

MAE3145: Homework 3

Due date: 2 458 031.197 916 666 5 JD

Problem 1. The relative motion of the two-body problem is described by

$$\ddot{\vec{r}} = -\frac{\mu}{r^3}\vec{r}. \quad (1)$$

The specific angular momentum \vec{h} and the eccentricity \vec{e} are defined as follows:

$$\vec{h} = \vec{r} \times \vec{v}, \quad \vec{e} = \frac{\vec{v} \times \vec{h}}{\mu} - \frac{\vec{r}}{r}.$$

In class, we found that \vec{h} is fixed, i.e. $\dot{\vec{h}} = 0$. Here, we wish to show \vec{e} is fixed according to the following steps:

(a) Using (1), show that $\frac{d}{dt}(\vec{v} \times \vec{h}) = -\frac{\mu}{r^3}\vec{r} \times \vec{h}$.

(b) Using the definition of \vec{h} , show that $\frac{1}{r^3}\vec{r} \times \vec{h} = \frac{\vec{r}\dot{r} - \dot{\vec{r}}r}{r^2}$.

(Hint: $\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$, $\vec{r} \cdot \vec{r} = r^2$, and $\vec{r} \cdot \dot{\vec{r}} = r\dot{r}$).

(c) Show that $\frac{d}{dt}\frac{\vec{r}}{r} = -\frac{\vec{r}\dot{r} - \dot{\vec{r}}r}{r^2}$.

(d) By combining the results of parts (a), (b), and (c), show that $\frac{d}{dt}\vec{e} = 0$, i.e, the eccentricity vector is fixed.

Problem 2. A satellite is on an elliptic orbit around the Earth with a perigee radius of $r_p = 7000$ km and an apogee radius of $r_a = 70000$ km. Assume that the gravitational parameter and the radius of the Earth are found on the constants sheet. Determine the following parameters (specify units in km, sec, degree).

(a) eccentricity e

(b) period T

(c) specific energy \mathcal{E}

(d) true anomaly θ at which the altitude is 1000 km.

(e) velocity v_r, v_θ at the point found in part (d).

Problem 3. The specific energy and angular momentum of several asteroids heading toward the Earth have been measured as follows:

Asteroid	\mathcal{E} (km ² /s ²)	h (km ² /s)
1	1	1×10^5
2	100	1×10^5
3	0	7×10^4
4	0	8×10^4
5	10	8×10^4

We wish to determine whether any asteroid is likely to hit the Earth. The trajectory of an asteroid is assumed to be the solution of the two-body problem of the asteroid and the Earth, where μ_\oplus is taken from the course constants sheet.

- (a) Using the fact that \mathcal{E} and h are conserved, show that the distance at the periapsis r_p satisfies the following quadratic equation:

$$2\mathcal{E} r_p^2 + 2\mu_E r_p - h^2 = 0. \quad (2)$$

(Hint: at the periapsis, $h = rv$ since \vec{r} is perpendicular to \vec{v} .)

- (b) Calculate r_p for all asteroids, and determine which asteroid will hit the surface of the Earth: an asteroid will hit the Earth if $r_p < R_\oplus = 6378.137$ km.

(Hint: In Python/`numpy`, the quadratic equation $ax^2 + bx + c = 0$ can be solved by the command `np.roots([a, b, c])`.)

- (c) For each asteroid that hits the surface of the Earth, calculate its impact velocity at the surface of the Earth.

(Note: the impact velocity is not same as the velocity at the periapsis.)

- (d) For each asteroid that does not hit the surface of the Earth, calculate its velocity when it is closest to the Earth.

Problem 4. Consider the point of intersection of an elliptical orbit with the semi-minor axis.

- (a) Prove that the following relationships are true:

$$\begin{aligned} r &= a \\ v &= \sqrt{\frac{\mu}{r}} \\ \theta &= \arccos(-e) \end{aligned}$$

Hint: The first thing to try is to draw a picture. Next utilize the equation of a conic section to investigate the relationships.

