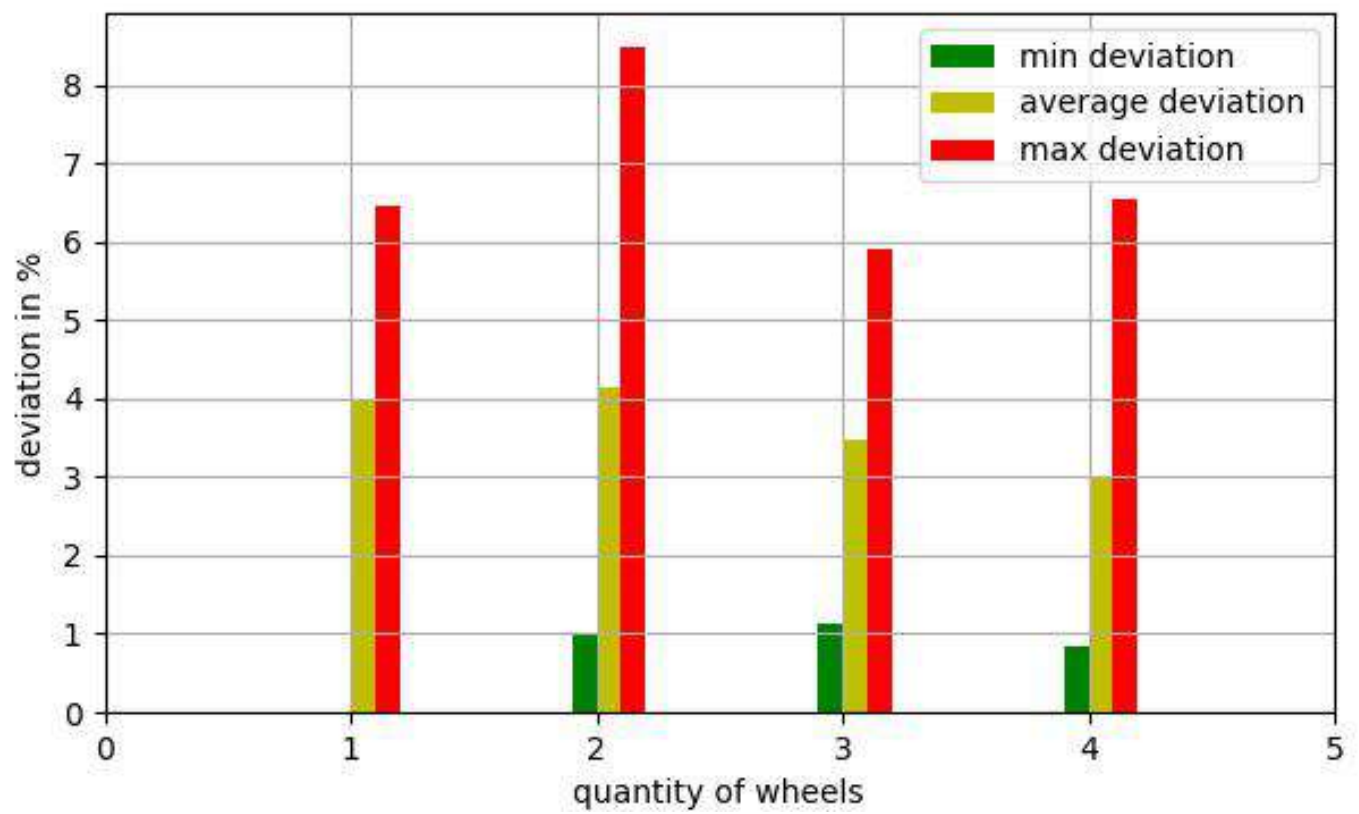
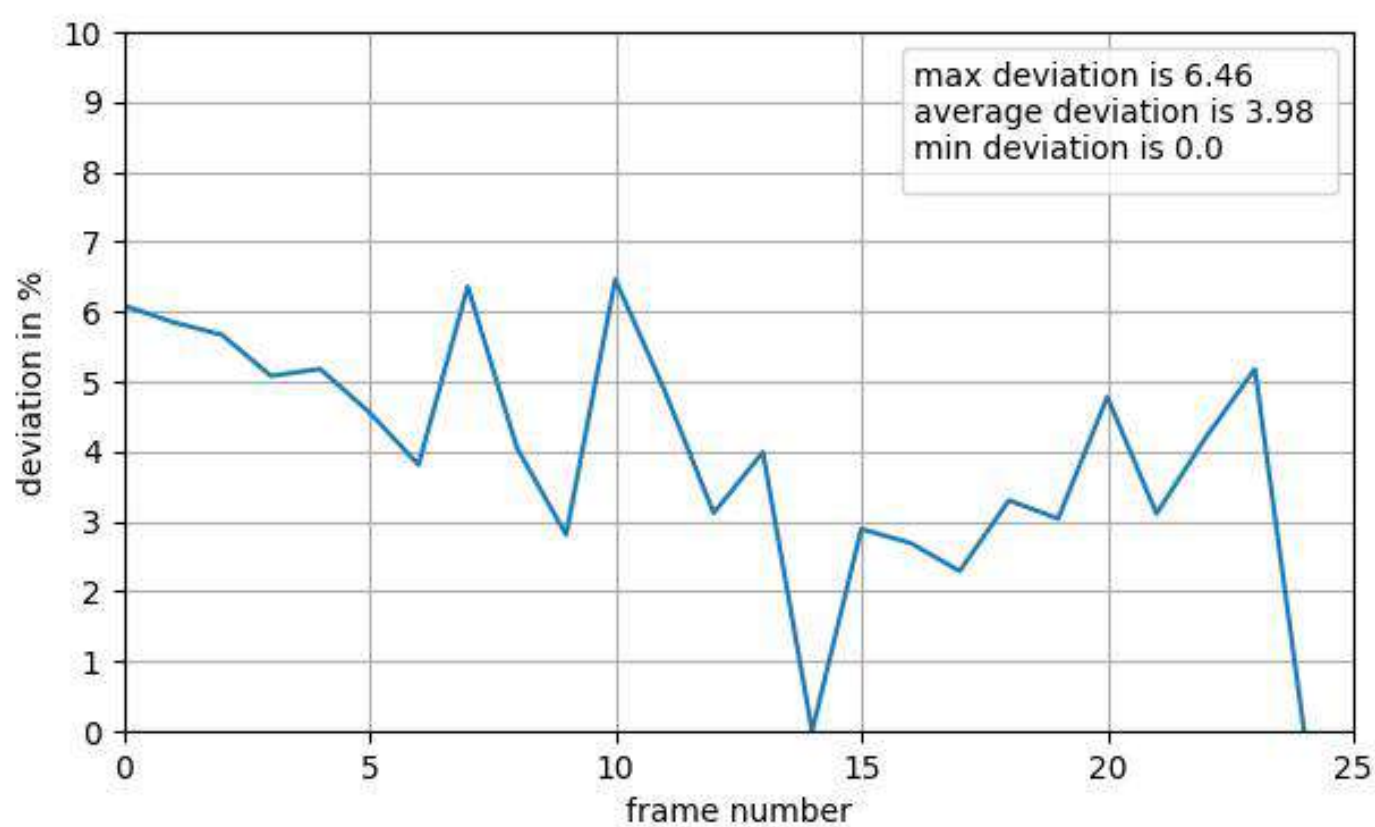


