```
> currentdir("../rationalSOS");
    (1)
# Example of a strictly positive polynomial that is a SOS over R
  # but not over Q
  # Load "Rational SOS" procedures
  read("rationalSOS.mpl");
  with(rationalSOS);
 # Display tables of any size
  interface(rtablesize = infinity);
                 rationalSOS := module() ... end module
[cancelDenominator, decompositionToMatrix, dimSimplex, evalMat, evalSolution, exactSOS,
  getCoeffs, getDiag, getExtension, getVars, homogenize, isHomogeneous, linIndepRows,
  listSubsets, matrixToPoly, minorsDet, nonRatCoef, numericSolver,
  numericSolverSubmatrix, numericSolverSubmatrixMaxRank,
  numericSolverSubmatrixRoundBefore, polyToMatrix, polyToMatrixVars, primitiveMatrix,
  randomRank, reduceByLinearEquation, reduceByLinearEquationLinear, roundAbs,
  roundMat, roundMatFloat, roundMatToZero, roundToIntMatrix, roundVec, rround,
  rrounde, sedumiCallMaxSpectralNorm, sedumiCallMaxSpectralNormSDP,
  sedumiCallObjective, smallToZero, smallToZeroMatrix, solveSubmatrixGeneral,
  solveSubset, solveToZero, vectorTrace, zeroDetSRows, zeroDetSys, zeroRows]
                              10
                                                                 (2)
\rightarrow matlabConnection := 1;
    ## Use this option if you have a working connection with Matlab. Matlab is used only for
    numerical experiments.
  \#matlabConnection := 0; \# Use this option if you don't have a working connection with
    Matlab.
                       matlabConnection := 1
                                                                 (3)
# Construction of the example
  # 1) A polynomial of degree 4 in 4 variables with no rational
    decomposition. This example was constructed by J. Capco,
    S. Laplagne and C. Scheiderer.
  # We define a polynomial as the sum of three squares in an algebraic
```

```
# extension of degree 3 with generic coefficients.
   mp := t^3 - 2;
   p1 := c1 * t^2 + b1 * t + a1;
   p2 := c2 * t^2 + b2 * t + a2;
   p3 := c3 * t^2 + b3 * t + a3;
  fGeneric := p1^2 + p2^2 + p3^2;
   fGeneric := expand(fGeneric);
                                            mp := t^3 - 2
                                      p1 := -t^2 x 0 + t x 0 + a 1
                                      p2 := -t^2 x 0 - t x 0 + a2
                                       p3 := t^2 x^3 + t x^1 + x^2
       fGeneric := (-t^2x0 + tx0 + a1)^2 + (-t^2x0 - tx0 + a2)^2 + (t^2x3 + tx1 + x2)^2
fGeneric := 2 t^4 x 0^2 + t^4 x 3^2 + 2 t^3 x 1 x 3 - 2 a 1 t^2 x 0 - 2 a 2 t^2 x 0 + 2 t^2 x 0^2 + t^2 x 1^2 + 2 t^2 x 2 x 3
                                                                                                          (4)
     +2 a1 tx0 - 2 a2 tx0 + 2 tx1 x2 + a1^{2} + a2^{2} + x2^{2}
> # We choose arbitrary parameters so that all terms in the resulting
   # expressions for a1 and a2 are multiples of x0, and the degree
   # is reduced after cancellation.
   b2 := -b1; c2 := b2; c1 := b2;
   b1 := x0; b3 := x1; a3 := x2; c3 := x3;
                                              b2 := -x0
                                              c2 := -x0
                                              c1 := -x0
                                              b1 := x0
                                              b3 := x1
                                               a3 := x2
                                               c3 := x3
                                                                                                          (5)
> # We solve the coefficients a1 and a2 so that the polynomial is in O.
  f2 := NormalForm(fGeneric, [mp], plex(a1, a2, x0, x1, x2, x3, t));
  f3 := collect(f2, t);
   lf := CoefficientList(f3, t);
   ss := solve(\{lf[2], lf[3]\}, \{a1, a2\});
f2 := -2 a1 t^2 x 0 - 2 a2 t^2 x 0 + 2 t^2 x 0^2 + t^2 x 1^2 + 2 t^2 x 2 x 3 + 2 a1 t x 0 - 2 a2 t x 0 + 4 t x 0^2
     +2 tx1 x2 + 2 tx3^{2} + a1^{2} + a2^{2} + 4 x1 x3 + x2^{2}
f3 := (-2 a1 x0 - 2 a2 x0 + 2 x0^2 + x1^2 + 2 x2 x3) t^2 + (2 a1 x0 - 2 a2 x0 + 4 x0^2 + 2 x1 x2)
     +2x3^{2}) t + a1^{2} + a2^{2} + 4x1x3 + x2^{2}
lf := [a1^2 + a2^2 + 4x1x3 + x2^2, 2a1x0 - 2a2x0 + 4x0^2 + 2x1x2 + 2x3^2, -2a1x0]
     -2 a2 x0 + 2 x0^{2} + xI^{2} + 2 x2 x3
```

. .

$$ss := \left\{ aI = -\frac{1}{4} \frac{2 x 0^2 - x I^2 + 2 x I x 2 - 2 x 2 x 3 + 2 x 3^2}{x 0}, a2 \right.$$

$$= \frac{1}{4} \frac{6 x 0^2 + x I^2 + 2 x I x 2 + 2 x 2 x 3 + 2 x 3^2}{x 0} \right\}$$
(6)

> # We plug in the solutions found for a1 and a2 and compute the resulting polynomial ssDen := denom(rhs(ss[1]));

p1s := simplify(subs(ss, p1) * ssDen);

p2s := simplify(subs(ss, p2) * ssDen);

p3s := simplify(subs(ss, p3) * ssDen);

$$ssDen := 4 x0$$

$$p1s := -4 t^{2} x 0^{2} + 4 t x 0^{2} - 2 x 0^{2} + x I^{2} - 2 x I x 2 + 2 x 2 x 3 - 2 x 3^{2}$$

$$p2s := -4 t^{2} x 0^{2} - 4 t x 0^{2} + 6 x 0^{2} + x I^{2} + 2 x I x 2 + 2 x 2 x 3 + 2 x 3^{2}$$

$$p3s := 4 (t^{2} x 3 + t x I + x 2) x 0$$
(7)

