```
# Example of a strictly positive polynomial that is a SOS over R
 # but not over O
 # Load "Rational SOS" procedures
 read("rationalSOS.mpl");
 with(rationalSOS);
 # Display tables of any size
 interface(rtablesize = infinity);
                    "Opening connection with Matlab"
                 rationalSOS := module() ... end module
[cancelDenominator, decompositionToMatrix, dimSimplex, evalMat, evalSolution, exactSOS,
  getCoeffs, getDiag, getExtension, getVars, homogenize, isHomogeneous, linIndepRows,
  listSubsets, matrixToPoly, minorsDet, nonRatCoef, numericSolver,
  numericSolverSubmatrix, numericSolverSubmatrixMaxRank,
  numericSolverSubmatrixRoundBefore, polyToMatrix, polyToMatrixVars, primitiveMatrix,
  randomRank, reduceByLinearEquation, reduceByLinearEquationLinear, roundAbs,
  roundMat, roundMatFloat, roundMatToZero, roundToIntMatrix, roundVec, rround,
  rrounde, sedumiCallMaxSpectralNorm, sedumiCallMaxSpectralNormSDP,
  sedumiCallObjective, smallToZero, smallToZeroMatrix, solveSubmatrixGeneral,
  solveSubset, solveToZero, vectorTrace, zeroDetSRows, zeroDetSys, zeroRows]
                                                                  (1)
# Construction of the example
 # 1) A polynomial of degree 4 in 4 variables with no rational
 # decomposition. This example was constructed by J. Capco,
 # S. Laplagne and C. Scheiderer.
 # We define a polynomial as the sum of three squares in an algebraic
 # extension of degree 3 with generic coefficients.
 mp := t^3 - 2;
 p1 := c1 * t^2 + b1 * t + a1;
 p2 := c2 * t^2 + b2 * t + a2;
 p3 := c3 * t^2 + b3 * t + a3;
 fGeneric := p1^2 + p2^2 + p3^2;
 fGeneric := expand(fGeneric);
```

$$mp := \hat{i} - 2$$

$$p1 := c1 \hat{i}^2 + b1 t + a1$$

$$p2 := c2 \hat{i}^2 + b2 t + a2$$

$$p3 := c3 \hat{i}^2 + b3 t + a3$$

$$fGeneric := (c1 \hat{i}^2 + b1 t + at)^2 + (c2 \hat{i}^2 + b2 t + a2)^2 + (c3 \hat{i}^2 + b3 t + a3)^2$$

$$fGeneric := c1^2 \hat{i}^4 + c2^2 \hat{i}^4 + c3^2 \hat{i}^4 + 2b1 c1 \hat{i}^2 + 2b2 c2 \hat{i}^2 + 2b3 c3 \hat{i}^3 + 2a1 c1 \hat{i}^2 + 2a2 c2 \hat{i}^2$$

$$+ 2a3 c3 \hat{i}^2 + b1^2 \hat{i}^2 + b2^2 \hat{i}^2 + b3^2 \hat{i}^2 + 2a1 b1 t + 2a2 b2 t + 2a3 b3 t + ai^2 + a2^2$$

$$+ a3^2$$

$$= \text{#We choose arbitrary parameters so that all terms in the resulting}$$
#expressions for al and a2 are multiples of x0, and the degree
#is reduced after cancellation.
$$b2 := -b1; c2 := b2; c1 := b2;$$

$$b1 := x0; b3 := x1; a3 := x2; c3 := x3;$$

$$b2 := -b1$$

$$c2 := -b1$$

$$c1 := -b1$$

$$b1 := x0$$

$$b3 := x1$$

$$a3 := x2$$

$$c3 := x3$$

$$(3)$$

$$f2 := NormalForm([Generic, [mp], plex(a1, a2, x0, x1, x2, x3, t));$$

$$f3 := collect([2, 1); [t]; [t]; (a1, a2));$$

$$f2 := -2a1 \hat{i}^2 x0 - 2a2 \hat{i}^2 x0 + 2\hat{i}^2 x0^2 + \hat{i}^2 x1^2 + 2\hat{i}^2 x2 x3 + 2a1 tx0 - 2a2 tx0 + 4 tx0^2$$

$$+ 2tx |x^2 + 2tx|^2 + a1^2 + a2^2 + 4x |x^3 + x2^2$$

$$f3 := (-2a1 x0 - 2a2 x0 + 2x0^2 + x1^2 + 2x2 x3) \hat{i}^2 + (2a1 x0 - 2a2 x0 + 4x0^2 + 2x1 x2 + 2x3^2) t + a1^2 + a2^2 + 4x |x^3 + x2^2|$$

$$f3 := (-2a1 x0 - 2a2 x0 + 2x0^2 + x1^2 + 2x2 x3)$$

$$f3 := [a1 - \frac{1}{4} \frac{2x0^2 - x1^2 + 2x1 x2 - 2x2 x3 + 2x3^2}{x0}, a2$$

