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% MSU Spring, 2019
% EMEC 303 Project 1
clear; clc
close all
% Set step size and length of time in seconds
h = 1;
Lt = 6000;
N = round(Lt/h);
% Preallocation
height = zeros(1,N);
den
          = zeros(1,N);
t
          = zeros(1,N);
phi
          = zeros(1,N);
force r = zeros(1,N);
force theta = zeros(1,N);
          = zeros(1,N);
m
% Define initial conditions and constants
                 % Thrust multiplier
t m = 1.1045;
t(1) = 0;
                      % Initial time
                      % Starting density
den(1) = rho(0);
r(1) = 6.378e6; % Radius of earth
vr(1) = 0;
                      % Inital radial velocity
th(1) = 0;
                      % Initial angle theta
w(1) = 7.29e-5; % Angular velocity of earth
phi(1) = deg2rad(73.8); % Launch angle relative to horizontal
height(1) = 0;
                      % Initial heigh above ground
% Call force function to determine additional initial conditions
[force r(1), force theta(1),m(1)] =...
    force (t(1), den(1), phi(1), vr(1), w(1), r(1), t m);
% Store dependent variables into y
y = [r, vr, th, w];
% ODEs describing motion of rocket
f = Q(t, y, force r, force theta, m) ...
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[y(2), force r/m + y(1)*y(4)^2,...
    y(4), (force theta/m - 2*y(2)*y(4))/y(1)];
for i = 1:N-1
    % Update height and density
    height(i+1) = y(i,1)-r(1);
    den(i+1) = rho(height(i));
    % Update time
    t(i+1) = t(i) + h;
    % Update phi based on height
    if height(i) <= 275000</pre>
        phi(i+1) = sqrt(phi(1)-phi(1)*(height(i)/275000)^2);
    else
        phi(i+1) = 0;
    end
    % Call force function to update force in r and theta directions
    [force r(i+1), force theta(i+1), m(i+1)] = ...
        force (t(i), den(i), phi(i), y(i, 2), y(i, 4), y(i, 1), t m);
    % Euler update for dependent variables
    y(i+1,:) = y(i,:) + h*f(t(i),y(i,:),force r(i),force theta(i),m(i));
end
% Plot results
figure
polarplot((y(:,3)),y(:,1))
hold on
polarplot(0:.01:2*pi,ones(size(0:.01:2*pi))*r(1))
title('Rocket Trajectory in Polar Coordinates')
word1={'Radius (m)'};
text(0,3000000,word1)
figure
subplot(2,2,1)
plot(height,phi)
title ('Rocket Angle Relative to Horizontal')
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```
ylabel('Angle (rad)')
xlabel('Height (m)')
subplot(2,2,2)
plot(t,height)
title ('Rocket Height vs Time')
ylabel('Height (m)')
xlabel('Time (s)')
subplot(2,2,3)
plot(t,y(:,2))
title ('Radial Velocity vs Time')
ylabel('Speed (m/s)')
xlabel('Time (s)')
subplot(2,2,4)
plot(t,y(:,4).*y(:,1))
title ('Velocity in the Theta Direction vs Time')
ylabel('Speed (m/s)')
xlabel('Time (s)')
```