- (b) Given the conic equation

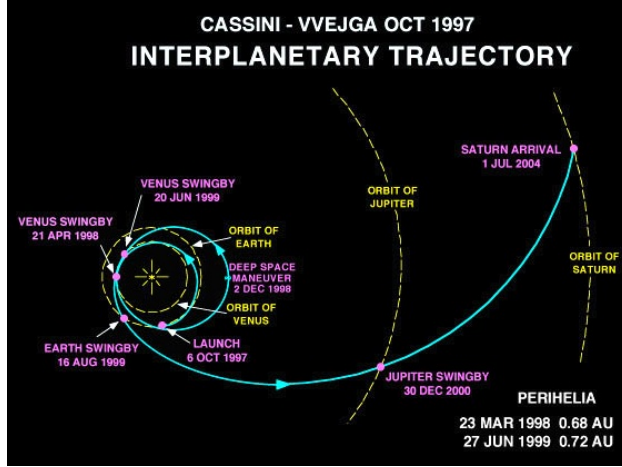
$$r = \frac{p}{1 + e \cos \theta}$$

find the derivative \dot{r} .

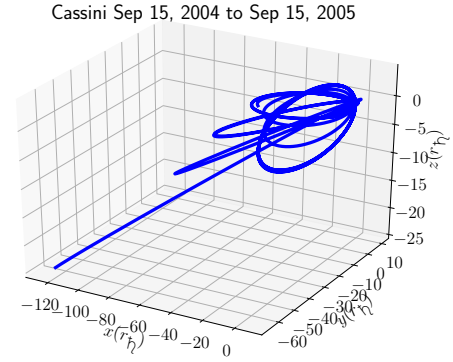
- (c) Prove that \dot{r} possesses a maximum magnitude at the ends of the semi-latus rectum.

- (d) Show that this maximum magnitude corresponds to $\pm e \sqrt{\frac{\mu}{p}}$.

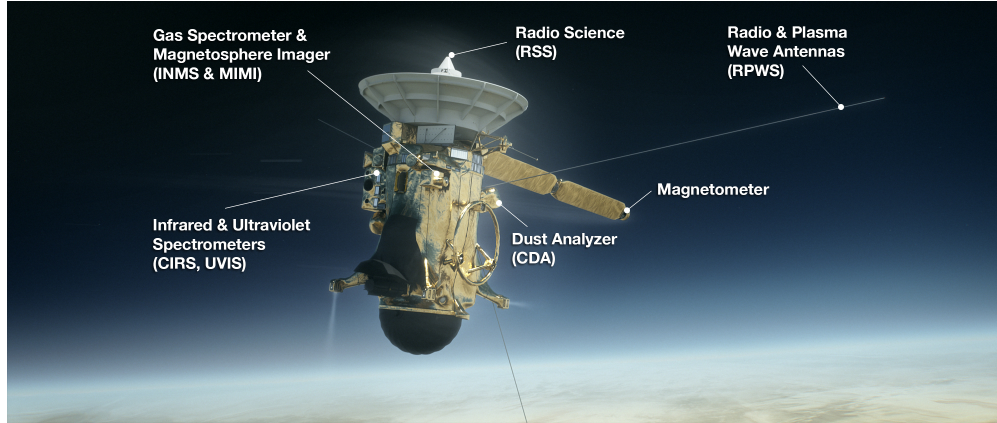
Problem 5. At approximately 2458 011.997 06 JD, Cassini orbiter completed its mission studying the Saturnian system and re-entered Saturn to avoid contamination of any possible extraterrestrial life in the Saturn system. Over the course of its nearly 20 yr mission, Cassini studied the planet Saturn, its ring system, and numerous natural satellites. In order to reach Saturn, Cassini used several gravity assist maneuvers of Venus, Earth and Jupiter, in order to increase its orbital velocity with respect to the Sun and gain enough energy to intercept Saturn. The Cassini mission remains the largest interplanetary vehicle launched by the United States, consisting of the Cassini Orbiter and Huygens lander. The Huygens lander parachuted to a soft landing on Titan on 2458 011.997 06 JD and remains the most distant interplanetary landing of any human-made vehicle.