$$= \frac{1}{4} \frac{6x0^2 + x1^2 + 2x1 x2 + 2x2 x3 + 2x3^2}{x0}$$

$$s5 := [a1 - \frac{1}{4} \frac{2x0^2 - x1^2 + 2x1 x2 + 2x2 x3 + 2x3^2}{x0}]$$

$$s6 := \sin bt/(ts) \sin t \text{ in the solutions found for al and a2 and compute the resulting polynomial solutions found for al and a2 and compute the resulting polynomial solutions found for al and a2 and compute the resulting polynomial solutions found for al and a2 and compute the resulting polynomial solutions found for al and a2 and compute the resulting polynomial solutions found for al and a2 and compute the resulting polynomial solutions.$$

```
p3s := simplify(subs(ss, p3) * ssDen);
                                             ssDen := 4 x0
               p1s := -4 t^2 x 0^2 + 4 t x 0^2 - 2 x 0^2 + x 1^2 - 2 x 1 x 2 + 2 x 2 x 3 - 2 x 3^2
               p2s := -4 t^2 x 0^2 - 4 t x 0^2 + 6 x 0^2 + x 1^2 + 2 x 1 x 2 + 2 x 2 x 3 + 2 x 3^2
                                    p3s := 4 (t^2 x^3 + t x^1 + x^2) x^0
                                                                                                             (5)
> # We replace t by the root of X^3-2
   p1ss := subs(\{t = RootOf(X^3 - 2)\}, p1s);
   p2ss := subs(\{t = RootOf(X^3 - 2)\}, p2s);
   p3ss := subs(\{t = RootOf(X^3 - 2)\}, p3s);
p1ss := -4x0^{2} RootOf(Z^{3} - 2)^{2} + 4x0^{2} RootOf(Z^{3} - 2) - 2x0^{2} + x1^{2} - 2x1x2 + 2x2x3
     -2 x 3^2
p2ss := -4x0^{2} RootOf(Z^{3} - 2)^{2} - 4x0^{2} RootOf(Z^{3} - 2) + 6x0^{2} + x1^{2} + 2x1x2 + 2x2x3
     +2 x3^{2}
                p3ss := 4 \left( RootOf(Z^3 - 2)^2 x3 + RootOf(Z^3 - 2) x1 + x2 \right) x0
                                                                                                             (6)
> # We compute f and verify that it is has rational coefficients
  f := p1ss^2 + p2ss^2 + p3ss^2;
   f := simplify(f);
f := (-4x0^2 RootOf(Z^3 - 2)^2 + 4x0^2 RootOf(Z^3 - 2) - 2x0^2 + x1^2 - 2x1x2 + 2x2x3
     -2x3^{2})<sup>2</sup> + (-4x0^{2}RootOf(Z^{3}-2)^{2}-4x0^{2}RootOf(Z^{3}-2)+6x0^{2}+x1^{2}
     +2x1x2+2x2x3+2x3^{2} +16\left(RootOf(Z^{3}-2)^{2}x3+RootOf(Z^{3}-2)x1\right)
     +x2) x0^{2}
f := 40 \times 0^4 + 8 \times 0^2 \times 1^2 + 32 \times 0^2 \times 1 \times 2 + 64 \times 0^2 \times 1 \times 3 + 16 \times 0^2 \times 2^2 + 16 \times 0^2 \times 2 \times 3 + 32 \times 0^2 \times 3^2
                                                                                                             (7)
     +2xI^{4}+8xI^{2}x2^{2}+8xI^{2}x2x3+16xIx2x3^{2}+8x2^{2}x3^{2}+8x3^{4}
> # We verify that there is no solution with x2 = 0
   sols := solve(\{p1ss, p2ss, p3ss, x2\});
                                sols := \{x0 = 0, x1 = 0, x2 = 0, x3 = 0\}
                                                                                                             (8)
> # Computation of a quadratic form associated to a linear functional in
   # the dual of the cone of SOS polynomials that vanishes at f
   # with kernel of small dimension.
   # We construct all monomials of degree 2 and 4
   d := 2:
   polVarsX := [x0, x1, x2, x3];
   varSum := add(polVarsX[i], i = 1 ..nops(polVarsX)):
   md := expand((varSum)^d):
   cfs := coeffs(md, polVarsX, 'ctdX'):
   print("Monomials of degree d: ", ctdX);
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m2d := expand(varSum^{(2*d)}):
   cfs := coeffs(m2d, polVarsX, 'ct2dX'):
   print("Monomials of degree 2d: ", ct2dX);
                                                 d := 2
                                     polVarsX := [x0, x1, x2, x3]
        "Monomials of degree d: ", x0^2, x1 x0, x0 x2, x3 x0, x1^2, x1 x2, x1 x3, x2^2, x2 x3, x3^2
"Monomials of degree 2d: ", x0^4, x0^3 x1, x0^3 x2, x0^3 x3, x0^2 x1^2, x0^2 x1 x2, x0^2 x1 x3, x0^2 x2^2.
                                                                                                             (9)
    x0^2 x2 x3, x0^2 x3^2, x0 x1^3, x0 x1^2 x2, x0 x1^2 x3, x0 x1 x2^2, x0 x1 x2 x3, x0 x1 x3^2, x0 x2^3
    x0x2^2x3, x0x2x3^2, x0x3^3, x1^4, x1^3x2, x1^3x3, x1^2x2^2, x1^2x2x3, x3^2x1^2, x1x2^3, x1x2^2x3,
    x1 \times 2 \times 3^{2}, x1 \times 3^{3}, x2^{4}, x2^{3} \times 3, x2^{2} \times 3^{2}, x2 \times 3^{3}, x3^{4}
> # We construct the linear form that vanishes at all products piss * h
   pListX := [p1ss, p2ss, p3ss]:
   MX := [\ ];
   for j from 1 to nops(pListX) do
    for i from 1 to nops([ctdX]) do
     p1tX := expand(pListX[j] * ctdX[i]);
      vec := LinearAlgebra[Transpose](getCoeffs(p1tX, [ct2dX]));
      if (nops(MX) = 0) then
       MX := \langle vec \rangle;
      else
       MX := \langle MX, vec \rangle;
      end if:
    end do:
   end do:
   rc := [Dimension(MX)];
   nr := rc[1];
   B := Vector(nr):
   sX := LinearAlgebra[LinearSolve](MX, B):
   varssX := indets(sX);
   nops(varssX); # 8 indeterminates left to solve
                                               MX := [ ]
                                             rc := [30, 35]
                                                nr := 30
                          varssX := \{ t_2, t_7, t_{10}, t_{20}, t_{31}, t_{33}, t_{34}, t_{35} \}
                                                                                                            (10)
> # We define a generic polynomial of degree d with coefficientes q i.
   qIndX := [seq(q[i], i=1 ..nops([ctdX]))]:
   psaX := add(q[i] * ctdX[i], i = 1 ..nops([ctdX]));
psaX := x0^2 q_1 + x0 x1 q_2 + x0 x2 q_3 + x0 x3 q_4 + x1^2 q_5 + x1 x2 q_6 + x1 x3 q_7 + x2^2 q_8
                                                                                                            (11)
     +x2x3q_9+x3^2q_{10}
> # The square of psaX and the coefficients
   ps2X := expand(psaX*psaX):
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aaX := getCoeffs(expand(ps2X), [ct2dX]):
> # We compute the form and look for a PSD matrix using SEDUMI
  ewX := LinearAlgebra[Transpose](sX) . aaX:
  ooX := polyToMatrixVars(expand(ewX), qIndX):
> # Numerical optimization using SEDUMI.
  # Numerically, the matrix has kernel of dimension 6.
  oEval := ooX[1]:
  outA := numericSolverSubmatrixMaxRank(evalf(oEval), "eig"):
  QEval := eval(oEval, Equate([op(outA[2])], outA[3][1..nops([op(outA[2])])])):
  smallToZeroMatrix(evalf(QEval), 8);
  print(eig(QEval));
                                      "rndRank", 7
                                   [3, 4, 6, 7, 8, 9, 10]
                                  "SEDUMI CALL - eig"
[0.09482924, 0, 0, 0, 0.31325558, -0.07786130, -0.19958157, 0.01935283, 0.04960703,
    0.12715753],
    [0, 0.31325558, -0.07786130, -0.19958157, 0, 0, 0, 0, 0, 0]
    [0, -0.07786130, 0.01935283, 0.04960703, 0, 0, 0, 0, 0, 0]
    [0, -0.19958157, 0.04960703, 0.12715753, 0, 0, 0, 0, 0, 0, 0]
    [0.31325558, 0, 0, 0, 1.22052476, -0.37420513, -0.51187895, 0.13763537, 0.07100650,
    0.53704856],
    [-0.07786130, 0, 0, 0, -0.37420513, 0.13763537, 0.07100650, -0.06232181, 0.01776965,
    -0.17811095],
    [-0.19958157, 0, 0, 0, -0.51187895, 0.07100650, 0.53704856, 0.01776965, -0.17811095,
    -0.17475741],
    [0.01935283, 0, 0, 0, 0.13763537, -0.06232181, 0.01776965, 0.44352360, -0.02672910,
    0.07238223],
    [0.04960703, 0, 0, 0, 0.07100650, 0.01776965, -0.17811095, -0.02672910, 0.07238223,
    [0.12715753, 0, 0, 0, 0.53704856, -0.17811095, -0.17475741, 0.07238223, 0.00801817,
    0.24421278]]
```

```
-8.15611288952737 \cdot 10^{-9}
                                         -2.40785649813595 \cdot 10^{-11}
                                         -5.54200099950070 10<sup>-12</sup>
                                         7.66214592535787 \cdot 10^{-11}
                                         9.20239493165339 \cdot 10^{-10}
                                                                                                                 (12)
                                          4.43807228701980 10<sup>-9</sup>
                                            0.320666707904826
                                            0.459765930092981
                                            0.512004830764087
                                            1.91748500909260
> # Based on the numerical solution, we compute exact values of the
   # unknowns to construct an exact PSD matrix.
    # The values obtained by SEDUMI are:
    # t = -0.0000, t = -0.1996, t = 0.1272, t = 0.0000,
   \# t \ 5 = 0.4435, t \ 6 = 0.0724, t \ 7 = 0.0080, t \ 8 = 0.2442
    ## We fix some variables to 0
    oEvalX := eval(ooX[1], \{varssX[1] = 0, varssX[4] = 0, varssX[7] = 0\}):
    ## We fix other variables with positive values
    oEvalX := eval(oEvalX, \{varssX[5] = 1, varssX[8] = 1, varssX[3] = 1/2\}):
> ## We compute exact values for the remaining two variables.
    # We observe that in the numerical solution, there are two singular
    evalf (Determinant(QEval[5 .. 7, 5 .. 7]));
    evalf (Determinant(QEval[2 .. 3, 2 .. 3]));
                                         -2.82782586236152\ 10^{-9}
                                         9.83991388370242 \cdot 10^{-10}
                                                                                                                 (13)
> # We compute symbolically the values of the unknowns that make the matrices singular.
    S \ 23 := solve(Determinant(oEvalX[2..3,2..3]), indets(oEvalX[2..3,2..3])):
    S 23 1 := simplify(S 23[1]);
S_{23}_{1} := \left\{ -t_{7} = -\frac{1}{4} \left( RootOf(\underline{Z}^{3} - 2)^{2} + \sqrt{-RootOf(\underline{Z}^{3} - 2)^{2} + 2 RootOf(\underline{Z}^{3} - 2) + 1} - 1 \right) RootOf(\underline{Z}^{3} - 2)^{2} \right\}
                                                                                                                 (14)
> oX_567 := eval(oEvalX[5..7, 5..7], S_23_1) :

S_567 := solve(Determinant(oX_567), indets(oX_567)) :
```

