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The project aims to analyze and model road traffic conditions. The goal of such analysis is to be able to predict and learn how to give traffic recommendations for better and relaxed travel in India's cities.



**Nericell** : Using GPS, Accelerometer and Microphone on a smartphone. estimate road and traffic conditions. Identify potholes and bumps using simple threshold heuristic on accelerometer data after reorienting with respect to vehicle's axes. Identify honking by checking for more than two energy spikes in frequency domain. Uses triggered sensing to save power.

**Wolverine** : Uses similar approach as Nericell. Uses magnetometer for reorientation. Use machine learning techniques for identifying potholes/bumps. Initially partition the data using K-means clustering into two classes for labeling. Use SVM classifier to classify after training.

**CloudAtlas** : Use GPS traces for map building. Initially GPS points are matched to road segments using Viterbi algorithm. The system is modeled as a Hidden Markov Model. Infer whether the trace is matched or not. After repetition of unmatched traces new roads are inferred.

**Driving Coach :** Obtains sensor data from CAN bus. Extract various features such as minimum, average and maximum of acceleration, velocity, instant fuel consumption and engine rpm, time vehicle has stopped. Classify into fuzzy outputs based on intuitive decision. For a specific set of driving hints, assign fuzzy likelihood values. Defuzzify using center average method and give the maximum likelihood hint.

**VTrack** : Uses sparse GPS and WiFi for delay estimation. Initially does HMM based map matching using Viterbi algorithm with interpolation, outlier removal and bad zone detection. Wardriving database is created and used to map WiFi APs to position estimates. Use the travel time estimates to detect hotspots and for real time route planning.

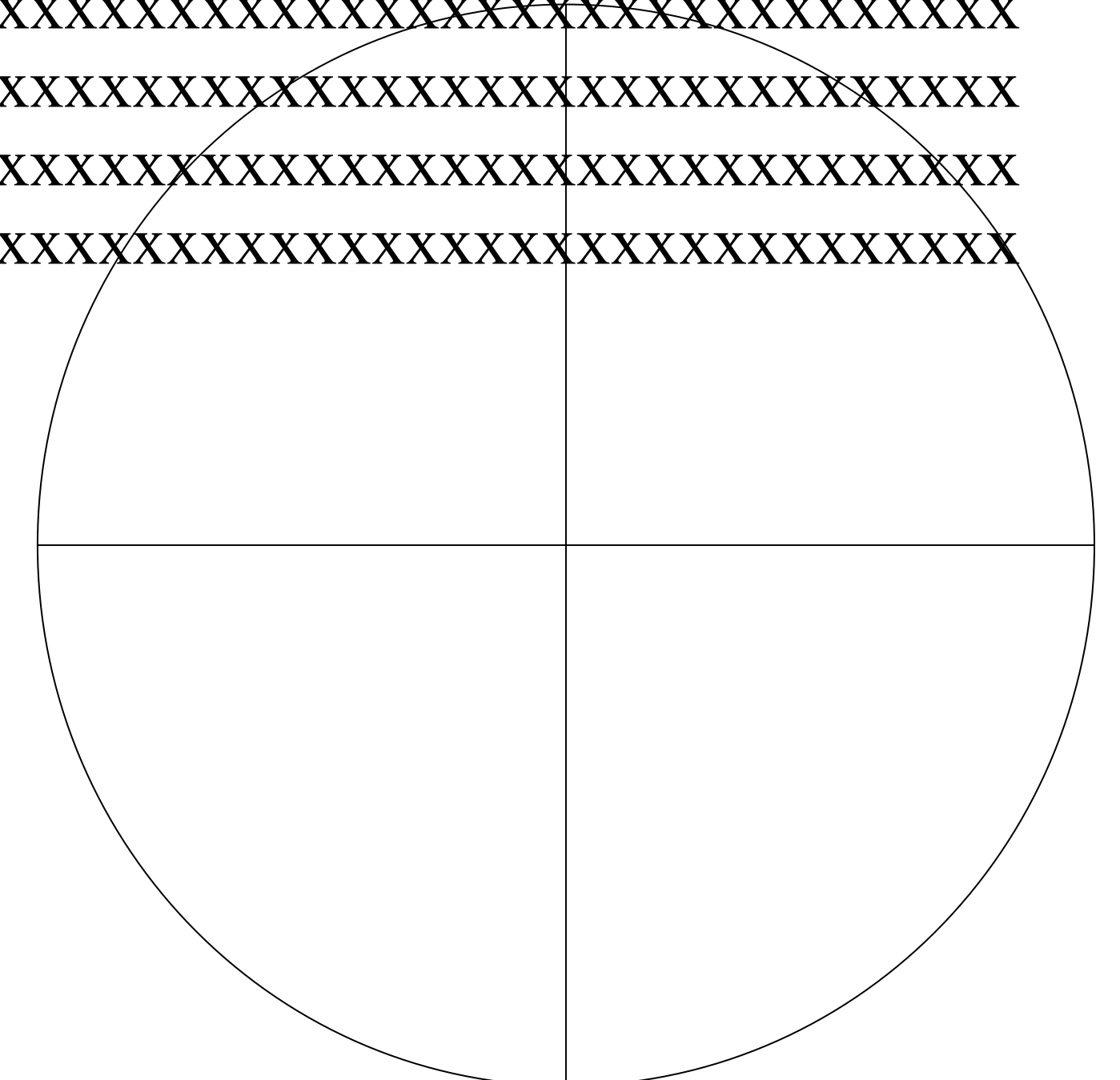
**SignalGuru** : GLOSA (Green Light Optimal Speed Advisory) using windshield mounted phone camera to estimate traffic signals by performing image processing on video frames. Opportunistic collaboration through WiFi connection. Estimates adaptive signals using SVR (Support Vector Regression) models.

## FUTURE WORK

[illegible]

Figure 1 and Figure 2 are diagrams illustrating the geometry of a circular sector. Figure 1 shows a circular sector with radius  $r$  and central angle  $\theta$ . The arc length is labeled  $s$ . Figure 2 shows the same sector with the radius  $r$  and central angle  $\theta$ , but the arc length is labeled  $s'$ .

CHART or PICTURE



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- Visualizing and analyzing GPS trace data : <https://github.com/sksavant/traffic-analysis>
- xlsx to csv converter : <https://github.com/dilshod/xlsx2csv>
- GTK widget for map display : <https://github.com/nzjrs/osm-gps-map>

Thanks to Vishnu Navda, Researcher, Microsoft Research, Bangalore for providing GPS traces dataset.