

Complexity of Reasoning in Kleene and Action Algebras

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Lecture 2

Recap: \mathbf{KA}_ω and \mathbf{KA}_∞

- We are studying infinitary logics for $*$ -continuous Kleene algebras.
- If you don't remember what a $*$ -continuous Kleene algebra means, just think about regular expressions, in their standard interpretation.
- Sequents are expressions of the form $\Pi \rightarrow B$, where B is a formula (reg. exp.) and Π is a sequence of formulae.
- Our calculi are sound and complete w.r.t. the standard interpretation, i.e., $\Pi \rightarrow B$ is derivable iff $v(\Pi) \subseteq v(B)$.

Recap: \mathbf{KA}_ω and \mathbf{KA}_∞

The first calculus, \mathbf{KA}_ω , has the ω -rule, but proofs are required to be well-founded.

$$\begin{array}{c}
 \frac{}{A \rightarrow A} Id \qquad \frac{}{\Gamma, 0, \Delta \rightarrow B} 0L \\
 \\
 \frac{\Gamma, \Delta \rightarrow B}{\Gamma, 1, \Delta \rightarrow B} 1L \qquad \frac{}{\rightarrow 1} 1R \\
 \\
 \frac{\Gamma, A, B, \Delta \rightarrow C}{\Gamma, A \cdot B, \Delta \rightarrow C} \cdot L \qquad \frac{\Gamma \rightarrow A \quad \Delta \rightarrow B}{\Gamma, \Delta \rightarrow A \cdot B} \cdot R \\
 \\
 \frac{\Gamma, A, \Delta \rightarrow C \quad \Gamma, B, \Delta \rightarrow C}{\Gamma, A + B, \Delta \rightarrow C} +L \qquad \frac{\Pi \rightarrow A}{\Pi \rightarrow A + B} +R_1 \quad \frac{\Pi \rightarrow B}{\Pi \rightarrow A + B} +R_2 \\
 \\
 \frac{(\Gamma, A^n, \Delta \rightarrow B)_{n=0}^\infty}{\Gamma, A^*, \Delta \rightarrow B} *L_\omega \qquad \frac{\Gamma_1 \rightarrow A \quad \dots \quad \Gamma_n \rightarrow A}{\Gamma_1, \dots, \Gamma_n \rightarrow A^*} *R_n, n \geq 0
 \end{array}$$

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- In contrast, proofs in \mathbf{KA}_∞ has only binary branching, but are allowed to be non-well-founded.
- The rules for $*$ in \mathbf{KA}_∞ are as follows:

$$\frac{\Gamma, \Delta \rightarrow B \quad \Gamma, A, A^*, \Delta \rightarrow B}{\Gamma, A^*, \Delta \rightarrow B} *L \qquad \frac{}{\rightarrow A^*} *R_0 \qquad \frac{\Gamma \rightarrow A \quad \Delta \rightarrow A^*}{\Gamma, \Delta \rightarrow A^*} *R$$

In $*R$ we require Γ to be non-empty.

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In $*R$ we require Γ to be non-empty.

- In the absence of *Cut*, no correctness condition on infinite paths is necessary.

Equivalence Between \mathbf{KA}_ω and \mathbf{KA}_∞

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$$\frac{\Gamma, \Delta \rightarrow B}{\Gamma, A^*, \Delta \rightarrow B} *L \quad \frac{\Gamma, A, \Delta \rightarrow B \quad \frac{\Gamma, A, A, A^*, \Delta \rightarrow B}{\Gamma, A, A, A^*, \Delta \rightarrow B} *L}{\Gamma, A, A, \Delta \rightarrow B} *L \quad \frac{\vdots}{\Gamma, A, A, A^*, \Delta \rightarrow B}$$

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- The $*R_n$ rules is several iterations of $*R$.

Equivalence Between \mathbf{KA}_ω and \mathbf{KA}_∞

- The opposite direction is based on the following lemma:

Lemma

If $\mathbf{KA}_\infty \vdash \Gamma, A^, \Delta \rightarrow B$, then $\mathbf{KA}_\infty \vdash \Gamma, A^n, \Delta \rightarrow B$ for each n .*

- This lemma is proved by induction on n .
 - We replace A^* with A^n and go upwards the proof. At the points of $*L$ we refer to the induction hypothesis.
- Now we may eagerly apply the ω -rule, and translate finitary rules to \mathbf{KA}_ω .

