1.



2. ReLU

$$\frac{dL}{dx} = \left(\frac{dL}{dx}, \frac{dY}{dx}\right)_{i} = \begin{cases} \frac{dL}{dx} & \text{if } x_{i} > 0 \\ 0 & \text{if } x_{i} \leq 0 \end{cases}$$

3. Propont
$$\frac{\partial X}{\partial L} = \frac{\partial Y}{\partial L} \cdot \frac{\partial X}{\partial Y} = \frac{\partial Y}{\partial L} \cdot M$$

4. BN
$$\frac{\partial N}{\partial x_{i}} = \frac{1}{n} \frac{\partial \sigma}{\partial x_{i}} \frac{1}{(n-1)(x_{i}-M)^{2}} \frac{\partial \sigma}{\partial x_{i}} \frac{1}{(n-1)(x_{i}-M)^{2}}$$

$$= \frac{1}{26n} \left(\sum_{j} (x_{j}-M)(x_{j}-M)^{2} \right)$$

$$= \frac{1}{6n^{2}} \left(\sum_{j} (x_{j}-M) + (n-1)(x_{i}-M) \right)$$

$$\frac{\partial L}{\partial x_{i}} = \frac{\partial L}{\partial Y_{i}} \cdot \frac{\partial D_{i}}{\partial x_{i}}$$

$$= \frac{\partial L}{\partial Y_{i}} \cdot \frac{\partial D_{i}}{\partial x_{i}} \cdot \frac{\partial D_{i}}{\partial x_{i}}$$

$$= \frac{\partial L}{\partial Y_{i}} \cdot \frac{\partial D_{i}}{\partial x_{i}} \cdot \frac{\partial D_{i}}{\partial x_{i}$$

EECS 498/598 Deep Learning HW1

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- Logistic regression and beyond: Binary classification with a sigmoid output layer
 - a. No hidden units:
 - i. Performance: train acc: 0.964000; val acc: 0.952000
 - ii. Model: input_dim=20, hidden_dim=None, weight_scale=1e-3, reg=0.2
 - iii. Solver: update rule: sgd_momentum, learning_rate=1, lr decay=0.95, num epochs=20, batch size = 50
 - b. With hidden units:
 - i. Performance: train acc: 0.962000; val acc: 0.952000
 - ii. Model: input_dim=20, hidden_dim=32, weight_scale=1e-3, reg=0.3
 - iii. Solver: update rule: sgd_momentum, learning_rate=8e-2, lr_decay=0.9, num_epochs=20, batch_size = 50
- 2. SVM and beyond: binary classification with a hinge-loss output layer
 - a. No hidden units:
 - i. Performance: train acc: 0.964000; val acc: 0.944000
 - ii. Model: input_dim=20, hidden_dim=None, weight_scale=1e-3, reg=0.1
 - iii. Solver: update rule: sgd_momentum, learning_rate=1, lr_decay=0.95, num_epochs=50, batch_size = 50
 - b. With hidden units:
 - i. Performance: train acc: 0.968000; val acc: 0.928000
 - ii. Model: input_dim=20, hidden_dim=32, weight_scale=1e-3, reg=0.3
 - iii. Solver: update rule: sgd_momentum, learning_rate=1e-1, lr decay=0.95, num epochs=50, batch size = 50
- 3. Softmax regression and beyond: multi-class classification with a softmax output layer
 - a. No hidden units:
 - i. Performance: train acc: 0.953000; val acc: 0.935556
 - ii. Model: input dim=784, hidden dim=None, weight scale=1e-3,

- reg = 0.01
- iii. Solver: update rule: rmsprop, learning_rate=5e-5, lr_decay=0.9, num_epochs=50, batch_size = 100
- b. With hidden units:
 - i. Performance: train acc: 0.993000; val acc: 0.977037
 - ii. Model: input_dim=784, hidden_dim=64, weight_scale=1e-3, reg=0.01
 - iii. Solver: update rule: rmsprop, learning_rate=1e-4, lr_decay=0.9, num_epochs=50, batch_size = 100

4. Convolutional Neural Network for multi-class classification

- a. No batch normalization and drop out:
 - i. Performance: train acc: 0.984000; val acc: 0.976200
 - ii. Model: input_dim=(1,28,28), num_filters=5, filter_size =7, hidden dim=16, num classes=10, weight scale=1e-3, reg=0
 - iii. Solver: update rule: sgd_momentum, learning_rate=1e-3, lr decay=0.9, num epochs=50, batch size = 100
- b. With batch normalization and drop out:
 - i. Performance: train acc: 0.914000; val_acc: 0.901200
 - ii. Model: input_dim=(1,28,28), num_filters=8, filter_size =7, hidden dim=16, num classes=10, weight scale=1e-3, reg=0
 - iii. Solver: update rule: sgd_momentum, learning_rate=1e-2, lr decay=0.9, num epochs=50, batch size = 100

5. Convolutional Neural Networks for CIFAR10 image classification.

- a. Performance: accuracy: 74%
- b. Architecture Improvement:
 - i. Double the filter_num of first two conv layers
 - ii. Add batch normalization and relu after each conv layers
 - iii. Add drop out after first fc layer
- c. Solver:
 - i. Learning_rate = 0.001
 - ii. Batch_size = 100
 - iii. Criterion = crossentropy loss
 - iv. Optimizer = adam

6. Short answer questions

a. Sigmoid projects large inputs to 0 or 1, causing its dsigmoid = sigmoid *(1-sigmoid) to vanish. In DNN, the gradient vanishing is even more severe due to chain rule, resulting in difficulty in training.

- b. When perform W in testing, multiply x by p to account for missing activations in training.
- c. I will reduce learning rate.