

# Linear Filters

## Introduction

STAT 464 / 864 | Fall 2024

Discrete Time Series Analysis

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# We learned something in Unit 1! 🕒



When you have a sequence of data taken over time, that's called a **Time Series**.

Over time, this kind of data might show a **trend**. We can estimate that trend by **fitting a polynomial**, or by **smoothing** out the noise to reveal a clearer shape.

The other thing we're interested in is **repetition**. We can model seasonal patterns by **fitting harmonic sinusoids**, or by examining the **average behaviour across cycles**.

What's left over should just be **residual noise**. We can **test** if the residual data is noisy enough by looking at its **self-similarities**, at different time-scales.

## What do we tell quin?

# Linear Filters

**Definition:** A linear filter is a sequence of coefficients  $\{a_j\}_{j \in \mathbb{Z}}$

Satisfying  $\sum_{j=-\infty}^{\infty} |a_j| < \infty$  (absolute summability)

**Finite Filter:** Finitely many nonzero filter coefficients (in practice, all filters are finite)

**Input process**  $Y_t$

**Output process**

$$X_t = \sum_{j=-\infty}^{\infty} a_j Y_{t-j}$$

*Convolution*

# Linear Processes

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**Definition:** If input  $\{Y_t\}$  is  $wn(\sigma^2)$  (Recall  $\mu$  is zero, WLOG)  
the output  $\{X_t\}$  is called a **linear process**

**Notes:** We will be considering **time-invariant** filters

Assume input  $\{Y_t\}$  is **stationary** and **zero-mean**

# Causality



# Causality

**The past is far behind us, the future doesn't exist.**

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**Definition:** A filter is called **causal** if  $a_j = 0$  for  $j < 0$

Its output  $\{X_t\}$  is called a **causal process**

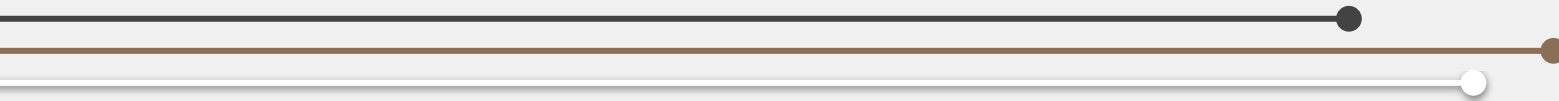
Depends only on past/present values of input  $\{Y_t\}$



Linear  
Filter

$$X_t = \sum_{j=-\infty}^{\infty} a_j Y_{t-j}$$

# Proposition 2.2.1



## Proposition 2.2.1 | Statement

$\{\psi_j\}$ : Linear filter

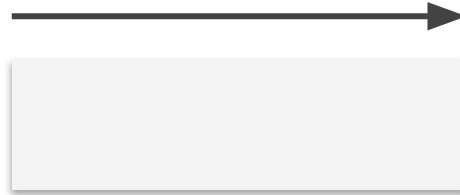
$\{Y_t\}$ : Input

⌚ Stationary

⌚ Zero-mean

⌚ ACVF:  $\gamma_Y(h)$

~ ConVoLuTioN ~



$\{X_t\}$ : Output

⌚ Stationary  $\begin{matrix} 1 \\ \swarrow \searrow \\ 2 \quad 3 \end{matrix}$

⌚ Zero-mean

⌚ ACVF  $\gamma_X(h)$

If input  $\{Y_t\}$  is  $\text{wn}(\sigma^2)$ ,

then  $\gamma_X(h)$  reduces to



## Proposition 2.2.1



**Proof**  $E[X_t] = 0$

Stationarity 1) time-invariant mean

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We can bring the  $E$  inside the sum  
because the sum (highlighted)  
is finite with probability 1

## Proposition 2.2.1



Deriving  $\gamma_X(h)$



Stationarity 2)

finite variance



Stationarity 3)

time-invariant ACVF

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Covariance independent of  $t$

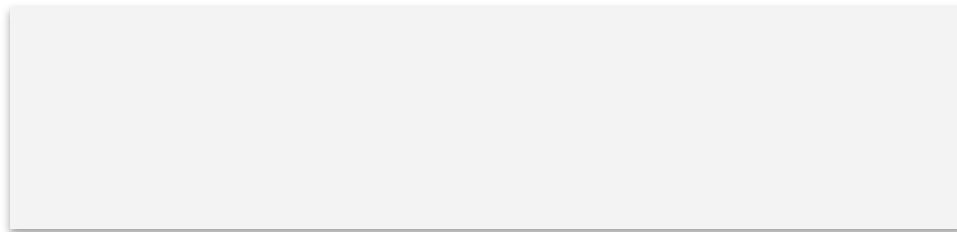


$Y_t$  is stationary  $\rightarrow \gamma_Y(h)$  finite for all  $h \rightarrow$  Variance  $\gamma_X(0)$  is finite  
Absolute summability  $\nearrow$

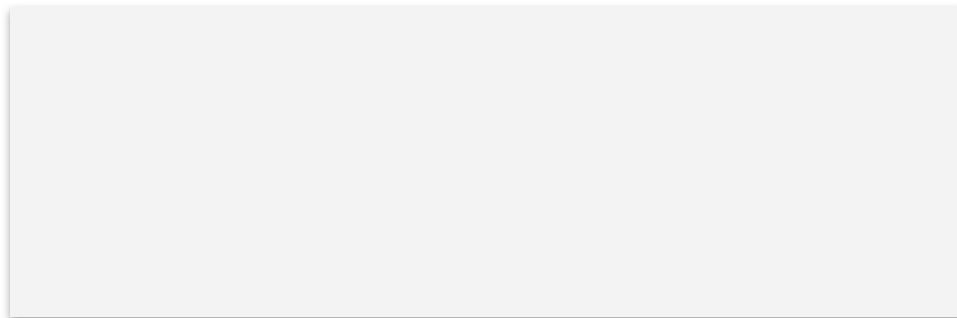
## Proposition 2.2.1 | Linear Processes

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If the input  $\{Y_t\}$  is a  $wn(\sigma^2)$  process,



For each  $j$ :



Therefore:

# We learned something Today, in Time Series 🕒



What do we tell quin?