```
"C:\Program Files\Maple 2015"
                                                                               (1)
# Load "Rational SOS" procedures
  read("rationalSOS.mpl");
  with(rationalSOS);
  # Display tables of any size
  interface(rtablesize = infinity);
                        "Opening connection with Matlab"
                     rationalSOS := module( ) ... end module
[cancelDenominator, decompositionToMatrix, evalMat, evalSolution, exactSOS, getDiag,
   getExtension, getVars, matrixToPoly, nonRatCoef, numericSolver, numericSolverSubmatrix,
   polyToMatrix, primitiveMatrix, randomRank, reduceByLinearEquation,
   reduceByLinearEquationLinear, roundMat, roundVec, vectorTrace, zeroDetSRows,
   zeroRows]
                                     10
                                                                               (2)
# Construction of the example
  # We define a polynomial z as the sum of three squares in an algebraic
  # extension of degree 3 with generic coefficients.
  mp := t^3 - 2;
  p1 := c1 * t^2 + b1 * t + a1;
  p2 := c2 * t^2 + b2 * t + a2;
 p3 := c3 * t^2 + b3 * t + a3;
 fGeneric := p1^2 + p2^2 + p3^2;
 fGeneric := expand(fGeneric);
  # We choose the parameters so that all terms are multiple by x, and we can reduce the degree.
  b2 := -b1; c2 := b2; c1 := b2;
  b1 := x0; b3 := x1; a3 := x2; c3 := x3;
  # We solve the coefficients a1 and a2 so that the polynomial is in Q,
 f2 := NormalForm(fGeneric, [mp], plex(a1, a2, x0, x1, x2, x3, t));
 f3 := collect(f2, t);
  lf := CoefficientList(f3, t);
  ss := solve(\{lf[2], lf[3]\}, \{a1, a2\});
  # We plug in the solutions found for a1 and a2 and compute the resulting polynomial
  ssDen := denom(rhs(ss[1]));
  p1s := simplify(subs(ss, p1) * ssDen);
  p2s := simplify(subs(ss, p2) * ssDen);
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p3s := simplify(subs(ss, p3) * ssDen);
          p1ss := subs(\{t = RootOf(x^3 - 2)\}, p1s);
          p2ss := subs(\{t = RootOf(x^3 - 2)\}, p2s);
          p3ss := subs(\{t = RootOf(x^3 - 2)\}, p3s);
          f := simplify(p1ss^2 + p2ss^2 + p3ss^2);
                           \# f := 40*x0^4 + 8*x0^2*x1^2 + 32*x0^2*x1*x2 + 64*x0^2*x1*x3 + 16*x0^2*x2^2 + 16*x0^2*x1^2 + 16*x0^2*x1^2 + 16*x0^2*x1^2 + 16*x0^2 + 1
                          x^{2}*x^{3}+3^{2}*x^{0}^{2}*x^{3}^{2}+2^{2}x^{1}^{4}+8^{2}x^{1}^{2}*x^{2}^{2}+8^{2}x^{1}^{2}*x^{2}*x^{3}+16^{2}x^{2}*x^{3}^{2}+8^{2}x^{2}^{2}
                           x3^2 + 8*x3^4
                                                                                                                                                             mp := t^3 - 2
                                                                                                                                        p1 := c1 t^2 + b1 t + a1
                                                                                                                                        p2 := c2 t^2 + b2 t + a2
                                                                                                                                        p3 := c3 t^2 + b3 t + a3
                              fGeneric := (c1 t^2 + b1 t + a1)^2 + (c2 t^2 + b2 t + a2)^2 + (c3 t^2 + b3 t + a3)^2
fGeneric := cl^2 t^4 + c2^2 t^4 + c3^2 t^4 + 2b1c1t^3 + 2b2c2t^3 + 2b3c3t^3 + 2a1c1t^2 + 2a2c2t^2
                   +2 a3 c3 t^{2} + b1^{2} t^{2} + b2^{2} t^{2} + b3^{2} t^{2} + 2 a1 b1 t + 2 a2 b2 t + 2 a3 b3 t + a1^{2} + a2^{2}
                  + a3^{2}
                                                                                                                                                                 b2 := -b1
                                                                                                                                                                 c2 := -b1
