

Warshall

```
#include<iostream.h>
```

```
#include<conio.h>
```

```
class WarAlgo
```

```
{
    int adjMatrix[20][20];
    int duplicateMatrix[20][20];
    int n;
    public:
    void graph();
    void displayMatrix();
    WarAlgo()
    {
        int i,j;
        for(i=0;i<n;i++)
        {
            for(j=0;j<n;j++)
            {
                adjMatrix[i][j]=0;
                duplicateMatrix[i][j]=0;
            }
        }
    }
};
```

```
void WarAlgo::graph()
```

```
{
    int temp1, temp2,i,j,k;
    cout<<"Enter Number of vertices:";
    cin>>n;
    cout<<"\nEnter the cost of edges in adjacency matrix:";
    for(i=0;i<n;i++)
    {
        for(j=0;j<n;j++)
        {
            cout<<"\nadjMatrix["<<i<<"]["<<j<<"]: ";
            cin>>adjMatrix[i][j];
        }
    }
    cout<<"\nDisplaying Matrix:"<<"\n";
    for(i=0;i<n;i++)
    {
        for(j=0;j<n;j++)
        {
            cout<<adjMatrix[i][j]<<" ";
        }
        cout<<"\n";
    }

    for(k=0;k<n;k++)
```

```

    {
        for(i=0;i<n;i++)
        {
            for(j=0;j<n;j++)
            {
                temp1 = adjMatrix[i][j];
                temp2 = adjMatrix[i][k]+adjMatrix[k][j];
                if(temp1<temp2)
                {
                    duplicateMatrix[i][j] = temp1;
                }
                else
                {
                    duplicateMatrix[i][j] = temp2;
                }
            }
        }
        for(i=0;i<n;i++)
        {
            for(j=0;j<n;j++)
            {
                adjMatrix[i][j] = duplicateMatrix[i][j];
            }
        }
    }
}

void WarAlgo::displayMatrix()
{
    cout<<"\nFinal Adjacency Matrix:"<<"\n";
    for(int i=0;i<n;i++)
    {
        for(int j=0;j<n;j++)
        {
            cout<<adjMatrix[i][j]<<"\t";
        }
        cout<<"\n";
    }
}

void main(){
    clrscr();
    WarAlgo w;
    w.graph();
    w.displayMatrix();
    getch();
}

```

Cost Adjusted matrix

```
#include<iostream.h>
```

```
#include<conio.h>
```

```
class WarAlgo
```

```
{
    int adjMatrix[20][20];
    int n;
    public:
    void adjgraph();
    void displayMatrix();
};
```

```
void WarAlgo::adjgraph()
```

```
{
    int i,j,k;
    cout<<"Enter Number of vertices:";
    cin>>n;
    cout<<"\nEnter the value of edges in adjagency matrix:"<<"\n";
    cout<<"if direct edge then enter 1 otherwise 0";
    for(i=0;i<n;i++)
    {
        for(j=0;j<n;j++)
        {
            cout<<"\nadjMatrix["<<i<<"]["<<j<<"]: ";
            cin>>k;
            if(k==0 || k==1)
            {
                adjMatrix[i][j]=k;
            }
            else
            {
                cout<<"Enter correct value";
            }
        }
    }
}
```

```
void WarAlgo::displayMatrix()
```

```
{
    cout<<"\nFinal Adjagency Matrix:"<<"\n";
    for(int i=0;i<n;i++)
    {
        for(int j=0;j<n;j++)
        {
            cout<<adjMatrix[i][j]<<"\t";
        }
        cout<<"\n";
    }
}
```

```
}
```

```
int main(){  
    clrscr();  
    WarAlgo w;  
    w.adjgraph();  
    w.displayMatrix();  
    getch();  
    return 0;  
}
```

