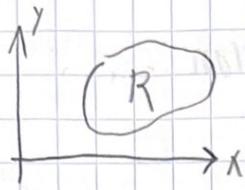


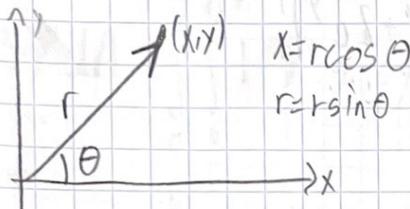
## 17: Polar Coordinates

$$\iint_R f(x,y) dA$$



$$= \iint_R f(x,y) dy dx$$

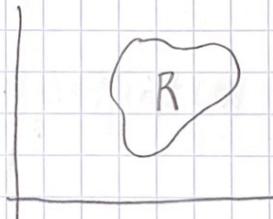
$$\iint_R 1-x^2-y^2 dA$$



$$\int_0^{\frac{\pi}{2}} \int_0^1 (1-r^2) r dr d\theta = \int_0^{\frac{\pi}{2}} \left[ \frac{1}{2}r^2 - \frac{1}{4}r^4 \right]_0^1 d\theta = \int_0^{\frac{\pi}{2}} \frac{1}{4} d\theta = \frac{\pi}{8}$$

i) Find Area of  $R$

$$\text{Area}(R) = \iint_R 1 dA$$



Mass of a flat object with density  $\delta$  = mass per unit area

$$\Delta m = \delta \Delta A \Rightarrow m = \iint_R \delta \cdot dA$$

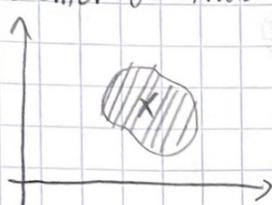
17: Polar Coordinates

2) Average value of  $f$  on a region

$$\bar{f} = \frac{1}{A} \iint_R f dA$$

$$w\bar{f} = \frac{1}{\text{Mass}(R)} \iint_R f \delta dA$$

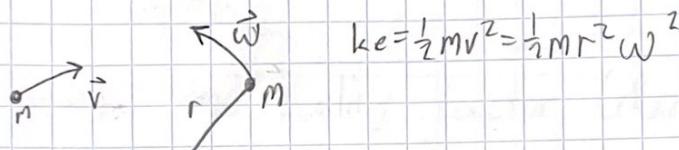
3) Center of Mass



$$(\bar{x}, \bar{y}), \bar{x} = \frac{1}{m} \iint_R x \delta dA$$

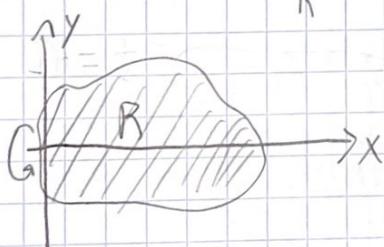
$$\bar{y} = \frac{1}{m} \iint_R y \delta dA$$

4) Moment of Inertia (how hard it is to rotate)



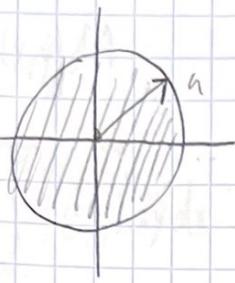
$$\Delta m \approx \delta \Delta A$$

$$\text{about } (0,0) = \iint_R r^2 \delta dA = I_0$$



$$I_x = \iint_R y^2 \delta dA$$

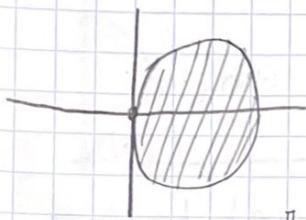
## 17: Polar Coordinates



disk of  $r=a$  ( $\delta=1$ )

$$I_0 = \iint r^2 dA = \int_0^{2\pi} \int_0^a r^2 r dr d\theta = \int_0^{2\pi} \left[ \frac{1}{4} r^4 \right]_0^a d\theta$$

