ENGR-301L: Digital Signal Processing and Applications Trinity College, Instructor: Professor T. Ning

Laboratory #7: Linear Phase FIR Filter Design Using Window Functions

Lab Description: Finite Impulse Response (FIR) filters are popular in a wide variety of applications due to its design simplicity, ease of implementation, and, most of all, effective performance. In FIR filter design, a set of finite number of filter coefficients (also commonly known as taps) $\{h(n); n = 0, 1...N\}$ is used. Some performance issues are taken into account in FIR filters design to assure effectiveness.

- 1. The abrupt discontinuity of the finite number of filter coefficients causes an undesirable effect in the frequency response of FIR filters, known as the *Gibbs* phenomenon. To alleviate this problem, a tapering function $\{w(n)\}$ such as Hamming, Hanning, or Bartlett function is often multiplied to the ideal filter coefficients $\{h_d(n)\}$, i.e., $\{h(n) = h_d(n) \ w(n)\}$, to allow a smooth transition to zero.
- 2. It is important in some applications that the phase information of the source signal is to be maintained after filtering. To achieve that, linear-phase FIR filters are designed to generate a phase response that is linearly proportional to the frequency with a ratio/slope of (N-1)/2. Linear-phase FIR filters impose a constraint that filter coefficients are symmetric around the center coefficient, namely h(n) = h(N-1-n).

Objective:

- Become familiar with linear-phase FIR filter design
- Generate FIR filter design specifications according to application requirements
- Understand window function effects on main-lobe width, side-lobe attenuation, and transition bandwidth

Linear Phase FIR Filter Design Procedure:

1. Determine the ideal linear phase FIR filter specification $H_d(e^{j\omega})$. Note that the half of the sampling frequency (F_{samp} / 2) in Hertz corresponds to π (radians) and the ideal filter frequency response within the passband is given by (1) and zero elsewhere.

$$H_d(e^{j\omega}) = e^{-\frac{j\omega(N-1)}{2}} \quad \omega_{p1} \le \omega \le \omega_{p2} \tag{1}$$

2. Derive the ideal impulse responses (filter coefficients) $\{h_d(n)\}$.

$$h_d(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(e^{j\omega}) e^{j\omega n} d\omega$$
 (2)

3. Choose a tapering window function $\{w(n)\}\$ to realize the actual FIR filter coefficients

$$h(n) = h_d(n)w(n) \quad n = 0,1,...(N-1)$$
 (3)

4. Perform FIR filtering using liner convolution: y(n) = x(n) *h(n)

Specific Goals:

You will evaluate the performance of FIR filter design through a test signal *Sig3.xlsx*, saved in Excel workbook format. You are required to design and implement three different types of linear-phase FIR filters to perform the following tasks:

 design and implement a *low-pass* linear-phase FIR filter to retain the lowest frequency component in Sig3.xlsx

- design and implement a high-pass linear-phase FIR filter to retain the highest frequency component in Sig3.xlsx
- design and implement a band-pass linear-phase FIR filter to retain the middle frequency component in Sig3.xlsx

To retrieve data from an excel spreadsheet, you can use the Matlab command below:

[xdata, xname] = xlsread('Sig3.xlsx');

Where *xdata* contains the two column data and *xname* contains the first row text information. The sampling frequency can be deducted from the sampling time instants. *Note: Excel 97-2003 workbook files use a different extension, i.e., '. xls'*.

- 1. Generate a 2x1 plot with the data on top and the power spectrum on the bottom.
- 2. Generate a 3x1 plot including h(n), $|H(e^{j\omega})|$, and $Phase(H(e^{j\omega}))$; generate a 2x1 plot having y(n), and $|Y(e^{j\omega})|$ to confirm your design for each type of filter described above.

Discuss the performance of the system response $|H(e^{i\omega})|$ with regard to:

- tapering function type Rectangular (no tapering), Triangular (Bartlett), Hamming, and Hanning window
- number of FIR filter taps (N)
- phase response of the filter

Evaluate the effectiveness of filtering through power spectrum estimation (using dB scale), e.g., if the undesired signals are sufficiently attenuated as design.