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Circular Proofs for \mathbf{KA}_ω

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- Let us denote this system by $\mathbf{KA}_{\omega\circ}$.

Circular Derivation: Example

$$\begin{array}{c}
 \frac{a \rightarrow a \quad (a+b)^* \rightarrow a^*(ba^*)^*}{a, (a+b)^* \rightarrow aa^*(ba^*)^*} \quad \frac{aa^*(ba^*)^* \rightarrow a^*(ba^*)^*}{a, (a+b)^* \rightarrow a^*(ba^*)^*} \\
 \frac{\rightarrow a^*(ba^*)^*}{a+b, (a+b)^* \rightarrow a^*(ba^*)^*} \quad \frac{b \rightarrow b \quad (a+b)^* \rightarrow a^*(ba^*)^*}{b, (a+b)^* \rightarrow ba^*(ba^*)^*} \quad \frac{ba^*(ba^*)^* \rightarrow (ba^*)^*}{b, (a+b)^* \rightarrow (ba^*)^*} \\
 \frac{\rightarrow a^* \quad b, (a+b)^* \rightarrow (ba^*)^*}{b, (a+b)^* \rightarrow a^*(ba^*)^*} \\
 \frac{a+b, (a+b)^* \rightarrow a^*(ba^*)^* \quad b, (a+b)^* \rightarrow a^*(ba^*)^*}{(a+b)^* \rightarrow a^*(ba^*)^*} \quad *L
 \end{array}$$

The diagram illustrates a circular derivation. It shows a sequence of logical steps that eventually lead back to the initial assumptions. Specifically, the final result $(a+b)^* \rightarrow a^*(ba^*)^*$ is derived from $a+b, (a+b)^* \rightarrow a^*(ba^*)^*$ and $b, (a+b)^* \rightarrow a^*(ba^*)^*$. The rule $*L$ is applied to these two. The left part of the rule is derived from $a \rightarrow a$ and $(a+b)^* \rightarrow a^*(ba^*)^*$. The right part is derived from $b \rightarrow b$ and $(a+b)^* \rightarrow a^*(ba^*)^*$. The $(a+b)^* \rightarrow a^*(ba^*)^*$ assumption is used in both branches and is also the final result, creating a circular dependency. Arrows in the original image highlight this circularity.

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- Furthermore, it is unclear how to reduce \mathbf{KA}_{∞} to $\mathbf{KA}_{\circlearrowleft}$ (even with cuts).
- However, it is possible to construct a cut-free circular calculus for \mathbf{KA} , but with a more involved sequential syntax.

- In a hypersequent $\Pi \rightarrow \mathcal{X}$ (Das & Pous 2017), the left-hand side Π is a sequence of formulae, and the right-hand side $\mathcal{X} = \Delta_1 \mid \dots \mid \Delta_m$ is a multiset of sequences of formulae.

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- The left rules are the same, e.g.:

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- The right-hand side enjoys structural rules:

$$\frac{\Pi \rightarrow \mathcal{X}}{\Pi \rightarrow \Delta \mid \mathcal{X}} WR \qquad \frac{\Pi \rightarrow \Delta \mid \Delta \mid \mathcal{X}}{\Pi \rightarrow \Delta \mid \mathcal{X}} CR$$

- The atomic case is handled as follows:

$$\frac{}{\varepsilon \rightarrow \varepsilon} Ax \qquad \frac{\Gamma \rightarrow \Delta_1 \mid \dots \mid \Delta_m}{a, \Gamma \rightarrow a, \Delta_1 \mid \dots \mid a, \Delta_m} K$$

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- Finally, the right rules are as follows:

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- \mathbf{HKA}_ω allows non-well-founded proofs, with the following **fairness condition**: each infinite path should traverse $*L$ infinitely many times.
- There is no cut rule in \mathbf{HKA}_∞ (it is even hard to formulate).

Equivalence of \mathbf{HKA}_∞ , \mathbf{KA}_∞ , and \mathbf{KA}_ω

Theorem (Das & Pous 2017)

Sequents of the form $\Pi \rightarrow B$ are equiderivable in \mathbf{HKA}_∞ , \mathbf{KA}_∞ , and \mathbf{KA}_ω .

