

Eliminating Trends

Fits & Filters

STAT 464 / 864 | Fall 2024

Discrete Time Series Analysis

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Eliminating m_t

$$X_t = m_t + s_t + Y_t \quad (\star)$$

Once m_t is accounted for,
we can examine the data's remaining periodic structures

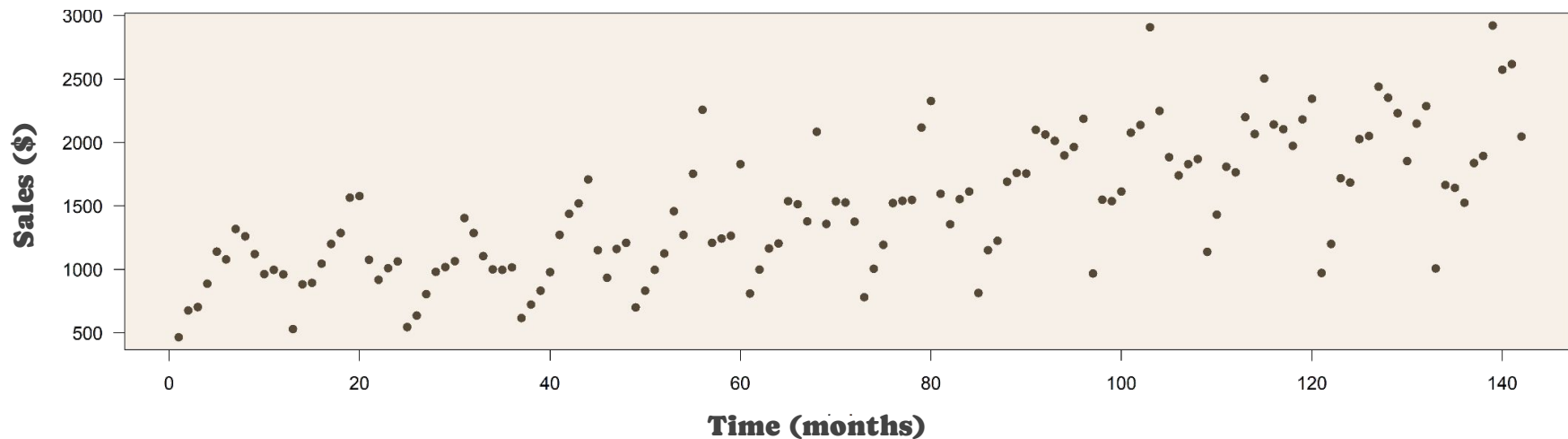


Fig 1: Australian Red Wine Sales from Jan. 1980 to Oct. 1991

Notice the fluctuations in sales are independent from the general upward trend

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Method 1

Polynomial Regression
(Similar to linear models)

Method 2

Moving Average (MA)
Smoothing Filters

Method 3

Exponential
Smoothing

Polynomial Regression

$$X_t = m_t + s_t + Y_t \quad (\star)$$

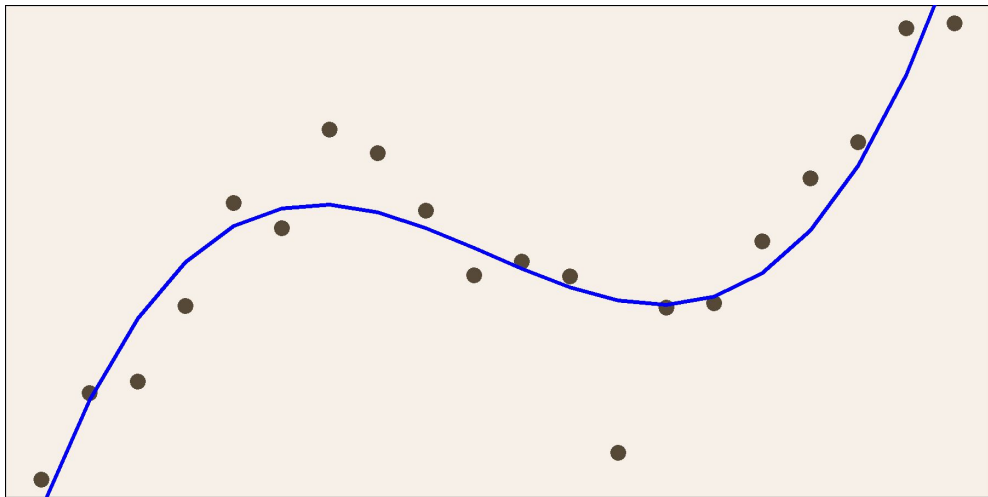
Assume m_t is well fit by a polynomial of some order $p \geq 1$

