W}{\partial y} (bx + 2cy) = 2c$$

$$A = 2a, \quad B = b, \quad C = 2c$$

$$AC - B^2 = 4ac - b^2$$

## 10: Second Derivative Test

### Quadratic Approximation

$$Df \approx f_y(x-x_0) + f_y(y-y_0) + \frac{1}{2} f_{xx}(x-x_0)^2 + f_{xy}(x-x_0)(y-y_0) + \frac{1}{2} f_{yy}(y-y_0)^2$$

$\Downarrow$  0 at crit    0 at crit

In degenerate case, what happens depends on higher order derivatives.

$$f(x,y) = x + y + \frac{1}{xy} \quad \{x, y \neq 0\}$$

$$f_x = 1 - \frac{1}{x^2y} = 0 \quad f_y = 1 - \frac{1}{xy^2} = 0$$

$$\begin{cases} x^2y = 1 \\ xy^2 = 1 \end{cases} \Rightarrow (1, 1)$$

$$f_{xx} = \frac{2}{x^3y} \Rightarrow A = 2 \quad f_{xy} = \frac{1}{x^2y^2} \Rightarrow B = 1 \quad f_{yy} = \frac{2}{xy^3} \Rightarrow C = 2$$

$A - B^2 = 3 > 0 \Rightarrow$  local min/max ( $A > 0$ )  $\Rightarrow$  local minimum

Maximum  $f \rightarrow 0$  when  $x \rightarrow 0$  or  $y \rightarrow 0$  or  $(x, y) \rightarrow 0$

## II: Differentials and Chain Rule

More tools to study functions

Implicit differentiation

$$y = f(x) \rightarrow dy = f'(x)dx$$

$$y = \sin^{-1}(x)$$

$$x = \sin y \rightarrow dx = \cos(y)dy$$

$$\frac{dy}{dx} = \frac{1}{\cos y} = \frac{1}{\sqrt{1-x^2}}$$

Total Differentials

$$f(x, y, z)$$

$$df = f_x dx + f_y dy + f_z dz$$

$$df \neq \Delta f$$

encode how change in  $x, y, z$  affect  $f$

placeholder for small variations to get approx formula

$$\Delta f \approx f_x \Delta x + f_y \Delta y + f_z \Delta z$$

divide by something like  $dt$  to get instant rate of change

$$\frac{df}{dt} = f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt} \leftarrow \text{Chain Rule}$$

## II: Differentials and Chain Rule

$$df = f_x dx + f_y dy + f_z dz$$

$$dx = x'(t) dt, \quad dy = y'(t) dt, \quad dz = z'(t) dt$$

$$df = f_x x'(t) dt + f_y y'(t) dt + f_z z'(t) dt$$

$$\frac{df}{dt} \rightarrow \frac{df}{dt}$$

$$\text{so } \frac{df}{dt} = f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt}$$

$$W = x^2 y + z, \quad x = t, \quad y = e^t, \quad z = \sin t$$

$$\frac{dw}{dt} = 2xy \frac{dx}{dt} + x^2 \frac{dy}{dt} + \frac{dz}{dt}$$

$$= 2te^t + t^2 e^t + \cos t$$

$$W = x^2 y + z$$

$$W(t) = t^2 e^t + \sin t$$

$$\frac{dw}{dt} = 2te^t + t^2 e^t + \cos t$$

$$f = uv \quad u = u(t) \quad v = v(t)$$

$$\frac{d(uv)}{dt} = f_u \frac{du}{dt} + f_v \frac{dv}{dt}$$

$$= v \frac{du}{dt} + u \frac{dv}{dt}$$

$$g = \frac{u}{v}, \quad u = u(t) \quad v = v(t)$$

$$\frac{d\left(\frac{u}{v}\right)}{dt} = \frac{1}{v} \frac{du}{dt} - \frac{u}{v^2} \frac{dv}{dt} = \frac{u'v - v'u}{v^2}$$

