# 1 Motivation problem

```
[PP, Chapter 7]
```

# Bentley's problem:

- Given an array A[1..n] of integer numbers.
- Find contiguous subarray which has the largest sum.

# Example:

```
31 -41 59 26 -53 58 97 -93 -23 84
187
```

# Quiz questions:

- What if all numbers are positive?
- What if all numbers are negative?

(Simple) Solution 1: Try all possible subarrays and choose one with the largest sum.

```
max:=0;
for i:=1 to n do
| for j:=i to n do
| | // compute sum of subarray A[i]..A[j]
| | sum:=0;
| | for k:=i to j do
| | | sum:=sum+A[k];
| | // compare to maximum
| | if sum>max then max:=sum;
```

**Recall:** O notation for measuring how running time grows with the size of the output. (cs240) Informally: Running time is O(f(n)) if it is "proportional" to f(n) for the input of size n.

Time:  $O(n^3)$ 

**Q:** Can we do better?

Solution 2a: We don't need to recompute sum from scratch every time.

```
max:=0;
for i:=1 to n do
| sum:=0;
| for j:=i to n do
| | sum:=sum+A[j];
| | // sum is now sum of subarray A[i]..A[j]
| | // compare to maximum
| | if sum>max then max:=sum;
```

Time:  $O(n^2)$ 

```
Solution 2b: We can compute sum in constant time if we do a little bit of pre-computation. Let B[i] be the sum of A[1] + \ldots + A[i]. Then A[i] + \ldots + A[j] = B[j] - B[i-1].

// precompute B[i] = A[1] + \ldots + A[i]
B[0] := 0;
for i := 1 to n do

| B[i] := B[i-1] + A[i];

max:=0;
for i := 1 to n do

| for j := i to n do

| i := 1 to n do

| i := 1 to i
```

#### Solution 3 (Divide-and-conquer):

Recall MergeSort: (cs240)

To sort the array:

- Divide an array into two equally-sized parts
- Sort each part separately
- Solution is obtained by "merging" the smaller solutions

The same approach can be used here:

- Divide an array into two equally-sized parts
- Our solution must either be entirely in the left part, or entirely in the right part, or must be going "through the midle"; therefore:
  - Find the maximum subarray for left part  $(\max_L)$  and right part  $(\max_R)$
  - Find the maximum subarray going "through the middle"  $(\max_M)$  this can be done in linear time O(n)
  - $-\max\{\max_L, \max_R, \max_M\}$  is the solution.

#### Examples:

**Time:**  $O(n \log n)$ , as in MergeSort. (If interested in the details, have a look at PP, chapter 7)

# Solution 4:

- $maxsol_i$  be the maximum sum subarray of array A[1..[i]].
- $tail_i$  be the maximum sum subarray that ends at position i.

What is the relationship between  $maxsol_i$  and  $maxsol_{i-1}$ ?

$$\begin{split} maxsol_i &= \max \left\{ \begin{array}{l} maxsol_{i-1}, \\ tail_i, \end{array} \right. \\ tail_i &= \max \left\{ \begin{array}{l} tail_{i-1} + A[i], \\ 0. \end{array} \right. \end{split}$$

```
maxsol:=0; tail:=0;
for i:=1 to n do
| // maxsol now corresponds to maxsol[i-1]
| // tail now corresponds to tail[i-1]
| tail:=max(tail+A[i],0);
| maxsol:=max(maxsol,tail);
```

Time: O(n)

# Time comparison

- Solutions implemented in C.
- Some of the values are measured (on Pentium II), some of them are estimated from the other measurements.
- Solution 0 is a fictitious exponential-time solution (just for comparison with others)
- $\varepsilon$  means under 0.01s

		Sol.4	Sol.3	Sol.2	Sol.1	Sol.0
		O(n)	$O(n \log n)$	$O(n^2)$	$O(n^3)$	$O(2^n)$
Time to	10	$\varepsilon$	arepsilon	$\varepsilon$	$\varepsilon$	$\varepsilon$
solve a	50	arepsilon	arepsilon	$\varepsilon$	arepsilon	2 weeks
problem	100	arepsilon	arepsilon	$\varepsilon$	arepsilon	2800 univ.
of size	1000	arepsilon	arepsilon	0.02s	4.5s	
	10000	$\varepsilon$	0.01s	2.1s	$75 \mathrm{m}$	
	100000	0.04s	0.12s	$3.5 \mathrm{m}$	52d	
	1 mil.	0.42s	1.4s	5.8h	142 yr	_
	10 mil.	4.2s	16.1s	24.3d	$140000 \mathrm{yr}$	_
Max size	1s	2.3 mil.	740000	6900	610	33
problem	$1 \mathrm{m}$	140 mil.	34 mil.	53000	2400	39
solved in	1d	200 bil.	35 bil.	2 mil.	26000	49
Increase in	+1		_		_	$\times 2$
time if $n$	$\times 2$	$\times 2$	$\times 2+$	$\times 4$	$\times 8$	
increases						

# Points to take home:

- Even with today's fast processors, designing better algorithms matters.
- Asymptotic notation is a relevant measure of the running time of algorithms. It allows us to easily analyze and compare algorithms and abstract away implementation details and computer-specific issues.
- For a single problem there can be several solutions with different time complexities. Sometimes a better solution can be even easier to implement.
- Polynomial-time algorithms are much better than exponential ones.