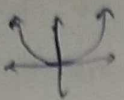
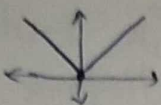
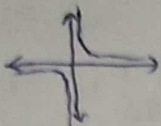
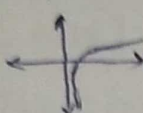
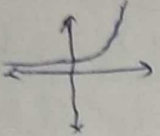
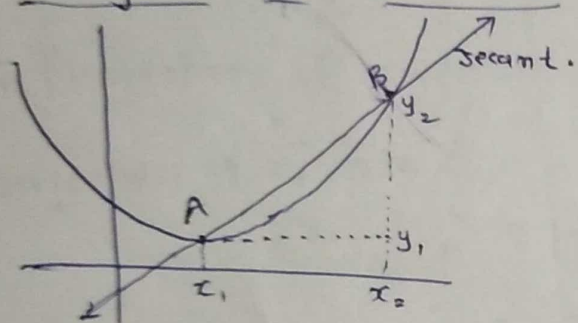


* Calculus *

* Limits range and domain of functions :-

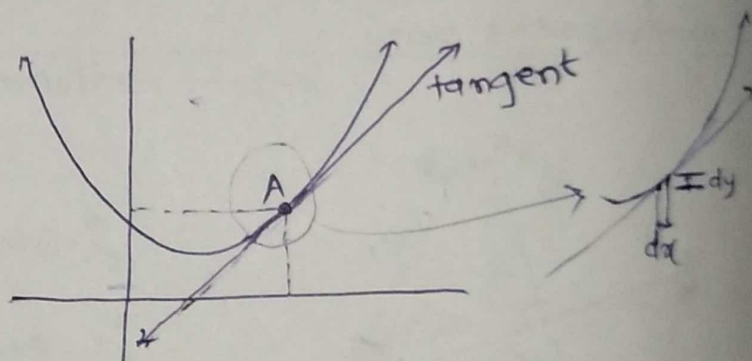
	function	graph	Domain	Range
①	x^2		\mathbb{R}	\mathbb{R}_0^+
②	$ x $		\mathbb{R}	\mathbb{R}_0^+
③	$1/x$		$\mathbb{R} - \{0\}$	$\mathbb{R} - \{0\}$
④	$\ln(x)$		\mathbb{R}^+	\mathbb{R}
⑤	e^x		\mathbb{R}	\mathbb{R}^+

* Tangent vs secant



secant gives rate of change of function in range

$$\text{slope (change)} = \frac{y_2 - y_1}{x_2 - x_1}$$



when $(x_2 - x_1) \rightarrow 0$, i.e. $dx \rightarrow 0$
 line touches the function at one and only point.

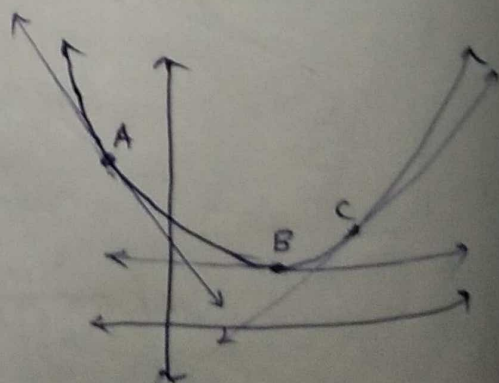
$$\text{slope} = \frac{dy}{dx} \text{ differentiation at point A.}$$

* Derivation/differentiation:

"Rate of change of function at point x." It is also defined using limit as,

$$f'(x) = \frac{df}{dx} = \lim_{dx \rightarrow 0} \frac{f(x+dx) - f(x)}{dx}$$

point	$\frac{df}{dx} \text{ at point}$	interpretation
A	< 0	f is decreasing
B	$= 0$	f is optimum
C	> 0	f is increasing



