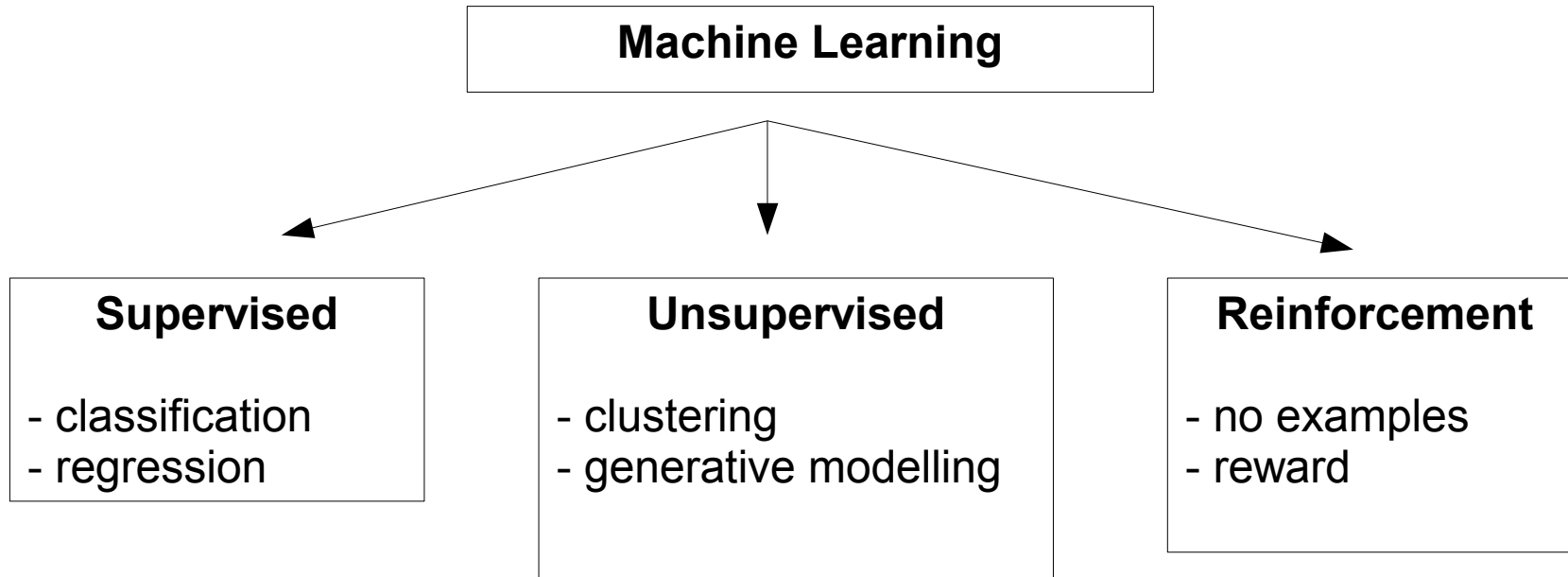


# Reinforcement Learning

on an example

# Overview

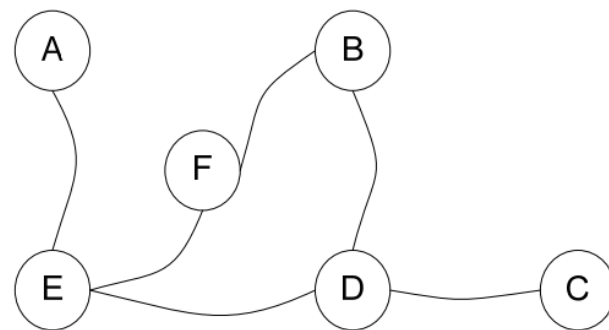
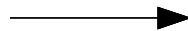
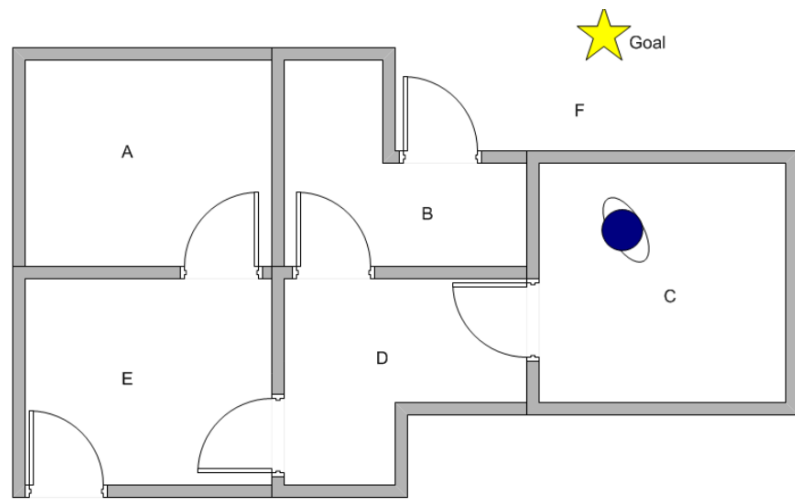