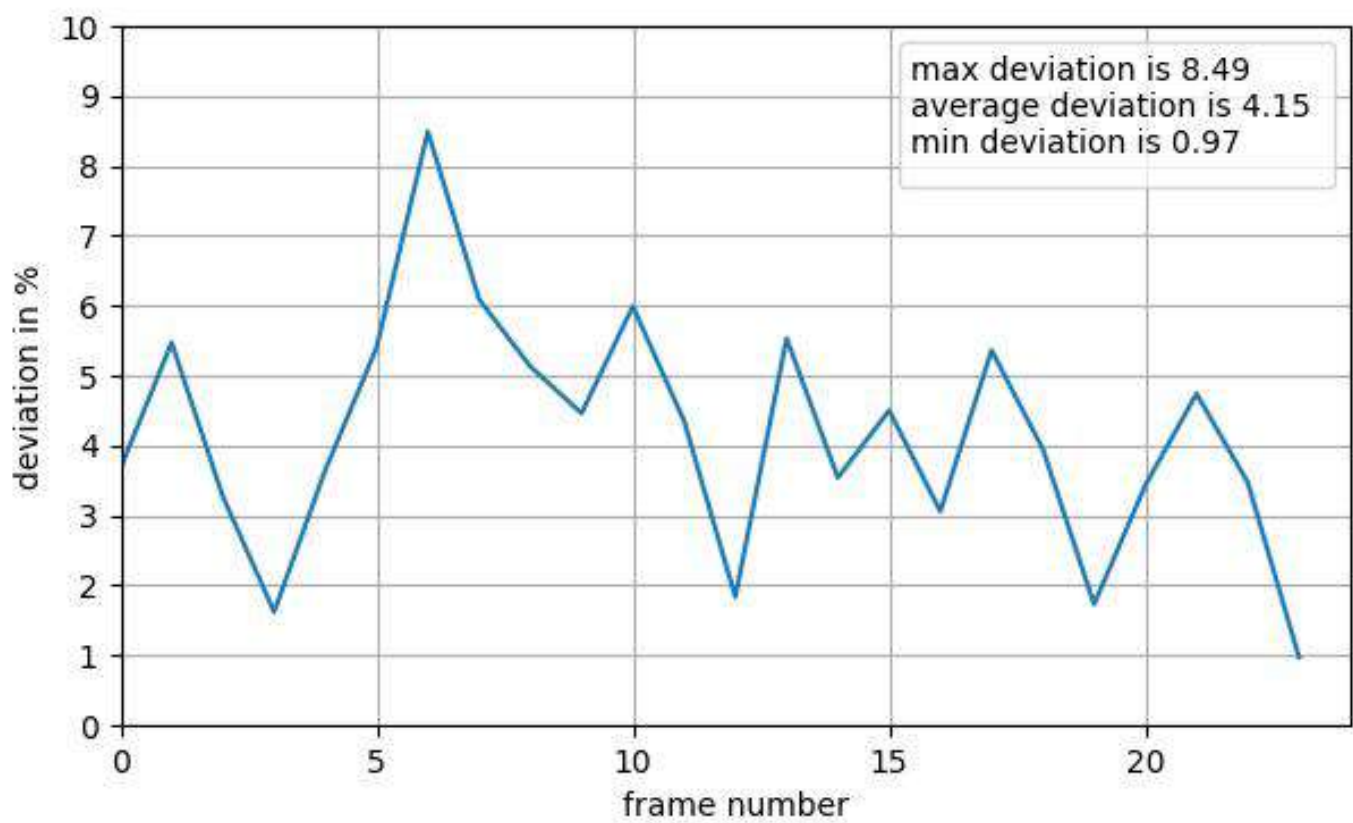
center deviation in %



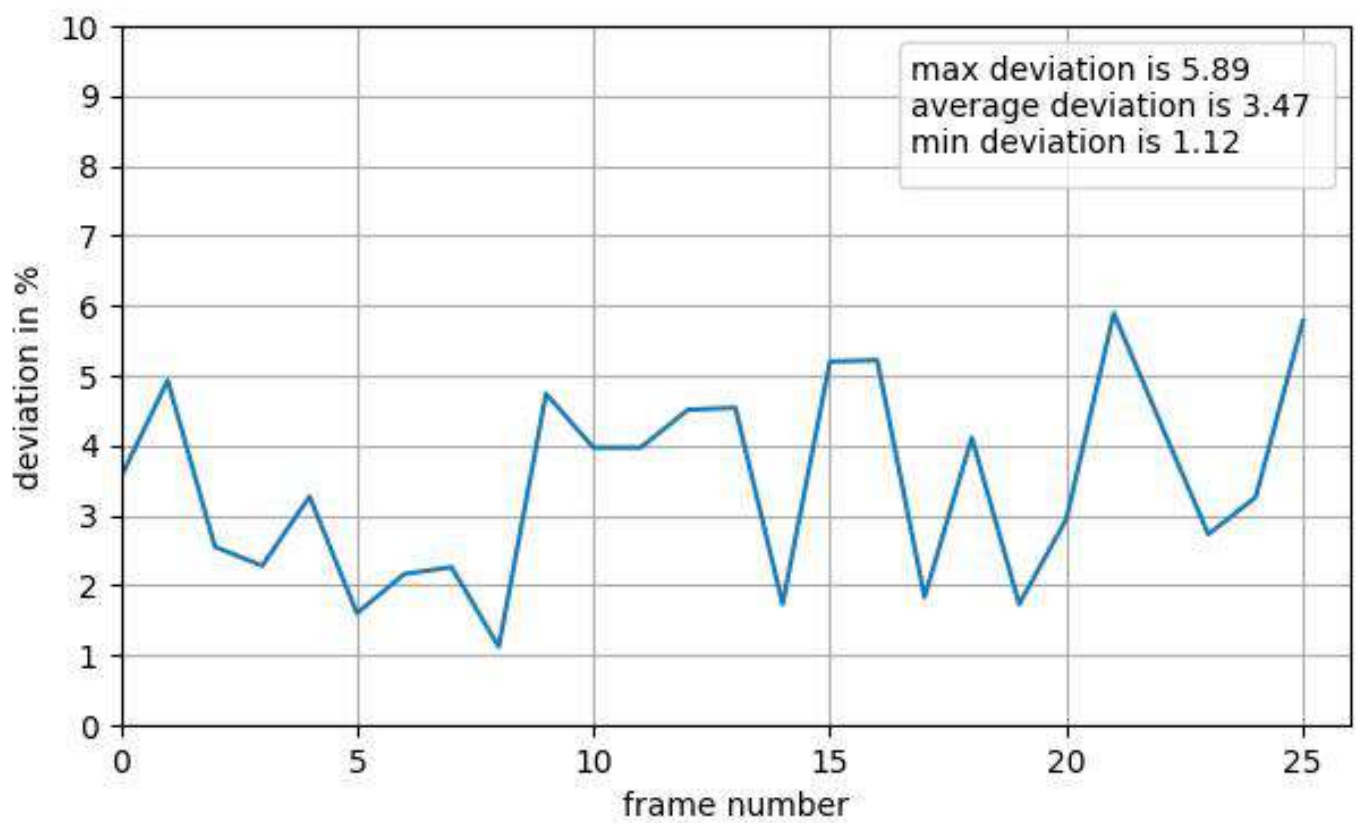