> # We replace t by the root of X^3 -2

 $plss := subs(\{t = RootOf(X^3 - 2)\}, pls);$

 $p2ss := subs(\{t = RootOf(X^3 - 2)\}, p2s);$ $p3ss := subs(\{t = RootOf(X^3 - 2)\}, p3s);$

$$p1ss := -4x0^{2} RootOf(_Z^{3} - 2)^{2} + 4x0^{2} RootOf(_Z^{3} - 2) - 2x0^{2} + x1^{2} - 2x1x2 + 2x2x3$$

$$p2ss := -4 x0^{2} RootOf(_Z^{3} - 2)^{2} - 4 x0^{2} RootOf(_Z^{3} - 2) + 6 x0^{2} + xI^{2} + 2 xI x2 + 2 x2 x3 + 2 x3^{2}$$

$$p3ss := 4 \left(RootOf(Z^3 - 2)^2 x3 + RootOf(Z^3 - 2) x1 + x2 \right) x0$$
 (8)

> # We compute f and verify that it is has rational coefficients $f := p1ss^2 + p2ss^2 + p3ss^2$; f := simplify(f);

$$f := (-4x0^{2} RootOf(_Z^{3} - 2)^{2} + 4x0^{2} RootOf(_Z^{3} - 2) - 2x0^{2} + xI^{2} - 2xIx2 + 2x2x3$$

$$-2x3^{2})^{2} + (-4x0^{2} RootOf(_Z^{3} - 2)^{2} - 4x0^{2} RootOf(_Z^{3} - 2) + 6x0^{2} + xI^{2}$$

$$+2xIx2 + 2x2x3 + 2x3^{2})^{2} + 16(RootOf(_Z^{3} - 2)^{2}x3 + RootOf(_Z^{3} - 2)xI$$

$$+x2)^{2}x0^{2}$$

$$f := 40 \times 0^4 + 8 \times 0^2 \times I^2 + 32 \times 0^2 \times I \times 2 + 64 \times 0^2 \times I \times 3 + 16 \times 0^2 \times 2^2 + 16 \times 0^2 \times 2 \times 3 + 32 \times 0^2 \times 3^2$$

$$+ 2 \times I^4 + 8 \times I^2 \times 2^2 + 8 \times I^2 \times 2 \times 3 + 16 \times I \times 2 \times 3^2 + 8 \times 2^2 \times 3^2 + 8 \times 3^4$$
(9)

> # We verify that there is no solution with x2 = 0 sols := solve($\{p1ss, p2ss, p3ss, x2\}$);

$$sols := \{x0 = 0, x1 = 0, x2 = 0, x3 = 0\}$$
 (10)

> # Computation of a quadratic form associated to a linear functional in # the dual of the cone of SOS polynomials that vanishes at f

```
# with kernel of small dimension.
   # We construct all monomials of degree 2 and 4
   d := 2;
  polVarsX := [x0, x1, x2, x3];
   varSum := add(polVarsX[i], i = 1 ..nops(polVarsX)):
   md := expand((varSum)^d):
   cfs := coeffs(md, polVarsX, 'ctdX'):
  print("Monomials of degree d: ", ctdX);
   m2d := expand(varSum^{(2*d)}):
   cfs := coeffs(m2d, polVarsX, 'ct2dX'):
   print("Monomials of degree 2d: ", ct2dX);
                                                d := 2
                                    polVarsX := [x0, x1, x2, x3]
       "Monomials of degree d: ", x0^2, x1 x0, x0 x2, x3 x0, x1^2, x1 x2, x1 x3, x2^2, x2 x3, x3^2
"Monomials of degree 2d: ", x0^4, x0^3 x1, x0^3 x2, x0^3 x3, x0^2 x1^2, x0^2 x1 x2, x0^2 x1 x3, x0^2 x2^2,
                                                                                                          (11)
    x0^2 x2 x3, x0^2 x3^2, x0 x1^3, x0 x1^2 x2, x0 x1^2 x3, x0 x1 x2^2, x0 x1 x2 x3, x0 x1 x3^2, x0 x2^3,
    x0x2^2x3, x0x2x3^2, x0x3^3, x1^4, x1^3x2, x1^3x3, x1^2x2^2, x1^2x2x3, x3^2x1^2, x1x2^3, x1x2^2x3,
    x1 x2 x3^{2}, x1 x3^{3}, x2^{4}, x2^{3} x3, x2^{2} x3^{2}, x2 x3^{3}, x3^{4}
> # We construct the linear form that vanishes at all products piss * h
  pListX := [p1ss, p2ss, p3ss]:
   MX := [\ ];
   for j from 1 to nops(pListX) do
    for i from 1 to nops(\lceil ctdX \rceil) do
     p1tX := expand(pListX[j] * ctdX[i]);
     vec := LinearAlgebra[Transpose](getCoeffs(p1tX, [ct2dX]));
     if (nops(MX) = 0) then
      MX := \langle vec \rangle;
     else
       MX := \langle MX, vec \rangle;
     end if;
    end do:
   end do:
   rc := [Dimension(MX)];
   nr := rc[1];
   B := Vector(nr):
   sX := LinearAlgebra[LinearSolve](MX, B):
   varssX := indets(sX);
   nops(varssX); # 8 indeterminates left to solve
                                              MX := [ ]
                                            rc := [30, 35]
                                               nr := 30
                   varssX := \{ tl_2, tl_7, tl_{10}, tl_{20}, tl_{31}, tl_{33}, tl_{34}, tl_{35} \}
                                                                                                          (12)
```

```
> # We define a generic polynomial of degree d with coefficientes q i.
   qIndX := \lceil seq(q\lceil i \rceil, i = 1 ..nops(\lceil ctdX \rceil)) \rceil:
  psaX := add(q[i] * ctdX[i], i = 1 ..nops([ctdX]));
psaX := x0^2 q_1 + x0 x1 q_2 + x0 x2 q_3 + x0 x3 q_4 + x1^2 q_5 + x1 x2 q_6 + x1 x3 q_7 + x2^2 q_8
                                                                                                   (13)
    + x2 x3 q_9 + x3^2 q_{10}
> # The square of psaX and the coefficients
  ps2X := expand(psaX*psaX):
   aaX := getCoeffs(expand(ps2X), [ct2dX]):
> # We compute the form and look for a PSD matrix using SEDUMI
   ewX := LinearAlgebra[Transpose](sX) . aaX:
   ooX := polyToMatrixVars(expand(ewX), qIndX):
> #####
   ## This block can be skipped if Matlab is not connected.
   if (matlabConnection = 1) then
    # Numerical optimization using SEDUMI.
    # Numerically, the matrix has kernel of dimension 6.
    oEval := ooX[1]:
    outA := numericSolverSubmatrixMaxRank(evalf(oEval), "eig"):
    QEval := eval(oEval, Equate([op(outA[2])], outA[3][1..nops([op(outA[2])])])):
    smallToZeroMatrix(evalf(QEval), 8);
    print(eig(QEval));
   end if:
                                    "SEDUMI CALL - eig"
                               "Opening connection with Matlab"
                                    -1.20089925866854\ 10^{-8}
                                   -2.52574800579448\ 10^{-11}
                                   -5.78923235550882 \cdot 10^{-12}
                                    8.03840592758803 \cdot 10^{-11}
                                    1.41951864243287 \cdot 10^{-9}
                                                                                                   (14)
                                    6.58154553229688 10<sup>-9</sup>
                                      0.335198431470853
                                      0.480960966002649
                                      0.535333846973967
                                      2.00597125966693
```