principal matrices.

```
S \ 567 \ 2 := simplify(S \ 567[2]);
S_{5672} := \left\{ t_{33} = \frac{1}{2} \ RootOf(\underline{Z}^3 - 2)^2 \left( \sqrt{-RootOf(\underline{Z}^3 - 2)^2 + 2 \ RootOf(\underline{Z}^3 - 2) + 1} \right) \right\}
                                                                                              (15)
> # We apply these substitutions (using simplified expressions equivalent to the results by Maple)
  rA := RootOf(Z^3-2):
  rB := RootOf(Z*rA^2-rA^2+Z^2+1):
  rC := -(1/2) * rA - (1/2) * rB:
\rightarrow oEvalX := eval(oEvalX, {varssX[2]=rC}):
  oEvalX := eval(oEvalX, \{varssX[6] = rB\}):
> # No indetermiantes in the resulting oEvalX
  evalf(oEvalX);
[0.3728809420, 0., 0., 0., 1.231761842, -0.3061607886, -0.7847808106, 0.07609785017,
                                                                                              (16)
    0.1950613368, 0.500000000000],
    [0., 1.231761842, -0.3061607886, -0.7847808106, 0., 0., 0., 0., 0., 0., 0.]
    [0, -0.3061607886, 0.07609785017, 0.1950613368, 0, 0, 0, 0, 0, 0, 0, 0]
    [0., -0.7847808106, 0.1950613368, 0.5000000000, 0., 0., 0., 0., 0., 0.]
    [1.231761842, 0., 0., 0., 4.899359550, -1.534480445, -1.933328015, 0.580923683,
    0.229158469, 2.174802104],
    [-0.3061607886, 0., 0., 0., -1.534480445, 0.580923683, 0.229158469, -0.2700817033,
    0.101401094, -0.740078950],
    [-0.7847808106, 0., 0., 0., -1.933328015, 0.229158469, 2.174802104, 0.101401094,
    -0.740078950, -0.6371205733],
    [0.07609785017, 0., 0., 0., 0.580923683, -0.2700817033, 0.101401094, 1., -0.124964077,
    0.3096405713],
    [0.1950613368, 0., 0., 0., 0.229158469, 0.101401094, -0.740078950, -0.124964077,
    0.3096405713, 0.],
    1.]]
> # The matrix has kernel of rank 6
```