$$m_t = a_0 + a_1t + a_2t^2 + \dots + a_pt^p$$

Use **linear regression** to estimate unknown coefficients $\{a_k\}$

Estimates chosen to minimize:

$$\sum_{t=1}^N \left(x_t - (a_0 + \dots + a_pt^p) \right)^2$$



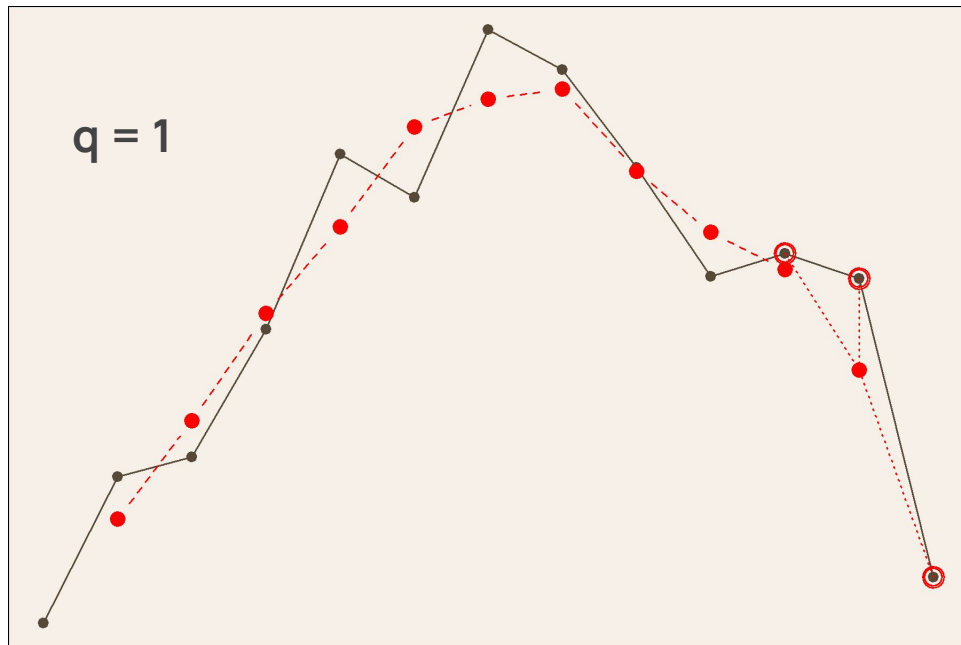
Moving Average (MA) Smoothing Filters

“Smooths” the series by estimating points using an average of surrounding data

Choose a **time-bandwidth** q
(non-negative integer)

