

27: 3D Vector Fields

At every point $\vec{F} = \langle P, Q, R \rangle$

Force fields

↑↑
Functions of (x, y, z)

$$\vec{F} = -c \frac{\langle x, y, z \rangle}{P^3}$$

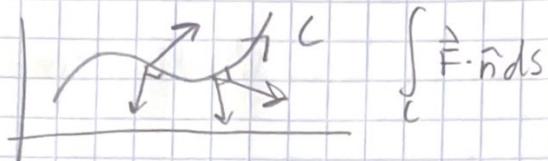
Velocity fields \vec{v}

Gradient fields

$$u = u(x, y, z)$$

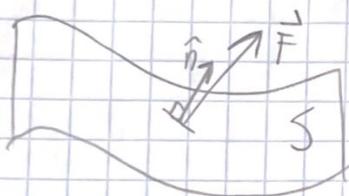
$$\nabla u = \langle u_x, u_y, u_z \rangle$$

Flux



Flux measured through a surface in 3D

\vec{F} vector field, S a surface in space



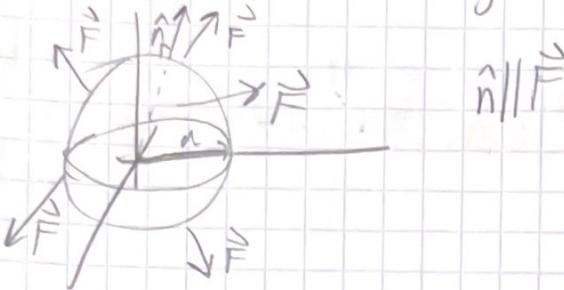
\hat{n} = unit normal to S

27: 3D Vector Fields

$$\text{Flux} = \iint_S \vec{F} \cdot \hat{n} dS$$

$$d\vec{S} = \hat{n} dS$$

Flux of $\vec{F} = (x, y, z)$ through sphere $r=a$ ($0, 0, 0$)



$$\iint_S \vec{F} \cdot d\vec{S} = \iint_S \vec{F} \cdot \hat{n} dS$$

$$\hat{n} = \frac{1}{a} (x, y, z)$$

$$\vec{F} \cdot \hat{n} = |\vec{F}| |\hat{n}| = |\vec{F}|$$

$$\iint_S \vec{F} \cdot \hat{n} dS = \iint_S a dS = a \iint_S dS = 4\pi a^3$$

Same sphere $\vec{F} = -z \hat{k}$, $\vec{F} \cdot \hat{n} = \frac{z^2}{a}$

$$\iint_S \vec{F} \cdot \hat{n} dS = \iint_S \frac{z^2}{a} dS \quad dS = \dots d\phi d\theta$$

$$dS = (a \sin \theta d\phi) (a \rho \sin \theta d\theta)$$

$$dS = a^2 \sin^2 \theta d\phi d\theta$$

$$\iint_0^{2\pi} \int_0^\pi \frac{a^2 \cos^2 \theta}{a} a^2 \sin \theta d\phi d\theta = 2\pi a^3 \left[-\frac{1}{3} \cos^3 \theta \right]_0^\pi = \frac{4}{3}\pi a^3$$

27: 3D Vector Fields

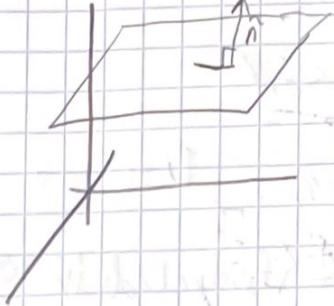
Use geometry

Set up $\iint_S \vec{F} \cdot \hat{n} dS$

$S = \text{horizontal plane } (z=a)$

$$\hat{n} = \pm \hat{k}$$

$dS = dx dy \Leftrightarrow dy dx$ (vertical)



