

ALGORITHM 493

Zeros of a Real Polynomial [C2]

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Key Words and Phrases: roots, zeros of a polynomial

CR Categories: 5.15

Language: Fortran

DESCRIPTION

The subroutine RPOLY is a Fortran program to find all the zeros of a real polynomial. The parameters are:

OP	double precision vector of coefficients in order of decreasing powers of the variable
DEGREE	integer degree of the polynomial
ZEROR, ZEROI	double precision vectors of real and imaginary parts of the zeros found by the algorithm
FAIL	logical parameter which is true only if the leading coefficient is zero or if RPOLY has found fewer than degree zeros; in the latter case the degree is reset to the number of zeros found.

The routine as written solves polynomials of degree up to 100; however, this can be modified by systematic changing of the declarations in the routines.

The program is based on the three-stage algorithm described in Jenkins and Traub [1]. The algorithm generates a sequence of polynomials of degree one less than the degree of the given polynomial from which an approximation to a zero or a quadratic factor can be extracted. The first stage is linearly convergent and involves no shift of origin. It is used primarily to bias the decision making process in the second stage in favor of the zeros of small magnitude. The second stage is also linearly convergent and involves a double shift to a complex point and its conjugate. The shift point is chosen arbitrarily on a circle whose radius is less than the magnitude of all the zeros. In most cases, either the shift is closest to a real zero, or the pair of shift points are equidistant and closest to a pair of zeros. In the former case the second stage yields an approximation to the real zero and in the latter case

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it yields an approximation to the real quadratic factor. The third stage involves one of two variable-shift iterations, where the latest approximation(s) is used as the shift point(s) for the generation of the next polynomial. The choice of iteration is based on which case is observed in stage two. The convergence is superquadratic and usually requires only a few steps. The decision processes are made in a fail-safe manner. If the third stage is entered prematurely or the incorrect iteration is chosen, the second stage is resumed. If no convergence is observed in the second stage after a fixed number of steps, a new shift is chosen and the second stage is restarted with a higher fixed limit. The third-stage iterations are terminated when a stopping criterion based on roundoff error analysis has been satisfied. The real zero or quadratic factor is removed by polynomial deflation and the algorithm is repeated on the reduced polynomial.

The first statements of RPOLY set the following four constants which describe the floating-point arithmetic of the computer being used:

ETA	maximum relative representation error, which can be described as the smallest positive floating-point number such that $1 + \text{ETA} > 1$ in floating-point arithmetic
INFIN	large floating-point number near the top of the range
SMALNO	small positive floating-point number near zero
BASE	exponent base for the floating-point number system.

The program is written in a portable subset of standard Fortran. It has been successfully used on the Burroughs B6700 and the IBM 360/50.

The program has been tested on a large number of polynomials, some chosen to test weaknesses common to zerofinding routines, others randomly generated by a number of techniques.

REFERENCES

1. JENKINS, M.A., AND TRAUB, J.F. A three-stage algorithm for real polynomials using quadratic iteration. *SIAM J. Numer. Anal.* 7 (1970), 545-566.
2. JENKINS, M.A., AND TRAUB, J.F. Principles for testing polynomial zerofinding programs. *ACM TOMS* 1, 1 (March 1975), 26-34.

ALGORITHM

SUBROUTINE RPOLY(OP, DEGREE, ZEROR, ZEROI,	RPO	10
* FAIL)	RPO	20
C FINDS THE ZEROS OF A REAL POLYNOMIAL	RPO	30
C OP - DOUBLE PRECISION VECTOR OF COEFFICIENTS IN	RPO	40
C ORDER OF DECREASING POWERS.	RPO	50
C DEGREE - INTEGER DEGREE OF POLYNOMIAL.	RPO	60
C ZEROR, ZEROI - OUTPUT DOUBLE PRECISION VECTORS OF	RPO	70
C REAL AND IMAGINARY PARTS OF THE	RPO	80
C ZEROS.	RPO	90
C FAIL - OUTPUT LOGICAL PARAMETER, TRUE ONLY IF	RPO	100
C LEADING COEFFICIENT IS ZERO OR IF RPOLY	RPO	110
C HAS FOUND FEWER THAN DEGREE ZEROS.	RPO	120
C IN THE LATTER CASE DEGREE IS RESET TO	RPO	130
C THE NUMBER OF ZEROS FOUND.	RPO	140
C TO CHANGE THE SIZE OF POLYNOMIALS WHICH CAN BE	RPO	150
C SOLVED, RESET THE DIMENSIONS OF THE ARRAYS IN THE	RPO	160
C COMMON AREA AND IN THE FOLLOWING DECLARATIONS.	RPO	170
C THE SUBROUTINE USES SINGLE PRECISION CALCULATIONS	RPO	180
C FOR SCALING, BOUNDS AND ERROR CALCULATIONS. ALL	RPO	190