> # Based on the numerical solution, we compute exact values of the # unknowns to construct an exact PSD matrix.

```
# The values obtained by SEDUMI are:
   # t = -0.0000, t = -0.1996, t = 0.1272, t = 0.0000,
   \# t \ 5 = 0.4435, t \ 6 = 0.0724, t \ 7 = 0.0080, t \ 8 = 0.2442
   ## We fix some variables to 0
   oEvalX := eval(ooX[1], \{varssX[1] = 0, varssX[4] = 0, varssX[7] = 0\}):
   ## We fix other variables with positive values
   oEvalX := eval(oEvalX, \{varssX[5] = 1, varssX[8] = 1, varssX[3] = 1/2\}):
> ## We compute exact values for the remaining two variables.
> #####
   ## This block can be skipped if Matlab is not connected.
   ## ##
   # We observe that in the numerical solution, there are two singular
   # principal matrices.
   if (matlabConnection = 1) then
     evalf (Determinant(QEval[5 .. 7, 5 .. 7]));
     evalf (Determinant(QEval[2 .. 3, 2 .. 3]));
    end if:
                                     -4.40990888250781 \cdot 10^{-9}
                                     1.53690277171492 10<sup>-9</sup>
                                                                                                       (15)
> # We compute symbolically the values of the unknowns that make the matrices singular.
   S \ 23 := solve(Determinant(oEvalX[2..3, 2..3]), indets(oEvalX[2..3, 2..3])):
   S 23 1 := simplify(S 23[1]);
S_23_1 := \left\{ t1_7 = -\frac{1}{4} \left( RootOf(_Z^3 - 2)^2 \right) \right\}
                                                                                                       (16)
     +\sqrt{-RootOf(Z^3-2)^2+2RootOf(Z^3-2)+1}-1 RootOf(Z^3-2)
\rightarrow oX \ 567 := eval(oEvalX[5..7,5..7], S \ 23 \ 1):
   S 567 := solve(Determinant(oX 567), indets(oX 567)):
   S 567 2 := simplify(S 567[2]);
S_{567_2} := \left\{ -t1_{33} = \frac{1}{2} \ RootOf(\underline{Z}^3 - 2)^2 \left( \sqrt{-RootOf(\underline{Z}^3 - 2)^2 + 2 \ RootOf(\underline{Z}^3 - 2) + 1} \right) \right\}
> # We apply these substitutions (using simplified expressions equivalent to the results by Maple)
   rA := RootOf(Z^3-2):
   rB := RootOf(Z*rA^2-rA^2+Z^2+1):
   rC := -(1/2) * rA - (1/2) * rB:
\rightarrow oEvalX := eval(oEvalX, \{varssX[2] = rC\}):
   oEvalX := eval(oEvalX, \{varssX[6] = rB\}):
> # No indetermiantes in the resulting oEvalX
   evalf (oEvalX);
```

```
[0.3728809420, 0., 0., 0., 1.231761842, -0.3061607886, -0.7847808106, 0.07609785017,
                                                                                        (18)
   0.1950613368, 0.500000000000],
   [0., 1.231761842, -0.3061607886, -0.7847808106, 0., 0., 0., 0., 0., 0., 0.]
    [0., -0.3061607886, 0.07609785017, 0.1950613368, 0., 0., 0., 0., 0., 0., 0.]
    [0., -0.7847808106, 0.1950613368, 0.5000000000, 0., 0., 0., 0., 0., 0.]
   [1.231761842, 0., 0., 0., 4.899359550, -1.534480445, -1.933328015, 0.580923683,
   0.229158469, 2.174802104],
   [-0.3061607886, 0., 0., 0., -1.534480445, 0.580923683, 0.229158469, -0.2700817033,
   0.101401094, -0.740078950],
   [-0.7847808106, 0., 0., 0., -1.933328015, 0.229158469, 2.174802104, 0.101401094,
    -0.740078950, -0.6371205733],
   [0.07609785017, 0., 0., 0., 0.580923683, -0.2700817033, 0.101401094, 1., -0.124964077,
   0.3096405713],
   [0.1950613368, 0., 0., 0., 0.229158469, 0.101401094, -0.740078950, -0.124964077,
   0.3096405713, 0.],
   1.]]
> # The matrix has kernel of rank 6
   evalf(Eigenvalues(oEvalX));
                                 0.773176732402680
                                  1.95800566763583
                                  7.60642445121149
                                     1.807859692
                                          0.
                                                                                        (19)
                                          0.
                                          0.
                                          0.
                                          0.
                                          0.
> # The kernel of the resulting form
  LX := NullSpace(oEvalX):
  nops(LX);
                                          6
                                                                                        (20)
> # The polynoials in the kernel
  LinearAlgebra[Transpose](simplify(LX[01]));
  LinearAlgebra[Transpose](simplify(LX[02]));
  LinearAlgebra[Transpose](simplify(LX[03]));
  LinearAlgebra[Transpose](simplify(LX[04]));
```

```
LinearAlgebra[Transpose](simplify(LX[05]));
     LinearAlgebra[Transpose](simplify(LX[06]));
  -RootOf(\_Z^3-2)+2,0,0,0,\frac{1}{2}(-2+2RootOf(\_Z^3-2)^2-RootOf(\_Z^3)
         -2) RootOf( ZRootOf( Z^3-2) + Z^2 - RootOf( Z^3-2) + 1))
        (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
        -2 RootOf(Z^3-2), 0, 0, 0, 0, 1
                                   -2 RootOf(_Z^3 - 2)^2 + 1 \quad 0 \quad 0 \quad 0 \quad \frac{1}{2} \quad 0 \quad 0 \quad 0 \quad 1 \quad 0
 \left| RootOf(\underline{Z}^3 - 2)^2 + 2 RootOf(\underline{Z}^3 - 2) + 2 RootOf(\underline{Z}^3 - 2)^2 + \underline{Z}^2 \right|
        - RootOf(\_Z^3 - 2)^2 + 1), 0, 0, 0, -\frac{1}{2} (RootOf(\_Z^3 - 2)^2 RootOf(\_ZRootOf(\_Z^3 - 2)^2)) + (RootOf(\_Z^3 - 2)^2) + (RootOf(\_Z^3 - 
        (-2)^{2} + Z^{2} - RootOf(Z^{3} - 2)^{2} + 1) - 4 + 2 RootOf(Z^{3} - 2)) / (RootOf(Z^{3} - 2)^{2})
        + RootOf(ZRootOf(Z^3 - 2)^2 + Z^2 - RootOf(Z^3 - 2)^2 + 1) - 2 RootOf(Z^3)
        (-2), 0, 1, 0, 0, 0
 \left[-RootOf(\_Z^3-2), 0, 0, 0, -\frac{1}{2}(-2+2 RootOf(\_Z^3-2)^2-RootOf(\_Z^3)\right]
        -2) RootOf(_{Z}RootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1))/
       (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
        -2 RootOf(Z^3-2), 1, 0, 0, 0, 0
[0, -(RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1) + RootOf(Z^3-2))]
        (RootOf(Z^3-2)^2 RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
        -2 RootOf(Z^3-2) RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
        -2 RootOf(Z^3-2)^2+1, 0, 1, 0, 0, 0, 0, 0, 0
[0, -(RootOf(Z^3-2)^2RootOf(ZRootOf(Z^3-2)^2+Z^2-RootOf(Z^3-2)^2+1)+2]
                                                                                                                                                                                      (21)
        -2 RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1) - RootOf(Z^3-2)^2
        (-2) / (RootOf(Z^3-2)^2 RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2)
        +1) - 2 RootOf(Z^3 - 2) RootOf(ZRootOf(Z^3 - 2)^2 + Z^2 - RootOf(Z^3 - 2)^2
         +1) - 2 RootOf(Z^3 - 2)^2 + 1), 1, 0, 0, 0, 0, 0, 0, 0
# 2) We add the second block from an example in the strictly
      # positive border of Sigma(4,4)
```