$$= \int_0^{2\pi} \frac{1}{4} a^4 d\theta = \frac{\pi a^4}{2}$$



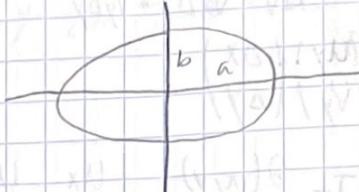
$$I_0 = \iint r^2 dA = \iint r^2 r dr d\theta = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_0^R r^2 r dr d\theta = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \left[ \frac{1}{4} r^4 \right]_0^R |^{2\cos\theta} d\theta$$

$$= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} 4a^4 \cos^4 \theta d\theta = \frac{3}{2} \pi a^4$$

## 18: Change of Variables

Area of ellipse with axes,  $a, b$

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1$$



$$\iint_R dx dy$$

$$R: \{(x, y) \mid \left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 \leq 1\}$$

$$\begin{cases} \frac{x}{a} = u \rightarrow du = \frac{1}{a} dx \\ \frac{y}{b} = v \rightarrow dv = \frac{1}{b} dy \end{cases}$$

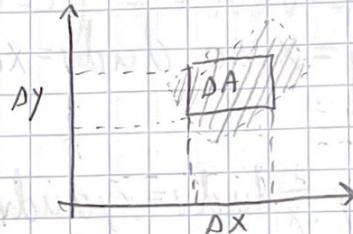
$$\iint_R dx dy = \iint_{u^2+v^2 \leq 1} du dv = \pi ab$$

In general: find scaling factor ( $dx dy$  vs  $du dv$ )

$$u = 3x - 2y, v = x + y$$

$$dA = dx dy$$

$$dA' = du dv$$



$$A' = \begin{vmatrix} 3 & -2 \\ 1 & 1 \end{vmatrix} = 5 \Rightarrow dA' = 5 dA$$

$$\iint_R dx dy = \iint \frac{1}{5} du dv$$

## 18: Change of Variables

$$u = u(x, y)$$

$$v = v(x, y)$$

$$\Delta u = u_x \Delta x + u_y \Delta y$$

$$\Delta v = v_x \Delta x + v_y \Delta y$$

$$\begin{pmatrix} \Delta u \\ \Delta v \end{pmatrix} \approx \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

Jacobian:  $J = \frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}$

$$dudv = |J| dx dy = \left| \frac{\partial(u, v)}{\partial(x, y)} \right| dx dy$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$$

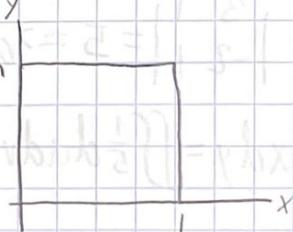
$$dx dy = r dr d\theta$$

$$\iint_R x^2 y dx dy \text{ by change of variables: } u = x, v = xy$$

$$\frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} 1 & 0 \\ y & x \end{vmatrix} = x \text{ so } dudv = x dx dy$$

$$x^2 y dx dy = x^2 y \frac{1}{x} dudv = xy dudv = v dudv$$

$$\iint_R v dudv = \iint_{D'} v dudv$$



## 18: Change of Variables

$$\iint_R x+y \, dA \quad R: \text{ bounded by } y=-2x, y=\frac{1}{2}x-\frac{15}{2}, y=-2x+10, y=\frac{11}{2}x$$

R

$$x=u+2v, y=v-2u$$

$$y=2x: v-2u=2u-4v \rightarrow v=0$$

$$y=\frac{1}{2}x-\frac{15}{2}: 2v-4u=u+2v-15 \rightarrow u=3$$

$$y=-2x+10: v-2u=-2u-4v+10 \rightarrow v=2$$

$$y=\frac{11}{2}x: 2v-4u=u+2v \rightarrow u=0$$

$$J = \begin{vmatrix} 1 & 2 \\ -2 & 1 \end{vmatrix} = 5$$

$$\iint_0^2 \int_0^3 (u+2v) + (v-2u) 5 \, du \, dv = 5 \iint_0^2 \int_0^3 -u+3v \, du \, dv$$