                                                                                                                                                                 c1 := -b1
                                                                                                                                                                    b1 := x0
                                                                                                                                                                    b3 := x1
                                                                                                                                                                     a3 := x2
                                                                                                                                                                     c3 := x3
f2 := -2 a1 t^2 x0 - 2 a2 t^2 x0 + 2 t^2 x0^2 + t^2 x1^2 + 2 t^2 x2 x3 + 2 a1 t x0 - 2 a2 t x0 + 4 t x0^2
                  +2 tx1 x2 + 2 tx3^{2} + a1^{2} + a2^{2} + 4 x1 x3 + x2^{2}
f3 := (-2 a1 x0 - 2 a2 x0 + 2 x0^{2} + x1^{2} + 2 x2 x3) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 + 4 x0^{2} + 2 x1 x2) t^{2} + (2 a1 x0 - 2 a2 x0 
                 +2x3^{2}) t + a1^{2} + a2^{2} + 4x1x3 + x2^{2}
lf := [a1^2 + a2^2 + 4x1x3 + x2^2, 2a1x0 - 2a2x0 + 4x0^2 + 2x1x2 + 2x3^2, -2a1x0]
                  -2 a2 x0 + 2 x0^{2} + x1^{2} + 2 x2 x3
ss := \left\{ aI = -\frac{1}{4} \right. \frac{2 \, x0^2 - xI^2 + 2 \, xI \, x2 - 2 \, x2 \, x3 + 2 \, x3^2}{x0}, \, a2 \right\}
                = \frac{1}{4} \left. \frac{6 x 0^2 + x I^2 + 2 x I x 2 + 2 x 2 x 3 + 2 x 3^2}{x 0} \right\}
                                                                                                                                                           ssDen := 4 x0
                                                     p1s := -4 t^2 x 0^2 + 4 t x 0^2 - 2 x 0^2 + x 1^2 - 2 x 1 x 2 + 2 x 2 x 3 - 2 x 3^2
                                                     p2s := -4 t^2 x 0^2 - 4 t x 0^2 + 6 x 0^2 + x 1^2 + 2 x 1 x 2 + 2 x 2 x 3 + 2 x 3^2
                                                                                                                          p3s := 4 (t^2 x^3 + t x^1 + x^2) x^0
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```
p1ss := -4x0^{2} RootOf(\underline{Z}^{3} - 2)^{2} + 4x0^{2} RootOf(\underline{Z}^{3} - 2) - 2x0^{2} + xI^{2} - 2xIx2 + 2x2x3
p2ss := -4 x0^{2} RootOf(Z^{3} - 2)^{2} - 4 x0^{2} RootOf(Z^{3} - 2) + 6 x0^{2} + x1^{2} + 2 x1 x2 + 2 x2 x3
                                                 p3ss := 4 \left( RootOf(Z^3 - 2)^2 x3 + RootOf(Z^3 - 2) x1 + x2 \right) x0
f := 40 \times 0^4 + 8 \times 0^2 \times 1^2 + 32 \times 0^2 \times 1 \times 2 + 64 \times 0^2 \times 1 \times 3 + 16 \times 0^2 \times 2^2 + 16 \times 0^2 \times 2 \times 3 + 32 \times 0^2 \times 3^2
                                                                                                                                                                                                                                                                                                                                                  (3)
                +2xI^{4} + 8xI^{2}x2^{2} + 8xI^{2}x2x3 + 16xIx2x3^{2} + 8x2^{2}x3^{2} + 8x3^{4}
> # We verify that the polynomial is absolutely irreducible
          evala(AIrreduc(f));
          ## -> true
          # Matrix Q associated to the problem (parametrization of the space L)
          Q, QVars, v := polyToMatrix(f):
         # Matrix associated to the original decomposition (for verifications)
          MNEW := decompositionToMatrix([p1ss, p2ss, p3ss], v):