g is the sum of 4 squares

```
g1 := v0^2 - v3^2;
     g2 := y1^2 - y3^2;
      g3 := y2^2 - y3^2;
      g4 := -y0^2 - y0^3 + y1 - y0^3 + y2 + y0^3 + y3 - y1^3 + y2 + y1^3 + y3 + y2^3 + y3^3 + y2^3 + y3^3 + y2^3 + y3^3 + y3^
      g := g1^2 + g2^2 + g3^2 + g4^2;
                                                                                     g1 := y0^2 - y3^2
                                                                                    g2 := v1^2 - v3^2
                                                                                    g3 := y2^2 - y3^2
                                     g4 := -y0^2 - y0y1 - y0y2 + y0y3 - y1y2 + y1y3 + y2y3
g := (y0^2 - y3^2)^2 + (y1^2 - y3^2)^2 + (y2^2 - y3^2)^2 + (-y0^2 - y0y1 - y0y2 + y0y3 - y1y2)^2
                                                                                                                                                                                                                (22)
          + y1 y3 + y2 y3)<sup>2</sup>
> # We look for a form in the y-monomials that vanishes in the g_i
      d := 2:
      polVarsY := [y0, y1, y2, y3];
      varSumY := add(polVarsY[i], i = 1 ..nops(polVarsY));
      mdY := expand((varSumY)^d);
      cfsY := coeffs(mdY, polVarsY, 'ctdY');
      m2dY := expand(varSumY^{(2*d)});
      cfsY := coeffs(m2dY, polVarsY, 'ct2dY');
                                                                                               d := 2
                                                                        polVarsY := [v0, v1, v2, v3]
                                                                     varSumY := v0 + v1 + v2 + v3
      mdY := y0^{2} + 2 y0 y1 + 2 y0 y2 + 2 y0 y3 + y1^{2} + 2 y1 y2 + 2 y1 y3 + y2^{2} + 2 y2 y3 + y3^{2}
                                                                    cfsY := 1, 2, 2, 2, 1, 2, 2, 1, 2, 1
m2dY := y0^4 + 4y0^3y1 + 4y0^3y2 + 4y0^3y3 + 6y0^2y1^2 + 12y0^2y1y2 + 12y0^2y1y3
          +6 v0^{2} v2^{2} + 12 v0^{2} v2 v3 + 6 v0^{2} v3^{2} + 4 v0 vI^{3} + 12 v0 vI^{2} v2 + 12 v0 vI^{2} v3
          + 12 y0 y1 y2^{2} + 24 y0 y1 y2 y3 + 12 y0 y1 y3^{2} + 4 y0 y2^{3} + 12 y0 y2^{2} y3 + 12 y0 y2 y3^{2}
          +4 v 0 v 3^{3} + v 1^{4} + 4 v 1^{3} v 2 + 4 v 1^{3} v 3 + 6 v 1^{2} v 2^{2} + 12 v 1^{2} v 2 v 3 + 6 v 1^{2} v 3^{2} + 4 v 1 v 2^{3}
          +12 v 1 v 2^{2} v 3 + 12 v 1 v 2 v 3^{2} + 4 v 1 v 3^{3} + v 2^{4} + 4 v 2^{3} v 3 + 6 v 2^{2} v 3^{2} + 4 v 2 v 3^{3} + v 3^{4}
(23)
         4, 1, 4, 6, 4, 1
> # We compute all the restrictions to phi: A4 -> R given
      # by the five polynomials. There are 20 restrictions for each polynomial
     pListY := [g1, g2, g3, g4];
      MY := [ ]:
      for j from 1 to nops(pListY) do
         for i from 1 to nops([ctdY]) do
           p1t := expand(pListY[j] * ctdY[i]);
           vec := LinearAlgebra[Transpose](getCoeffs(p1t, [ct2dY]));
           if (nops(MY) = 0) then
```

```
MY := \langle vec \rangle;
     else
      MY := \langle MY, vec \rangle;
     end if:
    end do:
   end do:
pListY := [y0^2 - y3^2, y1^2 - y3^2, y2^2 - y3^2, -y0^2 - y0y1 - y0y2 + y0y3 - y1y2 + y1y3]
                                                                                            (24)
    +y2y3
> # We solve the system using only these restrictions
  rc := [Dimension(MY)];
  nr := rc[1];
  B := Vector(nr):
  s := LinearAlgebra[LinearSolve](MY, B):
  varssY := indets(s);
  nops(varssY); # Onlt 1 indeterminate left to solve
                                      rc := [40, 35]
                                                                                            (25)
> # We define a generic polynomial of degree d with coefficientes q i.
  qIndY := [seq(qY[i], i=1 ..nops([ctdY]))]:
  psaY := add(qIndY[i] * ctdY[i], i = 1 ..nops([ctdY])):
  ps2Y := expand(psaY*psaY):
  aaY := getCoeffs(expand(ps2Y), [ct2dY]):
> # We compute the associated quadratic form
   ewY := LinearAlgebra[Transpose](s) . aaY:
   ooY := polyToMatrixVars(expand(ewY), qIndY):
   ooMY := ooY[1]:
> # We give value 1 to the only indeterminate and verify that the resulting form is positive definite
   oEvalY := eval(ooMY, \{varssY[1] = 1\});
                 (26)
  Eigenvalues(oEvalY);
```