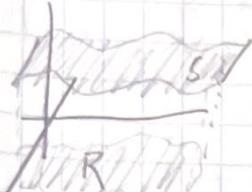
$$z = f(x, y)$$

$$\hat{n} dS = \pm (-f_x, -f_y, 1) dx dy$$

28: The Divergence Theorem

Flux of \vec{F} through S is $\iint_S \vec{F} \cdot \hat{n} dS$

If S is the graph of a function $z = f(x, y)$



$$\hat{n} dS = \pm \langle f_x, -f_y, 1 \rangle dx dy$$

$$\vec{u} \times \vec{v} = \Delta s \cdot \hat{n}$$

$$\hat{n} \Delta S = \vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & f_x \\ 0 & 1 & f_y \end{vmatrix} \Delta x \Delta y = \langle -f_x, -f_y, 1 \rangle \Delta x \Delta y$$

$\vec{F} = z\hat{k}$ through $z = x^2 + y^2$ above unit disk

$$\iint_S \vec{F} \cdot \hat{n} dS \Rightarrow \iint_S \langle 0, 0, z \rangle \cdot \langle -2x, -2y, 1 \rangle dx dy$$

$$= \iint_S (x^2 + y^2) dx dy = \iint_D (x^2 + y^2) dx dy = \int_0^{2\pi} \int_0^1 r^2 r dr d\theta$$

$$= \int_0^{2\pi} \left[\frac{1}{4} r^4 \right]_0^1 d\theta = \int_0^{2\pi} \frac{1}{4} d\theta = \frac{1}{4} \theta \Big|_0^{2\pi} = \frac{1}{4} 2\pi = \frac{\pi}{2}$$

Given

$$S = \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$$

$$\langle x, y, z \rangle = \vec{r} = \vec{r}(u, v)$$

28. The Divergence Theorem

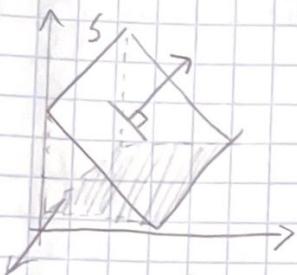


$\hat{n} dS$

$$\frac{\partial \vec{r}}{\partial u} \Delta u = \left\langle \frac{\partial x}{\partial u} \Delta u, \dots \right\rangle$$

$$\hat{n} dS = \left(\frac{\partial \vec{r}}{\partial u} \Delta u \right) \times \left(\frac{\partial \vec{r}}{\partial v} \Delta v \right) = \left(\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right) \Delta u \Delta v$$

If we know normal \vec{N}



$$\cos \alpha = \frac{\vec{N} \cdot \hat{k}}{|\vec{N}| |\hat{k}|}$$

$$\hat{n} dS = \frac{|\vec{N}| \hat{k}}{\vec{N} \cdot \hat{k}} \Delta A = \pm \frac{\vec{N}}{|\vec{N}| k} \Delta A$$

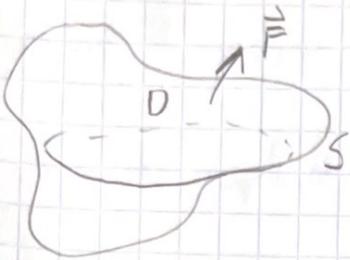
$$\hat{n} dS = \pm \frac{\vec{N}}{|\vec{N}| k} dx dy$$

If S is a closed surface enclosing D , \vec{F} is out, \vec{F} is differentiable in D

$$\iint_S \vec{F} \cdot d\vec{S} = \iiint_D \operatorname{div}(\vec{F}) dV$$

$$\operatorname{div} (P\hat{i} + Q\hat{j} + R\hat{k}) = P_x + Q_y + R_z$$

29: The Divergence Theorem



$$\iint_S \vec{F} \cdot d\vec{s} = \iiint_D \text{Div}(\vec{F}) dV$$

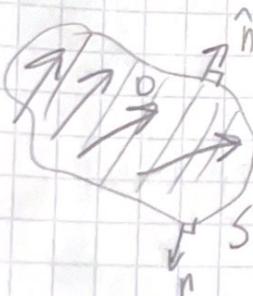
$$\iint_S (P, Q, R) \cdot \hat{n} ds = \iiint_D (P_x + Q_y + R_z) dV$$

∇ Notation

$$\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$\nabla \cdot \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