## II: Differentials and Chain Rule

$$w = f(x, y)$$

$$\begin{aligned} w &= x(u, v) \\ x &= x(u, v) \end{aligned}$$

$$= f(x(u, v), y(u, v))$$

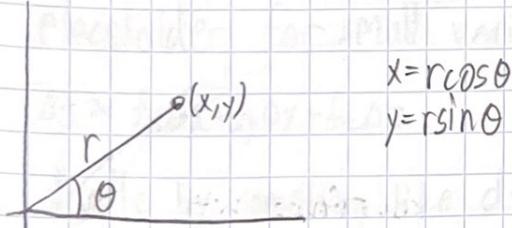
$$dw = f_x dx + f_y dy$$

$$= f_x(x_u du + x_v dv) + f_y(y_u du + y_v dv)$$

$$= (f_x x_u + f_y y_u) du + (f_x x_v + f_y y_v) dv$$

$$\frac{\partial f}{\partial u} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial u}$$

$$\frac{\partial f}{\partial v} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial v}$$



$$f = f(x, y)$$

$$\frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} = f_x \cos \theta + f_y \sin \theta$$

Gradient:

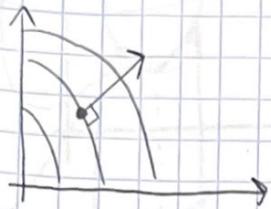
$$\nabla f = (f_x, f_y, f_z)$$

## 12: Gradient

$$\nabla w = \langle w_x, w_y, w_z \rangle$$

$$\frac{d\vec{r}}{dt} = \left\langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right\rangle$$

$\nabla w \perp$  to level surface  $\{w = \text{constant}\}$

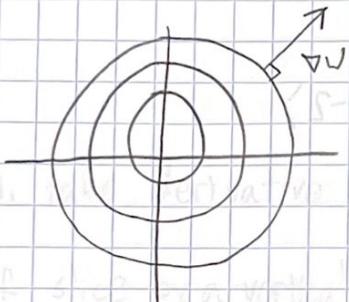


$$w = a_1x + a_2y + a_3z$$

$$\nabla = \langle a_1, a_2, a_3 \rangle$$

$$w = x^2 + y^2$$

$$\nabla w = \langle 2x, 2y \rangle$$



Take  $\vec{r} = \vec{r}(t)$  that stays on level surface  $w=c$



$\vec{v} = \frac{d\vec{r}}{dt}$  is tangent to the level  $w=c$

## 17: Gradient

$$\frac{dw}{dt} = \nabla w \cdot \frac{dr}{dt}$$
$$= \nabla w \cdot \vec{v} = 0$$

$$\nabla w \perp \vec{v}$$

Given any vector tangent to the level

$$\nabla w \perp \vec{v}$$
 always

$$\nabla w \perp \text{tangent plane to the level}$$

Tangent plane to  $x^2 + y^2 - z^2 = 1$  at  $(2, 1, 1)$ :

$$w = x^2 + y^2 - z^2$$

$$\nabla w = \langle 2x, 2y, -2z \rangle = \langle 4, 2, -2 \rangle$$

$$4x + 2y - 2z = 8$$

or:

$$dw = 2x dx + 2y dy - 2z dz$$
$$(2, 1, 1) = 4dx + 2dy - 2dz$$

$$\Delta w \approx 4\Delta x + 2\Delta y - 2\Delta z$$

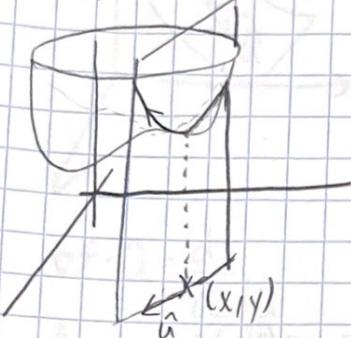
$$\text{Level at } \Delta w = 0 \Rightarrow 4\Delta x + 2\Delta y - 2\Delta z = 0$$
$$\Rightarrow 4(x-2) + 2(y-1) - 2(z-1) = 0$$

## 12: Gradient

Directional derivative:

$w(x, y) \rightarrow$  know  $\frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}$  = derivatives in  $\hat{i}, \hat{j}$

direction of  $\hat{u}$  = unit vector



$$\vec{r}(s), \frac{d\vec{r}}{ds} = \hat{u}$$

If  $\hat{u} = \langle a, b \rangle$

$$\begin{cases} x(s) = x_0 + as \\ y(s) = y_0 + bs \end{cases}$$

$$\begin{cases} x(s) = x_0 + as \\ y(s) = y_0 + bs \end{cases}$$

$\rightarrow$  plug into  $w$ , take derivative  $\frac{dw}{ds}$

$\frac{dw}{ds}|_{\hat{u}}$  = slope of slice by a vertical plane containing  $\hat{u}$