$$h := (-x2^2 + y2^2);$$

 $p := f + g1^2 + g2^2 + g3^2 + g4^2 + h^2:$
 $expand(p);$

$$h := -x2^2 + y2^2$$

$$40 x0^{4} + 8 x0^{2} x1^{2} + 32 x0^{2} x1 x2 + 64 x0^{2} x1 x3 + 16 x0^{2} x2^{2} + 16 x0^{2} x2 x3 + 32 x0^{2} x3^{2}$$

$$+ 2 x1^{4} + 8 x1^{2} x2^{2} + 8 x1^{2} x2 x3 + 16 x1 x2 x3^{2} + x2^{4} + 8 x2^{2} x3^{2} - 2 x2^{2} y2^{2} + 8 x3^{4}$$

$$+ 2 y0^{4} + 2 y0^{3} y1 + 2 y0^{3} y2 - 2 y0^{3} y3 + y0^{2} y1^{2} + 4 y0^{2} y1 y2 - 4 y0^{2} y1 y3 + y0^{2} y2^{2}$$

$$- 4 y0^{2} y2 y3 - y0^{2} y3^{2} + 2 y0 y1^{2} y2 - 2 y0 y1^{2} y3 + 2 y0 y1 y2^{2} - 6 y0 y1 y2 y3$$

$$+ 2 y0 y1 y3^{2} - 2 y0 y2^{2} y3 + 2 y0 y2 y3^{2} + y1^{4} + y1^{2} y2^{2} - 2 y1^{2} y2 y3 - y1^{2} y3^{2}$$

$$- 2 y1 y2^{2} y3 + 2 y1 y2 y3^{2} + 2 y2^{4} - y2^{2} y3^{2} + 3 y3^{4}$$

$$(28)$$

> # We construct a linear form in the dual of the SOS cone that # vanishes in all the 9 polynomials such that the associated # quadratic form has kernel of minimal rank.

$$d := 2$$
;

polVarsXY := [x0, x1, x2, x3, y0, y1, y2, y3];varSumXY := add(polVarsXY[i], i = 1 ..nops(polVarsXY));

$$d := 2$$

$$polVarsXY := [x0, x1, x2, x3, y0, y1, y2, y3]$$

$$varSumXY := x0 + x1 + x2 + x3 + y0 + y1 + y2 + y3$$
(29)