$\text{div}(\vec{F})$ = source rate



$$\iiint_D \text{div}(\vec{F}) dV = \iint_S \vec{F} \cdot \hat{n} ds$$

29: The Divergence Theorem

$$\iint_S \langle 0, 0, R \rangle \cdot \hat{n} dS = \iiint_D R_z dV$$

R:

$$\iiint_D R_z dV = \iint_D \int_{z(x,y)}^{z_2(x,y)} R_z dz dx dy$$

$$\iiint_D R_z dV = \iint_D [R(x, y, z_2(x, y)) - R(x, y, z_1(x, y))] dx dy$$

$$\iint_S \langle 0, 0, R \rangle \cdot \hat{n} dS = \iint_{\text{top}} + \iint_{\text{bottom}} + \iint_{\text{sides}}$$

$$\iint_B \langle 0, 0, R \rangle \cdot \hat{n} dS = \iint_B -R dx dy = \iint_B -R(x, y, z_1(x, y)) dx dy$$

$$\iiint_D R_z dV = \iint_{\text{top+bottom+sides}} \langle 0, 0, R \rangle \cdot \hat{n} dS$$



$$u(x, y, z, t) \quad \frac{\partial u}{\partial t} = k \nabla^2 u = k \nabla \cdot \nabla u \quad \operatorname{div}(\nabla)$$

$$\iint_S \vec{F} \cdot \hat{n} dS = \frac{d}{dt} \left(\iiint_D u dV \right) = \iiint_D \frac{\partial u}{\partial t} dV$$

$$\operatorname{div}(\vec{F}) = \frac{\partial u}{\partial t}$$

30: Line Integrals in Space

$$\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$$

Curve C in space

$$W = \int_C \vec{F} \cdot d\vec{r} \quad d\vec{r} = (dx, dy, dz)$$

$$\int_C P dx + Q dy + R dz$$

$$\vec{F} = \langle yz, xz, xy \rangle$$

$$C: x = t^3, y = t^2, z = t \quad 0 \leq t \leq 1$$

$$dx = 3t^2 dt, dy = 2t dt, dz = dt$$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C yz dx + xz dy + xy dz = \int_0^1 t^2 \cdot 3t^2 dt + t^4 \cdot 2t dt + t^5 dt \\ &= \int_0^1 6t^5 dt = [t^6]_0^1 = 1 \end{aligned}$$

$$\vec{F} = \nabla f(x, y, z) = \langle yz, xz, xy \rangle$$

$$\int_C \nabla f \cdot d\vec{r} = f(P_1) - f(P_0)$$

$$f(1, 1, 1) - f(0, 0, 0) = 1$$

$$P dx + Q dy + R dz = \text{exact} \quad (= df) \Leftrightarrow \dots$$

$$fx = 2xy \Rightarrow f = x^2y + g(y, z)$$

$$\int dx \quad \downarrow \frac{\partial}{\partial y}$$

$$fy = x^2 + z^3 \Rightarrow x^2 + gy = z^3 \Rightarrow g = yz^3 + h(z)$$

$$f_z = yz^2 - 4z^3 \Rightarrow yz^2 + h(z) \Rightarrow h = -z^4 + C \Rightarrow f = x^2y + yz^3 - z^4 + C$$

80: Line Integrals in Space

Curl in 3D: if $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k} \Rightarrow \text{curl}(\vec{F}) = (R_y - Q_z)\hat{i} + (P_z - R_x)\hat{j} + (Q_x - P_y)\hat{k}$

If \vec{F} defined

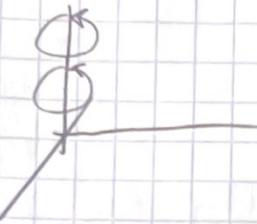
\vec{F} conservative $\Leftrightarrow \text{curl}(\vec{F}) = 0$

$$\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

$$\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle$$

$$\nabla \cdot \langle P, Q, R \rangle = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \text{div}(\vec{F})$$

