

↑ FRO started total internal reflection

Question 18

Not yet  
answered

Flag question

In FTIR fingerprint sensors, what is the component converting the light into an electric charge?

Select one:

- ☐ Imaging polarizer
- ☒ Array of photodiodes or phototransistors
- ☐ Light Emitting Diode (LED)
- ☐ Sheet prism
- ☐ Fiber optic Plate (FOP)

✓

Question **19**

Not yet  
answered

Flag question

Which of the following technologies or aspects are **not** included in the ISO/IEC JTC1 SC37.

Select one:

- ☐ Finger minutiae data format
- ☐ Face Image Data format
- ☐ Vascular Biometric Image Data
- ☒ Walking Pattern Sequence Data



Question 20

Not yet  
answered

Flag question

Given a generic face recognition system, select the **correctly ordered** sequence of processing steps.

Select one:

- ☐ Localization, alignment and normalization, feature extraction, processing, comparison.
- ☒ Localization, alignment and normalization, processing, feature extraction, comparison.
- ☐ Processing, localization, alignment and normalization, feature extraction, comparison.
- ☐ Alignment and normalization, localization, processing, feature extraction, comparison.
- ☐ Localization, alignment and normalization, feature extraction, processing, comparison.



- Localization
- Alignment + normalization
- processing → (eg: done prior illumination etc..)
- Extra facial
- comparison

Question 21

Not yet  
answered

Flag question

In CMOS imaging sensors based on a single chip color filter, the micro-lenses are localized:

Select one:

- ☐ Between the metal connections and the photo-sensitive Si area
- ☐ Outside the Si-chip
- ☒ Above the gate oxide of the MOS capacitor
- ☐ Just above the color filter layer
- ☐ At several depths inside the Si-chip, depending on the wavelength to be measured

?) = ring 407

i✓

Question 22

Not yet  
answered

Flag question

Select the **wrong** statement concerning Level 2 features for fingerprint matching.

Select one:

- ☐ They are computed on a ridge skeleton image.
- ☒ They are characterized by location, orientation and type.
- ☐ They identify points where ridges emerge, split, end or intersect.
- ☐ They require 500 dpi resolution to identify inner holes.

← gli parla  
di orientazione



Question 23

Not yet  
answered

Flag question

In verification biometric systems, the false rejection (or false non-match) event occurs when:

Select one:

- ☒ The user claims his real identity, but the user is not enrolled in the system
- ☐ The user is an impostor (not enrolled), he claims a fake identity, and the system find a match between the acquired features and the saved template
- ☐ The user is enrolled, he claims his real identity, and the system find a match between the acquired features and the saved template
- ☒ The user is enrolled, he claims his real identity, and the system does not find a match between the acquired features and the saved template



Question 24

Not yet  
answered

Flag question

The sensitive pixel array of fingerprint MEMS sensors contains:

Select one:

- ☐ A metal grounded ring
- ☐ Micro-antennas
- ☐ Single-plate capacitors
- ☒ Double-electrode capacitors
- ☐ Pyroelectric sensitive devices

→ 2 capacitors

OK, 99

✓  
~  
✓ ok.