> # We use a block ordering for the monomials $mdXY := [x0^2, x0*x1, x0*x2, x0*x3, x1^2, x1*x2, x1*x3, x2^2, x2*x3, x3^2, y0^2, y0*y1, y0*y2, y0*y3, y1^2, y1*y2, y1*y3, y2^2, y2*y3, y3^2, x0*y0, x0*y1, x0*y2, x0*y3, x1*y0, x1*y1, x1*y2, x1*y3, x2*y0, x2*y1, x2*y2, x2*y3, x3*y0, x3*y1, x3*y2, x3*y3]$

```
ctdXY := op(mdXY):
      print("Monomials of degree d: ", ctdXY);
      m2dXY := expand(varSumXY^{\wedge}(2*d)):
      cfs := coeffs(m2dXY, polVarsXY, 'ct2dXY'):
      print("Monomials of degree 2d: ", ct2dXY);
"Monomials of degree d: ", x0^2, x1 x0, x0 x2, x3 x0, x1^2, x1 x2, x1 x3, x2^2, x2 x3, x3^2, y0^2, y0 y1,
        v0 v2, v0 v3, v1^2, v1 v2, v1 v3, v2^2, v2 v3, v3^2, x0 v0, x0 v1, x0 v2, x0 v3, x1 v0, x1 v1, x1 v2,
        x1 y3, x2 y0, x2 y1, x2 y2, x2 y3, x3 y0, x3 y1, x3 y2, x3 y3
"Monomials of degree 2d: ", x0^4, x0^3 x1, x0^3 x2, x0^3 x3, x0^3 y0, x0^3 y1, x0^3 y2, x0^3 y3, x0^2 x1<sup>2</sup>,
                                                                                                                                                                                                                           (30)
        x0^{2} x1 x2, x0^{2} x1 x3, x0^{2} x1 y0, x0^{2} x1 y1, x0^{2} x1 y2, x0^{2} x1 y3, x0^{2} x2^{2}, x0^{2} x2 x3, x0^{2} x2 y0,
        x0^2 x2 y1, x0^2 x2 y2, x0^2 x2 y3, x0^2 x3^2, x0^2 x3 y0, x0^2 x3 y1, x0^2 x3 y2, x0^2 x3 y3, x0^2 y0^2,
        x0^2 y0 y1, x0^2 y0 y2, x0^2 y0 y3, x0^2 y1^2, x0^2 y1 y2, x0^2 y1 y3, x0^2 y2^2, x0^2 y2 y3, x0^2 y3^2,
        x0x1^{3}, x0x1^{2}x2, x0x1^{2}x3, x0x1^{2}y0, x0x1^{2}y1, x0x1^{2}y2, x0x1^{2}y3, x0x1x2^{2}, x0x1x2x3,
        x0 \times 1 \times 2 \times 90, x0 \times 1 \times 2 \times 1, x0 \times 1 \times 2 \times 2, x0 \times 1 \times 2 \times 3, x0 \times 1 \times 3^2, x0 \times 1 \times 3 \times 90, x0 \times 1 \times 3 \times 1,
        x0 \times 1 \times 3 \times 2, x0 \times 1 \times 3 \times 3, x0 \times 1 \times 0^2, x0 \times 1 \times 0 \times 1, x0 \times 1 \times 0 \times 2, x0 \times 1 \times 0 \times 3, x0 \times 1 \times 1^2,
        x0 \times 1 \times 1 \times 2, x0 \times 1 \times 1 \times 2, x0 \times 2
        x0 x2^{2} y1, x0 x2^{2} y2, x0 x2^{2} y3, x0 x2 x3^{2}, x0 x2 x3 y0, x0 x2 x3 y1, x0 x2 x3 y2, x0 x2 x3 y3,
        x0 x2 y0^{2}, x0 x2 y0 y1, x0 x2 y0 y2, x0 x2 y0 y3, x0 x2 y1^{2}, x0 x2 y1 y2, x0 x2 y1 y3, x0 x2 y2^{2},
        x0 x2 y2 y3, x0 x2 y3^{2}, x0 x3^{3}, x0 x3^{2} y0, x0 x3^{2} y1, x0 x3^{2} y2, x0 x3^{2} y3, x0 x3 y0^{2},
        x0 x3 y0 y1, x0 x3 y0 y2, x0 x3 y0 y3, x0 x3 y1^2, x0 x3 y1 y2, x0 x3 y1 y3, x0 x3 y2^2
        x0 x3 y2 y3, x0 x3 y3^{2}, x0 y0^{3}, x0 y0^{2} y1, x0 y0^{2} y2, x0 y0^{2} y3, x0 y0 y1^{2}, x0 y0 y1 y2,
        x0 y0 y1 y3, x0 y0 y2^{2}, x0 y0 y2 y3, x0 y0 y3^{2}, x0 y1^{3}, x0 y1^{2} y2, x0 y1^{2} y3, x0 y1 y2^{2},
        x0 y1 y2 y3, x0 y1 y3^{2}, x0 y2^{3}, x0 y2^{2} y3, x0 y2 y3^{2}, x0 y3^{3}, x1^{4}, x1^{3} x2, x1^{3} x3, x1^{3} y0, x1^{3} y1,
        x1^{3}y2, x1^{3}y3, x1^{2}x2^{2}, x1^{2}x2x3, x1^{2}x2y0, x1^{2}x2y1, x1^{2}x2y2, x1^{2}x2y3, x3^{2}x1^{2}, x1^{2}x3y0,
        x1^2 x3 y1, x1^2 x3 y2, x1^2 x3 y3, x1^2 y0^2, x1^2 y0 y1, x1^2 y0 y2, x1^2 y0 y3, x1^2 y1^2, x1^2 y1 y2,
        x1^{2}y1y3, x1^{2}y2^{2}, x1^{2}y2y3, x1^{2}y3^{2}, x1x2^{3}, x1x2^{2}x3, x1x2^{2}y0, x1x2^{2}y1, x1x2^{2}y2,
        x1 x2^{2} y3, x1 x2 x3^{2}, x1 x2 x3 y0, x1 x2 x3 y1, x1 x2 x3 y2, x1 x2 x3 y3, x1 x2 y0^{2}, x1 x2 y0 y1,
        x1 x2 y0 y2, x1 x2 y0 y3, x1 x2 y1^2, x1 x2 y1 y2, x1 x2 y1 y3, x1 x2 y2^2, x1 x2 y2 y3, x1 x2 y3^2,
        x1 x3^3, x1 x3^2 y0, x1 x3^2 y1, x1 x3^2 y2, x1 x3^2 y3, x1 x3 y0^2, x1 x3 y0 y1, x1 x3 y0 y2,
        x1 x3 y0 y3, x1 x3 y1^{2}, x1 x3 y1 y2, x1 x3 y1 y3, x1 x3 y2^{2}, x1 x3 y2 y3, x1 x3 y3^{2}, x1 y0^{3},
        x1 y0^{2} y1, x1 y0^{2} y2, x1 y0^{2} y3, x1 y0 y1^{2}, x1 y0 y1 y2, x1 y0 y1 y3, x1 y0 y2^{2}, x1 y0 y2 y3,
        x1 y0 y3^{2}, x1 y1^{3}, x1 y1^{2} y2, x1 y1^{2} y3, x1 y1 y2^{2}, x1 y1 y2 y3, x1 y1 y3^{2}, x1 y2^{3}, x1 y2^{2} y3,
        x1 v2 v3^2, x1 v3^3, x2^4, x2^3 x3, x2^3 v0, x2^3 v1, x2^3 v2, x2^3 v3, x2^2 x3^2, x2^2 x3 v0, x2^2 x3 v1,
        x2^2 x3 y2, x2^2 x3 y3, x2^2 y0^2, x2^2 y0 y1, x2^2 y0 y2, x2^2 y0 y3, x2^2 y1^2, x2^2 y1 y2, x2^2 y1 y3,
        x2^{2}v2^{2}, x2^{2}v2v3, x2^{2}v3^{2}, x2x3^{3}, x2x3^{2}v0, x2x3^{2}v1, x2x3^{2}v2, x2x3^{2}v3, x2x3v0^{2},
```

```
x2 x3 y0 y1, x2 x3 y0 y2, x2 x3 y0 y3, x2 x3 y1^2, x2 x3 y1 y2, x2 x3 y1 y3, x2 x3 y2^2,
    x2 x3 y2 y3, x2 x3 y3^{2}, x2 y0^{3}, x2 y0^{2} y1, x2 y0^{2} y2, x2 y0^{2} y3, x2 y0 y1^{2}, x2 y0 y1 y2,
    x2\ y0\ y1\ y3,\ x2\ y0\ y2^2,\ x2\ y0\ y2\ y3,\ x2\ y0\ y3^2,\ x2\ y1^3,\ x2\ y1^2\ y2,\ x2\ y1^2\ y3,\ x2\ y1\ y2^2,
    x2 y1 y2 y3, x2 y1 y3^{2}, x2 y2^{3}, x2 y2^{2} y3, x2 y2 y3^{2}, x2 y3^{3}, x3^{4}, x3^{3} y0, x3^{3} y1, x3^{3} y2, x3^{3} y3,
    x3^{2}v0^{2}, x3^{2}v0v1, x3^{2}v0v2, x3^{2}v0v3, x3^{2}v1^{2}, x3^{2}v1v2, x3^{2}v1v3, x3^{2}v2^{2}, x3^{2}v2v3,
    x3^{2}y3^{2}, x3y0^{3}, x3y0^{2}y1, x3y0^{2}y2, x3y0^{2}y3, x3y0y1^{2}, x3y0y1y2, x3y0y1y3, x3y0y2^{2},
    x3 v0 v2 v3, x3 v0 v3^{2}, x3 v1^{3}, x3 v1^{2} v2, x3 v1^{2} v3, x3 v1 v2^{2}, x3 v1 v2 v3, x3 v1 v3^{2}, x3 v2^{3},
    x3y2^2y3, x3y2y3^2, x3y3^3, y0^4, y0^3y1, y0^3y2, y0^3y3, y0^2y1^2, y0^2y1y2, y0^2y1y3, y0^2y2^2,
    y0^{2}y2y3, y0^{2}y3^{2}, y0y1^{3}, y0y1^{2}y2, y0y1^{2}y3, y0y1y2^{2}, y0y1y2y3, y0y1y3^{2}, v0y2^{3},
    y0y2^2y3, y0y2y3^2, y0y3^3, y1^4, y1^3y2, y1^3y3, y1^2y2^2, y1^2y2y3, y1^2y3^2, y1y2^3, y1y2^2y3,
    v1 v2 v3<sup>2</sup>, v1 v3<sup>3</sup>, v2<sup>4</sup>, v2<sup>3</sup> v3, v2<sup>2</sup> v3<sup>2</sup>, v2 v3<sup>3</sup>, v3<sup>4</sup>
\rightarrow # We compute all the restrictions to phi: A4 -> R given
   # by the five polynomials. There are 20 restrictions for each polynomial
   pList := [p1ss, p2ss, p3ss, g1, g2, g3, g4, h];
   MXY := [\ ]:
   for j from 1 to nops(pList) do
     for i from 1 to nops([ctdXY]) do
      p1t := expand(pList[j] * ctdXY[i]);
      vec := LinearAlgebra[Transpose](getCoeffs(p1t, [ct2dXY]));
      if (nops(MXY) = 0) then
       MXY := \langle vec \rangle;
      else
       MXY := \langle MXY, vec \rangle;
      end if:
     end do:
   end do:
pList := \left[ -4x0^2 RootOf(Z^3 - 2)^2 + 4x0^2 RootOf(Z^3 - 2) - 2x0^2 + xI^2 - 2xIx2 \right]
                                                                                                                  (31)
     +2x^2x^3-2x^3^2, -4x0^2 RootOf(z^3-2)^2-4x0^2 RootOf(z^3-2) +6x0^2+xI^2
     +2x1x2+2x2x3+2x3^{2}, 4 (RootOf(Z^{3}-2)^{2}x3+RootOf(Z^{3}-2)x1+x2)x0,
    v0^2 - v3^2, v1^2 - v3^2, v2^2 - v3^2, -v0^2 - v0, v1 - v0, v2 + v0, v3 - v1, v2 + v1, v3 + v2, v3 - x2^2
> # We solve the system using only these restrictions
   rc := [Dimension(MXY)];
   nr := rc[1];
   B := Vector(nr):
   sXY := LinearAlgebra[LinearSolve](MXY, B):
   varssXY := indets(sXY);
   nops(varssXY); # 70 indeterminates left to solve
                                              rc := [288, 330]
                                                  nr := 288
```

```
varssXY := \{ t3_2, t3_5, t3_6, t3_7, t3_8, t3_{11}, t3_{12}, t3_{13}, t3_{14}, t3_{15}, t3_{22}, t3_{23}, t3_{24}, t3_{25}, t3_
          \_t3_{26}, \_t3_{29}, \_t3_{30}, \_t3_{32}, \_t3_{33}, \_t3_{35}, \_t3_{52}, \_t3_{53}, \_t3_{54}, \_t3_{57}, \_t3_{58}, \_t3_{60}, \_t3_{61}, \_t3_{63},
           \_t3_{86}, \_t3_{93}, \_t3_{94}, \_t3_{96}, \_t3_{97}, \_t3_{99}, \_t3_{115}, \_t3_{177}, \_t3_{178}, \_t3_{180}, \_t3_{181}, \_t3_{183}, \_t3_{199},
           \_t3_{226}, \_t3_{228}, \_t3_{229}, \_t3_{230}, \_t3_{233}, \_t3_{234}, \_t3_{236}, \_t3_{237}, \_t3_{239}, \_t3_{255}, \_t3_{256}, \_t3_{259}, \_t3_{260},
           \_t3_{261}, \_t3_{262}, \_t3_{263}, \_t3_{264}, \_t3_{265}, \_t3_{268}, \_t3_{269}, \_t3_{271}, \_t3_{272}, \_t3_{274}, \_t3_{275}, \_t3_{290}, \_t3_{291},
           _{t3_{294}}, _{t3_{295}}, _{t3_{330}}
                                                                                                                           70
                                                                                                                                                                                                                                                                   (32)
> # We give values to the unknowns so that the form is PSD
        qIndXY := \lceil seq(qXY \lceil i \rceil, i = 1 ..nops(\lceil ctdXY \rceil)) \rceil:
        psaXY := add(qIndXY[i] * ctdXY[i], i = 1 ..nops([ctdXY])):
       ps2XY := expand(psaXY * psaXY):
       aaXY := getCoeffs(expand(ps2XY), [ct2dXY]):
> # We compute the associated form
        ewXY := LinearAlgebra[Transpose](sXY) . aaXY :
        ooXY := polyToMatrixVars(expand(ewXY), qIndXY):
        ooMXY := ooXY[1]:
\rightarrow # We copy O x and O y in O xy
        s1 := solve(Equate(ooMXY[1..10, 1..10], oEvalX)):
        oEvalXY := eval(ooMXY, \{ooMXY[20, 20] = 6\}):
        oEvalXY := eval(oEvalXY, s1):
> # We replace all the remaining variables by 0
        s2 := solve(Equate(\lceil op(indets(oEvalXY)) \rceil, ZeroVector(nops(indets(oEvalXY))))):
        oEvalXY := eval(oEvalXY, s2):
> # We verify that the matrix is positive semidefinite and has kernel
        # of rank 14.
        evalf(Eigenvalues(oEvalXY));
```

```
0.551105095682439
1.16935580263953
7.06066760967802
0.275755761932722
0.600977973484481
7.01383051958280
   1.807859692
0.275620309240295
0.589700596013643
3.01830865108949
7.00693469865657
1.72628035929815
6.66336637618740
7.83746821087346
31.1104919036410
   0.152195701
   0.076097850
   0.076097850
        7.
        7.
        7.
        7.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
        0.
```