* Continuity and differentiability:-

☆ Function is continuous at point a if,

1) $f(a)$ is defined

2) $\lim_{x \rightarrow a^+} f(x) = \lim_{x \rightarrow a^-} f(x) = f(a)$

☆ Function is differentiable at point a if,

$$f'(a) = \left. \frac{df}{dx} \right|_{x=a} = \lim_{\substack{dx \rightarrow 0^+ \text{ and } dx \rightarrow 0^-}} \frac{f(x+dx) - f(x)}{dx} \text{ is defined at } \underline{\underline{x=a}}$$

EXAMPLE: ① $f(x) = \frac{1}{x}$ is not defined at $x=0$. So it is not continuous.
 $\frac{d}{dx} \left(\frac{1}{x} \right)$ is not defined at $x=0$. So it is not differentiable.

② $|x| \Rightarrow$ is defined at $x=0$, $|x| = |0| = 0$. It is continuous.

But $\frac{d}{dx} |x|$ is not defined at $x=0$. So it is not differentiable. $\text{@ } x=0$.
 we can observe $|x|$ is not smooth @ $x=0$ ✓

* RULES of differentiation:-

① $(f \pm g)' = f' \pm g'$ $\frac{d}{dx} (x^2 + 2x - e^x) = 2x + 2 - e^x$

② $(f \cdot g)' = f'g + fg'$
 OR $f'g + fg'$ $\frac{d}{dx} (x^3 \cdot e^x) = 3x^2 \cdot e^x + x^3 \cdot e^x$

③ $\left(\frac{f}{g} \right)' = \frac{f'g - g'f}{g^2}$ $\frac{d}{dx} \left(\frac{\sin x}{x^2} \right) = \frac{\cos x \cdot x^2 - \sin x \cdot 2x}{x^4}$

④ $(f \circ g)'(x) = f'(g(x)) \cdot g'(x)$ $\frac{d}{dx} (\sin(x^2)) = \frac{\cos(x^2) \cdot 2x}{f' \cdot g'}$
 $(f \circ g \circ h)'(x) = f'(g(h(x))) \cdot g'(h(x)) \cdot h'(x)$

$$\frac{d}{dx} = e^{\sin(x^2)} = \frac{e^{\sin(x^2)}}{f'} \cdot \frac{\cos(x^2)}{g'} \cdot \frac{2x}{h'}$$

Variation.2 $y = f(u)$ and $u = f(x)$

$$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$$

$$y = 2u^2 \quad , \quad u = x^3$$

$$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$$

$$\frac{dy}{dx} = \frac{d}{du} (u^2) \cdot \frac{d}{dx} (x^3)$$

$$= 2 \cdot u \cdot 3x^2$$

$$= 2u(x^2) \cdot 3x^2$$

$$= 6x^5$$

$$y = 2x^2 = 2(x^3)^2 = 2x^6 \quad \therefore \frac{dy}{dx} = 12x^5$$

** OPTIMA OF A FUNCTION

* PARTIAL derivative :-

$$f(x, y) = x \cdot y$$

In case of multivariable function, we can differentiate function with respect to one variable which is defined as partial derivative.

