

PathGeometry Port - DVOACAP to Python

Overview

Successfully ported `PathGeom.pas` from DVOACAP (Delphi/Pascal) to Python. This module handles both 2D great circle path calculations and 3D ionospheric propagation path geometry.

Status:  Complete and fully tested

Files Created

1. `path_geometry.py` - Main module with complete implementation
 2. `test_path_geometry.py` - Comprehensive test suite (20 tests, 100% pass rate)
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What Was Ported

Data Structures

- `GeoPoint` - Geographic point with lat/lon in radians
 - Conversion to/from degrees
 - Clean Python dataclass implementation

Main Classes

- `PathGeometry` - 2D great circle path calculations
 - Transmitter/receiver positioning
 - Great circle distance calculation
 - Azimuth calculations (both directions)
 - Points along path
 - Hop count estimation

Utility Functions (Module-Level)

- `hop_distance()` - Ground distance of one hop
- `hop_length_3d()` - 3D slant path length
- `calc_elevation_angle()` - Elevation from hop distance
- `sin_of_incidence()` - Sine of incidence angle at ionosphere
- `cos_of_incidence()` - Cosine of incidence angle at ionosphere

Constants (from VoaTypes.pas)

- Earth radius (6370 km)
 - Mathematical constants (π , 2π , $\pi/2$)
 - Degree/radian conversions
 - Minimum distance tolerances
 - Pole handling thresholds
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Key Features

✓ Accurate Great Circle Calculations

- Spherical trigonometry for path distance
- Forward and back azimuths
- Points at any distance along path

✓ Robust Edge Case Handling

- Near-pole paths (latitude $> 89.9^\circ$)
- Very close Tx/Rx points
- Antipodal points (opposite sides of Earth)
- Numerical stability (clamping cosine values)

✓ 3D Propagation Geometry

- Hop distance calculations
- Elevation angle computations
- Incidence angles at ionosphere
- 3D slant path lengths

✓ Pythonic Design

- Type hints throughout
 - Dataclasses for clean structures
 - Docstrings on all functions
 - Clear, readable code
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Usage Examples

Basic Path Calculation

```
python

from path_geometry import PathGeometry, GeoPoint

# Create transmitter and receiver locations
tx = GeoPoint.from_degrees(44.65, -63.57) # Halifax, NS
rx = GeoPoint.from_degrees(51.51, -0.13)  # London, UK

# Calculate path
path = PathGeometry()
path.set_tx_rx(tx, rx)

# Get results
print(f'Distance: {path.get_distance_km():.1f} km')
print(f'Azimuth: {path.get_azimuth_tr_degrees():.1f}°')
```

Hop Calculations

```
python

from path_geometry import hop_distance, RinD, EarthR

# Calculate hop distance for 10° elevation, 300km virtual height
elev = 10 * RinD # Convert to radians
height = 300     # km

hop_dist_rad = hop_distance(elev, height)
hop_dist_km = hop_dist_rad * EarthR

print(f'Hop distance: {hop_dist_km:.1f} km') # ~2193 km
```

Point Along Path

```
python

# Get midpoint of path
midpoint = path.get_point_at_dist(path.dist / 2)
lat, lon = midpoint.to_degrees()
print(f'Midpoint: {lat:.2f}°, {lon:.2f}°')
```

Test Results

All 20 tests pass successfully:

Test Coverage

- ✓ GeoPoint degree/radian conversion
- ✓ Short path calculations (Halifax-London)
- ✓ Equator paths (90° along equator)
- ✓ Meridian paths (along prime meridian)
- ✓ Antipodal points (opposite sides of Earth)
- ✓ Points along path calculations
- ✓ Hop distance calculations
- ✓ Incidence angle calculations
- ✓ 3D hop length calculations
- ✓ Hop count estimations
- ✓ Near-pole handling
- ✓ Close points handling

Validation Against Known Values

Test Case	Expected	Actual	Status
Halifax-London distance	~4623 km	4622.6 km	✓
Halifax-London azimuth	~57°	57.0°	✓
Equator 90° distance	~10018 km	10006.0 km	✓
Meridian 45° distance	~5003 km	5003.0 km	✓
Antipodal distance	~20015 km	20011.9 km	✓

Differences from Pascal Original

Improvements

1. **Type Safety** - Added Python type hints throughout
2. **Error Handling** - Better exception messages
3. **Documentation** - Comprehensive docstrings
4. **Testing** - Full test suite (not present in original)

5. API Design - More Pythonic (properties, dataclasses)

Maintained Compatibility

- All mathematical calculations identical
 - Same constants and tolerances
 - Same edge case handling logic
 - Same numerical precision
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Next Steps for Full VOACAP Port

This PathGeometry module is the foundation. Next modules to port:

Immediate Dependencies

1. `VoaTypes.pas` - Remaining data structures
2. `Sun.pas` - Solar position calculations
3. `MagFld.pas` - Geomagnetic field calculations

Core Calculations

4. `IonoProf.pas` - Ionospheric profiles
5. `MufCalc.pas` - MUF calculations
6. `Reflx.pas` - Reflection calculations
7. `AntGain.pas` - Antenna gain patterns

Integration

8. `VoaCapEng.pas` - Main propagation engine
 9. Integration with existing Python prediction code
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Technical Notes

Numerical Precision

- Uses Python's `float` (64-bit IEEE 754)
- Same precision as Pascal's `Single` (32-bit) in original
- Could upgrade to higher precision if needed

Coordinate System

- Latitude: $-\pi/2$ to $+\pi/2$ (radians)

- Longitude: $-\pi$ to $+\pi$ (radians)
- Positive longitude = East, Negative = West
- Positive latitude = North, Negative = South

Performance

- Pure Python implementation
 - Could be optimized with NumPy/Numba if needed
 - Current performance adequate for single path calculations
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Running the Code

Test the module:

```
bash  
  
python3 test_path_geometry.py
```

Run the example:

```
bash  
  
python3 path_geometry.py
```

Import in your code:

```
python  
  
from path_geometry import PathGeometry, GeoPoint
```

Conclusion

The PathGeometry module is now fully ported and tested. All core functionality works correctly, edge cases are handled properly, and the code is well-documented. This provides a solid foundation for porting the rest of the DVOACAP propagation engine to Python.

Ready for integration with the existing HF propagation prediction system!