C CALCULATIONS FOR THE ITERATIONS ARE DONE IN DOUBLE PRECISION.	RPO 200
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,	RPO 210
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,	RPO 220
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN	RPO 230
DOUBLE PRECISION P(101), QP(101), K(101),	RPO 240
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,	RPO 250
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,	RPO 260
* LZR, LZI	RPO 270
REAL ETA, ARE, MRE	RPO 280
INTEGER N, NN	RPO 290
DOUBLE PRECISION OP(101), TEMP(101),	RPO 300
* ZEROR(100), ZEROI(100), T, AA, BB, CC, DABS,	RPO 310
* FACTOR	RPO 320
REAL PT(101), LO, MAX, MIN, XX, YY, COSR,	RPO 330
* SINR, XXX, X, SC, BND, XM, FF, DF, DX, INFIN,	RPO 340
* SMALNO, BASE	RPO 350
INTEGER DEGREE, CNT, NZ, I, J, JJ, NM1	RPO 360
LOGICAL FAIL, ZEROK	RPO 370
C THE FOLLOWING STATEMENTS SET MACHINE CONSTANTS USED	RPO 380
C IN VARIOUS PARTS OF THE PROGRAM. THE MEANING OF THE	RPO 390
C FOUR CONSTANTS ARE...	RPO 400
C ETA THE MAXIMUM RELATIVE REPRESENTATION ERROR	RPO 410
C WHICH CAN BE DESCRIBED AS THE SMALLEST	RPO 420
C POSITIVE FLOATING POINT NUMBER SUCH THAT	RPO 430
C 1.D0+ETA IS GREATER THAN 1.	RPO 440
C INFINY THE LARGEST FLOATING-POINT NUMBER.	RPO 450
C SMALNO THE SMALLEST POSITIVE FLOATING-POINT NUMBER	RPO 460
C IF THE EXPONENT RANGE DIFFERS IN SINGLE AND	RPO 470
C DOUBLE PRECISION THEN SMALNO AND INFIN	RPO 480
C SHOULD INDICATE THE SMALLER RANGE.	RPO 490
C BASE THE BASE OF THE FLOATING-POINT NUMBER	RPO 500
C SYSTEM USED.	RPO 510
C THE VALUES BELOW CORRESPOND TO THE BURROUGHS B6700	RPO 520
BASE = 8.	RPO 530
ETA = .5*BASE**(1-26)	RPO 540
INFIN = 4.3E68	RPO 550
SMALNO = 1.0E-45	RPO 560
C ARE AND MRE REFER TO THE UNIT ERROR IN + AND *	RPO 570
C RESPECTIVELY. THEY ARE ASSUMED TO BE THE SAME AS	RPO 580
C ETA.	RPO 590
ARE = ETA	RPO 600
MRE = ETA	RPO 610
LO = SMALNO/ETA	RPO 620
C INITIALIZATION OF CONSTANTS FOR SHIFT ROTATION	RPO 630
XX = .70710678	RPO 640
YY = -XX	RPO 650
COSR = -.069756474	RPO 660
SINR = .99756405	RPO 670
FAIL = .FALSE.	RPO 680
N = DEGREE	RPO 690
NN = N + 1	RPO 700
C ALGORITHM FAILS IF THE LEADING COEFFICIENT IS ZERO.	RPO 710
IF (OP(1).NE.0.D0) GO TO 10	RPO 720
FAIL = .TRUE.	RPO 730
DEGREE = 0	RPO 740
RETURN	RPO 750
C REMOVE THE ZEROS AT THE ORIGIN IF ANY	RPO 760
10 IF (OP(NN).NE.0.D0) GO TO 20	RPO 770
J = DEGREE - N + 1	RPO 780
ZEROR(J) = 0.D0	RPO 790
ZEROI(J) = 0.D0	RPO 800
NN = NN - 1	RPO 810
N = N - 1	RPO 820
GO TO 10	RPO 830
C MAKE A COPY OF THE COEFFICIENTS	RPO 840
20 DO 30 I=1,NN	RPO 850
P(I) = OP(I)	RPO 860
30 CONTINUE	RPO 870
C START THE ALGORITHM FOR ONE ZERO	RPO 880
40 IF (N.GT.2) GO TO 60	RPO 890
IF (N.LT.1) RETURN	RPO 900
C CALCULATE THE FINAL ZERO OR PAIR OF ZEROS	RPO 910
IF (N.EQ.2) GO TO 50	RPO 920
ZEROR(DEGREE) = -P(2)/P(1)	RPO 930
	RPO 940