(33)

```
> # The kernel is generated by 14 polynomials
                 L := NullSpace(oEvalXY):
                 nops(L);
                                                                                                                                                                                                                                                                          14
> # The polynoials in the kernel
                 simplify(L[01]) . convert(mdXY, Vector);
                 simplify(L[02]) . convert(mdXY, Vector);
                 simplify(L[03]) . convert(mdXY, Vector);
                 simplify(L[04]) . convert(mdXY, Vector);
                 simplify(L[05]) . convert(mdXY, Vector);
                simplify(L[06]) . convert(mdXY, Vector);
                 simplify(L[07]) . convert(mdXY, Vector);
                 simplify(L[08]) . convert(mdXY, Vector);
                 simplify(L[09]) . convert(mdXY, Vector);
                 simplify(L[10]) . convert(mdXY, Vector);
                simplify(L[11]) . convert(mdXY, Vector);
                 simplify(L[12]) . convert(mdXY, Vector);
                 simplify(L[13]) . convert(mdXY, Vector);
                 simplify(L[14]) . convert(mdXY, Vector);
 (-RootOf(Z^3-2)+2) \times 0^2 + \frac{1}{2} ((-2+2RootOf(Z^3-2)^2-RootOf(Z^3)^2) + \frac{1}{2} ((-2+2RootOf(Z^3-2)^2-RootOf(Z^3)^2) + \frac{1}{2} ((-2+2RootOf(Z^3-2)^2)^2 
                          -2) RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)) xI^2)
                        (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
                          -2 RootOf(Z^3-2) + x3^2
                                                                                                                               \left(-2 RootOf(Z^3-2)^2+1\right) x\theta^2+\frac{1}{2} xI^2+x2 x3
 (RootOf(\_Z^3-2)^2+2RootOf(\_Z^3-2)+2RootOf(\_ZRootOf(\_Z^3-2)^2+\_Z^2)
                          -RootOf(\underline{Z}^3-\underline{2})^2+\underline{1}))x\theta^2-\frac{1}{2}\left(\left(RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{2})^2RootOf(\underline{Z}^3-\underline{Z}^3-\underline{Z})^2RootOf(\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-\underline{Z}^3-
                          (-2)^2 + Z^2 - RootOf((Z^3 - 2)^2 + 1) - 4 + 2 RootOf((Z^3 - 2)) xl^2)
                        (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
                          -2 RootOf(Z^3-2) + x1 x3
  -x0^2 RootOf(Z^3-2) - \frac{1}{2} ((-2 + 2 RootOf(Z^3-2)^2 - RootOf(Z^3-2)^2) - RootOf(Z^3-2)^2 - RootOf
                          -2) RootOf(_{Z}RootOf(_{Z}^{3}-2)^{2}+Z^{2}-RootOf(_{Z}^{3}-2)^{2}+1))xI^{2})
                        (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
                           -2 RootOf(Z^3-2) + x1 x2
  -\left(\left(RootOf\left(\_ZRootOf\left(\_Z^3-2\right)^2+\_Z^2-RootOf\left(\_Z^3-2\right)^2+1\right)+RootOf\left(\_Z^3-2\right)\right)x1x0\right)\Big/\left(RootOf\left(\_Z^3-2\right)^2RootOf\left(\_ZRootOf\left(\_Z^3-2\right)^2+\_Z^2\right)
```