center deviation in frames for 1 wheel



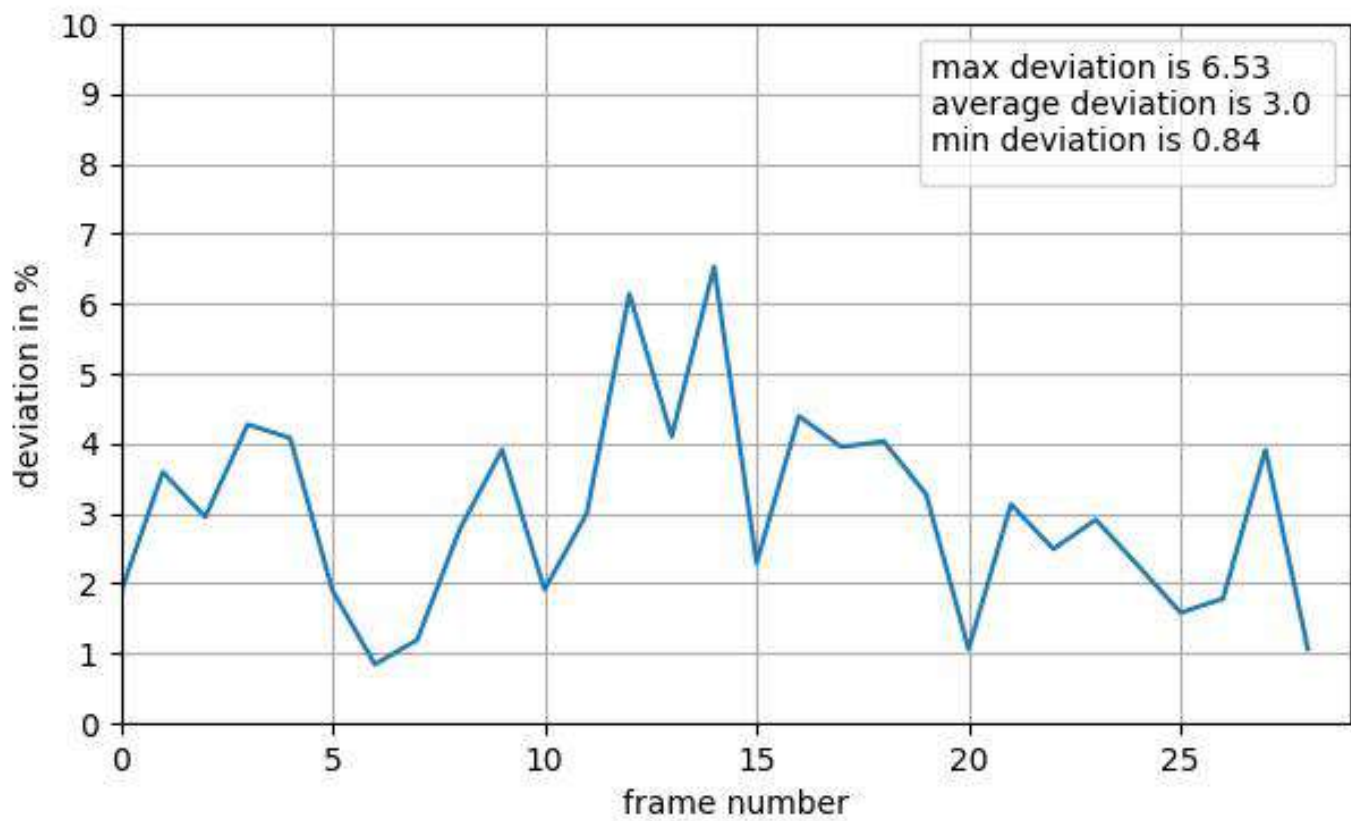
center deviation