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    ZEROI(DEGREE) = 0.0D0                                RPO 950
    RETURN                                                RPO 960
50 CALL QUAD(P(1), P(2), P(3), ZEROR(DEGREE-1),         RPO 970
    * ZEROI(DEGREE-1), ZEROR(DEGREE), ZEROI(DEGREE))    RPO 980
    RETURN                                                RPO 990
C FIND LARGEST AND SMALLEST MODULI OF COEFFICIENTS.      RPO 1000
60 MAX = 0.                                              RPO 1010
    MIN = INFIN                                          RPO 1020
    DO 70 I=1,NN                                         RPO 1030
        X = ABS(SNGL(P(I)))                             RPO 1040
        IF (X.GT.MAX) MAX = X                           RPO 1050
        IF (X.NE.0. .AND. X.LT.MIN) MIN = X             RPO 1060
    70 CONTINUE                                          RPO 1070
C SCALE IF THERE ARE LARGE OR VERY SMALL COEFFICIENTS   RPO 1080
C COMPUTES A SCALE FACTOR TO MULTIPLY THE               RPO 1090
C COEFFICIENTS OF THE POLYNOMIAL. THE SCALING IS DONE   RPO 1100
C TO AVOID OVERFLOW AND TO AVOID UNDETECTED UNDERFLOW  RPO 1110
C INTERFERING WITH THE CONVERGENCE CRITERION.           RPO 1120
C THE FACTOR IS A POWER OF THE BASE                     RPO 1130
    SC = LO/MIN                                          RPO 1140
    IF (SC.GT.1.0) GO TO 80                             RPO 1150
    IF (MAX.LT.10.) GO TO 110                           RPO 1160
    IF (SC.EQ.0.) SC = SMALNO                            RPO 1170
    GO TO 90                                              RPO 1180
    80 IF (INFIN/SC.LT.MAX) GO TO 110                   RPO 1190
    90 L = ALOG(SC)/ALOG(BASE) + .5                     RPO 1200
    FACTOR = (BASE*1.0D0)**L                             RPO 1210
    IF (FACTOR.EQ.1.0D0) GO TO 110                     RPO 1220
    DO 100 I=1,NN                                       RPO 1230
        P(I) = FACTOR*P(I)                             RPO 1240
    100 CONTINUE                                          RPO 1250
C COMPUTE LOWER BOUND ON MODULI OF ZEROS.               RPO 1260
110 DO 120 I=1,NN                                       RPO 1270
    PT(I) = ABS(SNGL(P(I)))                             RPO 1280
    120 CONTINUE                                          RPO 1290
    PT(NN) = -PT(NN)                                     RPO 1300
C COMPUTE UPPER ESTIMATE OF BOUND                       RPO 1310
    X = EXP((ALOG(-PT(NN))-ALOG(PT(1)))/FLOAT(N))        RPO 1320
    IF (PT(N).EQ.0.) GO TO 130                          RPO 1330
C IF NEWTON STEP AT THE ORIGIN IS BETTER, USE IT.       RPO 1340
    XM = -PT(NN)/PT(N)                                  RPO 1350
    IF (XM.LT.X) X = XM                                  RPO 1360
C CHOP THE INTERVAL (0,X) UNTIL FF .LE. 0              RPO 1370
130 XM = X*.1                                           RPO 1380
    FF = PT(1)                                           RPO 1390
    DO 140 I=2,NN                                       RPO 1400
        FF = FF*XM + PT(I)                             RPO 1410
    140 CONTINUE                                          RPO 1420
    IF (FF.LE.0.) GO TO 150                             RPO 1430
    X = XM                                                RPO 1440
    GO TO 130                                             RPO 1450
    150 DX = X                                           RPO 1460
C DO NEWTON ITERATION UNTIL X CONVERGES TO TWO          RPO 1470
C DECIMAL PLACES                                         RPO 1480
160 IF (ABS(DX/X).LE..005) GO TO 180                   RPO 1490
    FF = PT(1)                                           RPO 1500
    DF = FF                                              RPO 1510
    DO 170 I=2,N                                         RPO 1520
        FF = FF*X + PT(I)                             RPO 1530
        DF = DF*X + FF                                 RPO 1540
    170 CONTINUE                                          RPO 1550
    FF = FF*X + PT(NN)                                  RPO 1560
    DX = FF/DF                                           RPO 1570
    X = X - DX                                           RPO 1580
    GO TO 160                                             RPO 1590
    180 BND = X                                           RPO 1600
C COMPUTE THE DERIVATIVE AS THE INTIAL K POLYNOMIAL     RPO 1610
C AND DO 5 STEPS WITH NO SHIFT                          RPO 1620
    NM1 = N - 1                                          RPO 1630
    DO 190 I=2,N                                         RPO 1640
        K(I) = FLOAT(NN-I)*P(I)/FLOAT(N)              RPO 1650
    190 CONTINUE                                          RPO 1660
    K(1) = P(1)                                          RPO 1670
    AA = P(NN)                                           RPO 1680
    BB = P(N)                                             RPO 1690
    ZEROK = K(N).EQ.0.D0                                RPO 1700

