- > # Uncomment and set the path to rationalSOS.mpl file #currentdir("C:/Users/User/rationalSOS"); # Load "Rational SOS" procedures read("rationalSOS.mpl") : with(rationalSOS); "Opening connection with Matlab" [RoundMat, RoundVec, SOS, evalMat, getDiag, matrixToPoly, numericSolver, polyToMatrix, **(1)** randomRank, reduceByLinearEquation, vectorTrace, zeroDetSRows, zeroRows] > # Display tables of any size interface(rtablesize = infinity); 10 **(2)** # Example 2.1 in [1] # We define a polynomial f as the sum of two squares. $p1 := x^2 + 3 * x * y - 5 * x * z + 2 z^2;$ $p2 := 3 x^2 - 2 x^2 + y^2 + 5 y^2;$ $f := expand(p1^2 + p2^2);$ $p1 := x^2 + 3 x y - 5 x z + 2 z^2$ $p2 := 3 x^2 - 2 x z + 5 y^2 + y z$ $f := 10 x^4 + 6 x^3 y - 22 x^3 z + 39 x^2 y^2 - 24 x^2 y z + 33 x^2 z^2 - 20 x y^2 z + 8 x y z^2 - 20 x z^3$ **(3)** $+25v^4+10v^3z+v^2z^2+4z^4$ > # Compute the matrix Q associated to the problem Q, QVars, v := polyToMatrix(f);Q, QVars, v :=**(4)** -11 $a_{01,4}$ -12 $-a_{02,3}$ $a_{01,6}$ 3 $39 - 2 a_{01,4}$ $a_{02,3}$ 0 $-10 - a_{03,4}$ $4 - a_{03,5}$ $\{a_0\theta_{1,4}, a_0\theta_{1,6}, a_0\theta_{2,3}, a_0\theta_{3,4}, a_0\theta_{3,5}, a_0\theta_{4,6}\}, [x^2, xy, xz, y^2, yz, z^2]$
- > # Dimension and rank of Q
 nops(indets(Q));
 randomRank(Q);

➤ # Computes numerically a SDP solution using SEDUMI xVars, xSol := numericSolver(Q);

"SEDUMI CALL"

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SeDuMi 1.3 by AdvOL, 2005-2008 and Jos F. Sturm, 1998-2003.
Alg = 2: xz-corrector, Adaptive Step-Differentiation, theta =
0.250, beta = 0.500
eqs m = 7, order n = 7, dim = 37, blocks = 2
nnz(A) = 18 + 0, nnz(ADA) = 49, nnz(L) = 28
                   gap delta rate t/tP* t/tD*
                                                      feas cq
        b*v
cg prec 0:
                 1.79E+02 0.000
  1 : -1.48E+01 4.27E+01 0.000 0.2379 0.9000 0.9000
                                                      0.56
1 4.4E+00
  2 : -1.50E+00 1.06E+01 0.000 0.2489 0.9000 0.9000
                                                      1.81
                                                            1
1 1.3E+00
  3 : -3.52E-01 1.97E+00 0.000 0.1854 0.9000 0.9000
                                                      1.21
                                                            1
1 8.6E-01
  4: -1.05E-01 4.05E-01 0.000 0.2058 0.9000 0.9000
                                                      1.04
                                                            1
  8.7E-01
  5 : -5.49E-03 1.66E-02 0.000 0.0410 0.9900 0.9900
                                                      1.00
                                                           1
1 9.7E-01
 6: -1.45E-04 5.54E-04 0.172 0.0333 0.9900 0.9901
                                                      1.00
                                                           1
1 3.0E-01
 7: -4.81E-06 2.71E-05 0.000 0.0488 0.9903 0.9900
                                                      1.02
                                                            1
1 1.4E-02
  8 : -1.09E-06 7.00E-06 0.058 0.2587 0.9000 0.9150
                                                      1.02
2 3.6E-03
  9: -1.77E-07 1.15E-06 0.000 0.1643 0.9035 0.9000
                                                      1.02
                                                            3
  5.6E-04
10 : -2.92E-08 1.96E-07 0.000 0.1707 0.9005 0.9000
                                                      1.02
                                                            3
4 9.3E-05
11 : -4.22E-09 3.41E-08 0.000 0.1738 0.9000 0.9015
                                                      1.03 5
6 1.6E-05
Run into numerical problems.
iter seconds digits
                         C*X
                                           b*y
            4.1 2.3673831258e-08 -4.2205112054e-09
       0.1
|Ax-b| = 1.3e-09, [Ay-c] + = 1.1E-09, |x| = 9.4e-01, |y| = 1.1E-09
1.5e + 01
Detailed timing (sec)
   Pre
                IPM
                             Post
2.999E-02
             7.800E-02
                         1.600E-02
Max-norms: ||b||=1, ||c|| = 39,
Cholesky |add|=0, |skip| = 1, ||L.L|| = 53071.6.
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$$xVars, xSol := \{a_\theta_{1, 4}, a_\theta_{1, 6}, a_\theta_{2, 3}, a_\theta_{3, 4}, a_\theta_{3, 5}, a_\theta_{4, 6}\},$$

$$xVars, xSol := \{a_\theta_{1, 4}, a_\theta_{1, 6}, a_\theta_{2, 3}, a_\theta_{3, 4}, a_\theta_{3, 5}, a_\theta_{4, 6}\},$$

$$0.875865927183106$$

$$1.42553771817733$$

$$4.22051120541738 10^{-9}$$

→ # Solution matrix and eigenvalues
 Qsol := evalMat(Q, xVars, xSol) :
 eig(Qsol);

