

Medical Image Processing for Diagnostic Applications

Image Registration in Practice – Part 2

Online Course – Unit 68

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Pattern Recognition Lab (CS 5)



Topics

Applications of Image Registration

Multimodal Registration

Summary

Take Home Messages

Further Readings

Multimodal Registration

Historical remarks on the application of mutual information in computer vision and image processing:

- Maximization of mutual information is applied to solve parameter estimation problems, e. g., speech recognition (~1980).
- Maximization of mutual information was first applied to image registration by P. Viola, W. Wells and by Collignon (1995).
- Maximization of mutual information was first applied to active object recognition by B. Schiele and J. Crowley (1997).

Kullback-Leibler Divergence

A proper similarity measure for density functions is the *Kullback-Leibler Divergence* (KL divergence). The KL divergence between two bivariate probability density functions $p(f, g)$ and $q(f, g)$ is defined as:

$$KL(p, q) = \int \int p(f, g) \log \frac{p(f, g)}{q(f, g)} df dg.$$

Idea for Image Registration: Images that are correctly registered imply the highest probabilistic dependency of aligned intensity values. The more the random variables depend on each other, the more the probability density functions $p(f, g)$ and $p(f) \cdot p(g)$ differ. This difference can be measured by the KL divergence:

$$KL(p, q) = \int \int p(f, g) \log \frac{p(f, g)}{p(f)p(g)} df dg.$$

Optimization Problem for Image Registration

The transform T that maps the gray level of the model image to the image point of the reference image can be estimated as follows:

$$\hat{T} = \arg \max_T \sum_i p(f_i, g_{T(i)}) \log \frac{p(f_i, g_{T(i)})}{p(f_i) p(g_{T(i)})}.$$

In terms of information theory this is the maximization of **mutual information**:

We send an image $[f_i]_{i=1, \dots, N}$ and receive the image $[g_i]_{i=1, \dots, N}$, where the channel applies a transform to image coordinates and the intensity values change.