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DO 230 JJ=1,5
  CC = K(N)
  IF (ZEROK) GO TO 210
C USE SCALED FORM OF RECURRENCE IF VALUE OF K AT 0 IS
C NONZERO
  T = -AA/CC
  DO 200 I=1,NM1
    J = NN - I
    K(J) = T*K(J-1) + P(J)
  200 CONTINUE
  K(1) = P(1)
  ZEROK = DABS(K(N)) .LE. DABS(BB)*ETA*10.
  GO TO 230
C USE UNSCALED FORM OF RECURRENCE
  210 DO 220 I=1,NM1
    J = NN - I
    K(J) = K(J-1)
  220 CONTINUE
  K(1) = 0.D0
  ZEROK = K(N) .EQ. 0.D0
  230 CONTINUE
C SAVE K FOR RESTARTS WITH NEW SHIFTS
  DO 240 I=1,N
    TEMP(I) = K(I)
  240 CONTINUE
C LOOP TO SELECT THE QUADRATIC CORRESPONDING TO EACH
C NEW SHIFT
  DO 280 CNT=1,20
    C QUADRATIC CORRESPONDS TO A DOUBLE SHIFT TO A
    C NON-REAL POINT AND ITS COMPLEX CONJUGATE. THE POINT
    C HAS MODULUS BND AND AMPLITUDE ROTATED BY 94 DEGREES
    C FROM THE PREVIOUS SHIFT
    XXX = COSR*XX - SINR*YY
    YY = SINR*XX + COSR*YY
    XX = XXX
    SR = BND*XX
    SI = BND*YY
    U = -2.0D0*SR
    V = BND
  C SECOND STAGE CALCULATION, FIXED QUADRATIC
    CALL FXSHFR(20*CNT, NZ)
    IF (NZ.EQ.0) GO TO 260
  C THE SECOND STAGE JUMPS DIRECTLY TO ONE OF THE THIRD
  C STAGE ITERATIONS AND RETURNS HERE IF SUCCESSFUL.
  C DEFLATE THE POLYNOMIAL, STORE THE ZERO OR ZEROS AND
  C RETURN TO THE MAIN ALGORITHM.
    J = DEGREE - N + 1
    ZEROR(J) = SZR
    ZEROI(J) = SZI
    NN = NN - NZ
    N = NN - 1
    DO 250 I=1,NN
      P(I) = QP(I)
    250 CONTINUE
    IF (NZ.EQ.1) GO TO 40
    ZEROR(J+1) = LZR
    ZEROI(J+1) = LZI
    GO TO 40
  C IF THE ITERATION IS UNSUCCESSFUL ANOTHER QUADRATIC
  C IS CHOSEN AFTER RESTORING K
  260 DO 270 I=1,N
    K(I) = TEMP(I)
  270 CONTINUE
  280 CONTINUE
C RETURN WITH FAILURE IF NO CONVERGENCE WITH 20
C SHIFTS
  FAIL = .TRUE.
  DEGREE = DEGREE - N
  RETURN
END

```

RPO 1710
RPO 1720
RPO 1730
RPO 1740
RPO 1750
RPO 1760
RPO 1770
RPO 1780
RPO 1790
RPO 1800
RPO 1810
RPO 1820
RPO 1830
RPO 1840
RPO 1850
RPO 1860
RPO 1870
RPO 1880
RPO 1890
RPO 1900
RPO 1910
RPO 1920
RPO 1930
RPO 1940
RPO 1950
RPO 1960
RPO 1970
RPO 1980
RPO 1990
RPO 2000
RPO 2010
RPO 2020
RPO 2030
RPO 2040
RPO 2050
RPO 2060
RPO 2070
RPO 2080
RPO 2090
RPO 2100
RPO 2110
RPO 2120
RPO 2130
RPO 2140
RPO 2150
RPO 2160
RPO 2170
RPO 2180
RPO 2190
RPO 2200
RPO 2210
RPO 2220
RPO 2230
RPO 2240
RPO 2250
RPO 2260
RPO 2270
RPO 2280
RPO 2290
RPO 2300
RPO 2310
RPO 2320
RPO 2330
RPO 2340
RPO 2350
RPO 2360
RPO 2370
RPO 2380
RPO 2390
RPO 2400

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SUBROUTINE FXSHFR(L2, NZ)
C COMPUTES UP TO L2 FIXED SHIFT K-POLYNOMIALS,
C TESTING FOR CONVERGENCE IN THE LINEAR OR QUADRATIC

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FXS 10
FXS 20
FXS 30

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C CASE. INITIATES ONE OF THE VARIABLE SHIFT          FXS 40
C ITERATIONS AND RETURNS WITH THE NUMBER OF ZEROS    FXS 50
C FOUND.                                              FXS 60
C L2 - LIMIT OF FIXED SHIFT STEPS                   FXS 70
C NZ - NUMBER OF ZEROS FOUND                         FXS 80
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN        FXS 90
DOUBLE PRECISION P(101), QP(101), K(101),          FXS 100
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,      FXS 110
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,
* LZR, LZI                                           FXS 120
REAL ETA, ARE, MRE                                  FXS 130
INTEGER N, NN                                         FXS 140
DOUBLE PRECISION SVU, SVV, UI, VI, S                FXS 150
REAL BETAS, BETAV, OSS, OVV, SS, VV, TS, TV,
* OTS, OTV, TVV, TSS                                FXS 160
INTEGER L2, NZ, TYPE, I, J, IFLAG                   FXS 170
LOGICAL VPASS, SPASS, VTRY, STRY                     FXS 180
NZ = 0                                                 FXS 190
BETAV = .25                                           FXS 200
BETAS = .25                                           FXS 210
OSS = SR                                              FXS 220
OVV = V                                               FXS 230
C EVALUATE POLYNOMIAL BY SYNTHETIC DIVISION          FXS 240
CALL QUADSD(NN, U, V, P, QP, A, B)                  FXS 250
CALL CALSCS(TYPE)                                    FXS 260
DO 80 J=1,L2                                         FXS 270
C CALCULATE NEXT K POLYNOMIAL AND ESTIMATE V         FXS 280
CALL NEXTK(TYPE)                                     FXS 290
CALL CALSCS(TYPE)                                    FXS 300
CALL NEWEST(TYPE, UI, VI)                            FXS 310
VV = VI                                              FXS 320
C ESTIMATE S                                          FXS 330
SS = 0.                                               FXS 340
IF (K(N).NE.0.D0) SS = -P(NN)/K(N)                  FXS 350
TV = 1.                                               FXS 360