in frames for 2 wheels

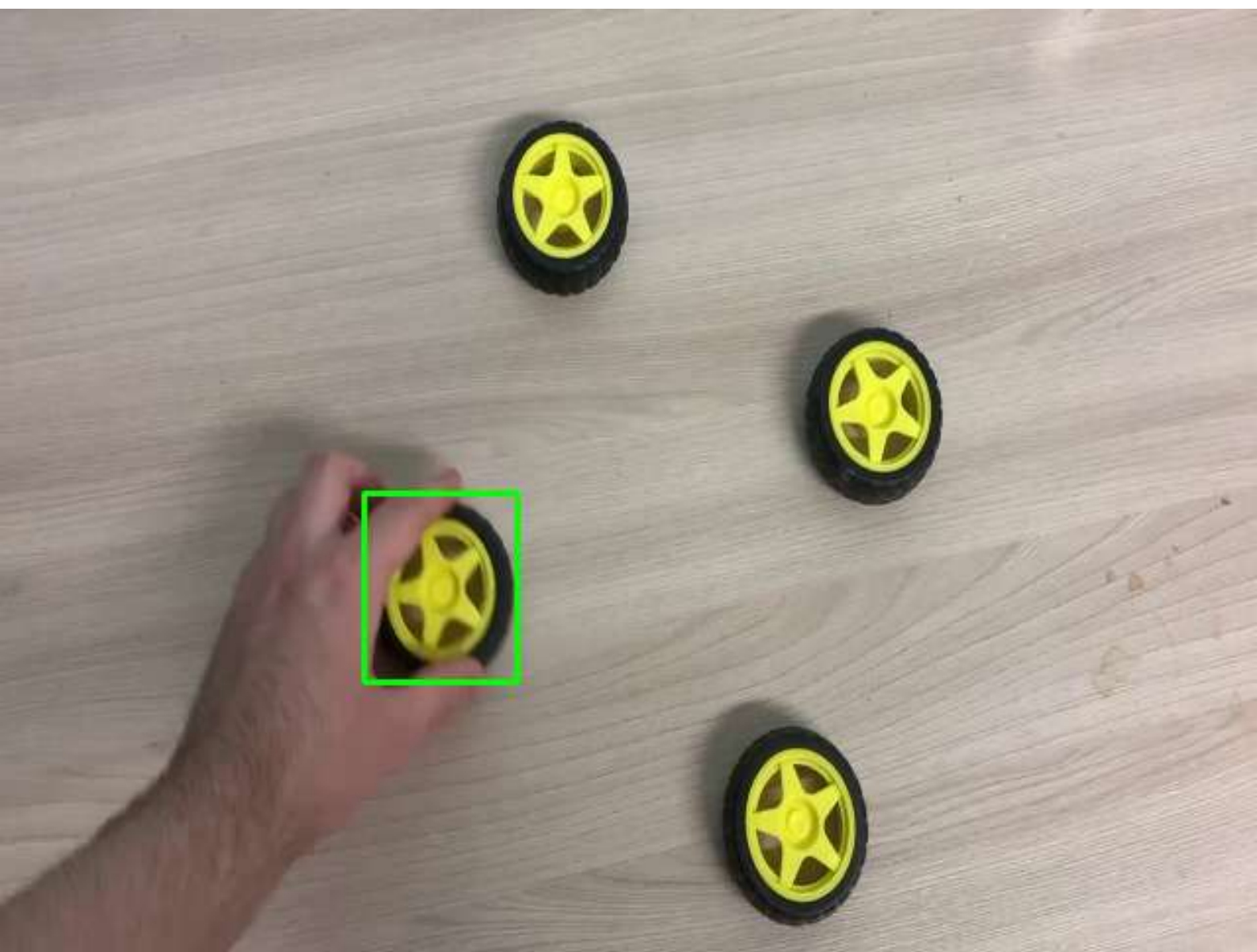


center deviation in frames for 3 wheels



center deviation in frames for 4 wheels





red — neural network  
green — etalon