evalf(Eigenvalues(oEvalX));

```
0.773176735490537
                                        1.95800566390025
                                        7.60642445185921
                                           1.807859692
                                                 0.
                                                                                                      (17)
                                                 0.
                                                 0.
                                                 0.
                                                 0.
                                                 0.
> # The kernel of the resulting form
                                                 6
                                                                                                      (18)
> # The polynoials in the kernel
   LinearAlgebra[Transpose](simplify(LX[01]));
   LinearAlgebra[Transpose](simplify(LX[02]));
   LinearAlgebra[Transpose](simplify(LX[03]));
   LinearAlgebra[Transpose](simplify(LX[04]));
   LinearAlgebra[Transpose](simplify(LX[05]));
   LinearAlgebra[Transpose](simplify(LX[06]));
 -RootOf(\_Z^3-2)+2, 0, 0, 0, -\frac{1}{2}(2+RootOf(\_Z^3-2)RootOf(\_ZRootOf(\_Z^3-2))^2
    + Z^{2} - RootOf(Z^{3} - 2)^{2} + 1) - 2 RootOf(Z^{3} - 2)^{2} / (RootOf(Z^{3} - 2)^{2})
    + RootOf(ZRootOf(Z^3 - 2)^2 + Z^2 - RootOf(Z^3 - 2)^2 + 1) - 2 RootOf(Z^3)
                     -2 RootOf(_Z^3 - 2)^2 + 1 \quad 0 \quad 0 \quad 0 \quad \frac{1}{2} \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 
\left| RootOf(\_Z^3 - 2)^2 + 2 RootOf(\_Z^3 - 2) + 2 RootOf(\_Z RootOf(\_Z^3 - 2)^2 + \_Z^2 \right|
    -RootOf(\_Z^3-2)^2+1), 0, 0, 0, -\frac{1}{2}(RootOf(\_Z^3-2)^2RootOf(\_ZRootOf(\_Z^3-2)^2))
    (-2)^{2} + Z^{2} - RootOf(Z^{3} - 2)^{2} + 1) - 4 + 2 RootOf(Z^{3} - 2)) / (RootOf(Z^{3} - 2)^{2})
    + RootOf(_ZRootOf(_Z^3 - 2)^2 + _Z^2 - RootOf(_Z^3 - 2)^2 + 1) - 2 RootOf(_Z^3 - 2)^2 + 1)
 -RootOf(\_Z^3-2), 0, 0, 0, \frac{1}{2}(2+RootOf(\_Z^3-2)RootOf(\_ZRootOf(\_Z^3-2)^2+\_Z^2))
```

LX := NullSpace(oEvalX):

(-2), 0, 0, 0, 0, 1

-2), 0, 1, 0, 0, 0

nops(LX);

```
-RootOf(Z^3-2)^2+1)-2RootOf(Z^3-2)^2)/(RootOf(Z^3-2)^2)
        + RootOf(ZRootOf(Z^3 - 2)^2 + Z^2 - RootOf(Z^3 - 2)^2 + 1) - 2 RootOf(Z^3)
        (-2), 1, 0, 0, 0, 0
[0, -(RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1) + RootOf(Z^3-2))
        (RootOf(Z^3-2)^2 RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
         -2 RootOf(Z^3-2) RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
         -2 RootOf(Z^3-2)^2+1, 0, 1, 0, 0, 0, 0, 0, 0
\left[0, -\left(RootOf(Z^3-2)^2RootOf(ZRootOf(Z^3-2)^2+Z^2-RootOf(Z^3-2)^2+1\right)+2\right]
                                                                                                                                                                                       (19)
         -2 RootOf(ZRootOf(Z^3-2)^2+Z^2-RootOf(Z^3-2)^2+1)-RootOf(Z^3-2)^2
         (-2) / (RootOf(Z^3-2)^2 RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2)
         +1) -2 RootOf(Z^3-2) RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2
        +1) - 2 RootOf(Z^3 - 2)^2 + 1), 1, 0, 0, 0, 0, 0, 0, 0
# 2) We add the second block from an example in the strictly
     # positive border of (4,4)
     # g is the sum of 4 squares
     g1 := v0^2 - v3^2:
     g2 := y1^2 - y3^2;
     g3 := v2^2 - v3^2;
     g4 := -v0^2 - v0^2 - v0^2 + 
     g := g1^2 + g2^2 + g3^2 + g4^2;
                                                                          g1 := y0^2 - v3^2
                                                                          g2 := vI^2 - v3^2
                                                                           g3 := v2^2 - v3^2
                                 g4 := -y0^2 - y0y1 - y0y2 + y0y3 - y1y2 + y1y3 + y2y3
g := (y0^2 - y3^2)^2 + (y1^2 - y3^2)^2 + (y2^2 - y3^2)^2 + (-y0^2 - y0y1 - y0y2 + y0y3 - y1y2)^2
                                                                                                                                                                                       (20)
         +v1v3+v2v3)<sup>2</sup>
> # We look for a form in the y-monomials that vanishes in the g i
     polVarsY := [y0, y1, y2, y3];
     varSumY := add(polVarsY[i], i = 1 ..nops(polVarsY));
     mdY := expand((varSumY)^d);
     cfsY := coeffs(mdY, polVarsY, 'ctdY');
     m2dY := expand(varSumY^{(2*d)});
     cfsY := coeffs(m2dY, polVarsY, 'ct2dY');
```

```
d := 2
                                    polVarsY := [y0, y1, y2, y3]
                                  varSumY := y0 + y1 + y2 + y3
   mdY := y0^{2} + 2 y0 y1 + 2 y0 y2 + 2 y0 y3 + y1^{2} + 2 y1 y2 + 2 y1 y3 + y2^{2} + 2 y2 y3 + y3^{2}
                                  cfsY := 1, 2, 2, 2, 1, 2, 2, 1, 2, 1
m2dY := y0^4 + 4y0^3yI + 4y0^3y2 + 4y0^3y3 + 6y0^2yI^2 + 12y0^2yIy2 + 12y0^2yIy3
     +6 v0^{2} v2^{2} + 12 v0^{2} v2 v3 + 6 v0^{2} v3^{2} + 4 v0 vI^{3} + 12 v0 vI^{2} v2 + 12 v0 vI^{2} v3
    +12 v 0 v 1 v 2^{2} + 24 v 0 v 1 v 2 v 3 + 12 v 0 v 1 v 3^{2} + 4 v 0 v 2^{3} + 12 v 0 v 2^{2} v 3 + 12 v 0 v 2 v 3^{2}
     +4 v 0 v 3^{3} + v I^{4} + 4 v I^{3} v 2 + 4 v I^{3} v 3 + 6 v I^{2} v 2^{2} + 12 v I^{2} v 2 v 3 + 6 v I^{2} v 3^{2} + 4 v I v 2^{3}
     +12 v 1 v 2^{2} v 3 + 12 v 1 v 2 v 3^{2} + 4 v 1 v 3^{3} + v 2^{4} + 4 v 2^{3} v 3 + 6 v 2^{2} v 3^{2} + 4 v 2 v 3^{3} + v 3^{4}
(21)
    4, 1, 4, 6, 4, 1
> # We compute all the restrictions to phi: A4 -> R given
   # by the five polynomials. There are 20 restrictions for each polynomial
  pListY := [g1, g2, g3, g4];
   MY := [\ ]:
   for j from 1 to nops( pListY) do
    for i from 1 to nops(\lceil ctdY \rceil) do
     p1t := expand(pListY[j] * ctdY[i]);
     vec := LinearAlgebra[Transpose](getCoeffs(p1t, [ct2dY]));
     if (nops(MY) = 0) then
       MY := \langle vec \rangle;
     else
       MY := \langle MY, vec \rangle;
     end if;
    end do:
   end do:
pListY := [v0^2 - v3^2, v1^2 - v3^2, v2^2 - v3^2, -v0^2 - v0 v1 - v0 v2 + v0 v3 - v1 v2 + v1 v3]
                                                                                                         (22)
     + v2 v3
> # We solve the system using only these restrictions
   rc := [Dimension(MY)];
   nr := rc[1];
   B := Vector(nr):
   s := LinearAlgebra[LinearSolve](MY, B):
   varssY := indets(s);
   nops(varssY); # Onlt 1 indeterminate left to solve
                                           rc := [40, 35]
                                              nr := 40
                                          varssY := \{ t\theta_9 \}
                                                  1
                                                                                                         (23)
> # We give values to the unknowns so that the form is PSD
   qIndY := [seq(qY[i], i = 1 ..nops([ctdY]))];
```

```
psaY := add(qIndY[i] * ctdY[i], i = 1 ..nops([ctdY])) : \\ ps2Y := expand(psaY * psaY) : \\ aaY := getCoeffs(expand(ps2Y), [ct2dY]) : \\ qIndY := [qY_1, qY_2, qY_3, qY_4, qY_5, qY_6, qY_7, qY_8, qY_9, qY_{10}] 
(24)
```