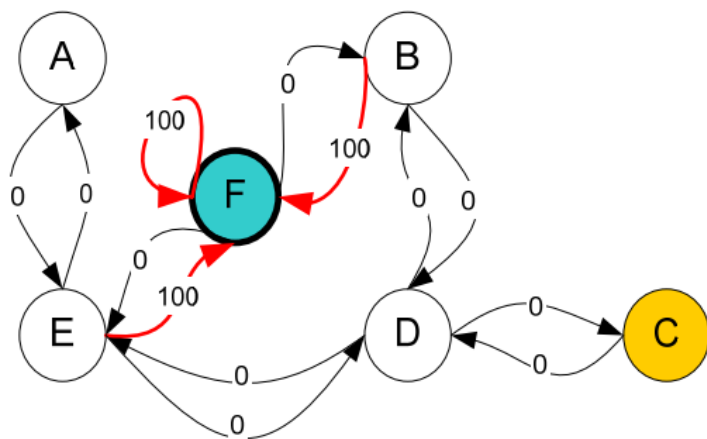
<https://deepmind.com/research/publications/playing-atari-deep-reinforcement-learning/>

## Theory Q-Learning:

- **exploration vs. exploitation dilemma** : example K-Armed-Bandit Problem
- **Markov-Decision-Process:**
  - $s_0$  : Initial state
  - $A(s)$  : all possible actions from state  $s$
  - $P(s'|s,a)$  : probability to get from state  $s$  to  $s'$
  - $R(s,a,s')$  : reward from state  $s$  to  $s'$
- **Q-Learning:**
  - find best policy  $\pi(s)$  to get best reward
  - model free, no Information about  $P(s'|s,a)$
  - Agent learns the value of state action pairs (Q-values)
  - **update function:**  $Q(s,a) = Q(s,a) + \alpha( R(s) + \gamma \max_{a'} Q(s',a') - Q(s,a) )$ 
    - $Q(s,a)$  : old Q-value or 0 (not defined)
    - $\alpha$  :  $0 \rightarrow 1$  learning rate
    - $R(s)$  : reward
    - $\gamma$  :  $0 \rightarrow 1$  discount factor, near 0 no reward in future, near 1 high reward
    - $\max Q(s',a')$ : maximum Q-value from state  $s'$  is next action  $a'$

# Q-Learning on an example





$\mathbf{R} =$

<i>state \ action</i>	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>
<i>A</i>	–	–	–	–	0	–
<i>B</i>	–	–	–	0	–	100
<i>C</i>	–	–	–	0	–	–
<i>D</i>	–	0	0	–	0	–
<i>E</i>	0	–	–	0	–	100
<i>F</i>	–	0	–	–	0	100

### **Q Learning**

**Given:** State diagram with a goal state (represented by matrix **R**)

**Find:** Minimum path from any initial state to the goal state (represented by matrix **Q**)

**Q Learning Algorithm** goes as follow

1. Set parameter  $\gamma$ , and environment reward matrix **R**
2. Initialize matrix **Q** as zero matrix
3. For each episode:
  - A. Select random initial state
  - B. Do while not reach goal state
    - a. Select one among all possible actions for the current state
    - b. Using this possible action, *consider* to go to the next state
    - c. Get maximum Q value of this next state based on all possible actions
    - d. Compute
$$Q(\text{state}, \text{action}) = R(\text{state}, \text{action}) + \gamma \cdot \text{Max}[Q(\text{next state}, \text{all actions})]$$
    - e. Set the next state as the current state
  - End Do
- End For



$$\mathbf{Q} = \begin{matrix} & A & B & C & D & E & F \\ \begin{matrix} A \\ B \\ C \\ D \\ E \\ F \end{matrix} & \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$$



$$\mathbf{Q} = \begin{matrix} & A & B & C & D & E & F \\ \begin{matrix} A \\ B \\ C \\ D \\ E \\ F \end{matrix} & \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$$

$$\mathbf{R} = \begin{matrix} \text{state} \backslash \text{action} & A & B & C & D & E & F \\ \begin{matrix} A \\ B \\ C \\ D \\ E \\ F \end{matrix} & \begin{bmatrix} - & - & - & - & 0 & - \\ - & - & - & 0 & - & 100 \\ - & - & - & 0 & - & - \\ - & 0 & 0 & - & 0 & - \\ 0 & - & - & 0 & - & 100 \\ - & 0 & - & - & 0 & 100 \end{bmatrix} \end{matrix}$$