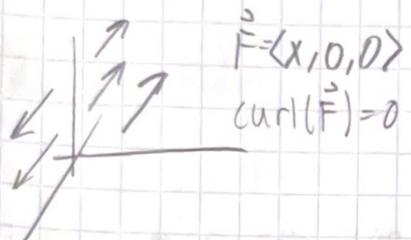
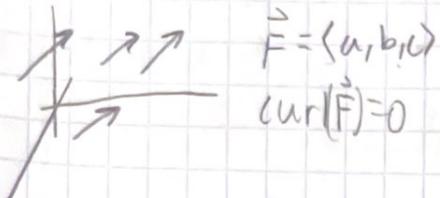
$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \hat{i} - \left(\frac{\partial R}{\partial x} + \frac{\partial P}{\partial z} \right) \hat{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \hat{k} = \text{curl}(\vec{F})$$



$$\vec{v} = \langle -wy, wx, 0 \rangle \quad \text{curl}(\vec{v}) = 2w\hat{k}$$

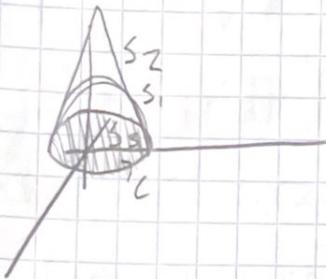
31: Stokes' Theorem

$$\operatorname{curl}(\vec{F}) = \nabla \times \vec{F}$$



$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS$$

S = any surface bounded by C



C, S compatible

RHR: thumb along C positively, the index finger tangent to S

middle finger points \hat{n}



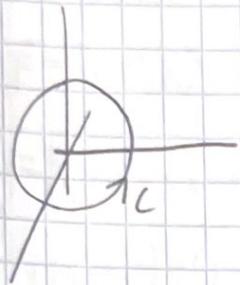
S = portion of XY bounded by C

$$\begin{aligned} \oint_C \vec{F} \cdot d\vec{r} &= \oint_C P dx + Q dy = \iint_S (\nabla \times \vec{F}) \cdot \hat{k} dS \\ &= \iint_S (Q_x - P_y) dx dy \end{aligned}$$

31: Stokes Theorem

Green's = special case (xy) of stoke's

$\vec{F} = z\hat{i} + x\hat{j} + y\hat{k}$ around unit circle in xy CCW



$$\oint_C zdx + xdy + ydz$$

$$x = \cos t$$

$$y = \sin t$$

$$z = 0$$

$$= \int_0^{2\pi} 0 + \cos t (\cos t dt) + 0$$

$$= \int_0^{2\pi} \cos^2 t dt = \pi$$

$$z = 1 - x^2 - y^2$$



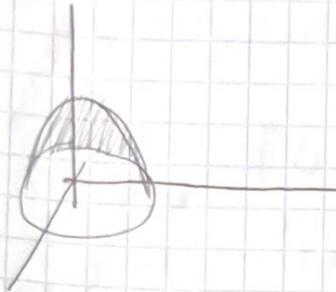
$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS \rightarrow \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z & x & y \end{vmatrix} = (1)\hat{i} - (-1)\hat{j} + (1)\hat{k} = \langle 1, 1, 1 \rangle$$

$$\hat{n} dS = \langle -f_x, -f_y, 1 \rangle dx dy = \langle 2x, 2y, 1 \rangle dx dy$$

$$\iint_S \langle 1, 1, 1 \rangle \cdot \langle 2x, 2y, 1 \rangle dx dy = \iint_S 2x + 2y + 1 dx dy = \pi$$

32: Stokes' Theorem

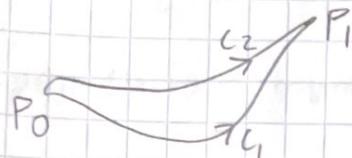
$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS$$



space with origin removed is
simply connected

$$\text{if } \vec{F} = \nabla f \Rightarrow \text{curl}(\vec{F}) = 0$$

$$\text{Assume } \text{curl}(\vec{F}) = 0$$



$$\begin{aligned} \oint_{C_1} \vec{F} \cdot d\vec{r} - \oint_{C_2} \vec{F} \cdot d\vec{r} &= \oint_C \vec{F} \cdot d\vec{r} \\ &= \iint_S (\text{curl}(\vec{F})) \cdot d\vec{S} = 0 \end{aligned}$$