Directed graph

```
#include<iostream.h>
```

```
#include<conio.h>
```

```
class AdjacencyMatrix
```

```
{
    int adjMatrix[20][20];
    int n;
    public:
    void createGraph();
    void insertVertex();
    void deleteVertex();
    void insertEdge(int, int);
    void deleteEdge(int, int);
    void displayMatrix();
    AdjacencyMatrix()
    {
        for(int i=0;i<20;i++)
        {
            for(int j=0;j<20;j++)
            {
                adjMatrix[i][j]=0;
            }
        }
    }
};
```

```
void AdjacencyMatrix::createGraph()
```

```
{
    int i, maxEdge, origin, destination;
    cout<<"Enter Number of vertices:";
    cin>>n;
    maxEdge = (n*(n-1));
    cout<<"\nEnter the value of edges in adjacency matrix:"<<"\n";
    for(i=1;i<=maxEdge;i++)
    {
        cout<<"Enter 0 0 to exit or enter origin and destination for: "<<i<<"\n";
        cin>>origin>>destination;
        if((origin==0) || (destination == 0))
        {
            break;
        }
        if((origin>n) || (origin<0) || (destination>n) || (destination<0))
        {
            cout<<"Invalid inputs"<<"\n";
            i--;
            return;
        }
        else
        {
            adjMatrix[origin][destination] = 1;
        }
    }
}
```

```

        // adjMatrix[destination][origin] = 1;
    }
}

void AdjacencyMatrix::insertVertex()
{
    int i;
    n++;
    cout<<"Number of vertices are:"<<n;
    for(i=0;i<=n;i++)
    {
        adjMatrix[i][n] = 0;
        adjMatrix[n][i] = 0;
    }
}

void AdjacencyMatrix::insertEdge(int origin, int destination)
{
    if((origin > n) || (origin>n))
    {
        cout<<"Source or Destination does not exist"<<"\n";
        return;
    }
    adjMatrix[origin][destination] = 1;
    // adjMatrix[destination][origin] = 1;
}

void AdjacencyMatrix::deleteVertex()
{
    int i;
    cout<<"Number of vertices are:"<<n;
    for(i=0;i<=n;i++)
    {
        adjMatrix[i][n] = 0;
        adjMatrix[n][i] = 0;
    }
    n--;
}

void AdjacencyMatrix::deleteEdge(int origin, int destination)
{
    if((origin > n) || (origin>n))
    {
        cout<<"Source or Destination does not exist"<<"\n";
        return;
    }
    adjMatrix[origin][destination] = 0;
    // adjMatrix[destination][origin] = 0;
}

```

```
}
```

```
void AdjacencyMatrix::displayMatrix(void)
{
    cout<<"\nFinal Adjacency Matrix:"<<"\n";
    for(int i=1;i<=n;i++)
    {
        for(int j=1;j<=n;j++)
        {
            cout<<adjMatrix[i][j]<<"\t";
        }
        cout<<"\n";
    }
}
```

```
}
```

```
void main()
{
    clrscr();

    AdjacencyMatrix a;
    char ch='y';
    int origin, destination, option;
    while(ch=='y')
    {
        cout<<"Selection operation:"<<"\n";
        cout<<"1. Create Graph"<<"\n";
        cout<<"2. Insert Vertex"<<"\n";
        cout<<"3. Insert Edge"<<"\n";
        cout<<"4. Delete Vertex"<<"\n";
        cout<<"5. Delete Edge"<<"\n";
        cout<<"6. Display Final Matrix"<<"\n";
        cout<<"Enter an option: ";
        cin>>option;
        switch(option)
        {
            case 1:
            {
                a.createGraph();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 2:
            {
                a.insertVertex();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 3:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 4:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 5:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 6:
            {
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
        }
    }
}
```

```

        {
            cout<<"Enter source & Destination:";
            cin>>origin>>destination;
            a.insertEdge(origin, destination);
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 4:
        {
            a.deleteVertex();
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 5:
        {
            cout<<"Enter source & Destination:";
            cin>>origin>>destination;
            a.deleteEdge(origin, destination);
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 6:
        {
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
    }
    cin>>ch;
}getch();
}