- > # We compute the form and verify it is PSD ewY := LinearAlgebra[Transpose](s) . aaY: ooY := polyToMatrixVars(expand(ewY), qIndY) : ooMY := ooY[1]:
- > # We give value 1 to the only indeterminate oEvalY := eval(ooMY, {varssY[1]=1});

$$h := (-x2^2 + y2^2);$$

 $p := f + g1^2 + g2^2 + g3^2 + g4^2 + h^2:$
 $expand(p);$

$$h := -x2^2 + y2^2$$

$$40 x0^{4} + 8 x0^{2} xI^{2} + 32 x0^{2} xI x2 + 64 x0^{2} xI x3 + 16 x0^{2} x2^{2} + 16 x0^{2} x2 x3 + 32 x0^{2} x3^{2}$$

$$+ 2 xI^{4} + 8 xI^{2} x2^{2} + 8 xI^{2} x2 x3 + 16 xI x2 x3^{2} + x2^{4} + 8 x2^{2} x3^{2} - 2 x2^{2} y2^{2} + 8 x3^{4}$$

$$+ 2 y0^{4} + 2 y0^{3} yI + 2 y0^{3} y2 - 2 y0^{3} y3 + y0^{2} yI^{2} + 4 y0^{2} yI y2 - 4 y0^{2} yI y3 + y0^{2} y2^{2}$$

$$- 4 y0^{2} y2 y3 - y0^{2} y3^{2} + 2 y0 yI^{2} y2 - 2 y0 yI^{2} y3 + 2 y0 yI y2^{2} - 6 y0 yI y2 y3$$

$$+ 2 y0 yI y3^{2} - 2 y0 y2^{2} y3 + 2 y0 y2 y3^{2} + yI^{4} + yI^{2} y2^{2} - 2 yI^{2} y2 y3 - yI^{2} y3^{2}$$

$$- 2 yI y2^{2} y3 + 2 yI y2 y3^{2} + 2 y2^{4} - y2^{2} y3^{2} + 3 y3^{4}$$

$$(26)$$

> # We construct a linear form in the dual of the SOS cone that # vanishes in all the 9 polynomials such that the associated # quadratic form has kernel of minimal rank.

