Requirements:
rated: 2 x DC Brushed motors (200 ml earch at highest voltage of 179); 2 x auxilliary motors (500 ml earch). These currents are blie maximum we need to supply.
max voltage of this battery is 4.21 Cuben fully day
Motor Driver Selection: The need a driver that can handle the abovementaged five motor driver should also support bidirectional control (forward of reverse motion) DRY 8833) left of right >60:6705 > Dual H-bridge motor driver. > Supports' up to 1.5A per channel
Power Supply: > must supply 200 mA x 2 = 400 mA to the brushed X me 1.4A = musk supply 500 mA x 2 = 1000 mA to auxiliary motors.
* Reccommendations: Add flyback diodes to add across the motor terminals to protect the motor driver from voltage spikes. caused by the motor's inductive roads. Verifying RV8833 as being suitable for solution total Plan Demotors each P=V1 = 4.2V × 0,2A = 0.84 W
total (P) for Aux maters each $P = VI = 4.20 \times 0.24 = 0.184 V$ total (P) for Aux maters each $P = VI = 4.20 \times 0.8 A = 2.1 W$ Portal = $(6.84 \times 2) + (02.1 W \times 2) = 5.88W$

Place an INA219 curions sensor on the 120 bust to monitory
the baltery. Dottery Monitoring. · Ensure proper configuration (AO anelA I can't be on GNB). 8 Hattery Charging. ·Charge the bouttery from a Winput pin. · Implement 2 charging modes: 200 mA ~ 600mA (1 100 mA) a) - Low etraiging mode: 200 mA b) & High elouiging mode: (400 mA (± 100 mA) Having two charging modes allow for flexibility. Objin. > Better battery health, especially if the battery is deeply discharged or if we want to extend its lifespan.

b) * Faster charging .
> Useful when we need to reclarge the battery quickly.

How to implement two changing Modes:

supports programmable charging current.

the value of an external resistor.

TP 4056-MS (Msksemi) is the ideal solution bet:

"It has a higher thermal regulation threshold (141%) > It supports programmable charging current up to LOO mA, which is well above 200 mA of 600 mA.

I which allows for better heart management.

Thus ensures softe operation even under higher power or high ambient temp.

> We can use the PROTI pin to set the draiging. current by selecting the appropriate resistor value:

~ DEOMA: R PROG = 1100 = 5.5 KS.

~ 600 mA : RproG = 1.83 k S.

The 1100 mt value comes from the TP4056 datastreet fis used to calculate charging current based on resister cornect 7 It has exposed thermal pad which improves heat dissipation It is ideal for compact designs.

(4) USB-C Integration (USBA105-GF-A) \$ 1.0875

· involves integrating a USB-C connector into our lower Madule to provide Woutput from the USB host.

·We need to include a USB-C receptable on our PCB Lo allow for correction to a USB-C coste.

5. External Load Switching (Breadboard Assignment) Provide 2x Lord external switching at 1A each (high-side com-) rected to SV

they should be controllable via a logic signal, GPIO from AP

We should use a P-Chamel MOSFET SI2301 FORSE Which is a P-MOSFET, SOT-23 package.

ST2301CDS-T1-GE3 ~80,0567

(6) Voltage Regulation. Provide et 3V3 (5% accuracy of 300 mA max) and 5V out (5% accuracy of 1.5 A max).

max 300 mA current. @ >313 output must deliver current.

more 1500mA

1 AP2112K-3.3TRG1 ~> \$ 0.0687

3 (TPS 562201DDCR) ~> \$0,0641

RT9193 LDO 3V3

= limithed current (300 mA)

than 3,3 V Sanefficient for high current)

* May overheat if load approaches 300 mA

AP2112K 3V3 3A16

- > 500 mA
- > = 2% accuracy.

LM25968X-5.0_ MOPB ~ 5V Buck Converter.

> Larger package (TO-263-5): May not fit compact PCB
> External components needed: Inductor, diade, capacitors
increase BOM cost.

* Size may be problematic.

TPS562201

- 7 2A
- * Smaller | chepper.

@ ON/OFF Switch.

Provide ONJOFF switch.

OFF state: Buttery draws that 30 MA

ON state: Can provide Robot with peak current 2A.

The switch needs to shut down 5 V and 3 V 3

Load Switch IC: (AP22802AW5-7) ~> \$ 0.1179

High side MOSFET, switch.

- > low leakage of < I HA in OFF state
- 3 A paak hornolling current.
- minimal voltage olop.

Controlled by GP10, no memual switch needed.

Circuit Design for AP22802AW5-7:

Input (IN): Connect to battery (3.7V. LiPo)
Out (CUT): Feeds 5V/3V3 regulators.

Enable (EN): Tie to 5TM32 GP10 (cg PAO)
GND: Ground.