Get average of points in a
 $(2q + 1)$ -diameter window,
centered at t

$$\hat{m}_t = \frac{1}{2q + 1} \sum_{j=-q}^q x_{t-j}$$



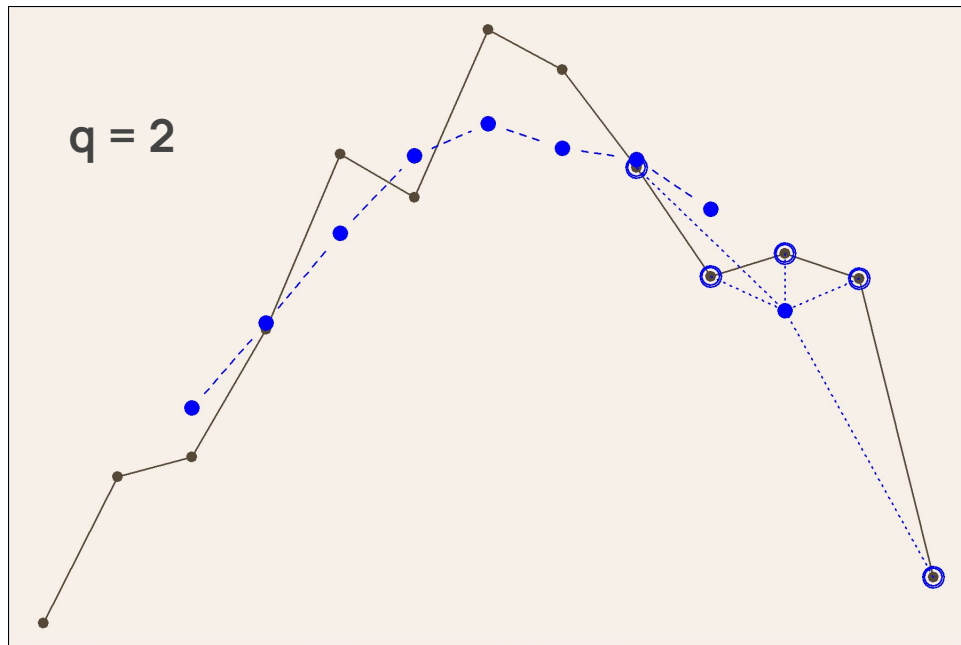
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MA Smoothers : Endpoint Issues

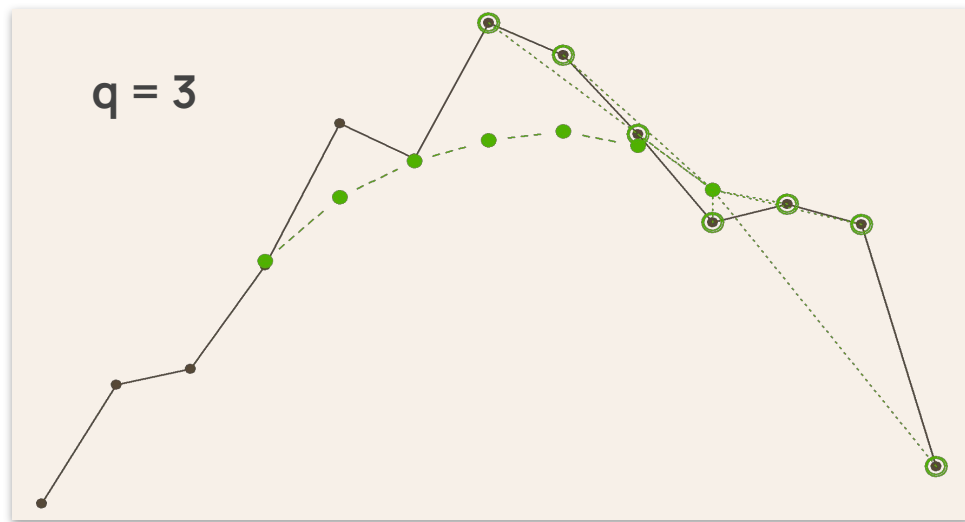
Near endpoints of series,

$$t \in [1, q] \text{ and } t \in [N - q + 1, N]$$

The estimate \hat{m}_t uses timepoints we don't get to observe

Possible Solutions:

- 1) pad" the ends with copies of x_1 and x_N (ITSMR does this)
- 2) set the missing data to 0
- 3) shorten window towards boundaries \rightarrow only ever covers observed values



