Medical Image Processing for Diagnostic Applications

Properties of the SVD

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Topics

Singular Value Decomposition (SVD) - Part 2 Properties of the SVD III-conditioned Matrix







Properties of the SVD: Rank and Norm

The singular value decomposition shows many extremely useful properties that are listed here without proof:

• rank of matrix A:

$$\operatorname{rank}(\mathbf{A}) = \#\{\sigma_i > 0\},\$$

numerical *e-rank* of matrix **A**:

$$\operatorname{rank}_{\varepsilon}(\mathbf{A}) = \#\{\sigma_i > \varepsilon\},\$$

• the *Frobenius norm* of the matrix $\mathbf{A} = (a_{i,j})_{i,j}$ is given by

$$\|\mathbf{A}\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n a_{i,j}^2} = \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2}.$$







Properties of the SVD: Eigenvectors

The singular value decomposition shows many extremely useful properties that are listed here without proof:

decomposition into rank 1 – matrices:

$$\mathbf{A} = \sum_{i=1}^{r} \sigma_i \mathbf{u}_i \mathbf{v}_i^{\mathsf{T}}, \quad r = \mathsf{rank}(\mathbf{A}),$$

- $\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i$ and $\mathbf{A}^\mathsf{T} \mathbf{u}_i = \sigma_i \mathbf{v}_i$,
- the column vectors of *U* are the eigenvectors of *AA*¹:

$$\mathbf{A}\mathbf{A}^{\mathsf{T}}\mathbf{u}_{i}=\sigma_{i}^{2}\mathbf{u}_{i},$$

• the column vectors of V are the eigenvectors of A^TA :

$$\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{v}_{i}=\sigma_{i}^{2}\mathbf{v}_{i}.$$







Mapping Effect of a Matrix

We want to find the directional vector **n** which **A** maps to a vector of maximal length compared to other vectors of the unit sphere:

$$\|\boldsymbol{A}\boldsymbol{n}\|_2^2 \longrightarrow \max.$$

A Lagrange multiplier is used to add the constraint $\|\boldsymbol{n}\|_2^2 = 1$:

$$\mathscr{L}(\mathbf{n}) = \|\mathbf{A}\mathbf{n}\|_{2}^{2} - \lambda \left(\|\mathbf{n}\|_{2}^{2} - 1\right) = \mathbf{n}^{\mathsf{T}}\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{n} - \lambda \mathbf{n}^{\mathsf{T}}\mathbf{n} - \lambda,$$

which can be solved by setting $\frac{d\mathcal{L}(n)}{dn} = 0$:

$$2\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{n} - 2\lambda\mathbf{n} = 0 \quad \Leftrightarrow \quad \mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{n} = \lambda\mathbf{n}.$$

Thus, the solution is an eigenvector of $\mathbf{A}^{\mathsf{T}}\mathbf{A}$.







Properties of the SVD

- The SVD yields orthonormal bases for the kernel (null-space) and the range of a matrix A:
 - The **kernel** of matrix **A** is spanned by the column vectors \mathbf{v}_i of \mathbf{V} , where the corresponding singular values fulfill $\sigma_i = 0$.
 - The *range* of matrix **A** is spanned by the column vectors \mathbf{u}_i of \mathbf{U} , where σ_i are the corresponding non-zero singular values.
- For the 2-norm of matrix A we get:

$$\|\boldsymbol{A}\|_2^2 = \max_{\|\boldsymbol{x}\|_2 = 1} \boldsymbol{x}^T \boldsymbol{A}^T \boldsymbol{A} \boldsymbol{x} = \sigma_1^2,$$

and if **A** is regular, we even have:

$$\|\mathbf{A}^{-1}\|_2^2 = \frac{1}{\sigma_p^2}.$$







Example







Example

- Obviously, matrix **A** has a rank deficiency if we select $\varepsilon = 10^{-3}$.
- The kernel of A is given by:

$$\ker(\mathbf{\emph{A}}) = \left\{\lambda \cdot \left(egin{array}{c} -0.6743 \\ 0.7384 \\ 0.0024 \end{array}
ight); \ \lambda \in \mathbb{R}
ight\}.$$