$$= 5 \int_0^2 \left[ -\frac{1}{2}u^2 + 3vu \right]_0^3 \, dv = 5 \int_0^2 \left[ -\frac{9}{2} + 9v \right] \, dv = 5 \left[ -\frac{9}{2}v + \frac{9}{2}v^2 \right]_0^2$$

$$= 45$$

## 14: Vector Fields

$\vec{F} = M\hat{i} + N\hat{j}$   $M$  and  $N$  are functions of  $x$  and  $y$

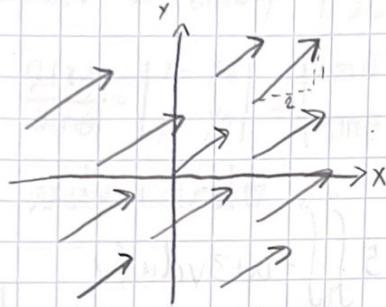
At each point in the plane, there is a vector  $\vec{F}$  that depends on  $x$  and  $y$

Examples

- velocity  $\vec{v}$

- force field  $\vec{F}$

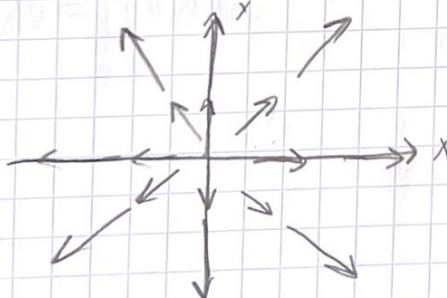
$$\vec{F} = 2\hat{i} + \hat{j}$$



$$\vec{F} = x\hat{i}$$



$$\vec{F} = x\hat{i} + y\hat{j}$$



## 19: Vector Fields

Work and line integral

$$W = \vec{F} \cdot \Delta \vec{r}$$

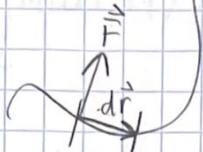
$$W = \int_C \vec{F} \cdot d\vec{r}$$

$$\left( \lim_{\Delta r_i \rightarrow 0} \sum \vec{F} \cdot d\vec{r}_i \right)$$

$$= \sum_i \vec{F} \cdot \left( \frac{\Delta \vec{r}}{\Delta t} \Delta t \right)$$

$$\downarrow \quad \nabla = \frac{d\vec{r}}{dt}$$

$$\int_{t_i}^{t_f} \vec{F} \cdot \frac{d\vec{r}}{dt} dt$$



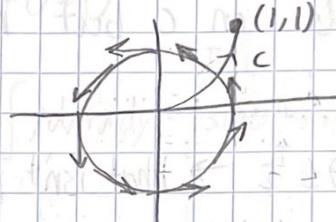
$$\vec{F} = -y\hat{i} + x\hat{j}$$

$$C: \{x=t, y=t^2, 0 \leq t \leq 1\}$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_0^1 \vec{F} \cdot \frac{d\vec{r}}{dt} dt$$

$$= \int_0^1 \langle -t^2, t \rangle \cdot \langle 1, 2t \rangle dt = \int_0^1 -t^2 + 2t^2 dt$$

$$= \int_0^1 t^2 dt = \frac{1}{3}$$



## 19: Vector Fields

$$\vec{F} = \langle M, N \rangle$$

$$d\vec{r} = \langle dx, dy \rangle$$

$$\vec{F} \cdot d\vec{r} = M dx + N dy$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C M dx + N dy$$

$$= \int_C -y dx + x dy \text{ in terms of}$$

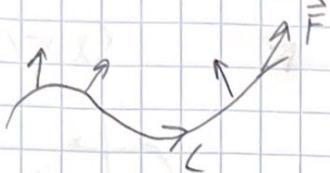
$$\begin{cases} x = t \\ y = t^2 \end{cases} \rightarrow \begin{cases} dx = dt \\ dy = 2t dt \end{cases}$$

$$\int_C -t^2 dt + t \cdot 2t dt = \int_0^1 t^2 dt = \frac{1}{3}$$

$\int_C \vec{F} \cdot d\vec{r}$  depends on  $C$  but not parameterization

$$\begin{cases} x = \sin \theta \\ y = \sin^2 \theta \end{cases} \quad 0 \leq \theta \leq \frac{\pi}{2} \rightarrow \text{that isn't practical}$$