(a) Cassini Interplanetary Trajectory



(b) Cassini Trajectory 2004 to 2005



(c) Cassini Orbiter

Figure 1: Cassini Mission

Here we will investigate the orbit of Cassini 13 years ago on Sep 15, 2004. On this date, the position and velocity of Cassini with respect to Saturn barycenter are given as

$$\bar{r} = \begin{bmatrix} -7546026.6144396 & -3717105.21901527 & -1515557.34280287 \end{bmatrix} \text{ km}$$

$$\bar{v} = \begin{bmatrix} 0.89506649 & -0.33312074 & 0.21519571 \end{bmatrix} \text{ km s}^{-1}$$

(a) Given this position and velocity vector, determine the type of orbit of Cassini.

- (b) Determine the period P , angular momentum vector \vec{h} , semi-latus rectum p , specific mechanical energy \mathcal{E} , eccentricity e , true anomaly ν , and radius of periapsis and apoapsis r_p, r_a .
- (c) How does the velocity of Cassini compare to the velocity of a circular orbit at this radius, i.e. compare v and $\sqrt{2}v_c$? Should the velocity of Cassini be less than or greater than $\sqrt{2}v_c$? Why or why not?
- (d) Using Python, create a diagram of the orbital plane and the location of Cassini. Mark the location of periapsis and the local horizontal/local vertical unit reference frame, $\hat{r}, \hat{\theta}$ as well as the perifocal reference frame \hat{p}, \hat{q} .
- (e) The major subdivisions of the Saturn ring system are copied below from Wikipedia. Based on the current orbital properties, which ring subdivision does Cassini pass through.

Major subdivisions [\[edit \]](#)

Name ⁽¹⁾	Distance from Saturn's center (km) ⁽²⁾	Width (km) ⁽²⁾	Named after
D Ring	66,900 – 74,510	7,500	
C Ring	74,658 – 92,000	17,500	
B Ring	92,000 – 117,580	25,500	
Cassini Division	117,580 – 122,170	4,700	Giovanni Cassini
A Ring	122,170 – 136,775	14,600	
Roche Division	136,775 – 139,380	2,600	Édouard Roche
F Ring	140,180 ⁽³⁾	30 – 500	
Janus/Epimetheus Ring ⁽⁴⁾	149,000 – 154,000	5,000	Janus and Epimetheus
G Ring	166,000 – 175,000	9,000	
Methone Ring Arc ⁽⁴⁾	194,230	?	Methone
Anthe Ring Arc ⁽⁴⁾	197,665	?	Anthe
Pallene Ring ⁽⁴⁾	211,000 – 213,500	2,500	Pallene
E Ring	180,000 – 480,000	300,000	
Phoebe Ring	~4,000,000 – >13,000,000		Phoebe

Figure 2: Ring Subdivisions

Problem 6. In a chance meeting in the Science and Engineering hall, you've bumped into Elon Musk. He is the CEO of Tesla Motors and SpaceX and is planning on sending manned missions to Mars. Unfortunately, Mr. Musk has never taken an astrodynamics class and is in need of your help to plan his latest mission.

- (a) The Dragon capsule is in a circular parking orbit of the Earth, at an altitude of 120 km. To begin a voyage to Mars, what velocity does the satellite require to escape the Earth.
- (b) Would your answer be different for an elliptical orbit ($e = 0.3$, $\nu = 145^\circ$, with a the same as the previous problem)? Why or why not?
- (c) If you assume both burns are tangent to the existing velocity, what are the required increases in velocity for each of the previous cases?

Problem 7. The data below are composed of position, \bar{r} in km, and velocity, \bar{v} in km s^{-1} vectors in the local vertical/local horizontal frame. Each row corresponds to the state of a particular satellite in Earth orbit. The first three columns define the position vector $\bar{r} = r_1\hat{r} + r_2\hat{\theta} + r_3\hat{h}$ km and the last three columns define the velocity vector $\bar{v} = v_1\hat{r} + v_2\hat{\theta} + v_3\hat{h}$ km s^{-1} .