The range (or image) of A is:

$$\text{im}(\textbf{\textit{A}}) = \left\{\lambda \cdot \left(\begin{array}{c} 0.1285 \\ -0.2396 \\ -0.9623 \end{array} \right) + \mu \cdot \left(\begin{array}{c} 0.8375 \\ 0.5459 \\ -0.0241 \end{array} \right); \ \lambda, \mu \in \mathbb{R} \right\}.$$







III-conditioned Matrix

Definition

A matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ is called *ill-conditioned* if for a given linear system

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

minor changes in $\mathbf{b} \in \mathbb{R}^m$ cause major changes in $\mathbf{x} \in \mathbb{R}^n$.

Definition

The *condition number* of a regular matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ with respect to a matrix norm ||.|| is defined by

$$\kappa(\mathbf{A}) = \|\mathbf{A}^{-1}\| \cdot \|\mathbf{A}\|.$$

If **A** is singular, $\kappa(\mathbf{A}) = +\infty$.







III-conditioned Matrix: Remarks

- A matrix with $\kappa(\mathbf{A})$ close to 1 is called **well-conditioned**.
- A matrix with $\kappa(\mathbf{A})$ significantly greater than 1 is said to be ill-conditioned
- The condition number is a measure of the stability or sensitivity of a matrix.
- Using the 2-norm, the condition number of a regular matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ can be computed by SVD:

$$\kappa(\mathbf{A}) = \frac{\sigma_1}{\sigma_n},$$

where σ_1 is the largest, and σ_n is the smallest singular value.

 The SVD allows for the exact computation of the condition number, but this is computationally expensive.







III-conditioned Matrix

Example

Consider the previous matrix

$$\mathbf{A} = \left(\begin{array}{rrr} 11 & 10 & 14 \\ 12 & 11 & -13 \\ 14 & 13 & -66 \end{array}\right),$$

where we have $det(\mathbf{A}) = 1$. The singular value decomposition of \mathbf{A} results in the singular values:

$$\sigma_1 = 71.3967$$
, $\sigma_2 = 21.7831$, and $\sigma_3 = 0.0006$.

Thus the condition number is $\kappa(\mathbf{A}) = 118994.5 \gg 1$.

Exercise: Show that a variation in **b** by 0.1% implies a change in **x** by 240%.







Topics

Properties of the SVD

Summary Take Home Messages **Further Readings**







Take Home Messages

- We learned about important properties of the SVD, like
 - analytical and numerical rank definition,
 - Frobenius norm and 2-norm.
 - the relation between U, V and the eigenvectors of AA^T , A^TA ,
 - the relation between the kernel/range of **A** and the columns of **V**, **U**.
- For every matrix a condition number can be computed. Ill-conditioned matrices are numerically rather instable.







Further Readings

Read the original:

Gene H. Golub and Charles F. Van Loan. *Matrix Computations*. 3rd ed. Johns Hopkins Studies in the Mathematical Sciences. Baltimore: The Johns Hopkins University Press. Oct. 1996

A very detailed and easy to follow introduction of the SVD can be found in:

Carlo Tomasi's class notes, chapter 3 (a must-read).

The theory is described in an easy to read format in:

Llovd N. Trefethen and David Bau III. Numerical Linear Algebra. Philadelphia: SIAM, 1997

For details about the numerical computation of SVD see:

William H. Press et al. Numerical Recipes - The Art of Scientific Computing. 3rd ed. Cambridge University Press, 2007. Get at http://numerical.recipes/(August 2016).

Finally, have a look at:

Kaare Brandt Petersen and Michael Syskind Pedersen. The Matrix Cookbook. Online. Accessed: 25. April 2017. Technical University of Denmark, Nov. 2012. URL: http://www2.imm.dtu.dk/pubdb/p.php?3274