$$\frac{dw}{ds} = \nabla w \cdot \frac{d\vec{r}}{ds} = \nabla w \cdot \hat{u}$$

$$\frac{dw}{ds}|_{\hat{u}} = \nabla \cdot \hat{u}$$

$$\frac{dw}{ds}|_{\hat{u}} = \nabla \cdot \hat{u} = \|\nabla w\| \|\hat{u}\| \cos \theta = \nabla \cdot \hat{u}$$

$$\hat{u} \cdot \nabla w$$

When  $\cos \theta = 1 \Rightarrow \theta = 0 \Rightarrow \hat{u} = \text{dir}(\nabla)$

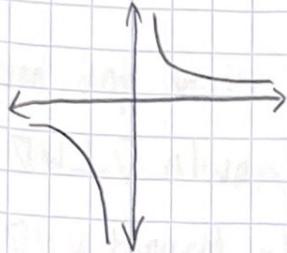
$$|\nabla w| = \frac{dw}{ds}|_{\hat{u}} = \text{dir}(\nabla)$$

### 13: Lagrange Multipliers

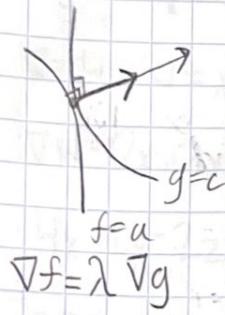
Min/Max of  $f(x_1, y_1, z)$  where  $x_1, y_1, z$  are not independent

$$g(x_1, y_1, z) = c$$

Point closest to origin on hyperbola  $xy=3$



$$f(x_1, y_1) = x^2 + y^2 \text{ subject to constraint } xy = 3 = g(x_1, y_1)$$



$$\nabla f = \lambda \nabla g$$

$$\begin{cases} f_x = \lambda g_x \\ f_y = \lambda g_y \\ g = c \end{cases} \rightarrow \begin{cases} 2x = \lambda y \\ 2y = \lambda x \\ xy = 3 \end{cases} \rightarrow \begin{cases} 2x - \lambda y = 0 \\ 2y - \lambda x = 0 \\ xy = 3 \end{cases}$$

$$\begin{pmatrix} 2 & -\lambda \\ \lambda & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{array}{l} \text{Trivial } (0,0) \text{ not good} \\ \text{Others exist if } \det(M) = 0 \end{array}$$

$$\begin{vmatrix} 2 & -\lambda \\ \lambda & 2 \end{vmatrix} = -4 + \lambda^2 = 0 \Rightarrow \lambda = \pm 2$$

$$\lambda = 2$$

$$x = y$$

$$(\sqrt{3}, \sqrt{3}) = (x, y) \text{ or } (-\sqrt{3}, -\sqrt{3})$$

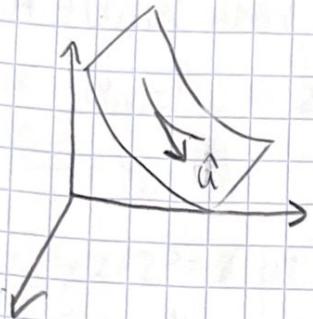
$$\lambda = -2$$

$$x = -y$$

no solutions here

### 13: Lagrange Multipliers

For  $\hat{u}$  to be tangent to  $g=c \Rightarrow \frac{df}{ds}|_{\hat{u}} = 0$



$$\nabla f \cdot \hat{u} = \frac{df}{ds}|_{\hat{u}}$$

Any  $u \perp \nabla f$

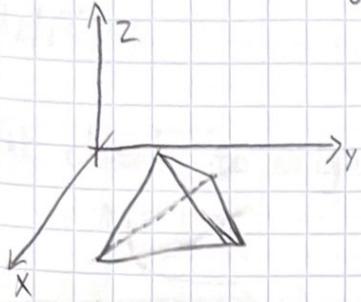
So  $\nabla f \perp$  level set of  $g$   
 $\nabla f \parallel \nabla g$

Method does not tell whether it is max or min  
and second derivative test cannot be used

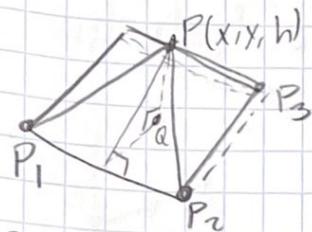
To find min or max we compare values of  $f$   
at the various solutions to the multiplier equations