Registration of CT and SPECT Images

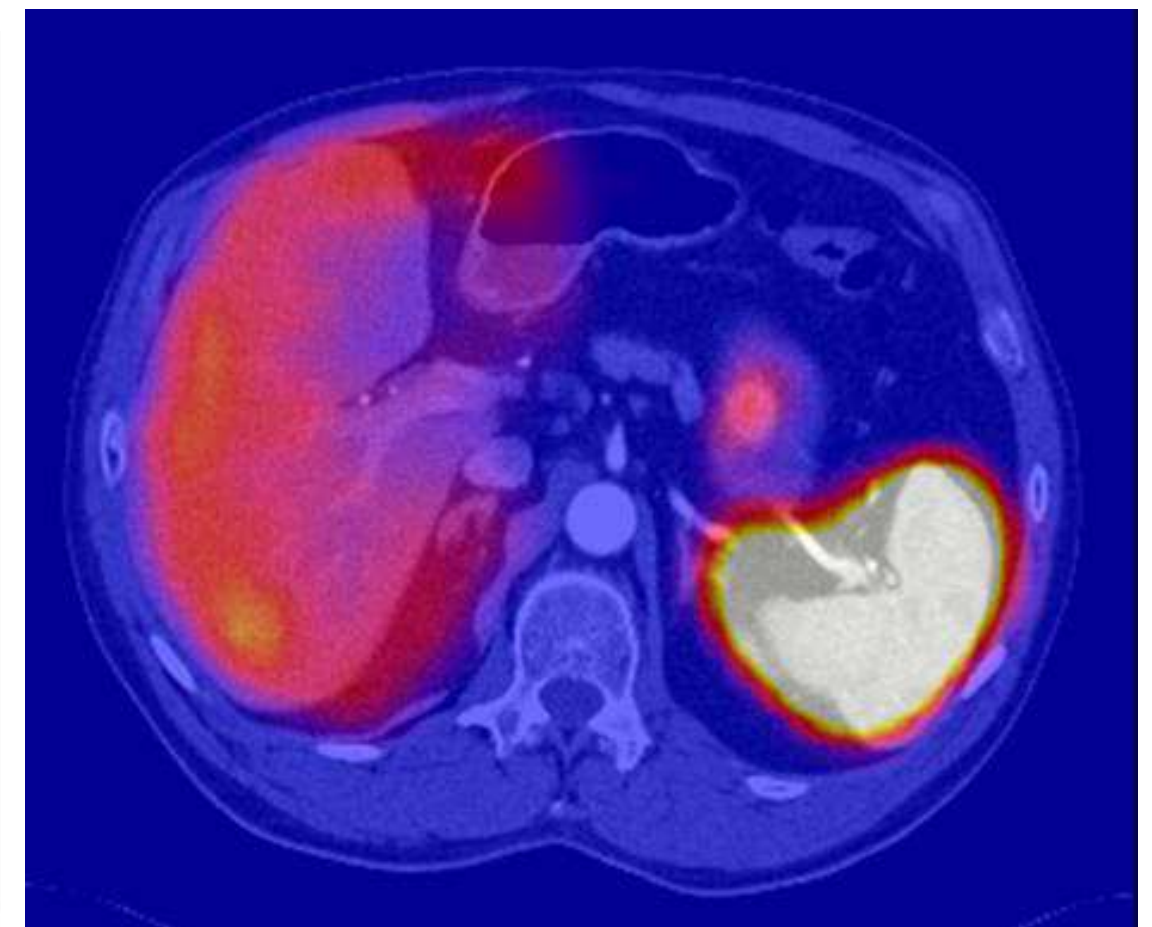
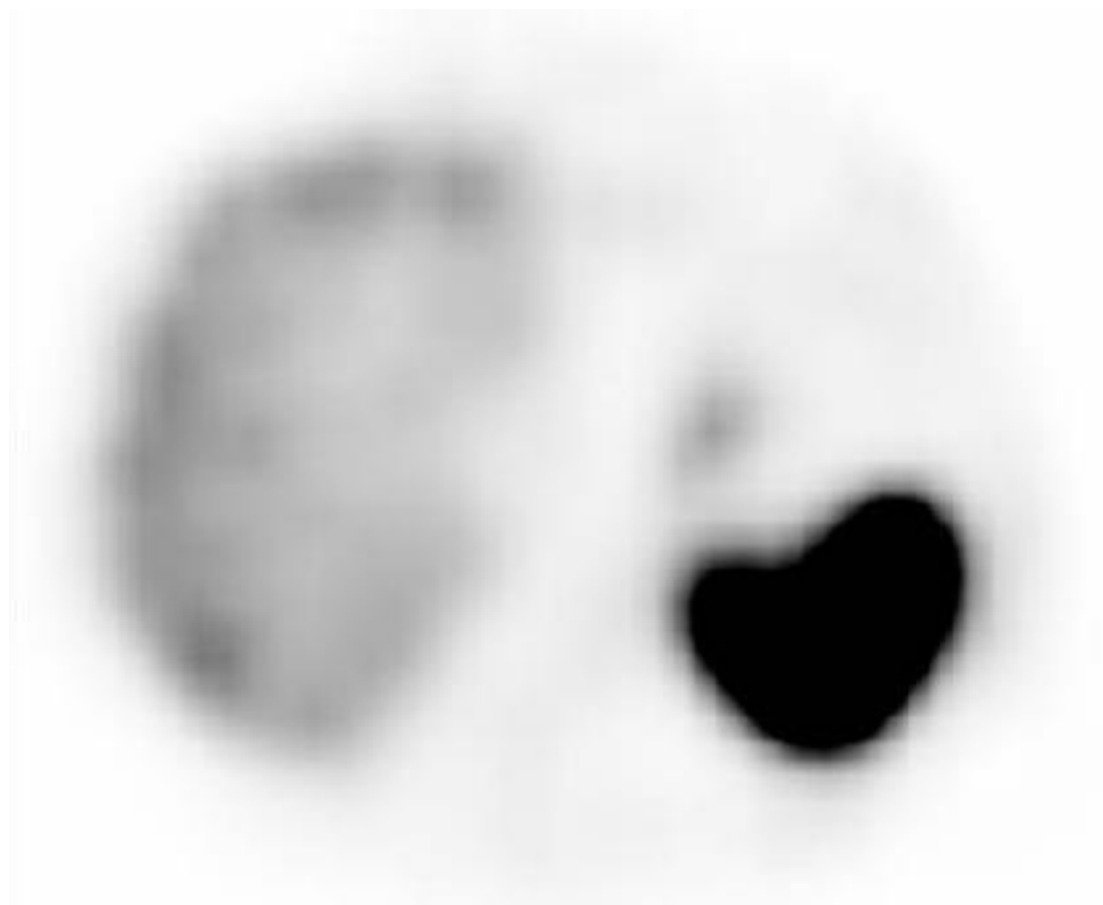


Figure 1: CT image (left), SPECT image (middle), result of image registration (right) (images courtesy of Dr. W. Römer, Nuclear Medicine, FAU)