## 20: Conservative Fields



$$\int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \hat{T} ds = \int_C M dx + N dy, \quad \vec{F} = \langle M, N \rangle$$

$$y\hat{i} + x\hat{j}$$

$$\int_C \vec{F} \cdot d\vec{r}$$

$$C = C_1 + C_2 + C_3$$

$$0 \leq \theta \leq \frac{\pi}{4}$$

$$C_1: y=0 \Rightarrow \int_{C_1} y dx + x dy = \int_{C_1} 0 dx + 0 = 0$$

$$C_2: \begin{aligned} x &= \cos \theta & dx &= -\sin \theta d\theta \\ y &= \sin \theta & dy &= \cos \theta d\theta \end{aligned} \Rightarrow \int_{C_2} y dx + x dy = \int_0^{\frac{\pi}{4}} \sin \theta (-\sin \theta) d\theta + \cos \theta \cdot \cos \theta d\theta = \int_0^{\frac{\pi}{4}} \cos^2 \theta - \sin^2 \theta d\theta = \left[ \frac{1}{2} \sin 2\theta \right]_0^{\frac{\pi}{4}} = \frac{1}{2}$$

$$C_3: \begin{aligned} x &= \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} t & \Rightarrow \int_{C_3} = - \int_{C_3} \Rightarrow \int_0^{\frac{1}{\sqrt{2}}} t dt + t dt = \left[ \frac{1}{2} t^2 \right]_0^{\frac{1}{\sqrt{2}}} = -\frac{1}{2} \\ y &= \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}} t & \end{aligned}$$

$$0 \leq t \leq 1$$

$$\int_{C_1} + \int_{C_2} + \int_{C_3} = 0 + \frac{1}{2} - \frac{1}{2} = 0$$

## 20: Conservative Fields

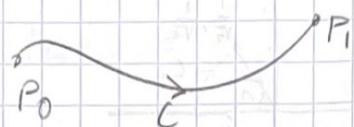
Special case:  $\vec{F} = \nabla f$  = gradient field

( $f(x, y)$ ) is called potential of  $\vec{F}$

Then we can simplify the  $\int_C \vec{F} \cdot d\vec{r}$

Fundamental Theorem of Line Integrals

$$\int_C \nabla f \cdot d\vec{r} = f(P_1) - f(P_0)$$



$$\int_C f_x dx + f_y dy = \int_C df = f(P_1) - f(P_0)$$

$$\int_C \nabla f \cdot d\vec{r} \Rightarrow C : x = x(t), y = y(t)$$

$dx = x'(t) dt, dy = y'(t) dt$

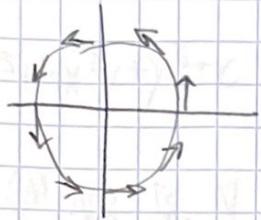
$$\int_C \left( f_x \frac{dx}{dt} + f_y \frac{dy}{dt} \right) dt = \int_C \frac{df}{dt} dt = \int_{t_0}^{t_1} \frac{df}{dt} dt$$

$$\vec{F} = \nabla f \Rightarrow \text{conservative}$$

$$\int_C \vec{F} \cdot d\vec{r} = 0$$

## 20: Conservative Fields

$$\vec{F} = \langle -y, x \rangle$$



$\vec{F}$  is tangent

$$\vec{F} \cdot \hat{T} = |\vec{F}| = 1$$

Not conservative, not path independent

If a force field  $\vec{F}$  is  $\nabla \phi$  potential

Energy is conserved