### 13: Lagrange Multipliers

Pyramid with triangular base and given volume



$$V = \frac{1}{3} A(b) h$$



$$Q(x, y, 0)$$

$$\nabla f = \lambda \nabla g =$$

$$\frac{\partial f}{\partial u_1} = \frac{1}{2} a_1 \frac{u_1}{\sqrt{u_1^2 + h^2}} = \lambda \frac{1}{2} a_1$$

$$\frac{\partial f}{\partial u_2} = \frac{1}{2} a_2 \frac{u_2}{\sqrt{u_2^2 + h^2}} = \lambda \frac{1}{2} a_2$$

$$\frac{\partial f}{\partial u_3} = \frac{1}{2} a_3 \frac{u_3}{\sqrt{u_3^2 + h^2}} = \lambda \frac{1}{2} a_3$$

$$u_1 = u_2 = u_3$$

$Q$  = in center

## 14: Non-independent Variables

$f(P, V, T)$  where  $PV = nRT$

or  $f(x, y, z)$  where  $g(x, y, z) = c$

If  $g(x, y, z) = c \Rightarrow z(x, y)$

$$\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}$$

$$x^2 + yz + z^3 = 8 \text{ at } (2, 3, 1)$$

$$2x dx + z dy + (y + 3z^2) dz = 0$$

$$\text{at } (2, 3, 1) : 4dx + dy + 6dz = 0$$

$$dz = -\frac{1}{6}(4dx + dy)$$

$$\frac{\partial z}{\partial x} = -\frac{4}{6} = -\frac{2}{3}, \quad \frac{\partial z}{\partial y} = -\frac{1}{6}$$

$$\text{Set } dy = 0 \quad \text{Set } dx = 0$$

$$dg = g_x dx + g_y dy + g_z dz = 0$$

$$dz = -\frac{g_x}{g_z} dx - \frac{g_y}{g_z} dy$$

$$\frac{\partial z}{\partial x} = -\frac{g_x}{g_z}$$

## 14: Non-Independent Variables

$$f(x, y) = x + y$$

$$\frac{\partial f}{\partial x} = 1$$

$$x = u$$

$$y = u + v$$

$$f(u, v) = 2u + v$$

$$\frac{\partial f}{\partial u} = 2, \quad \frac{\partial f}{\partial v} = 1$$

$$x = u \text{ but } \frac{\partial f}{\partial x} \neq \frac{\partial f}{\partial u}$$

$$\left(\frac{\partial f}{\partial x}\right)_y = \text{keep } y \text{ constant}$$

$$\left(\frac{\partial f}{\partial u}\right)_v = \text{keep } v \text{ constant}$$

$$\underbrace{\left(\frac{\partial f}{\partial x}\right)_y}_{1} \neq \underbrace{\left(\frac{\partial f}{\partial x}\right)_v}_{2} = \left(\frac{\partial f}{\partial u}\right)_v$$



$$A = \frac{1}{2}ab\sin\theta$$

$$a = b\cos\theta$$

$$\frac{\partial A}{\partial \theta} = \frac{1}{2}ab\cos\theta$$

$$b = b(a, \theta) = \frac{a}{\cos\theta}$$

## 14: Non-independent Variables

$$\left(\frac{\partial A}{\partial \theta}\right)_u : a = b \cos \theta \Rightarrow b = \frac{a}{\cos \theta} = a \sec \theta \Rightarrow \frac{1}{2} a^2 \tan^2 \theta \\ = \frac{1}{2} a^2 \sec^2 \theta$$

$$dA = \frac{1}{2} a \sin \theta (b \tan \theta d\theta) + \frac{1}{2} a b \cos \theta d\theta \\ = \frac{1}{2} ab (\sin \theta \tan \theta + \cos \theta) d\theta$$

$$\left(\frac{\partial A}{\partial \theta}\right)_a = \frac{1}{2} ab \sec \theta$$