          # We start from Q and go step by step.
          nops(indets(Q)); #20
          randomRank(Q); # 10
                                                                                                                                                           true
                                                                                                                                                              20
                                                                                                                                                              10
                                                                                                                                                                                                                                                                                                                                                  (4)
> # Real solutions
          sSym := solve(\{p1ss = 0, p2ss = 0, p3ss = 0\});
         # Alternative:
         \#sSym := solve(\{f=0, diff(f, x0)=0, diff(f, x1)=0, diff(f, x2)=0, diff(f, x3)=0\});
sSym := \left\{ x0 = x0, x1 = \right.
                                                                                                                                                                                                                                                                                                                                                  (5)
                    \frac{x0 \left(RootOf(3 Z^{4} - 4 + (-4 RootOf(Z^{3} - 2) + 4) Z^{2})^{2} + 2\right)}{RootOf(Z^{3} - 2)^{2} RootOf(3 Z^{4} - 4 + (-4 RootOf(Z^{3} - 2) + 4) Z^{2})}, x2 = \frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} + \frac{1}{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} + \frac{1}{2} \left(\frac{1}{2} - \frac{1}{2}\right)^{2} \left(\frac
              -(x\theta (RootOf(Z^3-2)^3 RootOf(3Z^4-4+(-4 RootOf(Z^3-2)+4)Z^2)^2)
                -RootOf(3\_Z^4-4+(-4RootOf(\_Z^3-2)+4)\_Z^2)^2-2))/(RootOf(\_Z^3-2)+4)\_Z^2)^2-2))
                -2) RootOf(3 Z^4 - 4 + (-4 RootOf(Z^3 - 2) + 4) <math>Z^2)), x3 = RootOf(3 Z^4 - 4
               + (-4 RootOf(_Z^3 - 2) + 4) _Z^2) x0, \{x0 = 0, x1 =
```

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-\frac{2 x^2 \left(RootOf(\underline{Z}^3+2)^2-RootOf(\underline{Z}^3+2)+1\right)}{RootOf(\underline{Z}^3+2)^2-RootOf(\underline{Z}^3+2)+2}, x2=x2, x3=RootOf(\underline{Z}^3+2) x2
          \{x0=0, x1=0, x2=x2, x3=0\}
> # We replace the RootOf(Z^3+2) by -RootOf(Z^3-2) in the second branch,
       # so that we have all solutions in terms of that root
       alias(r1 = RootOf(Z^3-2));
       s2 := \{x0 = 0, x1 = -2 * x2 * ((-r1)^2 - (-r1) + 1) / ((-r1)^2 - (-r1) + 2), x2 = x2, x3 = (-r1)^2 - (-r
                  -r1) * x2;
                                      s2 := \left\{ x0 = 0, x1 = -\frac{2 x2 (r1^2 + r1 + 1)}{r1^2 + r1 + 2}, x2 = x2, x3 = -r1 x2 \right\}
                                                                                                                                                                                                                                                         (6)
> ## Plain reduction
       ## sSym[3] plain equations - reduction to 14 variables and rank 9
       v1 := eval(Vector(v), sSvm[3]):
       v11 := eval(v1, \{x2 = 1\}):
       Q1 := reduceByLinearEquation(Q, v11):
       nops(indets(Q1)); # 14
       randomRank(Q1); # 9
                                                                                                                     14
                                                                                                                       9
                                                                                                                                                                                                                                                         (7)
> ## sSym[2] plain equations - reduction to 9 variables and rank 8
       v2 := eval(Vector(v), s2):
       v21 := eval(v2, \{x2 = 1\}):
       O2 := reduceByLinearEquation(O1, v21):
       nops(indets(Q2)); #9
       randomRank(Q2); #8
                                                                                                                       9
                                                                                                                                                                                                                                                          (8)
> ## sSym[3] plain equations - reduction to 5 variables and rank 7
      v3 := eval(Vector(v), sSym[1]):
       v31 := eval(v3, \{x0 = 1\}):
       Q3 := reduceByLinearEquation(Q2, v31):
       nops(indets(Q3)); #5
       randomRank(O3); #7
                                                                                                                       5
                                                                                                                                                                                                                                                         (9)