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- For the direction from \mathbf{HKA}_∞ to \mathbf{KA}_ω , we use the same argument as for \mathbf{KA}_∞ .
- Namely, we establish the following key lemma: if $\Gamma, A^*, \Delta \rightarrow \mathcal{X}$ is derivable in \mathbf{HKA}_∞ , then so is $\Gamma, A^n, \Delta \rightarrow \mathcal{X}$ for each n .
(Induction on n .)

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 - For example, $\{3, 3, 4, 0\} \gg \{2, 2, 2, 3, 4, 0\} \gg \{2, 2, 2, 3, 2, 2, 1, 0\}$.

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 - This is exactly what happens in our lemma, when A^* is replaced by $A^n = A, \dots, A$.

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- By our lemma, we get derivability of $\Gamma, A^n, \Delta \rightarrow \mathcal{X}$ for each n in \mathbf{HKA}_∞ , and since $\text{wh}_*(\Gamma, A^n, \Delta) \ll \text{wh}_*(\Gamma, A^*, \Delta) \leq \text{wh}_*(\Sigma)$, also in \mathbf{KA}_ω by induction hypothesis.

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- Now we finalise our proof by applying $*L_\omega$.
- Notice that induction here is more involved than for \mathbf{KA}_∞ .

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- Therefore, \mathbf{KA}_ω is enumerable, and by Post's theorem it is decidable.
- A more accurate analysis of circular proofs yields the PSPACE upper bound.
- Circular proofs in \mathbf{HKA}_∞ can be translated to \mathbf{KA}_\circ proofs (but with cuts), and therefore to \mathbf{KA} proofs. Thus, $\mathbf{KA} = \mathbf{KA}_\omega$. (We shall not go into this.)

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Leftmost Proofs

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- A proof in \mathbf{HKA}_∞ is called a **leftmost** one, if for each logical rule its active formula is the first formula in a sequence.

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- This holds for both left and right rules.
- Restricting ourselves to leftmost proofs means dropping left contexts in sequent rules.
- Now we have the following left logical rules:

$$\frac{\Gamma \rightarrow \mathcal{X} \quad A, A^*, \Gamma \rightarrow \mathcal{X}}{A^*, \Gamma \rightarrow \mathcal{X}} *L \qquad \frac{A, B, \Gamma \rightarrow \mathcal{X}}{A \cdot B, \Gamma \rightarrow \mathcal{X}} \cdot L$$
$$\frac{A, \Gamma \rightarrow \mathcal{X} \quad B, \Gamma \rightarrow \mathcal{X}}{A + B, \Gamma \rightarrow \mathcal{X}} +L \qquad \frac{\Gamma \rightarrow \mathcal{X}}{1, \Gamma \rightarrow \mathcal{X}} 1L \qquad \frac{}{0, \Gamma \rightarrow \mathcal{X}} 0L$$

- ... and the following right rules:

$$\frac{\Pi \rightarrow \Delta \mid A, A^*, \Delta \mid \mathcal{X}}{\Pi \rightarrow A^*, \Delta \mid \mathcal{X}} *R$$

$$\frac{\Pi \rightarrow A, B, \Delta \mid \mathcal{X}}{\Pi \rightarrow A \cdot B, \Delta \mid \mathcal{X}} \cdot R$$

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- Other rules are the same:

$$\overline{\varepsilon \rightarrow \varepsilon} \text{ } Ax \qquad \frac{\Gamma \rightarrow \Delta_1 \mid \dots \mid \Delta_m}{a, \Gamma \rightarrow a, \Delta_1 \mid \dots \mid a, \Delta_m} K$$

$$\frac{\Pi \rightarrow \mathcal{X}}{\Pi \rightarrow \Delta \mid \mathcal{X}} WR \qquad \frac{\Pi \rightarrow \Delta \mid \Delta \mid \mathcal{X}}{\Pi \rightarrow \Delta \mid \mathcal{X}} CR$$

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- This, of course, does not constitute a mathematical proof of the theorem in a reasonable sense.

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- This simulation is performed by eager application of $*L$ to one and the same instance of A^* .
- Leftmost proofs disallow this:

$$\frac{\Gamma \rightarrow \mathcal{X} \quad A, A^*, \Gamma \rightarrow \mathcal{X}}{A^*, \Gamma \rightarrow \mathcal{X}} *L$$

since now we are forced to decompose A before we are allowed to do the next iteration of A^* .