$$\frac{\partial f}{\partial x} = y \cdot \frac{\partial x}{\partial x} = y$$

$$\frac{\partial f}{\partial y} = x \cdot \frac{\partial y}{\partial y} = x$$

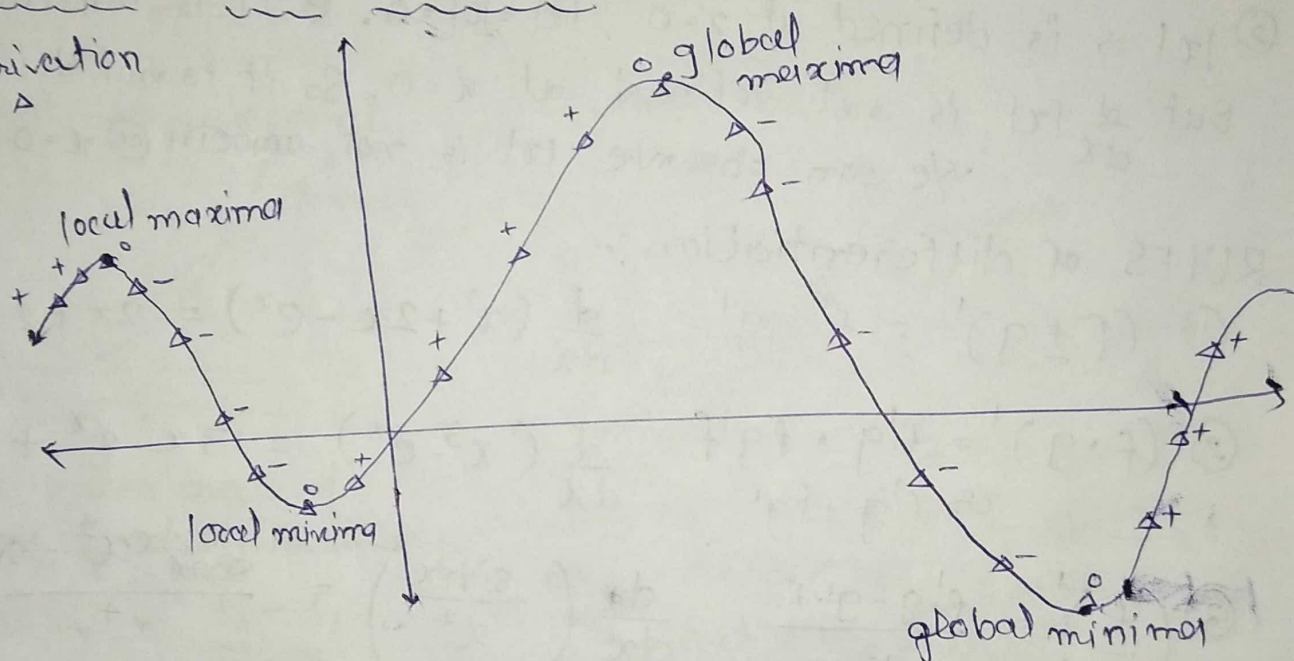
Ex. $f(x, y) = x^3 + y^2$

$$\frac{\partial f}{\partial x} = 3x^2 + 0 = 3x^2$$

$$\text{and } \frac{\partial f}{\partial y} = 0 + 2y = 2y$$

=> Minima and Maxima

Δ = deviation at Δ



$$* \quad \begin{matrix} + & + & + \end{matrix} \rightarrow 0 \quad \begin{matrix} - & - & - \end{matrix} \rightarrow \text{Maxima}$$

$$\begin{matrix} - & - & - \end{matrix} \rightarrow 0 \quad \begin{matrix} + & + & + \end{matrix} \rightarrow \text{Minima}$$

=> at optima $\frac{df}{dx} = f'(x) = 0$,

By evaluating $f'(x) = 0$, roots = C_1, C_2, \dots, C_n

For each root calculate

$$f''(C_i) \begin{cases} < 0, & \text{Maxima at } C_i \\ > 0, & \text{Minima at } C_i \\ = 0, & \text{CND. Investigate further.} \end{cases}$$

Intuition

<https://www.geogebra.org/calculator/pm7s54vc>

$f'(x) = 0$, f is optimum,

$f'(x) > 0$ means $f'(x)$ is increasing
 $f'(x) < 0$ means $f'(x)$ is decreasing.