Question 25

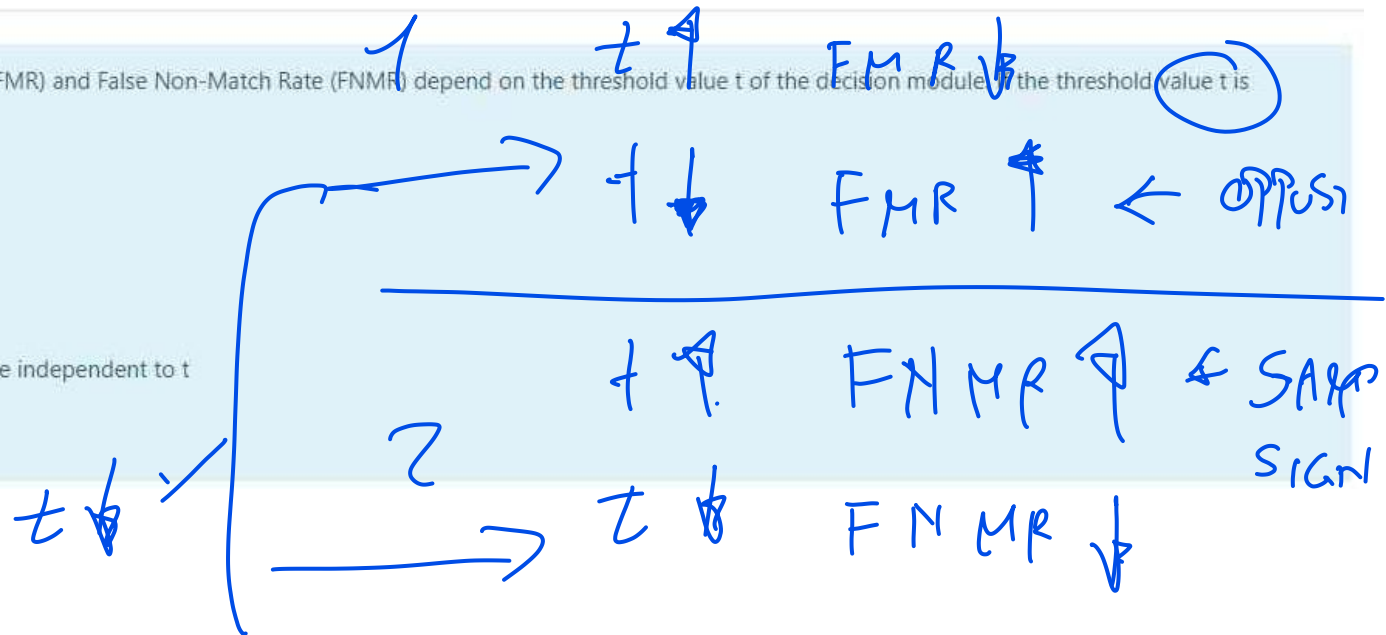
Not yet answered

Flag question

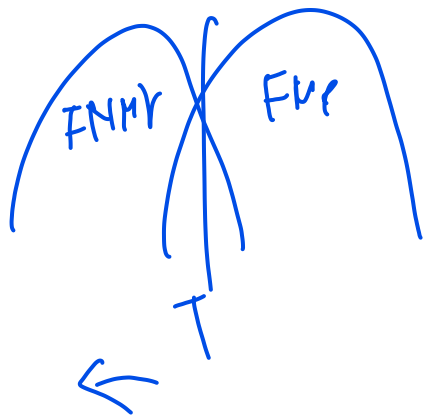
In verification biometric systems, the False Match Rate (FMR) and False Non-Match Rate (FNMR) depend on the threshold value  $t$  of the decision module. If the threshold value  $t$  is decreased:

Select one:

- ☒ The FMR increases and the FNMR decreases
- ☐ Both FMR and FNMR decrease
- ☐ The FMR decreases and the FNMR increases
- ☐ None of the answer is correct, as FMR and FNMR are independent to  $t$
- ☐ Both FMR and FNMR increase



OK  
100%





Question 26

Not yet  
answered

Flag question

The interface module integrated into a fingerprint scanner is responsible for:

Select one:

- ☒ The communication of the scanner with external electronics
- ☐ The mechanical and chemical protection of the sensor
- ☐ The matching or non-matching decision
- ☐ Acquiring the fingerprint pattern
- ☐ Converting the analog signal generated by the sensor to digital signal

✓ OK

Question 27

Not yet  
answered

Flag question

Which fingerprint scanner uses a CCD or CMOS camera to acquire the fingerprint pattern?

Select one:

- ☒ Frustrated Total Internal Reflection scanners
- ☐ Piezoelectric scanners
- ☐ Thermal scanners
- ☐ None of the answers is correct
- ☐ MEMS scanners

→ I know from s/me!

✓

Question 28

Not yet  
answered

Flag question

Which of the following types of minutiae are considered by the ANSI/NIST-ITL 1, 2007 standard.

Select one:

- ☐ Ending, bifurcation, spur, island
- ☐ Ending, bifurcation, lake, undefined.
- ☒ Ending, bifurcation, compound, undefined.
- ☐ Ending, trifurcation, compound, undefined.
- ☐ Ending, bifurcation, spur, undefined.

✓ o/L

Question 29

Not yet  
answered

Flag question

In digital cameras, one or a series of lenses may cause chromatic aberration effects in the final acquired image due to:

Select one:

- ☐ None of the answers is correct
- ☐ The use of an achromatic doublet
- ☐ Atomic defects in the lenses
- ☒ Geometrical deformations on lens surfaces

✓ --

Question 30

Not yet  
answered

Flag question

In relation to the Kazemi-Sullivan algorithm, select the **wrong** statement among the following:

Select one:

- ☐ It is based on cascade regressors.
- ☐ It employs a gradient boosting algorithm.
- ☒ Split decisions are made on the same pixel set.
- ☐ Landmarks are warped in order to make pixel intensities match.

Question 31

Not yet answered

Flag question

Given the Pointcaré index equation

$$PI = \frac{1}{\pi} \sum_{i=0}^7 \delta(O[(i+1) \bmod 8] - O[i])$$

select the **correct** statement among the following:

Select one:

☐

PI=-1 corresponds to a loop point.

☐

The function  $\delta$  outputs values from 0 to  $\pi$ .

☐

The function PI is computed from the orientation of 9 neighbors.

☐

PI is computed from the sum of the orientations.

☒

PI for whorl is a combination of two PI loops.

$$-1 = \text{whorl}$$

$$-\frac{\pi}{2} \leq \frac{\pi}{2}$$

$$\rightarrow \times \delta$$



Question 32

Not yet answered

Flag question

Considering the equation

$$\arg \max_W \frac{W^T W_{PCA}^T A B W_{PCA} W}{W^T W_{PCA}^T A W W_{PCA} W}$$

select among the following sentences the **wrong** one.