> ## sSym[3]b plain equations - reduction to 2 variables and rank 6
       # The first branch contain two real points. Here we take the second real point.
       sS3b := eval(sSym[1], \{x0=1\}):
       v3b := eval(Vector(v), sS3b):
```

```
v3b := eval(v3b, \{x0 = -1\}):
       simplify(LinearAlgebra[Transpose](v3b).MNEW.v3b); # Verification
       Q4 := reduceByLinearEquation(Q3, v3b):
       nops(indets(Q4)); # 2
       randomRank(Q4); # 6
                                                                                                                    0
                                                                                                                    2
                                                                                                                    6
                                                                                                                                                                                                                                                 (10)
> # Using the real points, we reduce to only two parameters, but we still don't get the uniqueness of
                 the Gram matrix.
       # We now look for ghost solutions
                 # We try to find some principal submatrix Q4S3 of Q4 for which there is a vector v with real
                 coordinates such that vt. Q4S3 \cdot v = 0.
       # This will imply that also vt . Q4 . v = 0 (filling v with zeros in the other entries).
       \# and hence Q4. v = 0, a new linear restriction.
       vv := [3, 4, 7]; # The indexes are chosen so that the system we obtain has real solutions
       # I have tried other triplets and this was the first one I found containing real points.
       Q4S3 := SubMatrix(Q4, vv, vv):
       indets(Q4S3); # {a 0[4, 6], a 0[7, 9]}
       vx := Vector([z0, z1, z2]);
       vxt := LinearAlgebra[Transpose](vx);
      ff := expand(vxt . Q4S3 . vx);
                                                                                                    vv := [3, 4, 7]
                                                                                                 \{a_0_3, a_0_7, a_0_7\}
                                                                                                     vx := \begin{bmatrix} z0 \\ z1 \\ z2 \end{bmatrix}
                                                                                             vxt := \begin{bmatrix} z0 & z1 & z2 \end{bmatrix}
ff := -2zI^2 a_{-0_{7,9}} + 32zI^2rI + 16z0^2 + 12z0zI RootOf(3_Z^4 - 4 + (-4rI)^2)
                                                                                                                                                                                                                                                 (11)
          +4) Z^{2}) a_{2}0_{3.5} + 2z0z1rI^{2}a_{2}0_{7.9} - 6z0z1a_{2}0_{7.9}rI - 2z0z2rI^{2}a_{2}0_{3.5}
           +z0z2r1a_{03,5}-3z1^2r1^5RootOf(3_Z^4-4+(-4r1+4)_Z^2)a_{03,5}
          +\frac{3}{2}zI^{2}rI^{3}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}a_{-0_{7,9}}+6zI^{2}RootOf(3Z^{4}-4+(-4rI+4)Z^{2})^{2}A^{2}+(-4rI+4)Z^{2})^{2}A^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4rI+4)Z^{2}+(-4r
          -4 r1 + 4) Z^{2} r1^{2} a_{03} - 4 z1 z2 r1 a_{03} + 3 z1 z2 RootOf(3 <math>Z^{4} - 4 + (-4 r1) r1 + 4)
```

+4) Z^{2} 2 $a_{3,5} - 3z0z1a_{0,9}r1RootOf(3Z^{4} - 4 + (-4r1 + 4)Z^{2})^{2}$

$$-6z0z1rI^{3}RootOf(3_Z^{4}-4+(-4rI+4)_Z^{2}) a_0_{3,5}+\frac{3}{2}z0z2RootOf(3_Z^{4}-4+(-4rI+4)_Z^{2}) a_0_{3,5}+zI^{2}rI^{3}a_0_{7,9}+zI^{2}rI^{4}a_0_{7,9}$$

$$-4+(-4rI+4)_Z^{2})^{2}rIa_0_{3,5}+zI^{2}rI^{3}a_0_{7,9}+zI^{2}rI^{4}a_0_{7,9}$$

$$-3zI^{2}RootOf(3_Z^{4}-4+(-4rI+4)_Z^{2})^{2}a_0_{7,9}-4zI^{2}a_0_{7,9}rI+2zIz2a_0_{3,5}$$

$$+z2^{2}a_0_{7,9}rI+32z0zIrI^{2}$$

 \rightarrow # We must find the values of (z0, z1, z2) for which ff is 0 for any choice of the

two parameters {a 0[4, 6], a 0[7, 9]} of the matrix Q4.

