

Linear Filters

Introduction

STAT 464 / 864 | Fall 2024

Discrete Time Series Analysis

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We learned something in Unit 1! 🕒



When you have a sequence of data taken over time, that's called a **Time Series**.

Over time, this kind of data might show a **trend**. We can estimate that trend by **fitting a polynomial**, or by **smoothing** out the noise to reveal a clearer shape.

The other thing we're interested in is **repetition**. We can model seasonal patterns by **fitting harmonic sinusoids**, or by examining the **average behaviour across cycles**.

What's left over should just be **residual noise**. We can **test** if the residual data is noisy enough by looking at its **self-similarities**, at different time-scales.

What do we tell quin?

Linear Filters

Definition: A linear filter is a sequence of coefficients $\{a_j\}_{j \in \mathbb{Z}}$

Satisfying $\sum_{j=-\infty}^{\infty} |a_j| < \infty$ (absolute summability)

Finite Filter: Finitely many nonzero filter coefficients (in practice, all filters are finite)

Input process Y_t

Output process

$$X_t = \sum_{j=-\infty}^{\infty} a_j Y_{t-j}$$

Convolution

Causality



Causality

The past is far behind us, the future doesn't exist.

Definition: A filter is called **causal** if $a_j = 0$ for $j < 0$

Its output $\{X_t\}$ is called a **causal process**

Depends only on past/present values of input $\{Y_t\}$



Linear
Filter

$$X_t = \sum_{j=-\infty}^{\infty} a_j Y_{t-j}$$

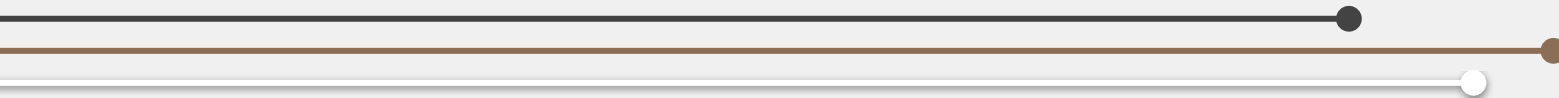
Linear Processes

Definition: If input $\{Y_t\}$ is $wn(\sigma^2)$ (Recall μ is zero, WLOG)
the output $\{X_t\}$ is called a **linear process**

Notes: We will be considering **time-invariant** filters

Assume input $\{Y_t\}$ is **stationary** and **zero-mean**

Proposition 2.2.1



Proposition 2.2.1 | Statement

$\{\psi_j\}$: Linear filter

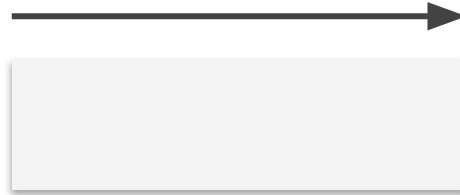
$\{Y_t\}$: Input

⌚ Stationary

⌚ Zero-mean

⌚ ACVF: $\gamma_Y(h)$

~ ConVoLuTioN ~



$\{X_t\}$: Output

⌚ Stationary ↙ ↘ ↗ ↘

⌚ Zero-mean

⌚ ACVF $\gamma_X(h)$

If input $\{Y_t\}$ is $\text{wn}(\sigma^2)$,

then $\gamma_X(h)$ reduces to

Proposition 2.2.1



Proof $E[X_t] = 0$

Stationarity 1) time-invariant mean

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We can bring the E inside the sum
because the sum (highlighted)
is finite with probability 1

Proposition 2.2.1



Deriving $\gamma_X(h)$



Stationarity 2)

finite variance



Stationarity 3)

time-invariant ACVF

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Covariance independent of t

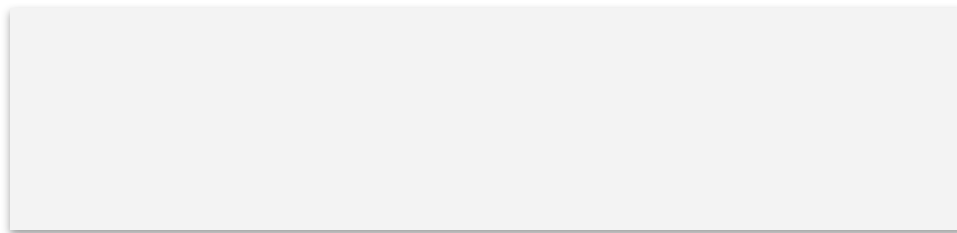


Y_t is stationary $\rightarrow \gamma_Y(h)$ finite for all $h \rightarrow$ Variance $\gamma_X(0)$ is finite

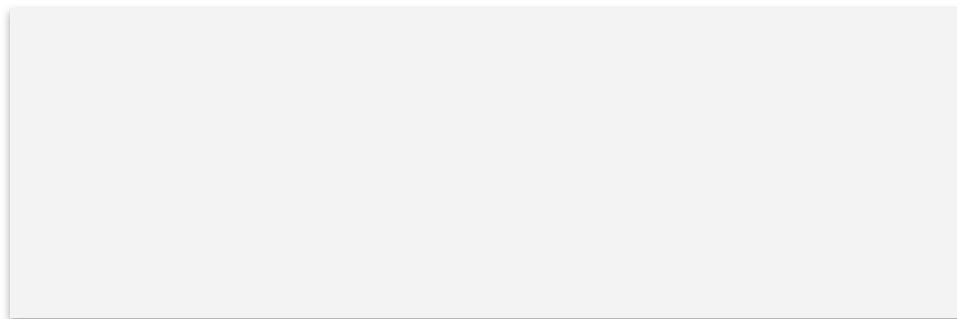
Absolute summability \nearrow

Proposition 2.2.1 | Linear Processes

If the input $\{Y_t\}$ is a $wn(\sigma^2)$ process,



For each j :



Therefore:

We learned something Today, in Time Series 🕒



What do we tell quin?