31606 Signals and Linear Systems in discrete time

Hands on 9 Group 1

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||| How finite should it be?

- i) Like a hot knive through a Butterworth We are asked to design a filter meeting the following requirements:
 - Passband from 0.2 to 0.3
 - Stopbands from 0 to 0.1 ad 0.4 to 1
 - Rippels in passband no greater than 2dB
 - Stopband attenuation min. 100dB

While the headline does imply that a butterworth filter could be used, this does not allow us to utilize that rippels in both the stop and passband are accepted.

We use the *Matlab* filter toolbox to design our filer:

Pole-Zero plot of the filter can be seen in fig. 1, frequency response (and specification boundaries) can be found in fig. 2 and impulse response in fig. 3

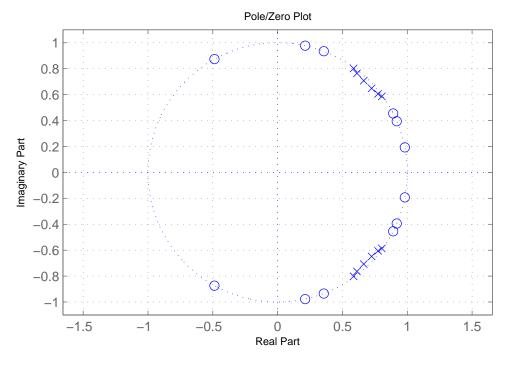


Figure 1: blablabla

We find that point i in the impulse response where the maximum amplitude is below a value of 10% of the maximum amplitude of the whole signal so that:

$$x[1:\inf] * 10\% > x[i:\inf]$$

This is done with the Matlab code:

```
%make list of max of remaining response:
maxrest = uncut_ir;
for i = 1:length(maxrest)
    maxrest(i) = max( abs( uncut_ir(i:end) ) );
    if maxrest(i) < maxval*sig
        break; %stop here, i is now the index, where all samples [i:inf[ < max end end</pre>
```

This gives an "effective" length of 134 samples. (Had we chosen a buttersworth filter instead this would have been 146 samples).

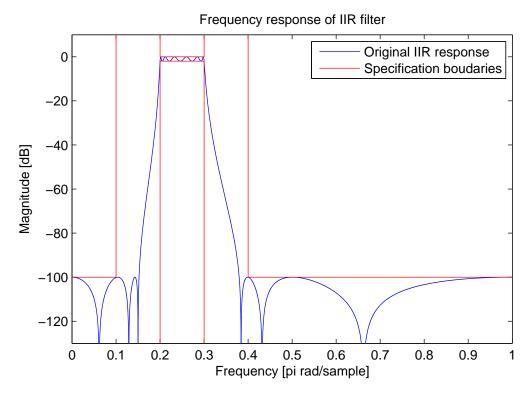


Figure 2: cornerfreq: 0.3004, 1.997

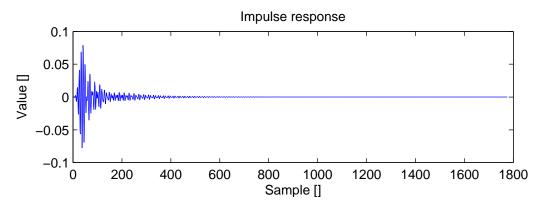


Figure 3: blablabla

We now use a rectangular window to cut the impulseresponse at 100%, 75%, 60%, 40% and 10% of the original. The frequency response of the filter with these impulseresponses as kernes are shown in fig. 4

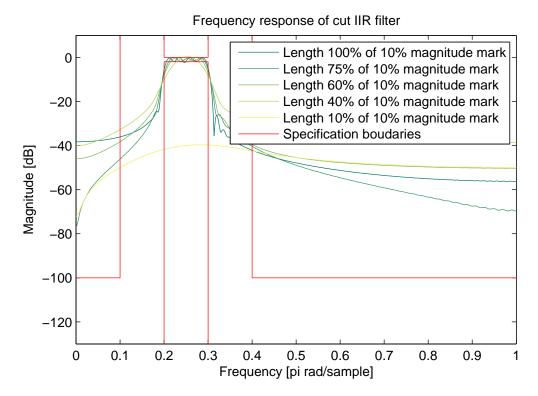


Figure 4: blablabla

It is quite clear that neither of the filters meet the requirements. As the impulse length is shortend there, surprisingly, is not that big of a difference in the filter, until somewhere between 40% and 10% of the length.

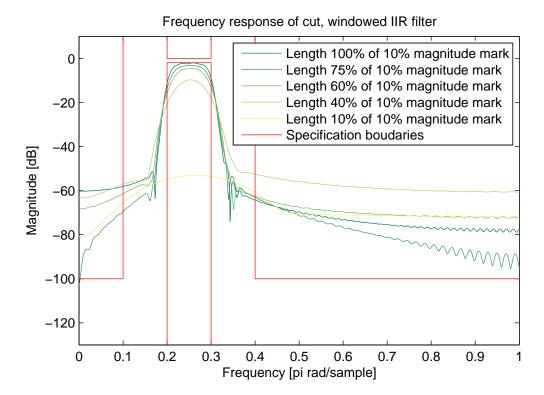


Figure 5: blablabla