For this, we compute the coefficient of each of the two parameters and the independent term.

fco := coeffs(ff, indets(Q4));

We get a system of the polynomial equations in (z0, z1, z2) and we solve it using command solve. newS := solve(Equate([fco], [0, 0, 0]));

> # The system has unique solution (up to conjugacy) and one of the conjugated points is real. # We can use it as a new restriction.

```
v10 := [0, 0, z0, z1, 0, 0, z2, 0, 0, 0] :

v10s := eval(v10, newS) :

v10s1 := eval(v10s, \{z1 = 1\}) :

v10sv := Vector(v10s1) :
```

> # We verify that this vector contains real points evalf (allvalues(v10sv));

| 0. | 0. | 0. | 0. |
|---------------|----------------|--------------|--------------|
| 0. | 0. | 0. | 0. |
| -1.587401044 | -1.587401044 | -1.587401052 | -1.587401052 |
| 1. | 1. | 1. | 1. |
| 0. | 0. | 0. | 0. |
| 0. | 0. | 0. | 0. |
| 3.148030321 I | -3.148030321 I | 1.100402874 | -1.100402874 |
| 0. | 0. | 0. | 0. |
| 0. | 0. | 0. | 0. |
| 0. | 0. | 0. | 0. |

(13)

| - | 7 | | | | | | |
|-------|----------|----------------|---|--------------|---|--------------|---|
| | 0. | 0. | | 0. | | 0. | |
| | 0. | 0. | | 0. | | 0. | |
| -1.58 | 37401044 | -1.587401044 | | -1.587401052 | | -1.587401052 | |
| | 1. | 1. | | 1. | | 1. | |
| | 0. | 0. | | 0. | | 0. | |
| | 0. | 0. | , | 0. | , | 0. | , |
| 3.148 | 030321 I | -3.148030321 I | | 1.100402874 | | -1.100402874 | |
| | 0. | 0. | | 0. | | 0. | |
| | 0. | 0. | | 0. | | 0. | |
| | 0. | 0. | | 0. | | 0. | |

| 0. | | 0. | | | | |
|-------------------------------|-----|--|--|--|--|--|
| 0. | | 0. | | | | |
| 0.793700532 + 1.374729686 I | | $0.793700532 + 1.374729686 \mathrm{I}$ | | | | |
| 1. | | 1. | | | | |
| 0. | | 0. | | | | |
| 0. | , | 0. | | | | |
| 0.3318133293 + 0.8268904100 | I | -0.3318133293 — 0.8268904100 I | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0.793700525 + 1.374729637 I | (| 0.793700525 + 1.374729637 I | | | | |
| 1. | | 1. | | | | |
| 0. | | 0. | | | | |
| 0. | , | 0. | | | | |
| 3.608288995 + 1.447928726 I | - | -3.608288995 — 1.447928726 I | | | | |
| 0. 0. | | 0. | | | | |
| | | 0. | | | | |
| 0. | | 0. | | | | |
| 0. |] [| 0. | | | | |
| 0. | | 0. | | | | |
| 0.793700532 + 1.374729686 I | | 0.793700532 + 1.374729686 I | | | | |
| 1. | | 1. | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0.3318133293 + 0.8268904100 I | | -0.3318133293 — 0.8268904100 I | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |
| 0. | | 0. | | | | |

| 0. | 0. | | | | |
|-------------------------------|------------------------------|--|--|--|--|
| 0. | 0. | | | | |
| 0.793700525 — 1.374729637 I | 0.793700525 — 1.374729637 I | | | | |
| 1. | 1. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 3.608288995 — 1.447928726 I | -3.608288995 + 1.447928726 I | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0.793700532 — 1.374729686 I | 0.793700532 - 1.374729686 I | | | | |
| 1. | 1. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0.3318133293 — 0.8268904100 I | -0.3318133293 + 0.8268904100 | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0.793700525 — 1.374729637 I | 0.793700525 — 1.374729637 I | | | | |
| 1. | 1. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 3.608288995 — 1.447928726 I | -3.608288995 + 1.447928726 I | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |
| 0. | 0. | | | | |

```
0.
