Brockwell & Davis | Section 1.3.3 | General approach to time series modelling

Modeling Xt is like dissecting a pen.

$$X_t = \boxed{m_t} + \boxed{s_t} + \boxed{Y_t}$$

 (\star)

Remove the frame giving it its shape

$$X_t - \hat{m}_t = s_t + Y_t$$

Polynomial regression MA smoothing **Exponential** smoothing

Take off the **spring** pushing **back & forth**

$$X_t - \hat{m}_t - \hat{s}_t = Y_t$$

Harmonic regression Season (S1) method

Examine the tube of **residual** ink

$$X_t - \hat{m}_t - \hat{s}_t = \hat{Y}_t$$

 $X_t - |\hat{m}_t| = |\hat{s}_t| + |\hat{Y}_t|$

WN Hypothesis test Autocorrelation Function

= unknown = estimated

Put the **body** of the pen back on

Put the **spring** back on the tube

 $X_t = |\hat{m}_t| + |\hat{s}_t| + |\hat{Y}_t|$

Unit 1 Finale

Classical Time Series Modelling

STAT 464 / 864 Fall 2024
Discrete Time Series Analysis
Skyepaphora Griffith, Queen's University

We learned something last time, in Time Series 🕛





ACVF of a classical-decomposition (*) time series is the same as the ACVF of its noise

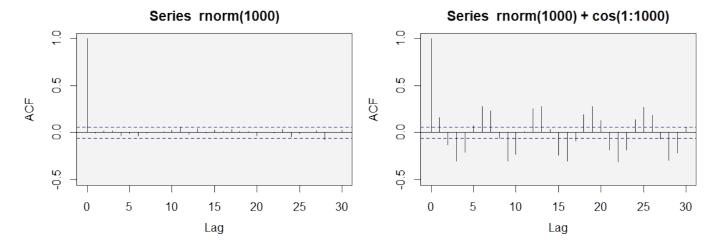
Not true for sample ACVFs

Theoretically, trend/seasonality don't affect ACVF In practice, they can influence the sample ACVF

How to test if a time series is white noise! If ACF doesn't look enough like the indicator fn: 1(h=0) Then reject the hypothesis that Xt ~ wn

What did we tell quin?

ACFs in R



- igoplus Function acf () plots 2 horizontal dashed blue lines at $~\pm 1.96/\sqrt{N}$
- $\hat{\rho}(h)$ that fall outside blue lines = evidence $\{X_t\}$ is not wn(0, σ^2)

Interpretation: If we compute $\hat{\rho}$ for white noise at m different lags, We expect $\hat{\rho}$ to fall outside the blue lines $m \times \alpha$ times

Something Skye forgot to say about ∇ !

We don't actually do anything on this page consider it a page for notes $\lceil (y) \rfloor / \lceil$

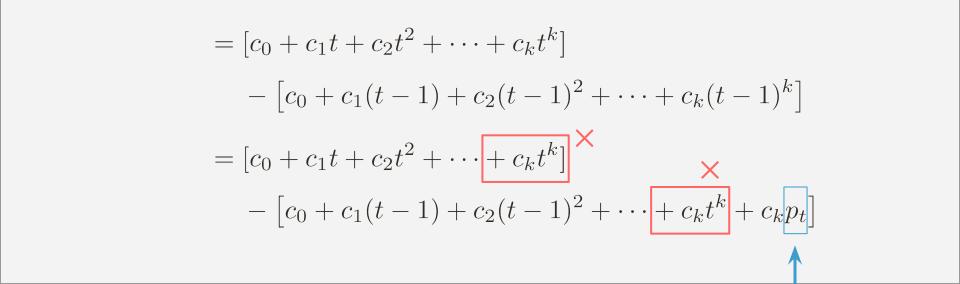
Applying ∇ to a polynomial

Output: Polynomial with reduced degree

Applying ∇ **to a polynomial**Output: Polynomial with reduced degree

 $\nabla m_t = m_t - m_{t-1}$

Consider the polynomial $m_t = c_0 + c_1 t + c_2 t^2 + \cdots + c_k t^k$



Something Skye forgot to say about ∇ !

 $m_t = c_0 + c_1 t + c_2 t^2 + \dots + c_k t^k$

- The polynomial **p**_t is of degree strictly less than **k**
- \bigcirc Input polynomial of degree $k \rightarrow$ output polynomial of smaller degree
- Applying ∇ k-many times will reduce a \mathbf{k}^{th} degree polynomial to a constant $\nabla^k m_t$ = some constant
- ∇^k will eliminate polynomial trends up to degree k







Linear Filters

Definition:

A linear filter is a sequence of coefficients $\{a_j\}_{j\in\mathbb{Z}}$

Satisfying
$$\sum_{j=-\infty}^{\infty} |a_j| < \infty$$
 (absolute summability)

Input process Y_t

Output process







Typical uses for Linear Filters

1) Shape desirable properties in the output Xt

Example:

a filter might pass/block select range of frequencies

low-pass / high-pass / band-pass

Another example:

2) Represent various time series models, themselves







Linear Filters we've seen

$$X_t = \sum_{j=-\infty}^{\infty} a_j Y_{t-j}$$

Difference operator

MA smoother with parameter q











End of Unit 1! (1) Classical Time Series Modelling



What do we tell quin?