TS = 1.                                               FXS 370
IF (J.EQ.1 .OR. TYPE.EQ.3) GO TO 70                 FXS 380
C COMPUTE RELATIVE MEASURES OF CONVERGENCE OF S AND V FXS 390
C SEQUENCES                                          FXS 400
IF (VV.NE.0.) TV = ABS((VV-OVV)/VV)                 FXS 410
IF (SS.NE.0.) TS = ABS((SS-OSS)/SS)                 FXS 420
C IF DECREASING, MULTIPLY TWO MOST RECENT           FXS 430
C CONVERGENCE MEASURES                              FXS 440
TVV = 1.                                              FXS 450
IF (TV.LT.OTV) TVV = TV*OTV                         FXS 460
TSS = 1.                                              FXS 470
IF (TS.LT.OTS) TSS = TS*OTS                         FXS 480
C COMPARE WITH CONVERGENCE CRITERIA                 FXS 490
VPASS = TVV.LT.BETAV                                 FXS 500
SPASS = TSS.LT.BETAS                                 FXS 510
IF (.NOT.(SPASS .OR. VPASS)) GO TO 70               FXS 520
C AT LEAST ONE SEQUENCE HAS PASSED THE CONVERGENCE  FXS 530
C TEST. STORE VARIABLES BEFORE ITERATING            FXS 540
SVU = U                                              FXS 550
SVV = V                                              FXS 560
DO 10 I=1,N                                          FXS 570
    SVK(I) = K(I)                                    FXS 580
10  CONTINUE                                         FXS 590
S = SS                                              FXS 600
C CHOOSE ITERATION ACCORDING TO THE FASTEST          FXS 610
C CONVERGING SEQUENCE                               FXS 620
VTRY = .FALSE.                                       FXS 630
STRY = .FALSE.                                       FXS 640
IF (SPASS .AND. (.NOT.VPASS) .OR.
*   TSS.LT.TVV)) GO TO 40                          FXS 650
20  CALL QUADIT(UI, VI, NZ)                         FXS 660
IF (NZ.GT.0) RETURN                                FXS 670
C QUADRATIC ITERATION HAS FAILED. FLAG THAT IT HAS  FXS 680
C BEEN TRIED AND DECREASE THE CONVERGENCE CRITERION. FXS 690
VTRY = .TRUE.                                       FXS 700
BETAV = BETAV*.25                                   FXS 710
C TRY LINEAR ITERATION IF IT HAS NOT BEEN TRIED AND FXS 720
C THE S SEQUENCE IS CONVERGING                     FXS 730
IF (STRY .OR. (.NOT.SPASS)) GO TO 50               FXS 740

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DO 30 I=1,N	FXS 800
K(I) = SVK(I)	FXS 810
30 CONTINUE	FXS 820
40 CALL REALIT(S, NZ, IFLAG)	FXS 830
IF (NZ.GT.0) RETURN	FXS 840
C LINEAR ITERATION HAS FAILED. FLAG THAT IT HAS BEEN	FXS 850
C TRIED AND DECREASE THE CONVERGENCE CRITERION	FXS 860
STRY = .TRUE.	FXS 870
BETAS = BETAS*.25	FXS 880
IF (IFLAG.EQ.0) GO TO 50	FXS 890
C IF LINEAR ITERATION SIGNALS AN ALMOST DOUBLE REAL	FXS 900
C ZERO ATTEMPT QUADRATIC ITERATION	FXS 910
UI = -(S+S)	FXS 920
VI = S*S	FXS 930
GO TO 20	FXS 940
C RESTORE VARIABLES	FXS 950
50 U = SVU	FXS 960
V = SVV	FXS 970
DO 60 I=1,N	FXS 980
K(I) = SVK(I)	FXS 990
60 CONTINUE	FXS 1000
C TRY QUADRATIC ITERATION IF IT HAS NOT BEEN TRIED	FXS 1010
C AND THE V SEQUENCE IS CONVERGING	FXS 1020
IF (VPASS .AND. (.NOT.VTRY)) GO TO 20	FXS 1030
C RECOMPUTE QP AND SCALAR VALUES TO CONTINUE THE	FXS 1040
C SECOND STAGE	FXS 1050
CALL QUADSD(NN, U, V, P, QP, A, B)	FXS 1060
CALL CALCSC(TYPE)	FXS 1070
70 OVV = VV	FXS 1080
OSS = SS	FXS 1090
OTV = TV	FXS 1100
OTS = TS	FXS 1110
80 CONTINUE	FXS 1120
RETURN	FXS 1130
END	FXS 1140
SUBROUTINE QUADIT(UU, VV, NZ)	QUA 10
C VARIABLE-SHIFT K-POLYNOMIAL ITERATION FOR A	QUA 20
C QUADRATIC FACTOR CONVERGES ONLY IF THE ZEROS ARE	QUA 30
C EQUIMODULAR OR NEARLY SO.	QUA 40
C UU,VV - COEFFICIENTS OF STARTING QUADRATIC	QUA 50
C NZ - NUMBER OF ZERO FOUND	QUA 60
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,	QUA 70
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,	QUA 80
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN	QUA 90
DOUBLE PRECISION P(101), QP(101), K(101),	QUA 100
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,	QUA 110
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,	QUA 120
* LZR, LZI	QUA 130
REAL ETA, ARE, MRE	QUA 140
INTEGER N, NN	QUA 150
DOUBLE PRECISION UI, VI, UU, VV, DABS	QUA 160
REAL MS, MP, OMP, EE, RELSTP, T, ZM	QUA 170
INTEGER NZ, TYPE, I, J	QUA 180
LOGICAL TRIED	QUA 190
NZ = 0	QUA 200
TRIED = .FALSE.	QUA 210
U = UU	QUA 220
V = VV	QUA 230
J = 0	QUA 240
C MAIN LOOP	QUA 250
10 CALL QUAD(1.D0, U, V, SZR, SZI, LZR, LZI)	QUA 260
C RETURN IF ROOTS OF THE QUADRATIC ARE REAL AND NOT	QUA 270
C CLOSE TO MULTIPLE OR NEARLY EQUAL AND OF OPPOSITE	QUA 280
C SIGN	QUA 290
IF (DABS(DABS(SZR)-DABS(LZR)).GT..01D0*	QUA 300
* DABS(LZR)) RETURN	QUA 310
C EVALUATE POLYNOMIAL BY QUADRATIC SYNTHETIC DIVISION	QUA 320
CALL QUADSD(NN, U, V, P, QP, A, B)	QUA 330
MP = DABS(A-SZR*B) + DABS(SZI*B)	QUA 340
C COMPUTE A RIGOROUS BOUND ON THE ROUNDING ERROR IN	QUA 350