(34)

$$-RootOf(_Z^3-2)^2+1)-2RootOf(_Z^3-2)RootOf(_ZRootOf(_Z^3-2)^2+_Z^2$$

$$-RootOf(_Z^3-2)^2+1)-2RootOf(_Z^3-2)^2+1)+x3x0$$

$$-((RootOf(_Z^3-2)^2RootOf(_ZRootOf(_Z^3-2)^2+_Z^2-RootOf(_Z^3-2)^2+1)+2$$

$$-2RootOf(_ZRootOf(_Z^3-2)^2+_Z^2-RootOf(_Z^3-2)^2+1)-RootOf(_Z^3$$

$$-2))x1x0)/(RootOf(_Z^3-2)^2RootOf(_ZRootOf(_Z^3-2)^2+_Z^2$$

$$-RootOf(_Z^3-2)^2+1)-2RootOf(_Z^3-2)RootOf(_ZRootOf(_Z^3-2)^2+_Z^2$$

$$-RootOf(_Z^3-2)^2+1)-2RootOf(_Z^3-2)^2+1)+x0x2$$

$$x3y0+x3y1$$

$$x1y0+x1y1$$

$$x0y0+x0y1$$

$$-x2^2+y3^2$$

$$-x2^2+y3^2$$

$$-x2^2+y2^2$$

$$-x2^2+y1^2$$

$$-x2^2+y0^2$$
(35)

> # We can verify that there is no polynomails in the kernel with rational coefficients that has non-zero coefficient in $x0^2$.