Write  $dA$  in terms of  $da, db, d\theta$

$a$  is constant  $\Rightarrow da = 0$

Differentiate constraint  $\rightarrow$  solve for  $db$  in terms of  $d\theta$

Plug into  $dA$  for answer

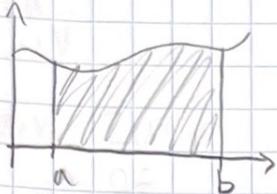
$\left(\frac{\partial}{\partial \theta}\right)_a$  in formula for  $A$

$$\left(\frac{\partial A}{\partial \theta}\right)_a = A_\theta \left(\frac{\partial \theta}{\partial \theta}\right)_u + A_a \left(\frac{\partial a}{\partial \theta}\right)_u + A_b \left(\frac{\partial b}{\partial \theta}\right)_u$$

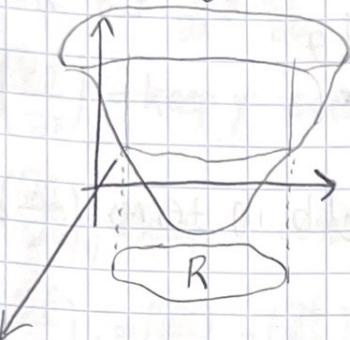
## 16: Double Integrals

Remember function of one variable:

$$\int_a^b f(x) dx = \text{area below the graph of } f \text{ over } [a, b]$$

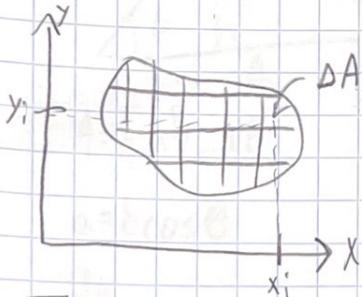


Double integral: Volume  $z = f(x, y)$  over region  $R$  in  $xy$



$$\iint_R f(x, y) dA$$

Cut  $R$  into small pieces  $\Delta A_i$



$$\sum_i f(x_i, y_i) \Delta A_i \rightarrow \Delta A_i \rightarrow 0 \Rightarrow \iint dA$$

## 1b: Double Integrals

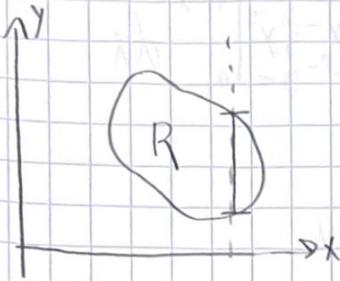
To compute  $\iint_R f(x,y) dA$ : take slices

$S(x)$  = area of slice by plane parallel  $yz$

$$V = \int S(x) dx$$

For a given  $x$ :

$$S(x) = \int f(x,y) dy$$

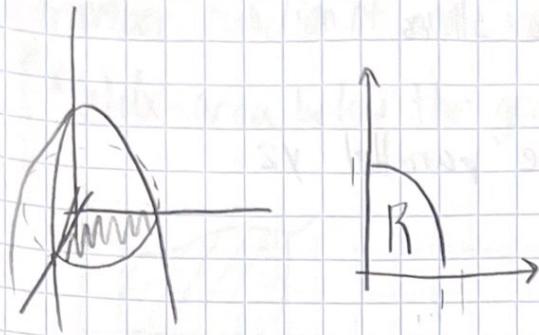


$$\iint_R f(x,y) dA = \int_{x_{\min}}^{x_{\max}} \left( \int_{y_{\min}(x)}^{y_{\max}(x)} f(x,y) dy \right) dx$$

$$z = 1 - x^2 - y^2; R: \begin{cases} 0 \leq x \leq 1 \\ 0 \leq y \leq 1 \end{cases}$$

$$\begin{aligned} \iint_0^1 1 - x^2 - y^2 dy dx &= \int_0^1 \left[ y - x^2 y - \frac{y^3}{3} \right]_0^1 dx = \int_0^1 \frac{2}{3} - x^2 dx \\ &= \left[ \frac{2}{3}x - \frac{1}{3}x^3 \right]_0^1 = \frac{2}{3} - \frac{1}{3} = \frac{1}{3} \end{aligned}$$