```

C EVALUTING P
  ZM = SQRT(ABS(SNGL(V)))
  EE = 2.*ABS(SNGL(QP(1)))
  T = -SZR*B
  DO 20 I=2,N
    EE = EE*ZM + ABS(SNGL(QP(I)))
  20 CONTINUE
  EE = EE*ZM + ABS(SNGL(A)+T)
  EE = (5.*MRE+4.*ARE)*EE - (5.*MRE+2.*ARE)*
    * (ABS(SNGL(A)+T)+ABS(SNGL(B))*ZM) +
    * 2.*ARE*ABS(T)
C ITERATION HAS CONVERGED SUFFICIENTLY IF THE
C POLYNOMIAL VALUE IS LESS THAN 20 TIMES THIS BOUND
  IF (MP.GT.20.*EE) GO TO 30
  NZ = 2
  RETURN
  30 J = J + 1
C STOP ITERATION AFTER 20 STEPS
  IF (J.GT.20) RETURN
  IF (J.LT.2) GO TO 50
  IF (RELSTP.GT..01 .OR. MP.LT.OMP .OR. TRIED)
    * GO TO 50
C A CLUSTER APPEARS TO BE STALLING THE CONVERGENCE.
C FIVE FIXED SHIFT STEPS ARE TAKEN WITH A U,V CLOSE
C TO THE CLUSTER
  IF (RELSTP.LT.ETA) RELSTP = ETA
  RELSTP = SQRT(RELSTP)
  U = U - U*RELSTP
  V = V + V*RELSTP
  CALL QUADSD(NN, U, V, P, QP, A, B)
  DO 40 I=1,5
    CALL CALCSC(TYPE)
    CALL NEXTK(TYPE)
  40 CONTINUE
  TRIED = .TRUE.
  J = 0
  50 OMP = MP
C CALCULATE NEXT K POLYNOMIAL AND NEW U AND V
  CALL CALCSC(TYPE)
  CALL NEXTK(TYPE)
  CALL CALCSC(TYPE)
  CALL NEWEST(TYPE, UI, VI)
C IF VI IS ZERO THE ITERATION IS NOT CONVERGING
  IF (VI.EQ.0.D0) RETURN
  RELSTP = DABS((VI-V)/VI)
  U = UI
  V = VI
  GO TO 10
END

```

```

  SUBROUTINE REALIT(SSS, NZ, IFLAG)
C VARIABLE-SHIFT H POLYNOMIAL ITERATION FOR A REAL
C ZERO.
C SSS - STARTING ITERATE
C NZ - NUMBER OF ZERO FOUND
C IFLAG - FLAG TO INDICATE A PAIR OF ZEROS NEAR REAL
C AXIS.
  COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,
    * V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,
    * H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN
  DOUBLE PRECISION P(101), QP(101), K(101),
    * QK(101), SVK(101), SR, SI, U, V, A, B, C, D,
    * A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,
    * LZR, LZI
  REAL ETA, ARE, MRE
  INTEGER N, NN
  DOUBLE PRECISION PV, KV, T, S, SSS, DABS
  REAL MS, MP, OMP, EE
  INTEGER NZ, IFLAG, I, J, NM1
  NM1 = N - 1
  NZ = 0
  S = SSS
  IFLAG = 0
  J = 0

```



```

C MAIN LOOP
  10 PV = P(1)
C EVALUATE P AT S
  QP(1) = PV
  DO 20 I=2,NN
    PV = PV*S + P(I)
    QP(I) = PV
  20 CONTINUE
  MP = DABS(PV)
C COMPUTE A RIGOROUS BOUND ON THE ERROR IN EVALUATING
C P
  MS = DABS(S)
  EE = (MRE/(ARE+MRE))*ABS(SNGL(QP(1)))
  DO 30 I=2,NN
    EE = EE*MS + ABS(SNGL(QP(I)))
  30 CONTINUE
C ITERATION HAS CONVERGED SUFFICIENTLY IF THE
C POLYNOMIAL VALUE IS LESS THAN 20 TIMES THIS BOUND
  IF (MP.GT.20.*((ARE+MRE)*EE-MRE*MP)) GO TO 40
  NZ = 1
  SZR = S
  SZI = 0.D0
  RETURN
  40 J = J + 1
C STOP ITERATION AFTER 10 STEPS
  IF (J.GT.10) RETURN
  IF (J.LT.2) GO TO 50
  IF (DABS(T).GT..001*DABS(S-T) .OR. MP.LE.OMP)
    * GO TO 50
C A CLUSTER OF ZEROS NEAR THE REAL AXIS HAS BEEN
C ENCOUNTERED RETURN WITH IFLAG SET TO INITIATE A
C QUADRATIC ITERATION
  IFLAG = 1
  SSS = S
  RETURN
C RETURN IF THE POLYNOMIAL VALUE HAS INCREASED
C SIGNIFICANTLY
  50 OMP = MP
C COMPUTE T, THE NEXT POLYNOMIAL, AND THE NEW ITERATE
  KV = K(1)
  QK(1) = KV
  DO 60 I=2,N
    KV = KV*S + K(I)
    QK(I) = KV
  60 CONTINUE
  IF (DABS(KV).LE.DABS(K(N))*10.*ETA) GO TO 80
C USE THE SCALED FORM OF THE RECURRENCE IF THE VALUE
C OF K AT S IS NONZERO
  T = -PV/KV
  K(1) = QP(1)
  DO 70 I=2,N
    K(I) = T*QK(I-1) + QP(I)
  70 CONTINUE
  GO TO 100
C USE UNSCALED FORM
  80 K(1) = 0.0D0
  DO 90 I=2,N
    K(I) = QK(I-1)
  90 CONTINUE
  100 KV = K(1)
  DO 110 I=2,N
    KV = KV*S + K(I)
  110 CONTINUE
  T = 0.D0
  IF (DABS(KV).GT.DABS(K(N))*10.*ETA) T = -PV/KV
  S = S + T
  GO TO 10
END

```

```

REA 250
REA 260
REA 270
REA 280
REA 290
REA 300
REA 310
REA 320
REA 330
REA 340
REA 350
REA 360
REA 370
REA 380
REA 390
REA 400
REA 410
REA 420
REA 430
REA 440
REA 450
REA 460
REA 470
REA 480
REA 490
REA 500
REA 510
REA 520
REA 530
REA 540
REA 550
REA 560
REA 570
REA 580
REA 590
REA 600
REA 610
REA 620
REA 630
REA 640
REA 650
REA 660
REA 670
REA 680
REA 690
REA 700
REA 710
REA 720
REA 730
REA 740
REA 750
REA 760
REA 770
REA 780
REA 790
REA 800
REA 810
REA 820
REA 830
REA 840
REA 850
REA 860
REA 870
REA 880
REA 890
REA 900
REA 910
REA 920