Surface of torus not simply connected

Two independent loops which bound nothing

$$\iint_{S_1} (\nabla \times \vec{F}) \cdot \hat{n} dS - \iint_{S_2} (\nabla \times \vec{F}) \cdot \hat{n} dS = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS$$

32: Stokes Theorem

$$= \iiint_D \operatorname{div}(\nabla \times \vec{F}) dV$$

$$\operatorname{div}(\nabla \times \vec{F}) = 0$$

$$\vec{F} = \langle P, Q, R \rangle \Rightarrow \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$= R_{yx} - Q_{zx} + P_{zy} - R_{xy} + Q_{xz} - P_{yz}$$

$$\nabla \cdot (\nabla \times \vec{F}) = 0$$

$$\iiint_R f dV$$

- rectangular: $dV = dz dx dy$

- cylindrical: $dV = dz r dr d\theta$

- spherical: $dV = \rho^2 \sin\phi d\rho d\phi d\theta$

- mass

- average value

- moment of inertia

- gravitational attraction at $(0,0,0)$

$$\iint_S \vec{F} \cdot \hat{n} dS$$

$$\hat{n} dS = \dots dx dy \Rightarrow \iint_S \dots dx dy$$

$$\oint_C \vec{F} \cdot d\vec{r} = \int P dx + Q dy + R dz$$

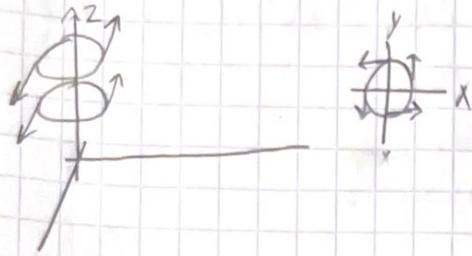
Parameterize $C \Rightarrow$ expression in terms of single variable

$$\iint_S \vec{F} \cdot \hat{n} dS = \iiint_D (\operatorname{div}(\vec{F})) dV$$

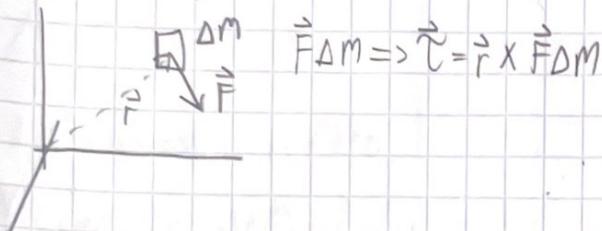
$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} dS$$

33: Maxwell's Equations

Curl: \vec{v} velocity field $\Rightarrow \text{curl}(\vec{v})$ measures 2. angular velocity vector



$$\vec{v} = \omega(-y\hat{i} + x\hat{j}) \Rightarrow \nabla \times \vec{v} = 2\omega\hat{k}$$

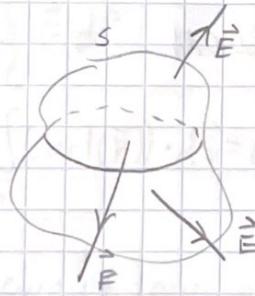


$$\vec{E}, \vec{B}$$

$$\vec{F} = q\vec{E}, \vec{F} = q\vec{v} \times \vec{B}$$

Gauss Coulomb Law

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$



$$\oint \vec{E} \cdot d\vec{s} = \iiint_D \text{div}(\vec{E}) dV = \frac{1}{\epsilon_0} \iiint_D \rho dV = \frac{Q}{\epsilon_0}$$

3B: Maxwell's Equations

Faraday's Law

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$



$$\oint_C \vec{E} \cdot d\vec{r} = \iint_S (\nabla \times \vec{E}) \cdot d\vec{s} = \iint_S \left(-\frac{\partial \vec{B}}{\partial t}\right) \cdot d\vec{s}$$

$$\nabla \cdot \vec{B} = 0 \quad (\text{Gauss Magnetism})$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} \quad (\text{Maxwell-Ampere})$$