AnalogDigitalConverter

- convertedValue :uint16 t
- AnalogDigitalConverter()
- getConvertedValue(int) :uint16_t
- getConvertedValueAsVoltage(int):float

Display

- buffer :char ([128])
- DMA_InitStruct :DMA_InitTypeDef
- OutputString :char*
- SendFirst :int
- Backlight(char, int) :void
- Display()
- Display(int)
- EnableSingelton() :void
- Init():void
- InitDMA() :void
- PutChar(uint16_t, int) :void
- SendByte(char*, int, int) :void
- SendMessage(char*, int) :void
- SendString(char*, int) :void
- SendViaDma(char*, int) :void
- SetCursorPosition(char, char, int) :void
- SpecialCommand(char, int) :void

Rotary

- button :bool = 0
- buttonState :int
- folgezustand :int
- istzustand :int
- position :int
- table :int ([16]) = { 0, 2, 1, 0, 1...
- EnableSingelton():void
- GetNumberFrom2Bool(int, int) :int
- GetPosition():int
- hasButtonPressd():bool
- Process() :void
- resetButtonPressd():bool

Led

- LED_PINS :unsigned long
- Led()
- ~Led()
- Off() :void
- On() :void

Menu

- currentMenu :menu_str*
- cursor :int = 0
- menu :int = 0
- menuBefore :int = 0
- sollwert :float = 0
- Cursor(int) :void
- DisplayMenu(int) :void
- DrawCursor() :void
- Init() :void
- Menu()
- MenuUP() :void
- PrintMenu(menu_str*) :void
- SetSollwert(float) :void
- Submit() :void

+currentMenu

«struct»

menu str

- Count :int
- menuEntrys :char*

Ampermeter

- Ampermeter()
- getCurrent() :float

Stepper

- currentStep :int
- direction :int
- position :int
- stepperEnd :int
- StepperStatus :int
- EnableSingelton():void
- GetPosition():int
- GetPositionInProzent():int
- Go2Step(int) :void
- Init():void
- InitTim2(int, int) :void
- Leerlauf() :void Left(int, int) :void
- Right(int, int) :void RunStep():void
- Stepper()

Terminal

- buffer :char*
- bufferSize :int
- currentKommandoChar :int
- DMA_InitStruct :DMA_InitTypeDef
- KommandoBuffer :char*
- KommandoTerminator :int
- OutputString :char*
- read :int
- SendFirst :int
- tmpBuffer :char ([KOMMANDO_BUFFER])
- # write :int
- # buffer_init() :void
- BufferIn(char) :int
- BufferOut(char*) :int
- # CommandoProzess(char*) :void
- EnableSingelton():void
- IsCommandoAvalible():int
- ProzessCommando() :void
- ReadBuffer() :char
- ReadBuffer(char*) :int
- SendMessage(char*) :void
- SendViaDma(char*, int) :void Terminal()
- Terminal(int)
- uartPutChar(uint16_t) :void
- uartSendString(char*) :void
- usart3Init() :void
- usart3InitDMA():void

Fassade

- + type :int
- Fassade()
- Fassade(int)
- GetSolltemp() :float
- InitGewaechshaus() :void
- RegelungFenster():void
- SendMassageToDisplay(char*) :void
- SendValuesToRemoteDisplay() :void
- SetSolltemp(float) :void
- TerminalDisplayTemp():void
- UpdateDisplayValues() :void
- UpdateDisplayValues2():void
- Window2Position(int) :void

Xbee

- buffer :char*
- bufferSize :int
- currentKommandoChar :unsigned int
- DMA_InitStruct :DMA_InitTypeDef
- KommandoBuffer :char*
- KommandoTerminator :unsigned int
- OutputString :char*
- read :int
- SendFirst :int
- tmpBuffer :char ([KOMMANDO_BUFFER])
- txin:int=0
- values :PValues = {0.0, 0.0, 0.0,...
- write int
- writeBuffer :char ([256])
- xbeeType :int
- buffer_init() :void
- BufferIn(char) :int
- BufferOut(char*) :int
- CommandoProzess(char*) :void EnableSingelton():void
- Init() :void
- InitDMA() :void IsCommandoAvalible():int
- ProzessCommando():void
- PutChar(uint16_t) :void
- ReadBuffer() :char'
- ReadBuffer(char*) :int
- SendMessage(char*) :void SendTransmission(char, char, char, char, char*, char):void
- SendViaDma(char*, int) :void TransmittPValues() :void
- Xbee()
- Xbee(int)
- Xbee(int, int)

+values

«struct» **PValues**

- current :float
- indor :float
- outdor :float sollwert :float
- voltage :float windowP :int

TemperaturSensoren

- gefundeTempSensoren :uint8_t
- sensorAdressen :uint8_t ([MAX_EXPECTED_SENSORS][8])
- sensorTemperaturen :float ([MAX_EXPECTED_SENSORS])
- getAlleTempWerte(float*) :void
- getAnzahlGefunderSensoren() :uint8_t
- getTempWertFromSensor(uint8_t) :float startTempMeasurementAllSensors():void
- TemperaturSensoren()