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- An example is $a, a^* \rightarrow a^* \cdot a$.
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- We think of decomposing a^* on the right, but this would yield a choice: $a^*a \equiv a + (aa^*a)$, and this choice should actually be made **after** applying $*L$.
 - On the left branch of $*L$ we choose $a \rightarrow a$, and on the right one we choose $aaa^* \rightarrow aa^*a$.

Some Speculations

This is handled by the hypersequential version of the $*R$ rule, which keeps both choices in the sequent, and postpones the decision to applications of WR above:

$$\begin{array}{c}
 \frac{\varepsilon \rightarrow \varepsilon}{\varepsilon \rightarrow \varepsilon \mid a^*, a} \text{ } WR \quad \frac{a, a^* \rightarrow a^*, a}{a, a^* \rightarrow \varepsilon \mid a^*, a} \text{ } WR \\
 \hline
 \frac{a^* \rightarrow \varepsilon \mid a^*, a}{a, a^* \rightarrow a \mid a, a^*, a} \text{ } K \\
 \hline
 \frac{a, a^* \rightarrow a^*, a}{a, a^* \rightarrow a^* \cdot a} \text{ } \cdot R \\
 \hline
 \text{ } *L
 \end{array}$$

Now we are going to prove the following two statements, which give the necessary result:

1. If $v(A) \subseteq v(B)$, then $A \rightarrow B$ has a leftmost proof in \mathbf{HKA}_∞ .
2. Each leftmost proof can be transformed into a circular one.

Lemma

If there is a subderivation

$$\frac{\frac{\Gamma \rightarrow A^*, \Delta \mid \mathcal{X}}{\vdots \pi}}{\Gamma \rightarrow \Delta \mid A, A^*, \Delta \mid \mathcal{Y}} \quad *R$$

where π consists only of right logical rules, and the sequent $\Gamma \rightarrow A^, \Delta \mid \mathcal{Y}$ is valid in the standard interpretation, then so is $\Gamma \rightarrow \mathcal{X}$ (i.e., A^*, Δ there is redundant).*

Productivity Lemma

- All right rules are invertible, so $\Gamma \rightarrow A^*, \Delta \mid \mathcal{X}$ is also valid.
- It is sufficient to prove $A^*, \Delta \rightarrow \mathcal{X}$ in \mathbf{HKA}_∞ .
- By soundness, this means $v(A^*, \Delta) \subseteq v(\mathcal{X})$, and thus $v(\Gamma) \subseteq v(A^*, \Delta) + v(\mathcal{X}) = v(\mathcal{X})$.
- Proving $A^*, \Delta \rightarrow \mathcal{X}$ is performed by using the left rules corresponding to the rules from π :

$$\frac{\frac{\vdots \pi'}{\Delta \rightarrow \mathcal{X}} \quad \frac{\vdots \pi''}{A, A^*, \Delta \rightarrow \mathcal{X}}}{A^*, \Delta \rightarrow \mathcal{X}} *L$$

Productivity Lemma

- In π' and π'' , antecedents will be the corresponding sequences from the succedents in π . For example, if π had a step of the form

$$\frac{\Gamma \rightarrow B, \Delta' \mid \mathcal{L} \quad \Gamma \rightarrow C, \Delta' \mid \mathcal{L}}{\Gamma \rightarrow B + C, \Delta' \mid \mathcal{L}} +R$$

where $B + C, \Delta'$ was the antecedent in π' or π'' , then we proceed as

$$\frac{B, \Delta' \rightarrow \mathcal{X} \quad C, \Delta' \rightarrow \mathcal{X}}{B + C, \Delta' \rightarrow \mathcal{X}} +L$$

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- Thus, a linear derivation π with rich succedents is decomposed into branching derivations π' and π'' with simple antecedents.
- In π'' , on top we shall have either $\Phi \rightarrow \mathcal{X}$ where $\Phi \in \mathcal{X}$ (derivable by WR), or $A^*, \Delta \rightarrow \mathcal{X}$, which is derived by backlink to the goal.

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- Fairness is maintained by the lowermost $*L$.
- For π' , we do not have this guarantee of fairness.
- However, we claim that if a leaf of π' is of the form $A^*, \Delta \rightarrow \mathcal{X}$, then the corresponding path should have traversed $*L$.
- Indeed, all rules in π' are left logical rules, and such rules other than $*L$ decrease the size of the antecedent. On the other hand, A^*, Δ is bigger than Δ .