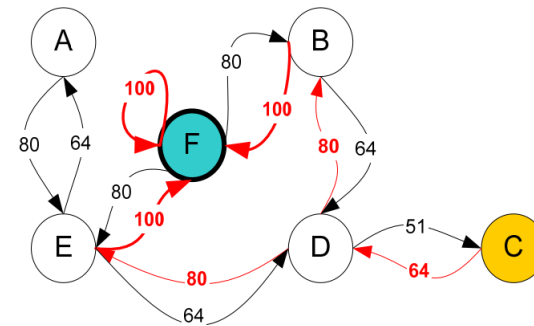
By random selection, we select to go to F as our action

$$\mathbf{Q}(\text{state}, \text{action}) = \mathbf{R}(\text{state}, \text{action}) + \gamma \cdot \text{Max}[\mathbf{Q}(\text{next state}, \text{all actions})]$$

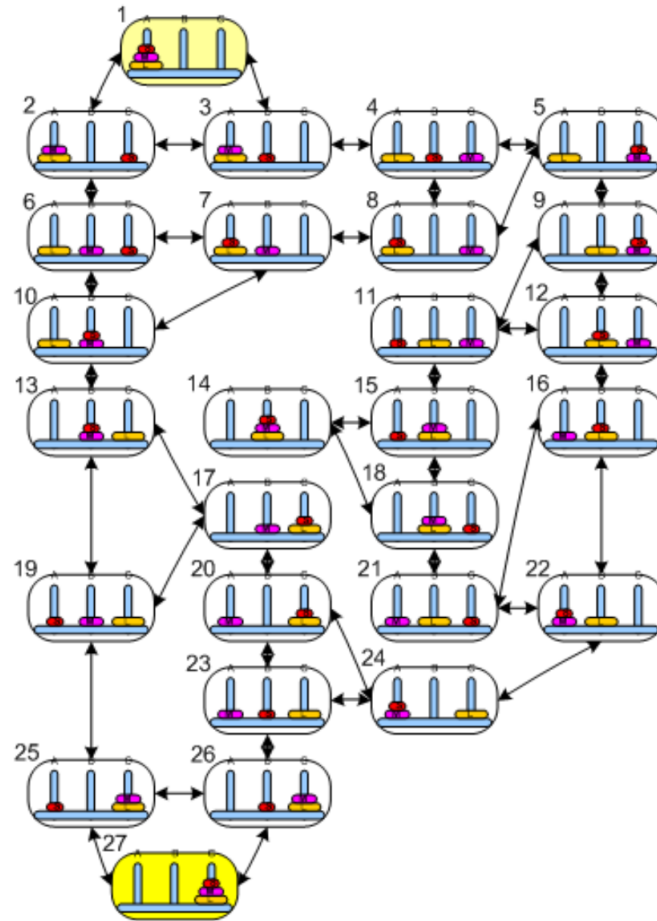
$$\mathbf{Q}(B, F) = \mathbf{R}(B, F) + 0.8 \cdot \text{Max}\{\mathbf{Q}(F, B), \mathbf{Q}(F, E), \mathbf{Q}(F, F)\} = 100 + 0.8 \cdot 0 = 100$$

**Q** =

<i>state \ action</i>	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>
<i>A</i>	—	—	—	—	400	—
<i>B</i>	—	—	—	320	—	500
<i>C</i>	—	—	—	320	—	—
<i>D</i>	—	400	256	—	400	—
<i>E</i>	320	—	—	320	—	500
<i>F</i>	—	400	—	—	400	500



# Towers of Hanoi



- setRMatrix();
- hanoiGame.setLambda(lambda);
- for ( int i = 0; i < rounds; i++ ) {  
    String res = hanoiGame.learn();  
    System.out.print(".");  
    //         System.out.print(res);  
}
- System.out.print(hanoiGame.bestMoves());

<https://github.com/sky4walk/HanoiTowersSolver>

### R-Matrix:

[illegible]

Q-Matrix:

0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	1	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	3	0	0	6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	3	0	1	0	6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	0	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	0	0	0	0	0	3	6	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	3	3	0	0	0	0	0	12	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	3	0	0	6	0	0	1	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	3	0	3	0	0	0	0	12	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	6	0	0	0	0	0	0	12	0	25	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	3	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	3	0	0	1	0	0	0	3	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	6	0	0	0	0	0	0	0	6	0	25	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	12	0	0	0	0	0	25	12	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	6	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	12	0	0	0	12	0	0	0	0	0	50	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	12	0	0	0	0	25	12	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	12	0	3	0	0	0	6	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	12	0	0	0	6	0	0	12	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	12	0	0	0	12	0	50	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	12	0	6	25	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25	0	0	0	0	0	50	100	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25	0	50	0	100
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

## Ablauf:

1)

+		
-+-		
--+--		
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2)

-+-		
--+--		+
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6)

--+--	-+-	+
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10)

	+	
--+--	-+-	
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13)

	+	
	-+-	--+--
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19)

+	-+-	--+--
-----		

25)

		-+-
+		--+--
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27)

		+
		-+-
		--+--
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