6781.675224	0.000000	0.000000	-0.002574	7.667057	0.000000
41655.940637	0.000000	0.000000	-1.103624	1.706184	0.000000
6894.474715	0.000000	0.000000	-0.184823	8.038042	0.000000
7491.578823	0.000000	0.000000	-0.859794	7.408067	0.000000
35855.749929	0.000000	0.000000	-1.479844	1.890930	0.000000
38208.441964	0.000000	0.000000	-0.925821	2.167744	0.000000

For example, the first row of this data set corresponds to the position and velocity of the International Space Station,

$$\bar{r} = 6781.675224\hat{r} + 0\hat{\theta} + 0\hat{h} \text{ km},$$

$$\bar{v} = -0.002574\hat{r} + 7.667057\hat{\theta} + h\hat{h} \text{ km s}^{-1}.$$

For the given orbital data determine the following for each satellite. Units should be provided in seconds, degrees, and kilometers.

(a) Orbital properties

- Period – P
- Specific mechanical energy – \mathcal{E}
- Semi-major axis, semi-latus rectum, eccentricity, true anomaly
- Radius of periapsis and apoapsis – r_p, r_a
- Angular momentum vector and magnitude – \bar{h}
- Flight path angle – γ
- Position and Velocity vectors in the perifocal reference frame

The orbital properties of the first satellite (first row) is given below. You should provide your hand calculations demonstrating the computation of the orbital properties for this case. This test case is used to verify your software is working correctly. For the other cases, you can simply provide the output of your program.

(b) Using Python, plot the orbit of each satellite in the perifocal reference frame and mark the location of the satellite. Mark the location of periapsis and apoapsis on your plot as well as the local horizontal/local vertical frame, and flight path angle. Some of these satellites are in nearly circular orbits so the difference between periapsis and apoapsis will be difficult to notice in your plots.

Solution for first satellite:

0 ISS (ZARYA) 25544

Satellite State

Position and Velocity in LVLH frame

r_hat:	6781.6752240256 km	rd_hat:	-0.00257359868086831 km/sec
t_hat:	0 km	td_hat:	7.66705746939915 km/sec
h_hat:	0 km	hd_hat:	0 km/sec

Position and Velocity in EPH/PQW frame

e_hat:	2453.84042760766 km	ed_hat:	7.14662603444703 km/sec
p_hat:	-6322.16624267355 km	pd_hat:	2.77660101315318 km/sec
h_hat:	0 km	hd_hat:	0 km/sec

Position and Velocity in IJK frame

i_hat:	-4226.54578373763 km	id_hat:	-1.66958104755974 km/sec
j_hat:	3746.04288415422 km	jd_hat:	-6.15442824782474 km/sec
k_hat:	-3754.27653379581 km	kd_hat:	-4.25667580753874 km/sec

RAD_MAG : 6781.6752240256 km = 4.53326990820498e-05 AU

VEL_MAG : 7.66705790133865 km/sec

Orbital Elements

sma:	6782.55976540987 km	raan:	286.709516148979 deg
ecc:	0.000360113803137797	arg_p:	293.694918634304 deg
inc:	51.643 deg	nuc:	291.21286881209 deg

Elliptic Orbital Parameters

P	:	6782.55888583428 km	=	4.53386059964241e-05 AU
ANG MOM	:	51995.4936814046 km ² /sec		
PERIOD	:	5559.06039988679 sec	=	1.544183444413 hr
ENERGY	:	-29.3842231979148 km ² /sec ²		
RAD_PER	:	6780.11727201773 km	=	4.53222848160721e-05 AU
RAD_APO	:	6785.002258802 km	=	4.53549389359755e-05 AU

VEL_CIRC	:	7.66655800402987 km/sec
VEL_ESC	:	10.8421503060191 km/sec
TRUE_ANOM	:	291.21286881209 deg
FPA	:	-0.0192324549052291 deg
ECC_ANOM	:	291.232102521087 deg
MEAN_ANOM	:	291.251334975467 deg
MEAN_MOT	:	0.064759145269825 deg/sec

T_PAST_PER: 4497.45489632301 sec = 1.24929302675639 hr