



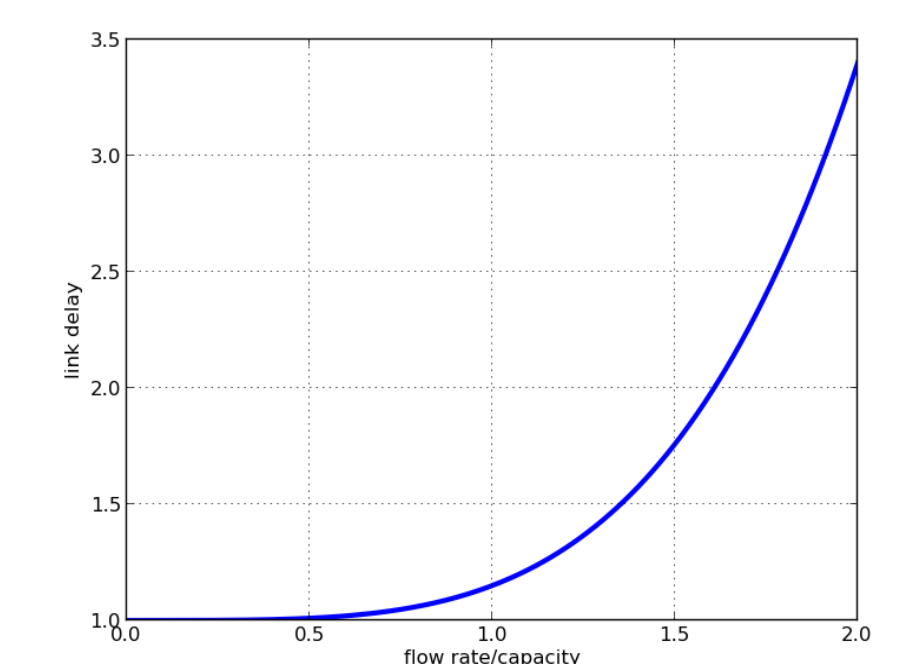
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graph LR
    subgraph Sensor_data [Sensor data]
        GPS[GPS]
        AG[Accelerometer/Gyroscope]
        M[Magnetometer]
        Micro[Microphone]
    end
    subgraph Classification [Classification]
        Loc[Localization  
(Position estimate and map matching)]
        VC[Vehicle Classification]
        RC[Road Classification]
    end
    subgraph Regression_Prediction_Analysis [Regression/Prediction/Analysis]
        Out[Annotating maps  
Intelligent routing  
...]
    end
    GPS --> Loc
    AG --> Loc
    AG --> VC
    AG --> RC
    M --> VC
    M --> RC
    Micro --> RC
    Loc --> Out
    VC --> Out
    RC --> Out
  
```

SignalGuru : GLOSA (Green Light Optimal Speed Advisory) using windshield mounted phone camera to estimate traffic signals by performing image processing on video frames. Opportunistic collaboration through WiFi connection. Estimates adaptive signals using SVR (Support Vector Regression) models.

t_a^F is free flow travel time on link a
 u_a is flow capacity of link a

[illegible]

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- Visualizing and analyzing GPS trace data : <https://github.com/sksavant/traffic-analysis>
- xlsx to csv converter : <https://github.com/dilshod/xlsx2csv>
- GTK widget for map display : <https://github.com/nzjrs/osm-gps-map>

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