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      SUBROUTINE CALCSC(TYPE)
C THIS ROUTINE CALCULATES SCALAR QUANTITIES USED TO
C COMPUTE THE NEXT K POLYNOMIAL AND NEW ESTIMATES OF

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CAL 10
CAL 20
CAL 30

```

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C THE QUADRATIC COEFFICIENTS.                                CAL  40
C TYPE - INTEGER VARIABLE SET HERE INDICATING HOW THE      CAL  50
C CALCULATIONS ARE NORMALIZED TO AVOID OVERFLOW           CAL  60
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,              CAL  70
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,              CAL  80
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN              CAL  90
DOUBLE PRECISION P(101), QP(101), K(101),                CAL 100
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,            CAL 110
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,              CAL 120
* LZR, LZI                                                CAL 130
REAL ETA, ARE, MRE                                        CAL 140
INTEGER N, NN                                             CAL 150
DOUBLE PRECISION DABS                                    CAL 160
INTEGER TYPE                                              CAL 170
C SYNTHETIC DIVISION OF K BY THE QUADRATIC 1,U,V          CAL 180
CALL QUADSD(N, U, V, K, QK, C, D)                       CAL 190
IF (DABS(C).GT.DABS(K(N))*100.*ETA) GO TO 10              CAL 200
IF (DABS(D).GT.DABS(K(N-1))*100.*ETA) GO TO 10            CAL 210
TYPE = 3                                                  CAL 220
C TYPE=3 INDICATES THE QUADRATIC IS ALMOST A FACTOR      CAL 230
C OF K                                                    CAL 240
RETURN                                                    CAL 250
10 IF (DABS(D).LT.DABS(C)) GO TO 20                       CAL 260
TYPE = 2                                                  CAL 270
C TYPE=2 INDICATES THAT ALL FORMULAS ARE DIVIDED BY D    CAL 280
E = A/D                                                  CAL 290
F = C/D                                                  CAL 300
G = U*B                                                  CAL 310
H = V*B                                                  CAL 320
A3 = (A+G)*E + H*(B/D)                                  CAL 330
A1 = B*F - A                                             CAL 340
A7 = (F+U)*A + H                                         CAL 350
RETURN                                                    CAL 360
20 TYPE = 1                                              CAL 370
C TYPE=1 INDICATES THAT ALL FORMULAS ARE DIVIDED BY C    CAL 380
E = A/C                                                  CAL 390
F = D/C                                                  CAL 400
G = U*E                                                  CAL 410
H = V*B                                                  CAL 420
A3 = A*E + (H/C+G)*B                                    CAL 430
A1 = B - A*(D/C)                                         CAL 440
A7 = A + G*D + H*F                                       CAL 450
RETURN                                                    CAL 460
END                                                        CAL 470

SUBROUTINE NEXTK(TYPE)                                    NEX  10
C COMPUTES THE NEXT K POLYNOMIALS USING SCALARS          NEX  20
C COMPUTED IN CALCSK                                     NEX  30
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,           NEX  40
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,           NEX  50
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN           NEX  60
DOUBLE PRECISION P(101), QP(101), K(101),              NEX  70
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,          NEX  80
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,             NEX  90
* LZR, LZI                                               NEX 100
REAL ETA, ARE, MRE                                       NEX 110
INTEGER N, NN                                            NEX 120
DOUBLE PRECISION TEMP, DABS                             NEX 130
INTEGER TYPE                                              NEX 140
IF (TYPE.EQ.3) GO TO 40                                  NEX 150
TEMP = A                                                  NEX 160
IF (TYPE.EQ.1) TEMP = B                                   NEX 170
IF (DABS(A1).GT.DABS(TEMP)*ETA*10.) GO TO 20             NEX 180
C IF A1 IS NEARLY ZERO THEN USE A SPECIAL FORM OF THE    NEX 190
C RECURRENCE                                              NEX 200
K(1) = 0.D0                                              NEX 210
K(2) = -A7*QP(1)                                         NEX 220
DO 10 I=3,N                                              NEX 230
K(I) = A3*QK(I-2) - A7*QP(I-1)                          NEX 240
10 CONTINUE                                              NEX 250
RETURN                                                    NEX 260
C USE SCALED FORM OF THE RECURRENCE                     NEX 270
20 A7 = A7/A1                                             NEX 280
A3 = A3/A1                                               NEX 290