⇒ OPTIMA of Multivariable function

$$z = f(x, y) = x^2 - y^2$$

here $f_x = \frac{\partial f}{\partial x}$, $f_{xx} = \frac{\partial^2 f}{\partial x^2}$, $f_y = \frac{\partial f}{\partial y}$, $f_{yy} = \frac{\partial^2 f}{\partial y^2}$

$$f_{xy} = f_{yx} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

1) Evaluate $f_x = 0$ and $f_y = 0$, Roots = $(a_1, b_1), (a_2, b_2), \dots, (a_n, b_n)$

2) For each root calculate $D = f_{xx} \cdot f_{yy} - f_{xy}^2$
@ (a_i, b_i)

case I $D > 0$, f is optimum

↳ case I.I: $f_{xx} < 0$, $f_{yy} < 0$ — f is maximum

↳ case I.II: $f_{xx} > 0$, $f_{yy} > 0$ — f is minimum

case II $D < 0$, saddle point at (a_i, b_i)

case III $D = 0$, CND.

* Above methods are not good in higher order functions.
We use gradient method to find minima.
Descent

$$f(x) = x^6 + x^5 + 4x^2 \quad f'(x) = 6x^5 + 5x^4 + 8x = 0$$

Very difficult to find roots.

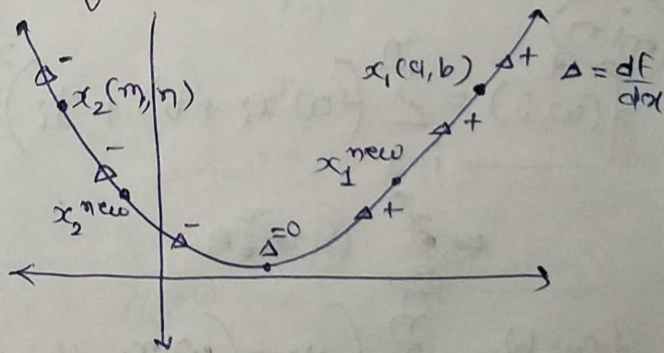
How gradient descent works to find Minima?

→ If Δ is positive, f is increasing, we are climbing the hill.

To go back to valley we need to go in opposite direction.

→ If Δ is negative, f is decreasing, we are walking down to valley.

To go down to valley we need to go in same direction.



CASE 1 we are at $(a, b) = x_1$
 $\lambda > 0$ Δ is negative

$$x_2^{\text{new}} = x_2^{\text{old}} + \lambda \cdot (-\Delta)$$

$$\Delta < 0, \therefore \lambda \cdot (-\Delta) > 0$$

$\therefore x_2^{\text{new}} > x_2^{\text{old}}$ → we walk towards valley

CASE 2 we are at $x_2 = (m, n)$
 $\lambda > 0$ Δ is positive

$$x_2^{\text{new}} = x_2^{\text{old}} + \lambda \cdot (-\Delta)$$

$$\Delta > 0 \therefore \lambda \cdot (-\Delta) < 0$$

$\therefore x_2^{\text{new}} < x_2^{\text{old}}$ → we walk towards valley

* So we can find minima by repeating,

$$x^{\text{new}} = x^{\text{old}} + \lambda \cdot (-f'_{x^{\text{old}}})$$

* For multivariable function,

$$z = f(x, y)$$

$$x^{\text{new}} = x^{\text{old}} + \lambda (-f'_x(x^{\text{old}}, y^{\text{old}}))$$

$$y^{\text{new}} = y^{\text{old}} + \lambda (-f'_y(x^{\text{old}}, y^{\text{old}}))$$

$$f'_x = \frac{\partial f}{\partial x}$$

$$f'_y = \frac{\partial f}{\partial y}$$

* Regression problem and solve using A.D.

i^{th} data point

$$x_i = [x_{i1}, x_{i2}, \dots, x_{id}]$$

i^{th} output value y_i

$$\text{Error} = y_i - y_{\text{pred}i}$$

n datapoints	$x_i \downarrow$	x_{i1}	x_{i2}	---	x_{id}	y_i	MODEL REFR	y_{pred}
	x_1	x_{11}	x_{12}	---	x_{1d}	y_1		$y_{\text{pred}1}$
	x_2	x_{21}	x_{22}	---	x_{2d}	y_2		$y_{\text{pred}2}$
	x_3	x_{31}	x_{32}	---	x_{3d}	y_3		$y_{\text{pred}3}$
	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots		\vdots
	x_n	x_{n1}	x_{n2}	---	x_{nd}	y_n		$y_{\text{pred}n}$
		features, dimension				output value		

