

view\_frames Result

Recorded at time: 130.970

world

Broadcaster: /gazebo  
Average rate: 100.201 Hz  
Most recent transform: 130.970 ( 0.000 sec old)  
Buffer length: 4.980 sec

Broadcaster: /gazebo  
Average rate: 100.201 Hz  
Most recent transform: 130.970 ( 0.000 sec old)  
Buffer length: 4.980 sec

firefly/base\_link

firefly/odometry\_sensor1

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

rgb\_camera/base\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

firefly/base\_link\_inertia

Broadcaster: /firefly/robot\_state\_publisher  
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Buffer length: 0.000 sec

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

base\_groud\_link\_1

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

base\_groud\_link\_2

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
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Buffer length: 0.000 sec

firefly/rotor\_0

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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firefly/rotor\_1

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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Buffer length: 4.960 sec

firefly/rotor\_2

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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Buffer length: 4.960 sec

firefly/rotor\_3

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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Buffer length: 4.960 sec

firefly/rotor\_4

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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Buffer length: 4.960 sec

firefly/rotor\_5

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 59.677 Hz  
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Buffer length: 4.960 sec

firefly/imu\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 130.900 ( 0.070 sec old)  
Buffer length: 4.900 sec

firefly/imugt\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 130.900 ( 0.070 sec old)  
Buffer length: 4.900 sec

firefly/odometry\_sensor1\_link

Broadcaster: /firefly/robot\_state\_publisher  
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Buffer length: 4.900 sec

firefly/odometry\_sensorgt\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

firefly/rgb/camera\_depth\_2\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 130.970 sec old)  
Buffer length: 0.000 sec

firefly/rgb/camera\_depth\_2\_optical\_center\_link

Broadcaster: /firefly/robot\_state\_publisher  
Average rate: 10000.000 Hz  
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Buffer length: 0.000 sec

firefly/rgb/camera\_depth\_link

Broadcaster: /firefly/robot\_state\_publisher  
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Buffer length: 0.000 sec

firefly/rgb/camera\_depth\_optical\_center\_link

Broadcaster: /firefly/robot\_state\_publisher  
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firefly/rgb/camera\_rgb\_link

Broadcaster: /firefly/robot\_state\_publisher  
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firefly/rgb/camera\_rgb\_optical\_link