Channel Model

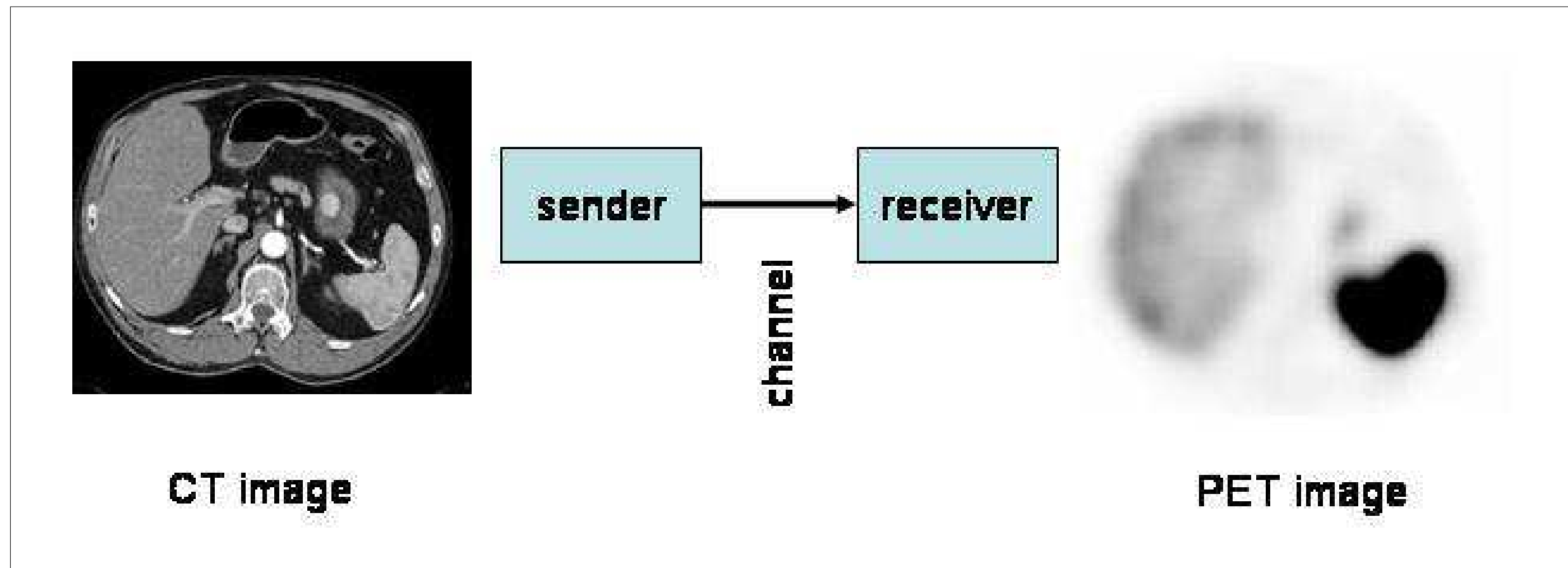


Figure 2: Channel model that defines the transition of CT to PET images (according to Wells et al., 1995).

Definition of Mutual Information

- Entropy is defined as:

$$H(F) = - \sum_f p(f) \log p(f).$$

- Entropy in the bivariate case is:

$$H(F, G) = - \sum_{f,g} p(f, g) \log p(f, g).$$

- Mutual information is defined as:

$$I(F, G) = H(F) + H(G) - H(F, G) = I(G, F).$$

Stochastic Maximization of Mutual Information

	draw N_A samples for i
	draw N_B samples for i
	Set $\hat{T} = \hat{T} + \lambda \frac{dI}{dT}$
	UNTIL convergence

Figure 3: Stochastic maximization

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Further Readings

Take Home Messages

- Multimodal registration is often performed using measures of probability theory.
- KL divergence and mutual information are important similarity measures for registration.

Further Readings – Part 1

Survey papers on medical image registration:

- Derek L. G. Hill et al. “Medical Image Registration”. In: *Physics in Medicine and Biology* 46.3 (2001), R1–R45
- J. B. Antoine Maintz and Max A. Viergever. “A Survey of Medical Image Registration”. In: *Medical Image Analysis* 2.1 (1998), pp. 1–36. DOI: 10.1016/S1361-8415(01)80026-8
- L. G. Brown. “A Survey of Image Registration Techniques”. In: *ACM Computing Surveys* 24.4 (Dec. 1992), pp. 325–376. DOI: 10.1145/146370.146374
- Josien P. W. Pluim, J. B. Antoine Maintz, and Max A. Viergever. “Mutual-Information-Based Registration of Medical Images: A Survey”. In: *IEEE Transactions on Medical Imaging* 22.8 (Aug. 2003), pp. 986–1004. DOI: 10.1109/TMI.2003.815867

A paper that inspired all the sections on complex numbers, quaternions, and dual quaternions:

Konstantinos Daniilidis. “Hand-Eye Calibration Using Dual Quaternions”. In: *The International Journal of Robotics Research* 18.3 (Mar. 1999), pp. 286–298. DOI: 10.1177/02783649922066213

Further Readings – Part 2

Non-parametric mappings for image registration:

- Nonlinear registration methods applied to DSA can be found in [Erik Meijering's papers](#).
- [Jan Modersitzki](#). *Numerical Methods for Image Registration*. Numerical Mathematics and Scientific Computations. Oxford Scholarship Online, 2007. Oxford: Oxford University Press, 2003. DOI: [10.1093/acprof:oso/9780198528418.001.0001](https://doi.org/10.1093/acprof:oso/9780198528418.001.0001)
- Many of Jan Modersitzki's and Bernd Fischer's papers on image registration can be found in the [publication list](#) of the Institute of Mathematics and Image Computing (Lübeck).
- The group of Martin Rumpf also published on non-parametric image registration. Details on their work can be found on the institute's [webpage](#).