```

K(1) = QP(1)	NEX	300
K(2) = QP(2) - A7*QP(1)	NEX	310
DO 30 I=3,N	NEX	320
K(I) = A3*QK(I-2) - A7*QP(I-1) + QP(I)	NEX	330
30 CONTINUE	NEX	340
RETURN	NEX	350
C USE UNSCALED FORM OF THE RECURRENCE IF TYPE IS 3	NEX	360
40 K(1) = 0.D0	NEX	370
K(2) = 0.D0	NEX	380
DO 50 I=3,N	NEX	390
K(I) = QK(I-2)	NEX	400
50 CONTINUE	NEX	410
RETURN	NEX	420
END	NEX	430
SUBROUTINE NEWEST(TYPE, UU, VV)	NEW	10
C COMPUTE NEW ESTIMATES OF THE QUADRATIC COEFFICIENTS	NEW	20
C USING THE SCALARS COMPUTED IN CALCSC.	NEW	30
COMMON /GLOBAL/ P, QP, K, QK, SVK, SR, SI, U,	NEW	40
* V, A, B, C, D, A1, A2, A3, A6, A7, E, F, G,	NEW	50
* H, SZR, SZI, LZR, LZI, ETA, ARE, MRE, N, NN	NEW	60
DOUBLE PRECISION P(101), QP(101), K(101),	NEW	70
* QK(101), SVK(101), SR, SI, U, V, A, B, C, D,	NEW	80
* A1, A2, A3, A6, A7, E, F, G, H, SZR, SZI,	NEW	90
* LZR, LZI	NEW	100
REAL ETA, ARE, MRE	NEW	110
INTEGER N, NN	NEW	120
DOUBLE PRECISION A4, A5, B1, B2, C1, C2, C3,	NEW	130
* C4, TEMP, UU, VV	NEW	140
INTEGER TYPE	NEW	150
C USE FORMULAS APPROPRIATE TO SETTING OF TYPE.	NEW	160
IF (TYPE.EQ.3) GO TO 30	NEW	170
IF (TYPE.EQ.2) GO TO 10	NEW	180
A4 = A + U*B + H*F	NEW	190
A5 = C + (U+V*F)*D	NEW	200
GO TO 20	NEW	210
10 A4 = (A+G)*F + H	NEW	220
A5 = (F+U)*C + V*D	NEW	230
C EVALUATE NEW QUADRATIC COEFFICIENTS.	NEW	240
20 B1 = -K(N)/P(NN)	NEW	250
B2 = -(K(N-1)+B1*P(N))/P(NN)	NEW	260
C1 = V*B2*A1	NEW	270
C2 = B1*A7	NEW	280
C3 = B1*B1*A3	NEW	290
C4 = C1 - C2 - C3	NEW	300
TEMP = A5 + B1*A4 - C4	NEW	310
IF (TEMP.EQ.0.D0) GO TO 30	NEW	320
UU = U - (U*(C3+C2)+V*(B1*A1+B2*A7))/TEMP	NEW	330
VV = V*(1.+C4/TEMP)	NEW	340
RETURN	NEW	350
C IF TYPE=3 THE QUADRATIC IS ZEROED	NEW	360
30 UU = 0.D0	NEW	370
VV = 0.D0	NEW	380
RETURN	NEW	390
END	NEW	400
SUBROUTINE QUADSD(NN, U, V, P, Q, A, B)	QUA	10
C DIVIDES P BY THE QUADRATIC 1,U,V PLACING THE	QUA	20
C QUOTIENT IN Q AND THE REMAINDER IN A,B	QUA	30
DOUBLE PRECISION P(NN), Q(NN), U, V, A, B, C	QUA	40
INTEGER I	QUA	50
B = P(1)	QUA	60
Q(1) = B	QUA	70
A = P(2) - U*B	QUA	80
Q(2) = A	QUA	90
DO 10 I=3,NN	QUA	100
C = P(I) - U*A - V*B	QUA	110
Q(I) = C	QUA	120
B = A	QUA	130
A = C	QUA	140
10 CONTINUE	QUA	150
RETURN	QUA	160
END	QUA	170

SUBROUTINE QUAD(A, B1, C, SR, SI, LR, LI)	QUA 10
C CALCULATE THE ZEROS OF THE QUADRATIC $A^2Z^2+B1Z+C$.	QUA 20
C THE QUADRATIC FORMULA, MODIFIED TO AVOID	QUA 30
C OVERFLOW, IS USED TO FIND THE LARGER ZERO IF THE	QUA 40
C ZEROS ARE REAL AND BOTH ZEROS ARE COMPLEX.	QUA 50
C THE SMALLER REAL ZERO IS FOUND DIRECTLY FROM THE	QUA 60
C PRODUCT OF THE ZEROS C/A.	QUA 70
DOUBLE PRECISION A, B1, C, SR, SI, LR, LI, B,	QUA 80
* D, E, DABS, DSQRT	QUA 90
IF (A.NE.0.D0) GO TO 20	QUA 100
SR = 0.D0	QUA 110
IF (B1.NE.0.D0) SR = -C/B1	QUA 120
LR = 0.D0	QUA 130
10 SI = 0.D0	QUA 140
LI = 0.D0	QUA 150
RETURN	QUA 160
20 IF (C.NE.0.D0) GO TO 30	QUA 170
SR = 0.D0	QUA 180
LR = -B1/A	QUA 190
GO TO 10	QUA 200
C COMPUTE DISCRIMINANT AVOIDING OVERFLOW	QUA 210
30 B = B1/2.D0	QUA 220
IF (DABS(B).LT.DABS(C)) GO TO 40	QUA 230
E = 1.D0 - (A/B)*(C/B)	QUA 240
D = DSQRT(DABS(E))*DABS(B)	QUA 250
GO TO 50	QUA 260
40 E = A	QUA 270
IF (C.LT.0.D0) E = -A	QUA 280
E = B*(B/DABS(C)) - E	QUA 290
D = DSQRT(DABS(E))*DSQRT(DABS(C))	QUA 300
50 IF (E.LT.0.D0) GO TO 60	QUA 310
C REAL ZEROS	QUA 320
IF (B.GE.0.D0) D = -D	QUA 330
LR = (-B+D)/A	QUA 340
SR = 0.D0	QUA 350
IF (LR.NE.0.D0) SR = (C/LR)/A	QUA 360
GO TO 10	QUA 370
C COMPLEX CONJUGATE ZEROS	QUA 380
60 SR = -B/A	QUA 390
LR = SR	QUA 400
SI = DABS(D/A)	QUA 410
LI = -SI	QUA 420
RETURN	QUA 430
END	QUA 440