d := 2

```
polVarsXY := [x0, x1, x2, x3, y0, y1, y2, y3];
      varSumXY := add(polVarsXY[i], i = 1 ..nops(polVarsXY));
                                                                                          d := 2
                                                    polVarsXY := [x0, x1, x2, x3, y0, y1, y2, y3]
                                          varSumXY := x0 + x1 + x2 + x3 + v0 + v1 + v2 + v3
                                                                                                                                                                                                    (27)
> # We use a block ordering for the monomials
      mdXY := [x0^2, x0^*x1, x0^*x2, x0^*x3, x1^2, x1^*x2, x1^*x3, x2^2, x2^*x3, x3^2, v0^2, v0^*v1, x0^2, x0^2,
               y0*y2, y0*y3, y1^2, y1*y2, y1*y3, y2^2, y2*y3, y3^2, x0*y0, x0*y1, x0*y2, x0*y3, x1
               * v0, x1 * v1, x1 * v2, x1 * v3, x2 * v0, x2 * v1, x2 * v2, x2 * v3, x3 * v0, x3 * v1, x3 * v2, x3 * v3
      ctdXY := op(mdXY):
     print("Monomials of degree d: ", ctdXY);
     m2dXY := expand(varSumXY^{\wedge}(2*d)):
      cfs := coeffs(m2dXY, polVarsXY, 'ct2dXY'):
     print("Monomials of degree 2d: ", ct2dXY);
"Monomials of degree d: ", x0^2, x1 x0, x0 x2, x3 x0, x1^2, x1 x2, x1 x3, x2^2, x2 x3, x3^2, y0^2, y0 y1,
       v0 v2, v0 v3, v1^2, v1 v2, v1 v3, v2^2, v2 v3, v3^2, x0 v0, x0 v1, x0 v2, x0 v3, x1 v0, x1 v1, x1 v2,
       x1 y3, x2 y0, x2 y1, x2 y2, x2 y3, x3 y0, x3 y1, x3 y2, x3 y3
"Monomials of degree 2d: ", x0^4, x0^3 x1, x0^3 x2, x0^3 x3, x0^3 y0, x0^3 y1, x0^3 y2, x0^3 y3, x0^2 x1^2,
                                                                                                                                                                                                    (28)
       x0^{2}x1x2, x0^{2}x1x3, x0^{2}x1y0, x0^{2}x1y1, x0^{2}x1y2, x0^{2}x1y3, x0^{2}x2^{2}, x0^{2}x2x3, x0^{2}x2y0,
       x0^2 x2 y1, x0^2 x2 y2, x0^2 x2 y3, x0^2 x3^2, x0^2 x3 y0, x0^2 x3 y1, x0^2 x3 y2, x0^2 x3 y3, x0^2 y0^2,
       x0^{2} y0 y1, x0^{2} y0 y2, x0^{2} y0 y3, x0^{2} y1^{2}, x0^{2} y1 y2, x0^{2} y1 y3, x0^{2} y2^{2}, x0^{2} y2 y3, x0^{2} y3^{2},
       x0x1^{3}, x0x1^{2}x2, x0x1^{2}x3, x0x1^{2}y0, x0x1^{2}y1, x0x1^{2}y2, x0x1^{2}y3, x0x1x2^{2}, x0x1x2x3,
       x0 \times 1 \times 2 \times 0, x0 \times 1 \times 2 \times 1, x0 \times 1 \times 2 \times 2, x0 \times 1 \times 2 \times 3, x0 \times 1 \times 3^2, x0 \times 1 \times 3 \times 0, x0 \times 1 \times 3 \times 1,
       x0 \times 1 \times 3 \times 2, x0 \times 1 \times 3 \times 3, x0 \times 1 \times 0^2, x0 \times 1 \times 0 \times 1, x0 \times 1 \times 0 \times 2, x0 \times 1 \times 0 \times 3, x0 \times 1 \times 1^2,
       x0 \, x1 \, y1 \, y2, x0 \, x1 \, y1 \, y3, x0 \, x1 \, y2^2, x0 \, x1 \, y2 \, y3, x0 \, x1 \, y3^2, x0 \, x2^3, x0 \, x2^2 \, x3, x0 \, x2^2 \, y0,
       x0x2^{2}y1, x0x2^{2}y2, x0x2^{2}y3, x0x2x3^{2}, x0x2x3y0, x0x2x3y1, x0x2x3y2, x0x2x3y3,
       x0 x2 y0^{2}, x0 x2 y0 y1, x0 x2 y0 y2, x0 x2 y0 y3, x0 x2 y1^{2}, x0 x2 y1 y2, x0 x2 y1 y3, x0 x2 y2^{2},
       x0 x2 y2 y3, x0 x2 y3^{2}, x0 x3^{3}, x0 x3^{2} y0, x0 x3^{2} y1, x0 x3^{2} y2, x0 x3^{2} y3, x0 x3 y0^{2},
       x0 x3 y0 y1, x0 x3 y0 y2, x0 x3 y0 y3, x0 x3 y1^2, x0 x3 y1 y2, x0 x3 y1 y3, x0 x3 y2^2,
       x0 x3 y2 y3, x0 x3 y3^{2}, x0 y0^{3}, x0 y0^{2} y1, x0 y0^{2} y2, x0 y0^{2} y3, x0 y0 y1^{2}, x0 y0 y1 y2,
       x0\ v0\ v1\ v3, x0\ v0\ v2^2, x0\ v0\ v2\ v3, x0\ v0\ v3^2, x0\ v1^3, x0\ v1^2\ v2, x0\ v1^2\ v3, x0\ v1\ v2^2,
       x0 v1 v2 v3, x0 v1 v3^{2}, x0 v2^{3}, x0 v2^{2} v3, x0 v2 v3^{2}, x0 v3^{3}, x1^{4}, x1^{3} x2, x1^{3} x3, x1^{3} v0, x1^{3} v1,
       x1^{3}y2, x1^{3}y3, x1^{2}x2^{2}, x1^{2}x2x3, x1^{2}x2y0, x1^{2}x2y1, x1^{2}x2y2, x1^{2}x2y3, x3^{2}x1^{2}, x1^{2}x3y0,
       x1^2 x3 y1, x1^2 x3 y2, x1^2 x3 y3, x1^2 y0^2, x1^2 y0 y1, x1^2 y0 y2, x1^2 y0 y3, x1^2 y1^2, x1^2 y1 y2,
       x1^2y1y3, x1^2y2^2, x1^2y2y3, x1^2y3^2, x1x2^3, x1x2^2x3, x1x2^2y0, x1x2^2y1, x1x2^2y2,
       x1 x2^{2} y3, x1 x2 x3^{2}, x1 x2 x3 y0, x1 x2 x3 y1, x1 x2 x3 y2, x1 x2 x3 y3, x1 x2 y0^{2}, x1 x2 y0 y1,
```

```
x1 x2 y0 y2, x1 x2 y0 y3, x1 x2 y1<sup>2</sup>, x1 x2 y1 y2, x1 x2 y1 y3, x1 x2 y2<sup>2</sup>, x1 x2 y2 y3, x1 x2 y3<sup>2</sup>,
    x1 x3^3, x1 x3^2 y0, x1 x3^2 y1, x1 x3^2 y2, x1 x3^2 y3, x1 x3 y0^2, x1 x3 y0 y1, x1 x3 y0 y2,
    x1 x3 y0 y3, x1 x3 y1^{2}, x1 x3 y1 y2, x1 x3 y1 y3, x1 x3 y2^{2}, x1 x3 y2 y3, x1 x3 y3^{2}, x1 y0^{3},
    x1 y0^{2} y1, x1 y0^{2} y2, x1 y0^{2} y3, x1 y0 y1^{2}, x1 y0 y1 y2, x1 y0 y1 y3, x1 y0 y2^{2}, x1 y0 y2 y3,
    x1 y0 y3^{2}, x1 y1^{3}, x1 y1^{2} y2, x1 y1^{2} y3, x1 y1 y2^{2}, x1 y1 y2 y3, x1 y1 y3^{2}, x1 y2^{3}, x1 y2^{2} y3,
    x1 y2 y3^2, x1 y3^3, x2^4, x2^3 x3, x2^3 y0, x2^3 y1, x2^3 y2, x2^3 y3, x2^2 x3^2, x2^2 x3 y0, x2^2 x3 y1,
    x2^2 x3 y2, x2^2 x3 y3, x2^2 y0^2, x2^2 y0 y1, x2^2 y0 y2, x2^2 y0 y3, x2^2 y1^2, x2^2 y1 y2, x2^2 y1 y3,
    x2^{2}y2^{2}, x2^{2}y2y3, x2^{2}y3^{2}, x2x3^{3}, x2x3^{2}y0, x2x3^{2}y1, x2x3^{2}y2, x2x3^{2}y3, x2x3y0^{2},