# 1b: Double Integrals



$$R = \{x \geq 0, y \geq 0\}$$

$$\begin{aligned}
 \iint_R 1 - x^2 - y^2 dA &= \int_0^1 \int_0^{\sqrt{1-x^2}} 1 - x^2 - y^2 dy dx = \int_0^1 \left[ y - x^2 y - \frac{1}{3} y^3 \right]_0^{\sqrt{1-x^2}} dx \\
 &= \int_0^1 \left( \sqrt{1-x^2} - x^2 \sqrt{1-x^2} - \frac{1}{3} (1-x^2)^{\frac{3}{2}} \right) dx \\
 &= \int_0^1 \frac{2}{3} (1-x^2)^{\frac{3}{2}} dx \Rightarrow \begin{cases} x = \sin \theta \\ dx = \cos \theta d\theta \end{cases} = \int_0^{\frac{\pi}{2}} \frac{2}{3} \cos^3 \theta \cos \theta d\theta \\
 &= \frac{2}{3} \int_0^{\frac{\pi}{2}} \cos^4 \theta d\theta = \frac{2}{3} \int_0^{\frac{\pi}{2}} \left( \frac{1+\cos 2\theta}{2} \right)^2 d\theta \\
 &= \frac{2}{3} \int_0^{\frac{\pi}{2}} \left( \frac{1}{4} + \frac{1}{2} \cos 2\theta + \frac{1}{4} \cos^2 2\theta \right) d\theta = \frac{\pi}{8}
 \end{aligned}$$

## 1b: Double Integrals

Exchange order of integration

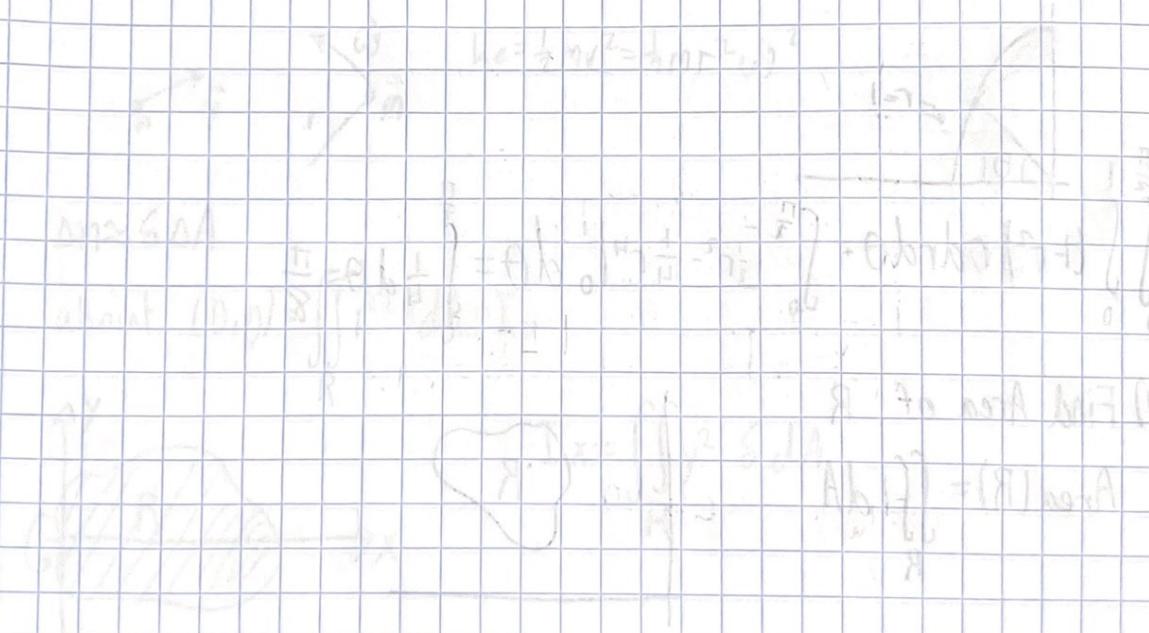
$$\iint_{0,0}^{1,2} dx dy = \iint_{0,0}^{2,1} dy dx$$

$$\iint_{0,x}^{\sqrt{x}} \frac{e^x}{y} dy dx = \int_0^{\sqrt{x}} \int_y^x \frac{e^x}{y} dx dy = \int_0^{\sqrt{x}} \left[ \frac{e^x}{y} x \right]_y^x dy$$

$$= \int_0^{\sqrt{x}} e^y - ye^y dy = \left[ -ye^y + 2e^y \right]_0^{\sqrt{x}}$$

$$= e^{-2}$$

4) Moment of inertia about the y-axis



Find the moment of inertia about the y-axis

$$A_b \cdot R^2 = m \cdot I_{yy} = A \cdot R^2 \cdot m$$