```


Undirected graph

```
#include<iostream.h>
```

```
#include<conio.h>
```

```
class AdjacencyMatrix
```

```
{
    int adjMatrix[20][20];
    int n;
    public:
    void createGraph();
    void insertVertex();
    void deleteVertex();
    void insertEdge(int, int);
    void deleteEdge(int, int);
    void displayMatrix();
    AdjacencyMatrix()
    {
        for(int i=0;i<20;i++)
        {
            for(int j=0;j<20;j++)
            {
                adjMatrix[i][j]=0;
            }
        }
    }
};
```

```
void AdjacencyMatrix::createGraph()
```

```
{
    int i, maxEdge, origin, destination;
    cout<<"Enter Number of vertices:";
    cin>>n;
    maxEdge = (n*(n-1))/2;
    cout<<"\nEnter the value of edges in adjacency matrix:"<<"\n";
    for(i=1;i<=maxEdge;i++)
    {
        cout<<"Enter 0 0 to exit or enter origin and destination for: "<<i<<"\n";
        cin>>origin>>destination;
        if((origin==0) || (destination == 0))
        {
            break;
        }
        if((origin>n) || (origin<0) || (destination>n) || (destination<0))
        {
            cout<<"Invalid inputs"<<"\n";
            i--;
            return;
        }
        else
        {
            adjMatrix[origin][destination] = 1;
        }
    }
}
```

```

        adjMatrix[destination][origin] = 1;
    }
}

void AdjacencyMatrix::insertVertex()
{
    int i;
    n++;
    cout<<"Number of vertices are:"<<n;
    for(i=0;i<=n;i++)
    {
        adjMatrix[i][n] = 0;
        adjMatrix[n][i] = 0;
    }
}

void AdjacencyMatrix::insertEdge(int origin, int destination)
{
    if((origin > n) || (origin>n))
    {
        cout<<"Source or Destination does not exist"<<"\n";
        return;
    }
    adjMatrix[origin][destination] = 1;
    adjMatrix[destination][origin] = 1;
}

void AdjacencyMatrix::deleteVertex(void)
{
    int i;
    cout<<"Number of vertices are:"<<n;
    for(i=0;i<=n;i++)
    {
        adjMatrix[i][n] = 0;
        adjMatrix[n][i] = 0;
    }
    n--;
}

void AdjacencyMatrix::deleteEdge(int origin, int destination)
{
    if((origin > n) || (origin>n))
    {
        cout<<"Source or Destination does not exist"<<"\n";
        return;
    }
    adjMatrix[origin][destination] = 0;
    adjMatrix[destination][origin] = 0;
}

```

```
}
```

```
void AdjacencyMatrix::displayMatrix(void)
{
    cout<<"\nFinal Adjacency Matrix:"<<"\n";
    for(int i=1;i<=n;i++)
    {
        for(int j=1;j<=n;j++)
        {
            cout<<adjMatrix[i][j]<<" ";
        }
        cout<<"\n";
    }
}
```

```
}
```

```
void main()
{
    clrscr();

    AdjacencyMatrix a;
    char ch='y';
    int origin, destination, option;
    while(ch=='y')
    {
        cout<<"Selection operation:"<<"\n";
        cout<<"1. Create Graph"<<"\n";
        cout<<"2. Insert Vertex"<<"\n";
        cout<<"3. Insert Edge"<<"\n";
        cout<<"4. Delete Vertex"<<"\n";
        cout<<"5. Delete Edge"<<"\n";
        cout<<"6. Display Final Matrix"<<"\n";
        cout<<"Enter an option: ";
        cin>>option;
        switch(option)
        {
            case 1:
            {
                a.createGraph();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 2:
            {
                a.insertVertex();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 3:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 4:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 5:
            {
                a.deleteVertex();
                a.deleteEdge();
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
            case 6:
            {
                a.displayMatrix();
                cout<<"\nDo you want to continue?";
                break;
            }
        }
    }
}
```

```

        {
            cout<<"Enter source & Destination:";
            cin>>origin>>destination;
            a.insertEdge(origin, destination);
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 4:
        {
            a.deleteVertex();
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 5:
        {
            cout<<"Enter source & Destination:";
            cin>>origin>>destination;
            a.deleteEdge(origin, destination);
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
        case 6:
        {
            a.displayMatrix();
            cout<<"\nDo you want to continue?";
            break;
        }
    }
    cin>>ch;
}getch();
}

```

Graph Traversal DFS

```
#include<iostream.h>
#include<conio.h>
class gtdfs
{
    int adj[10][10],varr[10],n;
    public:
    gtdfs()
    {
        int i,j;
        for(i=0;i<n;i++)
        {
            for(j=0;j<n;j++)
                adj[i][j]=0;
            varr[i]=0;
        }
    }
    void buildadj();
    void dfs(int);
};
void gtdfs::buildadj()
{
    int i,j;
    cout<<"\nEnter number of vertex: ";
    cin>>n;
    cout<<"\nEnter the edges: ";
    for(i=0;i<n;i++)
    {
        for(j=0;j<n;j++)
            cin>>adj[i][j];
    }
}
void gtdfs::dfs(int x)
{
    int j;
    varr[x]=1;
    cout<<"\n"<<x<<" is visited";
    for(j=0;j<n;j++)
    {
        if(adj[x][j]==1 && varr[j]==0)
            dfs(j);
    }
}
void main() {
    clrscr();
    gtdfs g;
    int i;
    g.buildadj();
    g.dfs(0);
    getch();
}
```