    x2 x3 v0 v1, x2 x3 v0 v2, x2 x3 v0 v3, x2 x3 v1^2, x2 x3 v1 v2, x2 x3 v1 v3, x2 x3 v2^2
    x2 x3 y2 y3, x2 x3 y3^{2}, x2 y0^{3}, x2 y0^{2} y1, x2 y0^{2} y2, x2 y0^{2} y3, x2 y0 y1^{2}, x2 y0 y1 y2,
    x2 y0 y1 y3, x2 y0 y2^{2}, x2 y0 y2 y3, x2 y0 y3^{2}, x2 y1^{3}, x2 y1^{2} y2, x2 y1^{2} y3, x2 y1 y2^{2},
    x2 v1 v2 v3, x2 v1 v3^{2}, x2 v2^{3}, x2 v2^{2} v3, x2 v2 v3^{2}, x2 v3^{3}, x3^{4}, x3^{3} v0, x3^{3} v1, x3^{3} v2, x3^{3} v3,
    x3^{2}y0^{2}, x3^{2}y0y1, x3^{2}y0y2, x3^{2}y0y3, x3^{2}y1^{2}, x3^{2}y1y2, x3^{2}y1y3, x3^{2}y2^{2}, x3^{2}y2y3,
    x3^{2}v3^{2}, x3v0^{3}, x3v0^{2}v1, x3v0^{2}v2, x3v0^{2}v3, x3v0v1^{2}, x3v0v1v2, x3v0v1v3, x3v0v2^{2},
    x3\ y0\ y2\ y3,\ x3\ y0\ y3^2,\ x3\ y1^3,\ x3\ y1^2\ y2,\ x3\ y1^2\ y3,\ x3\ y1\ y2^2,\ x3\ y1\ y2\ y3,\ x3\ y1\ y3^2,\ x3\ y2^3,
    x3y2^2y3, x3y2y3^2, x3y3^3, y0^4, y0^3y1, y0^3y2, y0^3y3, y0^2y1^2, y0^2y1y2, y0^2y1y3, y0^2y2^2,
    y0^{2}y2y3, y0^{2}y3^{2}, y0y1^{3}, y0y1^{2}y2, y0y1^{2}y3, y0y1y2^{2}, y0y1y2y3, y0y1y3^{2}, y0y2^{3},
    v0v2^2v3, v0v2v3^2, v0v3^3, v1^4, v1^3v2, v1^3v3, v1^2v2^2, v1^2v2v3, v1^2v3^2, v1v2^3, v1v2^2v3,
    y1 y2 y3^2, y1 y3^3, y2^4, y2^3 y3, y2^2 y3^2, y2 y3^3, y3^4
> # We compute all the restrictions to phi: A4 -> R given
   # by the five polynomials. There are 20 restrictions for each polynomial
   pList := [p1ss, p2ss, p3ss, g1, g2, g3, g4, h];
   MXY := [ ]:
   for j from 1 to nops(pList) do
     for i from 1 to nops(\lceil ctdXY \rceil) do
      p1t := expand(pList[i] * ctdXY[i]);
      vec := LinearAlgebra[Transpose](getCoeffs(p1t, [ct2dXY]));
      if (nops(MXY) = 0) then
       MXY := \langle vec \rangle;
      else
       MXY := \langle MXY, vec \rangle;
      end if:
     end do:
   end do:
pList := \left[ -4x0^2 RootOf(Z^3 - 2)^2 + 4x0^2 RootOf(Z^3 - 2) - 2x0^2 + x1^2 - 2x1x2 \right]
                                                                                                                    (29)
     +2x^2x^3-2x^3^2, -4x0^2 RootOf(z^3-2)^2-4x0^2 RootOf(z^3-2) +6x0^2+xI^2
     +2x1x2+2x2x3+2x3^{2}, 4 (RootOf(_Z^3-2)^2x3+RootOf(_Z^3-2)x1+x2)x0,
    y0^2 - y3^2, y1^2 - y3^2, y2^2 - y3^2, -y0^2 - y0 y1 - y0 y2 + y0 y3 - y1 y2 + y1 y3 + y2 y3, -x2^2
```

```
> # We solve the system using only these restrictions
           rc := [Dimension(MXY)];
          nr := rc[1];
           B := Vector(nr):
           sXY := LinearAlgebra[LinearSolve](MXY, B):
            varssXY := indets(sXY);
           nops(varssXY); # 70 indeterminates left to solve
                                                                                                                                                             rc := [288, 330]
                                                                                                                                                                         nr := 288
varssXY := \{ tl_2, tl_5, tl_6, tl_7, tl_8, tl_{11}, tl_{12}, tl_{13}, tl_{14}, tl_{15}, tl_{22}, tl_{23}, tl_{24}, tl_{25}, tl_
                tl_{26}, tl_{29}, tl_{30}, tl_{32}, tl_{33}, tl_{35}, tl_{52}, tl_{53}, tl_{54}, tl_{57}, tl_{58}, tl_{60}, tl_{61}, tl_{63},
               \_tl_{86}, \_tl_{93}, \_tl_{94}, \_tl_{96}, \_tl_{97}, \_tl_{99}, \_tl_{115}, \_tl_{177}, \_tl_{178}, \_tl_{180}, \_tl_{181}, \_tl_{183}, \_tl_{199}, \_tl_
               -tl_{226}, -tl_{228}, -tl_{229}, -tl_{230}, -tl_{233}, -tl_{234}, -tl_{236}, -tl_{237}, -tl_{239}, -tl_{255}, -tl_{256}, -tl_{259}, -tl_{260}
               \_tl_{261}, \_tl_{262}, \_tl_{263}, \_tl_{264}, \_tl_{265}, \_tl_{268}, \_tl_{269}, \_tl_{271}, \_tl_{272}, \_tl_{274}, \_tl_{275}, \_tl_{290}, \_tl_{291},
               _tl<sub>294</sub>, _tl<sub>295</sub>, _tl<sub>330</sub>}
                                                                                                                                                                                                                                                                                                                                                                                                  (30)
> # We give values to the unknowns so that the form is PSD
            qIndXY := [seq(qXY[i], i=1 ..nops([ctdXY]))]:
          psaXY := add(qIndXY[i] * ctdXY[i], i = 1 ..nops([ctdXY])):
          ps2XY := expand(psaXY * psaXY):
          aaXY := getCoeffs(expand(ps2XY), \lceil ct2dXY \rceil):
\rightarrow # We copy O x and O y in O xy
           s1 := solve(Equate(ooMXY[1..10, 1..10], oEvalX)):
            oEvalXY := eval(ooMXY, \{ooMXY[20, 20] = 6\}):
            oEvalXY := eval(oEvalXY, s1):
> # We replace all the remaining variables by 0
           s2 := solve(Equate([op(indets(oEvalXY))], ZeroVector(nops(indets(oEvalXY))))):
            oEvalXY := eval(oEvalXY, s2):
> # We verify that the matrix is positive semidefinite and has kernel
           # of rank 14.
            evalf(Eigenvalues(oEvalXY));
```

