

Autocovariance Functions (ACVFs)

& Autocorrelation Functions (ACFs)

STAT 464 / 864 | Fall 2024
Discrete Time Series Analysis
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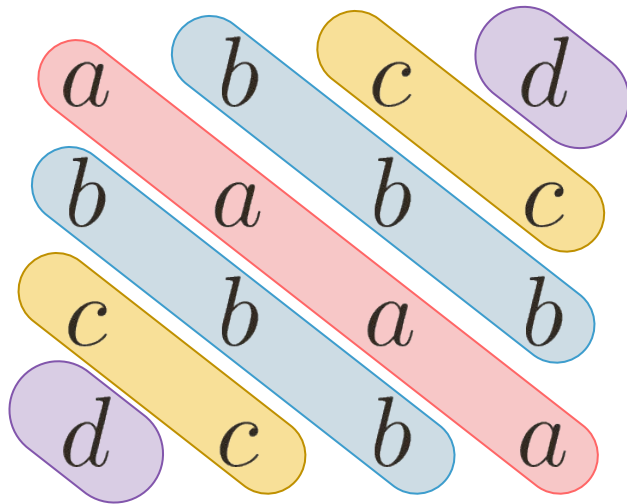
Covariance Matrices of Stationary Processes

The covariance matrix Γ_N
of a **stationary** time series is **Toeplitz**

Toeplitz: Identical entries along diagonals

There are only **N** distinct values in Γ_N

We can capture all info about Γ_N
in one **N**-length vector (or... function?)



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Autocovariance Functions | ACVFs

Covariance Kernel: $\gamma_X(t, t+h) \stackrel{\text{def}}{=} \text{Cov}(X_t, X_{t+h}) \quad t \in T, h \in \mathbb{Z}$

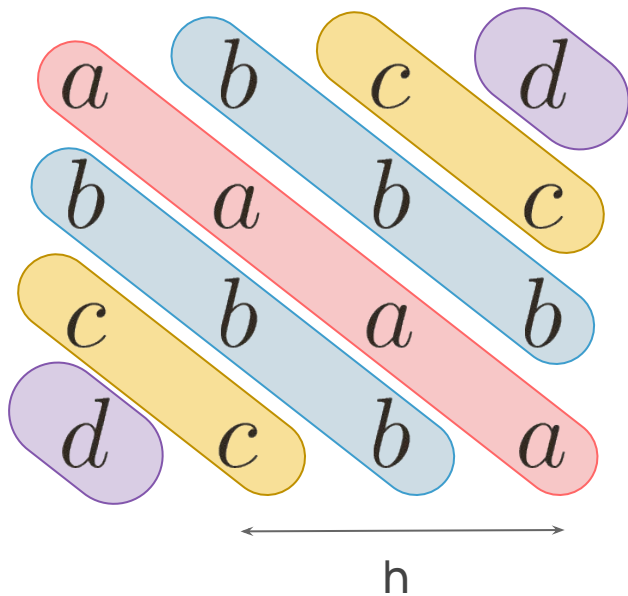
$$= \text{Cov}(X_s, X_{s+h}) \quad \forall s \in T$$

The time difference h is called “lag”

Autocovariance Function:

$$\gamma_X(h) \stackrel{\text{def}}{=} \text{Cov}(X_t, X_{t+h}) \quad t \in T, h \in \mathbb{Z}$$

$$\gamma_X(0, h)$$



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ACVFs and Stationarity

To show X_t is stationary:

- 1) Show that $E[X_t]$ is time independent
- 2) Show that $\text{Cov}(X_t, X_{t+h})$ is time independent

This will show up in your assignments and stuff. A lot.

If I ask you to find the ACVF of X_t , you can assume X_t is stationary

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Autocorrelation Functions (ACFs)

Denoted $\rho_X(h)$, or just $\rho(h)$

ACVFs are easy to standardize!

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Properties of ACVFs and ACFs

- 1) $\gamma_X(0)$ is the variance $\text{Var}(X_t) \quad \forall t \in T$ (independent of t)
- 2) γ_X is an even function. So is ρ_X , by extension.

$$\gamma_X(-h) = \text{Cov}(X_t, X_{t-h})$$

$$= \text{Cov}(X_{t-h}, X_t)$$

$$= \text{Cov}(X_t, X_{t+h}) = \gamma_X(h)$$

$$\text{3) } \rho_X(0) = 1. \text{ Always.}$$

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Example: White Noise

Definition:

A time series $\{X_t\}$ is called **white noise** if

- 1) It's weakly stationary (assume mean = 0, WLOG)
- 2) All X_t are pairwise uncorrelated: $\rho_X(h) = 0 \quad \forall h \neq 0$

If the mean is μ and the variance is σ^2 , we write: $X_t \sim \text{wn}(\mu, \sigma^2)$

i.i.d. Time Series $\begin{matrix} \Rightarrow \\ \Leftarrow \end{matrix}$ White noise

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