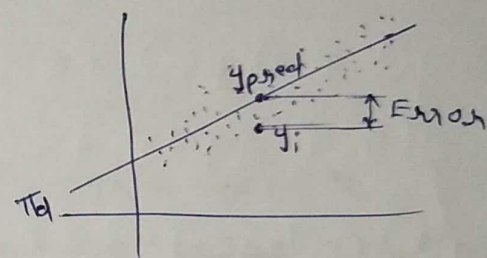
$$\text{Total Error} = \sum_{i=1}^n (y_i - y_{\text{pred}i})$$

Now our job is to find hyperplane $Td = w^T x_i + b$ s.t. sum of squares of Error is minimum.

$$\text{Error } E_i = y_i - y_{\text{pred}}$$

$$E_i = y_i - (w^T x_i + b)$$

$$\min_{\text{Total}} E = f(w, b) = \sum_{i=1}^n (y_i - (w^T x_i + b))^2$$



$$f(w, b) = \sum_{i=1}^n (y_i - (w_1 x_{i1} + w_2 x_{i2} + \dots + w_d x_{id} + b))^2$$

To minimize $f(w, b)$ or $f(w_1, w_2, w_3, \dots, w_d, b)$ we need to find $\frac{\partial f}{\partial w_j} = 0$ $j=1$ to d and $\frac{\partial f}{\partial b} = 0 \Rightarrow$ This is tough

So, To, use gradient descent

$$w_j^{\text{new}} = w_j^{\text{old}} + \lambda \left(-\frac{\partial f}{\partial w_j} \right)_{(w^{\text{old}}, b^{\text{old}})} \quad \text{--- ①}$$

$$b^{\text{new}} = b^{\text{old}} + \lambda \left(-\frac{\partial f}{\partial b} \right)_{(w^{\text{old}}, b^{\text{old}})} \quad \text{--- ②}$$

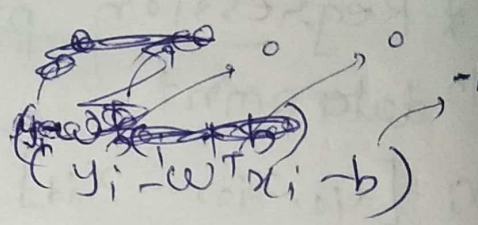
We need to compute $\frac{\partial f}{\partial w_j}$ and $\frac{\partial f}{\partial b}$ for C.D. eqn.

$$f(w, b) = \sum_{i=1}^n (y_i - (w^T x_i + b))^2$$

$$\therefore \frac{\partial f}{\partial w_j} = \sum_{i=1}^n 2(y_i - (w^T x_i + b)) \cdot \frac{\partial}{\partial w_j} (y_i - (w_1 x_{i1} + w_2 x_{i2} + \dots + w_d x_{id} + b))$$

$$\boxed{\frac{\partial f}{\partial w_j} = \sum_{i=1}^n -2(x_{ij})(y_i - (w^T x_i + b))}$$

similarly

$$\frac{\partial f}{\partial b} = \sum_{i=1}^n 2 \cdot (y_i - (w^T x_i + b)) \cdot \frac{\partial}{\partial b} (y_i - w^T x_i - b)$$


$$\boxed{\frac{\partial f}{\partial b} = \sum_{i=1}^n (-2) \cdot (y_i - (w^T x_i + b))}$$

By repeating eqn (1) and (2), we find optimum w^*, b^k such that $E_{\text{total}} = F(w, b)$ is minimum, i.e. Error is minimum and $w^T x_{\text{pred}}$ is near to y_i .