> # Four positive eigenvalues and two approximate zeros

$$sSym := solve(\{f = 0, diff(f, x) = 0, diff(f, y) = 0, diff(f, z) = 0\});$$

$$sSym := \left\{ x = x, y = RootOf(50 _Z^{4} + 28 _Z^{3} - _Z^{2} + 23 _Z - 8) x, z \right.$$

$$= \frac{1}{46} x \left(50 RootOf(50 _Z^{4} + 28 _Z^{3} - _Z^{2} + 23 _Z - 8)^{3} + 128 RootOf(50 _Z^{4} + 28 _Z^{3} - _Z^{2} + 23 _Z - 8)^{2} + 25 RootOf(50 _Z^{4} + 28 _Z^{3} - _Z^{2} + 23 _Z - 8) + 73) \right\}$$

$$+ 28 _Z^{3} - _Z^{2} + 23 _Z - 8)^{2} + 25 RootOf(50 _Z^{4} + 28 _Z^{3} - _Z^{2} + 23 _Z - 8) + 73) \right\}$$

> ## sSym[1] plain equation v0 := eval(Vector(v), sSym); $v01 := eval(v0, \{x = 1\}) :$

$$v\theta := \left[\begin{bmatrix} x^2 \end{bmatrix}, \\ x^2 RootOf(50 _Z^4 + 28 _Z^3 - _Z^2 + 23 _Z - 8) \right],$$

```
 \left[ \frac{1}{46} x^{2} \left( 50 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{3} + 128 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8) + 73 \right) \right] 
 \left[ \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} x^{2} \right], 
 \left[ \frac{1}{46} \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8) x^{2} \left( 50 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8) \right) x^{2} \left( 50 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8) + 73 \right) \right], 
 \left[ \frac{1}{2116} x^{2} \left( 50 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{3} + 128 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{3} + 128 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{3} + 128 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{3} + 128 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z}^{2} + 23 \underline{Z} - 8)^{2} + 25 \operatorname{RootOf} (50 \underline{Z}^{4} + 28 \underline{Z}^{3} - \underline{Z
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> # We verify that it satisfies the condition vt.Q.v = 0, which must always # be satisfied for real solutions simplify(LinearAlgebra[Transpose](v01).Q.v01);

0 (10)

> # We reduce the dimension Q1 := reduceByLinearEquation(Q, v01) : nops(indets(Q1));randomRank(Q1);

We reduced the dimension to 5 but we need to reduce to 4,

because the numerical solution had 2 null eigenvalues

35(11)

 $\gt{v01t} := vectorTrace(v01)$:

(12)

$$v01t := \begin{bmatrix} 4 \\ -\frac{14}{25} \\ \frac{53}{10} \\ \frac{221}{625} \\ -\frac{396}{125} \\ \frac{1209}{100} \end{bmatrix}$$
 (12)

 \rightarrow # We took the trace, so the equation vt.Q.v=0 may not be satisfied simplify(LinearAlgebra[Transpose](v01t).Q.v01t);

$$\frac{17367}{125} + \frac{1376}{625} a_{-}\theta_{1,4} + \frac{2426}{125} a_{-}\theta_{2,3} + \frac{2027}{50} a_{-}\theta_{1,6} + \frac{1}{5} a_{-}\theta_{3,4} - \frac{501}{25} a_{-}\theta_{3,5} - \frac{14403}{1250} a_{-}\theta_{4,6}$$
(13)

> Q1 := reduceByLinearEquation(Q, v01t) : nops(indets(Q1));randomRank(Q1);

- \nearrow # The problem was completely solved, no need to call the numerical solver. \searrow L, DD, Lt, fNew, a, p := matrixToPoly(Q1, v) : \nearrow fNew;

$$\begin{cases}
 fNew; \\
 10 \left(x^2 + \frac{3}{10} xy - \frac{11}{10} xz + \frac{3}{2} y^2 + \frac{3}{10} yz + \frac{1}{5} z^2 \right)^2 + \frac{81}{10} \left(xy - \frac{13}{9} xz - \frac{5}{9} y^2 - \frac{1}{9} yz + \frac{2}{3} z^2 \right)^2
\end{cases}$$
(15)