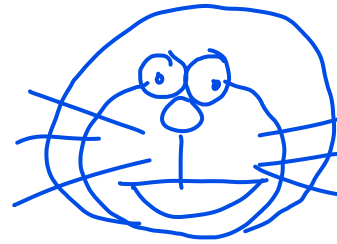
Select one:

- ☐ The equation computes a Fisherface matrix for face identification.
- ☐  $W$  allows to compute a set of global features for face identification.
- ☐  $W_{PCA}$  define a basis change to represent data.
- ☒ The equation is used in Elastic Bunch Graph Matching for face identification.

PCA } are  
LDA, global

?

this  
is for local



Question 33

Not yet  
answered

Flag question

Pixels of cameras working at Near-InfraRed (NIR) range are commonly built in:

Select one:

- ☐ Si, as Si energy gap is higher than the NIR photons
- ☐ InGaAs, as InGaAs energy gap is higher than the NIR photons
- ☐ InGaAs, as InGaAs energy gap is lower than the NIR photons
- ☒ Si, as Si energy gap is lower than the NIR photons



Question 34

Not yet  
answered

Flag question

Considering the Mel-Cepstrum features, select the **wrong** statement among the following.

Select one:

- ☐ Histogram-based normalization can be used to increase the accuracy.
- ☒ Usually, 39 coefficient related features are used.
- ☐ They can be configured to capture middle-term variations.
- ☐ The first 12-13 DCT coefficients are used with their first and second derivatives.

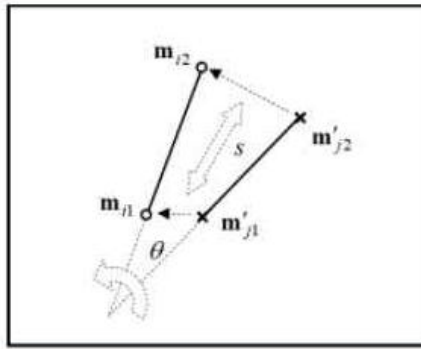
✓ +

Question 35

Not yet  
answered

Flag question

Considering the scaling factor computation in a refinement of fingerprint alignment (described by the parameter  $s$  in the following image)



Select the **wrong** statement among the following ones.

Select one:

- ☐ Minutiae  $m_{i1}, m_{j1}$  belong to the same fingerprint.
- ☐ The parameter  $s$  corresponds to the ratio between the length of  $m_{i1}, m_{i2}$  and the length  $m_{j1}, m_{j2}$ .
- ☐ An iterative optimization can be applied.
- ☒ Parameter  $s$  is computed after computing maximum Matching Pair Support.
- ☐ The final set of parameters is  $\Delta x, \Delta y, \theta, s$ .



Question 36

Not yet  
answered

Flag question

In active appearance model (AAM), the coordinates of a fiducial point  $\mathbf{p}_j$  can be expressed as

$$\mathbf{p}_j = \mathbf{p}_\mu + E_s \omega_{s,j}.$$

Select the **wrong** statement among the following:

Select one:

- ☐  $\omega_{s,j}$  is obtained from a minimization routine.
- ☐ Texture variations are modelled by a similar warping equation.
- ☐  $E_s$  is optimized from a PCA decomposition.
- ☒  $\omega_{s,j}$  is computed separately from the texture warping coefficients  $\omega_{g,j}$ .

Question 37

Not yet  
answered

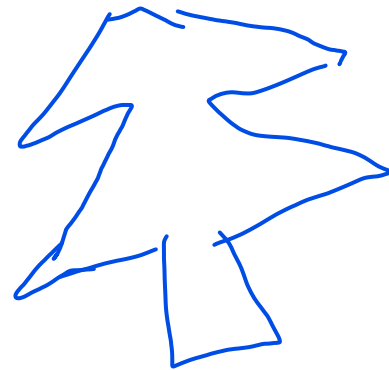
Flag question

Passive thermal fingerprint scanners based on pyroelectric pixels acquire the fingerprint pattern:

Select one:

- ☒ By applying a low-power heat pulse, which generates an higher heat variation at valleys than at ridges
- ☐ By applying a low-power heat sinusoid, which generates an higher heat variation at valleys than at ridges
- ☐ By applying a low-power heat pulse, which generates an higher heat variation at ridges than at valleys
- ☐ By measuring the increase of temperature induced by the body temperature on pixels in contact with ridges

OK +



Question 38

Not yet  
answered

Flag question

Considering the thinning operation, select the **wrong** answer among the following:

Select one:

- ☐ It is based on a Hit-and-Miss transform. ✓
- ☒ A structuring element can be applied only. ✗
- ☐ The output pixel values depends on whether pixels of the image and pixels of the structuring element match. ✓
- ☐ It operates on a bilevel image. ✓

Question 39

Not yet  
answered

Flag question

In CCTV video surveillance systems, box-style security cameras have the main advantage of:

Select one:

- ☐ Controlling the movement and the zoom by joystick or by software
- ☐ Dome shape housing, which is resistant to vandal attacks
- ☒ Customization of the focal length of lenses
- ☐ Night vision thanks to the pre-installed infra-red illuminators
- ☐ Small dimensions