## **HW2 - Extra problem 2: Euler Equations**

## **Generate initial conditions**

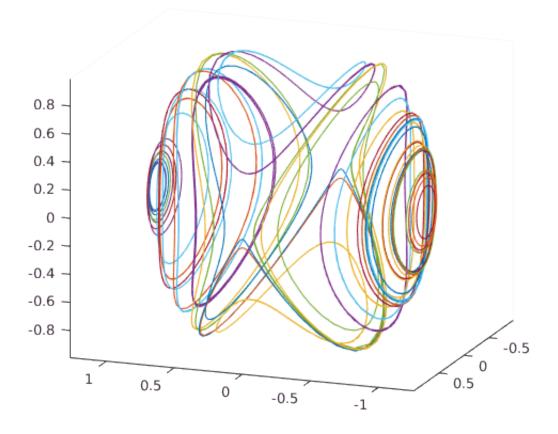
```
I1 = 3;
I2 = 2;
I3 = 1;

N = 50;
w_rand = randn(3,N);
w0 = zeros(3,N);
for i=1:N
    hg = w_rand(:,i).*[I1, I2, I3]';
    w0(:,i) = hg/norm(hg);
end
```

## Generate and plot trajectories

```
tspan = [0 40];

clf;
figure(1)
hold on
for i=1:N
    [t,y] = ode45(@euler_ode,tspan,w0(:,i));
    plot3(y(:,1), y(:,2), y(:,3));
end
axis equal
axis vis3d
view(-160, 15)
```



## **Define ODE**

```
function [yout] = euler_ode(t, yin)
    I1 = 3;
    I2 = 2;
    I3 = 1;

a = (I2 - I3)/I1;
b = (I3 - I1)/I2;
c = (I1 - I2)/I3;

w1 = yin(1);
w2 = yin(2);
w3 = yin(3);
w1dot = a*w2*w3;
w2dot = b*w1*w3;
w2dot = b*w1*w3;
w3dot = c*w1*w2;

yout = [w1dot; w2dot; w3dot];
end
```