

Time allowed: 1.5 hours

Max. Marks: 30

Note: All questions are compulsory.

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| a) The coordinates of four control points relative to a current WCS are given by $P_0(5, 5)$, $P_1(5, 6)$, $P_2(6, 6)$, $P_3(6, 5)$. Find the equation of the resulting Bezier curve. Also find points on curve for $u = 0, 0.25, 0.35, 0.5, 0.65, 0.75, 1$. Plot the curve and display control points also. Find slope of the Bezier curve at the mid of the curve. | (8) |
| b) A 2 degree B-Spline curve has 6 control points. Find the continuity and no. of segments of the curve. | (2) |
| c) An object with vertices A (1, 1), B (3, 3), C (5, 1) and D (3, 5) is rotated about A by 90° counterclockwise direction followed by reflection about $x=y$ line. Find and plot the intermediate and final position of the object. Use Homogeneous transformations. | (7) |
| d) What is the difference between 2d, 2.5d and 3d models? Write the advantages and disadvantages of wireframe modeling. | (3) |
| a) Why parametric equations are required. Describe parametric and nonparametric equations of line, circle and ellipse. | (4) |
| b) Explain 2d homogeneous shear transformations by taking suitable example. | (3) |
| c) Describe and two examples of fixed automation. What are the advantage and disadvantages of fixed automation? | (2) |