



Singular Value Decomposition (SVD)

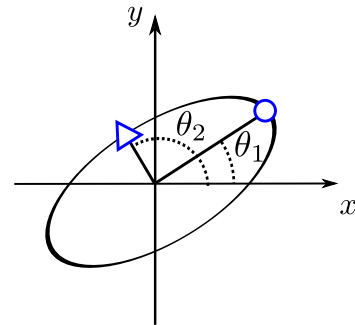
1 Understanding SVD

- (i) Take a look at the ellipse on the right. Let $\theta_1 = 30^\circ$, $\theta_2 = 120^\circ$, the coordinates of the circle and triangle in the shown axes are $(3\sqrt{3}, 3)$ and $(-1, \sqrt{3})$.

Use your knowledge about the SVD to find a matrix, that maps the ellipse to the unit sphere. Is that a unique mapping?

Can you also find a transformation that preserves the direction from the origin to both the circle and the triangle, respectively?

(You can solve this exercise analytically, but a correct numerical solution using SVD is also accepted.)



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- (ii) Which of the following are common applications of the SVD?

- ☐ computation of condition numbers
- ☐ ranking matrices
- ☐ low-rank approximations of images
- ☐ solving linear systems
- ☐ computation of multiple values
- ☐ computation of the null space

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2 Condition of a matrix

In the lecture we have seen the matrix

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T = \begin{pmatrix} 11 & 10 & 14 \\ 12 & 11 & -13 \\ 14 & 13 & -66 \end{pmatrix}.$$

- (i) Compute the condition number of \mathbf{A} with respect to the 2-norm and compare your result with the lecture (*hint*: class `DecompositionSVD`).
- (ii) Recall that the numerical rank of a matrix \mathbf{M} is defined by the number

$$\text{rank}_\epsilon(\mathbf{M}) = \# \{ \sigma_i > \epsilon, \sigma_i \text{ singular value of } \mathbf{M} \}.$$

By setting $\epsilon = 10^{-3}$, we get a rank deficiency in \mathbf{A} . Can you directly tell nullspace and range from your SVD computations in (i)? What are those?

- (iii) Given the equation $\mathbf{Ax} = \mathbf{b}$, where $\mathbf{b} = \begin{pmatrix} 1.001 \\ 0.999 \\ 1.001 \end{pmatrix}$, show that a variation of the elements of \mathbf{b} by 0.1 % implies a change in $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$ by at least 240 %.
- (iv) Compute the condition number (w.r.t. 2-norm) for the matrix $\mathbf{B} \in \mathbb{R}^{20 \times 20}$ defined by

$$\mathbf{B} = \mathbf{U} \text{diag}(a_1, \dots, a_{20}) \mathbf{V}^T, \quad a_n = \frac{1}{(n-5)^2 + 4}, \quad n = 1, \dots, 20.$$

2+1+2+1

3 Optimization Problems

- (i) Implement and verify optimization problem 1 from the lecture.
- (ii) Optimization problem 2: Four 2-D vectors were given on the lecture slides. Implement the optimization problem for the general case, e.g. 5, 6, 20 or N vectors.
- (iii) Implement the third optimization problem using the image `mr_head_angio.jpg`. How many approximations do we have? Which rank-k-approximations are sufficient? Plot the RMSE for $k=1, \dots, 150$ (*hint*: class `NumericGridOperator`).
- (iv) Compute the regression line through the following set of 2-D points:

$$\{(-3, 7), (-2, 8), (-1, 9), (0, 3.3), (1.5, 2), (2, -3), (3.1, 4), (5.9, -0.1), (7.3, -0.5)\}.$$

2+1+3+1

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