                                                               0.
                      0.
                                                               0.
       0.793700532 - 1.374729686 I
                                                0.793700532 - 1.374729686 I
                      1.
                                                               1.
                      0.
                                                               0.
                      0.
                                                               0.
      0.3318133293 - 0.8268904100 I
                                              -0.3318133293 + 0.8268904100 I
                      0.
                                                               0.
                      0.
                                                               0.
                      0.
                                                               0.
> # We verify that indeed vt . Q4 \cdot v = 0
   v10svt := LinearAlgebra[Transpose](v10sv):
  ff := expand(v10svt \cdot Q4 \cdot v10sv):
   simplify(ff);
   \# 0 -> We found a new vector that must be in the kernel
                                                 0
                                                                                                       (14)
> # We add this restriction
   Q5 := reduceByLinearEquation(Q4, v10sv):
   nops(indets(Q5)); #0
   randomRank(Q5); #3
                                                 0
                                                 3
                                                                                                       (15)
> # We proved unique solution!
   Q5; # The matrix found
   MNEW; # The original matrix corresponding to the real SOS decomposition
   # The matrix obtained corresponds to the real SOS decomposition.
[40, 0, 0, 0, -8 rI^2 + 4, -16 rI + 16, 0, 0, -16 rI^2 + 8, -16 rI + 16],
    [0, 16 \, rl^2, 16 \, rl, 32, 0, 0, 0, 0, 0, 0]
    [0, 16 \, rl, 16, 16 \, rl^2, 0, 0, 0, 0, 0, 0],
    [0, 32, 16 rI^2, 32 rI, 0, 0, 0, 0, 0, 0]
    [-8 rI^2 + 4, 0, 0, 0, 2, 0, 0, 0, 4, 0],
    [-16 \, rl + 16, 0, 0, 0, 0, 8, 0, 0, 0, 8],
    [0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
    [0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
    [-16 rI^2 + 8, 0, 0, 0, 4, 0, 0, 0, 8, 0],
```

```
 \begin{bmatrix} -16 rI + 16, 0, 0, 0, 0, 8, 0, 0, 0, 8 \end{bmatrix} 
 \begin{bmatrix} [40, 0, 0, 0, -8 rI^2 + 4, -16 rI + 16, 0, 0, -16 rI^2 + 8, -16 rI + 16], \\ [0, 16 rI^2, 16 rI, 32, 0, 0, 0, 0, 0, 0], \\ [0, 16 rI, 16, 16 rI^2, 0, 0, 0, 0, 0, 0], \\ [0, 32, 16 rI^2, 32 rI, 0, 0, 0, 0, 0, 0], \\ [-8 rI^2 + 4, 0, 0, 0, 2, 0, 0, 0, 4, 0], \\ [-16 rI + 16, 0, 0, 0, 0, 8, 0, 0, 0, 8], \\ [0, 0, 0, 0, 0, 0, 0, 0, 0, 0], \\ [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0], \\ [-16 rI^2 + 8, 0, 0, 0, 4, 0, 0, 8, 0], \\ [-16 rI + 16, 0, 0, 0, 0, 8, 0, 0, 0, 8]]
```