The Linear Prediction Operator

Properties + Minimum MSE

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Discrete Time Series Analysis
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Minimizing the MSE:

$$E\left[\left(Y - \left(a_0 + \overbrace{a_1 W_N + \dots + a_N W_1}\right)\right)^2\right]$$

Differentiate with respect to coefficient $\mathbf{a}_i \to \text{set}$ equal to $0 \to \text{solve}$ for coefficient

We found
$$a_0 = \mu_Y - a^T \mu_W$$

Plug that in, and we find that \mathbf{a} , the vector of remaining coefficients, solves $\Gamma a = \gamma$

$$\gamma = \operatorname{Cov}(Y, W)$$

$$= (\operatorname{Cov}(Y, W_N), \dots, \operatorname{Cov}(Y, W_1))$$

$$\Gamma[i, j] = \operatorname{Cov}(W_{N+1-i}W_{N+1-j})$$

Linear Prediction: best linear predictor of Y, based on W, that minimizes MSE

$$P(Y|W) = \mu_Y - a^T \mu_W + a^T W = \mu_Y + a^T (W - \mu_W)$$

Note: this result is theoretical. Values highlighted in blue must be estimated, in practice.

Minimum MSE

We know our predictor minimized it, but what is it, anyway?

$$MSE = E[(Y - P(Y|W))^{2}]$$

$$= E[(Y - (\mu_{Y} + a^{T}(W - \mu_{W})))^{2}] = E[((Y - \mu_{Y}) - a^{T}(W - \mu_{W}))^{2}]$$

$$= E[(Y - \mu_{Y})^{2} - 2(Y - \mu_{y})a^{T}(W - \mu_{W}) + a^{T}(W - \mu_{W})(W - \mu_{W})^{T}a]$$

$$= E[(Y - \mu_{Y})^{2}] - 2a^{T}E[(Y - \mu_{y})(W - \mu_{W})] + a^{T}E[(W - \mu_{W})(W - \mu_{W})^{T}]a$$

$$= Var(Y) - 2a^{T}\gamma + a^{T}\Gamma a = Var(Y) - 2a^{T}\gamma + a^{T}\gamma = Var(Y) - a^{T}\gamma$$

Properties of P(| W)

Overview

$$P(c_0 + c_1 U + c_2 V | W) = c_0 + c_1 P(U|W) + c_2 P(V|W)$$

$$P(Y|W) = E[Y]$$

$$\operatorname{Cov}(W_i, Y - P(Y|W)) = 0,$$

$$i = 1, \dots, N$$

$$P(W_i|W) = W_i$$

P1) Linearity

$$P(c_0 + c_1 U + c_2 V | W) = c_0 + c_1 P(U|W) + c_2 P(V|W)$$

$$= E[c_0 + c_1 U + c_2 V] + a^T (W - \mu_W)$$

$$= E[c_0] + c_1 E[U] + c_2 E[V] + a^T (W - \mu_W)$$

a satisfies
$$\Gamma a = \gamma$$

 Γ is the covariance matrix of W,

$$\gamma$$
 is the vector of covariances:

$$\gamma = \text{Cov}(c_0 + c_1 U + c_2 V, W)$$
$$= c_1 \text{Cov}(U, W) + c_2 \text{Cov}(V, W)$$
$$= c_1 \gamma_U + c_2 \gamma_V$$

RHS

P1) Linearity

$$P(c_0 + c_1 U + c_2 V | W) = c_0 + c_1 P(U|W) + c_2 P(V|W)$$

$$c_0 + c_1 \left(\mathbf{E}[U] + a_1^T (W - \mu_W) \right) + c_2 \left(\mathbf{E}[V] + a_2^T (W - \mu_W) \right)$$

$$= c_0 + c_1 \mathbf{E}[U] + c_2 \mathbf{E}[V] + c_1 a_1^T (W - \mu_W) + c_2 a_2^T (W - \mu_W)$$

$$= c_0 + c_1 \mathbf{E}[U] + c_2 \mathbf{E}[V] + \left(c_1 a_1^T + c_2 a_2^T \right) (W - \mu_W)$$

$$\square$$
LHS = $\mathbf{E}[c_0] + c_1 \mathbf{E}[U] + c_2 \mathbf{E}[V] + a^T (W - \mu_W)$

$$a_1$$
 satisfies $\Gamma a_1 = \gamma_U$

 a_2 satisfies $\Gamma a_2 = \gamma_V$

$$\Gamma(c_1 a_1 + c_2 a_2) = \gamma = c_1 \gamma_U + c_2 \gamma_V$$

P1) Uncorrelated Y and W

Recall: the best linear predictor is

$$\mu_Y + a^T (W - \mu_W)$$
$$\Gamma a = \gamma$$

If Y is uncorrelated with predictors W_i for all i, then $\gamma=0$

The solution is
$$a = 0$$
 $\Longrightarrow P(Y|W) = \mu_Y$

P3) Uncorrelated Predictors and Residuals

Residuals

Mean of Residuals

$$Y - P(Y|W) = Y - \mu_Y - a^T(W - \mu_W)$$

$$E[Y - P(Y|W)] = \mu_Y - \mu_Y - a^T(\mu_W - \mu_W) = 0$$

Cov[Residuals, Predictor i]

$$Cov(Y - P(Y|W), W_i) = E[(Y - \mu_Y - a^T(W - \mu_W))W_i]$$

This was set equal to 0 when we optimized the MSE of our LP

P4) the best LP of a predictor is itself

$$P(W_{N+1-i}|W) = E[W_{N+1-i}] + \underline{a}^{T}(W - \mu_{W})$$

$$= E[W_{N+1-i}] + (W_{N+1-i} - E[W_{N+1-i}])$$

$$= W_{N+1-i}$$

$$\Gamma[\cdot,i] = \left(\operatorname{Cov}(W_{N+1-i},W_N),\ldots,\operatorname{Cov}(W_{N+1-i},W_1)\right)^T$$

$$= \gamma \qquad \qquad \text{ith component}$$

$$\underline{a} = (0,\ldots,0,1,0,\ldots,0)^T$$