MA-Smothers: Choice of q

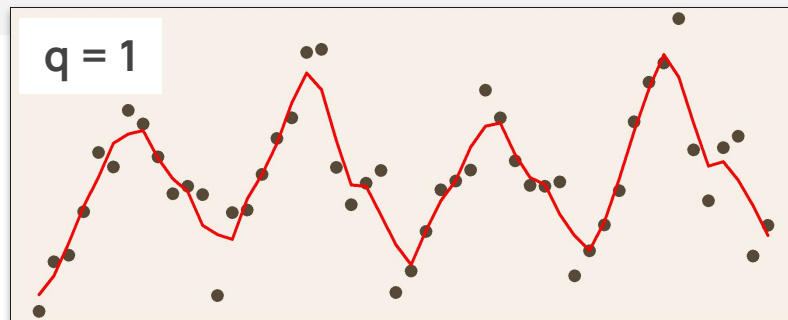
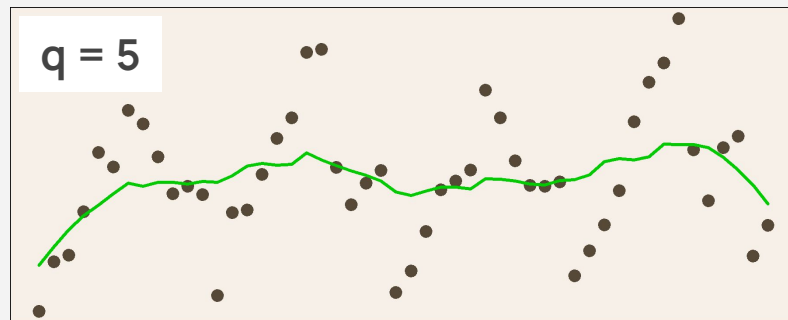
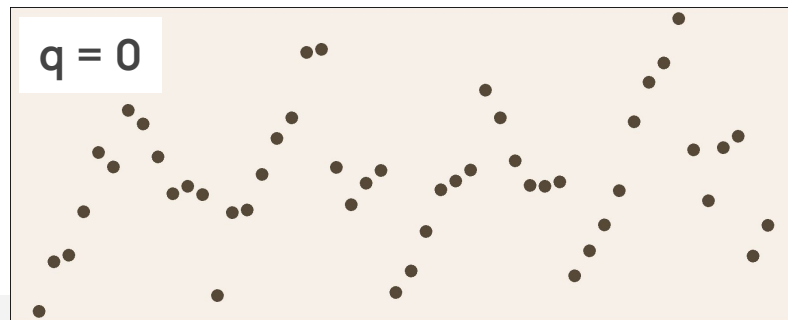
Too small: Not smooth enough.

Extreme: If $q = 0$ you're doing nothing

Too big: smooth but lose apparent evolution of trend over time

Extreme: If $q \geq N$, you're just taking the mean at all t (flattening effect!)

Just right: smallest q capable of smoothing significant trends



Exponential Smoothing: Derivation (room to write here)

Exponential Smoothing: Derivation

Let $\alpha \in [0, 1]$. Then

$$\hat{m}_1 = x_1, \quad \text{For } t \geq 2, \quad \hat{m}_t = \alpha x_t + (1-\alpha)\hat{m}_{t-1}$$

Note that

$$\hat{m}_t = \alpha x_t + (1-\alpha)\hat{m}_{t-1}$$

$$= \alpha x_t + (1-\alpha)(\alpha x_{t-1} + (1-\alpha)\hat{m}_{t-2})$$

$$= \alpha x_t + \alpha(1-\alpha)x_{t-1} + (1-\alpha)^2\hat{m}_{t-2}$$

\vdots

$$= \alpha x_t + \alpha(1-\alpha)x_{t-1} + \alpha(1-\alpha)^2x_{t-2} + \dots + \alpha(1-\alpha)^{t-2}x_2 + (1-\alpha)^{t-1}x_1$$

$$= \sum_{j=0}^{t-2} \alpha(1-\alpha)^j x_{t-j} + (1-\alpha)^{t-1}x_1$$

\uparrow
this is
 \hat{m}_1

Exponential Smoothing: Discussion

The weights $\alpha(1 - \alpha)^j$ decrease exponentially as j increases ie) as we go further into the past

In the case $\alpha = 0$, we have $\hat{m}_t = \hat{m}_1 = x_1 \quad \forall t$
→ you never take current value into account

In the case $\alpha = 1$, we have $\hat{m}_t = x_t$...so nothing happened

Note \hat{m}_t is computed only from the past relative to t
→ this smoother is one-sided
→ it behaves in the spirit of forecasting