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- Each leaf is either $\rightarrow \mathcal{X}$ or $a, \Gamma \rightarrow \mathcal{X}$.
- An important thing to mention here is that Stage 1 could generate infinite paths, e.g.:

$$\frac{\Gamma \rightarrow \mathcal{X} \quad \frac{\frac{\vdots}{1^*, \Gamma \rightarrow \mathcal{X}}}{1, 1^*, \Gamma \rightarrow \mathcal{X}} \quad 1L}{1^*, \Gamma \rightarrow \mathcal{X}} *L$$

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- These rules are also invertible.
- However, here we cannot go eagerly, since this would result in proofs violating fairness:

$$\frac{\frac{\frac{\vdots}{\Pi \rightarrow 1^*, \Delta \mid \mathcal{X}}}{\Pi \rightarrow 1, 1^*, \Delta \mid \mathcal{X}} 1R}{\Pi \rightarrow 1^*, \Delta \mid \mathcal{X}} *R$$

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- The latter get weakened out by Productivity Lemma (weakenings form **Stage 3**).
- Recall that our leaves are $\rightarrow \mathcal{X}$ or $a, \Gamma \rightarrow \mathcal{X}$.
- In the first case, by validity, we have $\varepsilon \in v(\mathcal{X})$. Thus, \mathcal{X} contains the empty sequence. Everything else gets weakened out.

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- Above K , we have new valid sequents, on which we again start with Stage 1.
- Notice that there is not (transfinite) induction here, we do not care for reducing any sort of parameter.
- The only thing we should care about is that the proof never gets stuck, and fairness is maintained.

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- Case 1: the branch eventually ends in one stage. Then it should be Stage 1, and fairness is maintained (see above).
- Case 2: the branch traverses Stages 1–4 infinitely.
- In this case, consider the size of the antecedent. This size gets strictly reduced at each Stage 4, thus, it should be restored, which can be done only by $*L$.

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Lemma

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- Corollary: the length of such a sequence is bounded by the size of the goal sequent.

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- This makes \mathbf{KA}_ω r.e., and by Post's theorem we obtain decidability.
- A more accurate consideration shows that each path reaches its cycle in polynomial number of steps, which makes \mathbf{KA}_ω PSPACE.

Example

$$\begin{array}{c}
 \frac{\varepsilon \rightarrow \varepsilon}{\varepsilon \rightarrow \varepsilon \mid aa, (aa)^* \mid a(aa)^*} \text{WR} \\
 \frac{\varepsilon \rightarrow (aa)^* \mid a(aa)^*}{\varepsilon \rightarrow (aa)^* + a(aa)^*} \text{*R} \\
 \frac{\varepsilon \rightarrow (aa)^* + a(aa)^*}{a^* \rightarrow (aa)^* + a(aa)^*} \text{+R}
 \end{array}
 \qquad
 \begin{array}{c}
 \frac{a^* \rightarrow a, (aa)^* \mid (aa)^*}{\vdots} \\
 \frac{a^* \rightarrow a, (aa)^* \mid (aa)^*}{a, a^* \rightarrow a, a, (aa)^* \mid a, (aa)^*} \text{K} \\
 \frac{a, a^* \rightarrow a, a, (aa)^* \mid a, (aa)^*}{a, a^* \rightarrow \varepsilon \mid a, a, (aa)^* \mid a, (aa)^*} \text{WR} \\
 \frac{a, a^* \rightarrow \varepsilon \mid a, a, (aa)^* \mid a, (aa)^*}{a, a^* \rightarrow \varepsilon \mid aa, (aa)^* \mid a(aa)^*} \text{*R} \\
 \frac{a, a^* \rightarrow \varepsilon \mid aa, (aa)^* \mid a(aa)^*}{a, a^* \rightarrow (aa)^* \mid a(aa)^*} \text{*R} \\
 \frac{a, a^* \rightarrow (aa)^* \mid a(aa)^*}{a, a^* \rightarrow (aa)^* + a(aa)^*} \text{+R} \\
 \frac{a, a^* \rightarrow (aa)^* + a(aa)^*}{a^* \rightarrow (aa)^* + a(aa)^*} \text{*L}
 \end{array}$$