0.275755770741317
0.600977953313586
7.01383053094510
0.152195701
1.72628036257243
6.66336623908240
7.83746836150327
31.1104918868419
0.275620309502316
0.589700594592797
3.01830865794753
7.00693469295736
1.807859692
0.551105092943717
1.16935580906050
7.06066760599579
0.076097850
0.076097850
7.
7.
7.
7.
0.
0.
0.
0.
0.
0.
0.
0.
0.
0.
0.
0.

(31)

```
L := NullSpace(oEvalXY):
           nops(L);
                                                                                                                                                                               14
> # The polynoials in the kernel
           simplify(L[01]) . convert(mdXY, Vector);
           simplify(L[02]) . convert(mdXY, Vector);
           simplify(L[03]) . convert(mdXY, Vector);
           simplify(L[04]) . convert(mdXY, Vector);
           simplify(L[05]) . convert(mdXY, Vector);
           simplify(L[06]) . convert(mdXY, Vector);
           simplify(L[07]) . convert(mdXY, Vector);
           simplify(L[08]) . convert(mdXY, Vector);
           simplify(L[09]) . convert(mdXY, Vector);
          simplify(L[10]) . convert(mdXY, Vector);
          simplify(L[11]) . convert(mdXY, Vector);
           simplify(L[12]) . convert(mdXY, Vector);
           simplify(L[13]) . convert(mdXY, Vector);
           simplify(L[14]) . convert(mdXY, Vector);
                                                                                                                                                              -x2^2 + v3^2
                                                                              -x2^{2} - y0y1 - y0y2 + y0y3 - y1y2 + y1y3 + y2y3
                                                                                                                                                              -x2^2 + v2^2
                                                                                                                                                              -x2^2 + yI^2
                                                                                                                                                              -x2^{2} + y0^{2}
 (-RootOf(Z^3-2)+2) \times 0^2 - \frac{1}{2} ((2+RootOf(Z^3-2) RootOf(ZRootOf(Z^3-2))^2 + 2) \times 0^2 - \frac{1}{2} ((2+RootOf(Z^3-2) RootOf(Z^3-2))^2 + 2) \times 0^2 - \frac
                 + Z^{2} - RootOf(Z^{3} - 2)^{2} + 1) - 2 RootOf(Z^{3} - 2)^{2} xI^{2}) / (RootOf(Z^{3} - 2)^{2})
                 + RootOf(ZRootOf(Z^3 - 2)^2 + Z^2 - RootOf(Z^3 - 2)^2 + 1) - 2 RootOf(Z^3 - 2)^2 + 1)
                 (-2) + x3^2
                                                                                    \left(-2 RootOf(Z^3-2)^2+1\right) x0^2+\frac{1}{2} xI^2+x2 x3
 (RootOf(Z^3-2)^2+2RootOf(Z^3-2)+2RootOf(ZRootOf(Z^3-2)^2+Z^2)
                 -RootOf(Z^{3}-2)^{2}+1)x\theta^{2}-\frac{1}{2}\left(\left(RootOf(Z^{3}-2)^{2}RootOf(ZRootOf(Z^{3}-2)^{2}RootOf(ZRootOf(Z^{3}-2)^{2}RootOf(ZRootOf(ZRootOf(Z^{3}-2)^{2}RootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(ZRootOf(
                 (-2)^{2} + Z^{2} - RootOf(Z^{3} - 2)^{2} + 1) - 4 + 2 RootOf(Z^{3} - 2) xI^{2})
                (RootOf(Z^3-2)^2 + RootOf(ZRootOf(Z^3-2)^2 + Z^2 - RootOf(Z^3-2)^2 + 1)
                 -2 RootOf(Z^3-2) + x1 x3
 -x0^{2} RootOf(\_Z^{3}-2) + \frac{1}{2} ((2 + RootOf(\_Z^{3}-2) RootOf(\_ZRootOf(\_Z^{3}-2))^{2} + \_Z^{2})
```

(32)

> # The kernel is generated by 14 polynomials

$$-RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2)^2) x i^2)/(RootOf(_Z^3-2)^2 + RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3 - 2)^2 + RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3 - 2))+x i x 2$$

$$-((RootOf(_Z RootOf(_Z^3-2)^2+_Z^2-RootOf(_Z^3-2)^2+1)+RootOf(_Z^3 - 2)) x i x 0)/(RootOf(_Z^3-2)^2 RootOf(_Z^3-2)^2+_Z^2 - RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2) RootOf(_Z RootOf(_Z^3-2)^2+_Z^2 - RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2)^2+1)+x 3 x 0$$

$$-((RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2)^2+_Z^2-RootOf(_Z^3-2)^2+1)+2 -2 RootOf(_Z^3-2)^2+_Z^2-RootOf(_Z^3-2)^2+1)-RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+1)-RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2) RootOf(_Z^3-2)^2+Z^2-RootOf(_Z^3-2)^2+1)-2 RootOf(_Z^3-2)^2+1)+x 0 x 2 x 3 y 0 + x 3 y 1 x 1 y 0 + x 1 y 1 x 0 y 0 + x 0 y 1$$

$$(33)$$

> # There is no polynomails in the kernel with rational coefficients that has non-zero coefficient in $x0^2$.