# Bayesian Neural Networks for GW parameter Estimation

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### Spotlights

Bayesian Neural Network on GW Parameter Estimation

TensorFlow Application

### Backgrounds

Assume Likelihood function on noisy observations x:

$$p(x | m_1, m_2)$$

• Assume flat prior on parameters (e.g. masses  $m_1, m_2$ )

$$p(m_1, m_2)$$

Apply Bayesian rules to achieve the the posterior of the parameters

$$p(m_1, m_2 | x) \propto p(x | m_1, m_2) p(m_1, m_2)$$

# Backgrounds

 Posterior function is not easy to evaluate due to difficulties in exploring the whole space of the parameters (red and blue)-> use MCMC sampling instead -> time-consuming

$$p(m_1, m_2 | x) = \frac{p(x | m_1, m_2)p(m_1, m_2)}{p(x)}$$

$$p(x \mid m_1, m_2) = \frac{1}{Z} \exp(-\frac{1}{2}(x - f(m_1, m_2))^{\mathsf{T}} \Sigma^{-1}(x - f(m_1, m_2)))$$

 We can make improvements with Bayesian Neural Networks!

### Content

Hands-on Linear Regression Model

 Apply ideas from Linear Regression on GW parameter Estimation

 How to write DIY Bayesian Neural Networks using TensorFlow

#### Resource

#### https://github.com/skyve2012/ BayesianNetTutorial

Consider the following problem:

$$y = ax + b + \epsilon$$

- y and x are data; a and b are parameters to be learned. 
   é
   is universal noise across all values of x (0 mean, fixed
   variance)
- Best solution is least square under the linear assumption in the true model.

$$\min_{a,b} ||ax + b - y||^2 = \max_{a,b} p(y|x; a, b)$$
$$p(y|x; a, b) \sim N(ax + b, \sigma_{\epsilon}^2)$$

What if the problem is slightly changed:

$$y = ax + b + \epsilon(x)$$

- $\epsilon$  is dependent on x in this case (0 mean).
- One way is to use weighted least square
- The other way is to treat  $e(x) = e_{\theta}(x)$

$$max_{a,b,\theta}p(y | x; a, b, \theta)$$

$$p(y | x; a, b, \theta) \sim N(ax + b, \sigma_{\epsilon_{\theta}(x)}^2)$$

- What if we want to also consider the variance on the estimation  $\hat{a}, \hat{b}$  given the distribution of the data: p(x, y). Or equivalently,  $p(a, b \mid x)$ .
- Consider the previous problem:  $\max_{a,b,\theta} p(y | x; a, b, \theta)$
- We re-write the problem as:  $max_{\theta,w}p(y|x;\theta,w)$

$$p(y \mid x; \theta, w) = \int_{a,b} p(y \mid a, b, x; \theta) p_w(a, b \mid x) dadb$$

The blue part is can be learned via Variational Inference

### Variational Inference

 Learn a parameterized distribution to approximate the true posterior via minimizing the KL-divergence, making it as close to the true posterior as possible.

$$KL(q_{\theta}(y) \mid \mid p(y \mid x)) = E_q[\log \frac{q_{\theta}(y)}{p(y \mid x)}]$$

$$E_q[\log \frac{q_{\theta}(y)}{p(y \mid x)}] = E_q[\log q_{\theta}(y)] - E_q[\log \frac{p(x \mid y)p(y)}{p(x)}]$$

$$\log p(x) - KL(q_{\theta}(y) | | p(y|x)) = E_q[\log p(x|y)] + E_q[\log \frac{p(y)}{q_{\theta}(y)}]$$

Demo

#### **GW** Parameter Estimation

- This is no difference to the linear regression
- Linear Regression:  $y = ax + b + \epsilon(x)$
- GW Parameter Estimation:  $y = f(x) + \epsilon(x)$ ,  $y = f(x, \epsilon(x))$
- Assume we have a parameterized model  $\hat{f}_{\tau}(x)$ :

$$max_{\theta,w}p(y|x;\theta,w)$$

$$p(y | x; \theta, w) = \int_{\tau} p(y | \tau, x; \theta) p_{w}(\tau | x) d\tau$$

#### **GW Parameter Estimation**

Demo

- A well-constructed deep learning model: Inputs, outputs, loss, and optimizer.
- Dataset Feeder: pass data from a dataset object to model during training
- Training, Testing, Prediction Wrappers: Handle the training, testing and prediction process, respectively

Model:

```
def gen_model():
    initialze input and output variabes,
    return the model wrapper that takes inputs and outputs as its input parameters
    1 1 1
    inputs = tf.keras.layers.Input(shape=(BATCH SIZE, 8192), dtype=tf.float32)
    x = inputs
    # get std
    x branch = tf.keras.layers.Dense(units=512, activation=tf.nn.relu)(x)
    std x = tf.keras.layers.Dense(units=1, activation=tf.nn.relu)(x branch)
    # get mean estimation
    x = tfp.layers.DenseFlipout(512, activation=None)(x)
    x = tfp.layers.DenseFlipout(1, activation=tf.nn.relu)(x)
    model = tf.keras.models.Model(inputs=inputs, outputs=[x, std x])
    return model
```

Dataset:

```
def generator(filename, shuffle=True, batch size = 32, ...):
    1 1 1
    filename: dataset file name
    shuffle: if shuffle the dataset
    batch size: batch size for training with stochastic approaches
    return: an iterable object
    return iterable object
```

Training, Testing, Prediction Wrappers

```
: def ModelFunc(features, labels, mode):
     features: [batch size, 8192]
     labels: [batch size, label dim] # label dim = 1 for just single parameter
     mode: train, test, predictions, controlled by the Estimator object in TensorFlow
     return proper wrappers (training, testing and prediciton)
     x, y = features, labels
     model = gen model()
     out mean, out std = model(x)
     final_distribution = tfd.Normal(loc=out mean, scale=out std + 1e-3)
     final outputs = final distribution.sample(SAMPLE PER PASS)
     ###########
     #predictions
     ############
     predictions = {'predictions': tf.transpose(final outputs, [1, 0, 2])}
     if mode == tf.estimator.ModeKeys.PREDICT:
         return tf.estimator.EstimatorSpec(mode=mode, predictions=predictions)
     #############
     #training
     ##############
     if mode == tf.estimator.ModeKeys.TRAIN:
         optimizer = tf.compat.v1.train.AdamOptimizer(learning rate = 0.0005, beta1=0.9, beta2=0.999,epsilon=1e-08)
         train op = optimizer.minimize(loss=loss)
         global step = tf.compat.v1.train.get global step()
          update global step = tf.compat.v1.assign(global step, global step + 1, name = 'update global step')
         return tf.estimator.EstimatorSpec(mode=mode,
                                            train op=tf.group(train op, update global step))
     #############
     #evaluation
     #############
     eval metric ops = {
              'relative error test': tf.compat.vl.metrics.mean relative error(y, final outputs, y),
              'mse loss test': tf.compat.vl.metrics.mean squared error(y, final outputs)}
     return tf.estimator.EstimatorSpec(mode=mode, loss=loss, eval metric ops=eval metric ops)
```

Demo