

PySDM: particle-based cloud modeling package with CPU and GPU number-crunching backends

Sylwester Arabas¹²

UIUC Atmospheric Sciences Seminar, 7 Sept. 2021

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²on leave @ Faculty of Math. & CS at uj.edu.pl

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@caltech.edu: A. Jaruga, C. Singer, ...

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- ▶ 1917 Smoluchowski elected as Rector (professor since 1913)

Plan of the talk

PySDM: context

PySDM: statement of need & goals

PySDM: tour of the features

PySDM: demo (role play: reviewer)

PySDM: technological stack

context: aerosol-cloud-precipitation interactions (scales!)



"Cloud and ship. Ukraine, Crimea, Black sea, view from Ai-Petri mountain"
(photo: Yevgen Timashov / National Geographic)

Smoluchowski's coagulation equation (SCE)

concentration of particles of size x at time t : $c(x, t): \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$

collision kernel: $a(x_1, x_2): \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$

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$$\dot{c}(x) = \frac{1}{2} \int_0^x a(y, x-y) c(y) c(x-y) dy - \int_0^\infty a(y, x) c(y) c(x) dy \quad (1)$$

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discretised particle concentration: $c_i = c(x_i)$ where $x_i = i \cdot x_0$

$$\dot{c}_i = \frac{1}{2} \sum_{k=1}^{i-1} a(x_k, x_{i-k}) c_k c_{i-k} - \sum_{k=1}^\infty a(x_k, x_i) c_k c_i \quad (2)$$

cloud droplet collisional growth

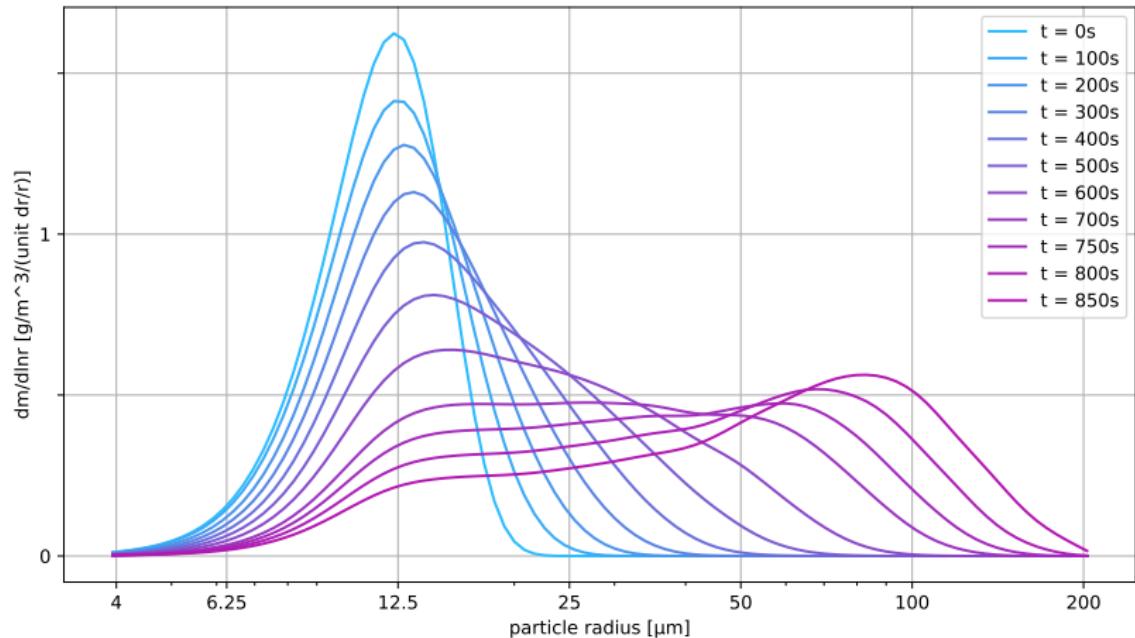


figure (PySDM simulation): Bartman, Arabas et al. 2021, LNCS
(doi:10.1007/978-3-030-77964-1_2)

SCE: challenges/problems

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- ▶ ...

Monte-Carlo SCE alternatives: e.g., SDM by Shima et al.

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Shima et al. 2020 (doi:10.5194/gmd-13-4107-2020): mixed-phase

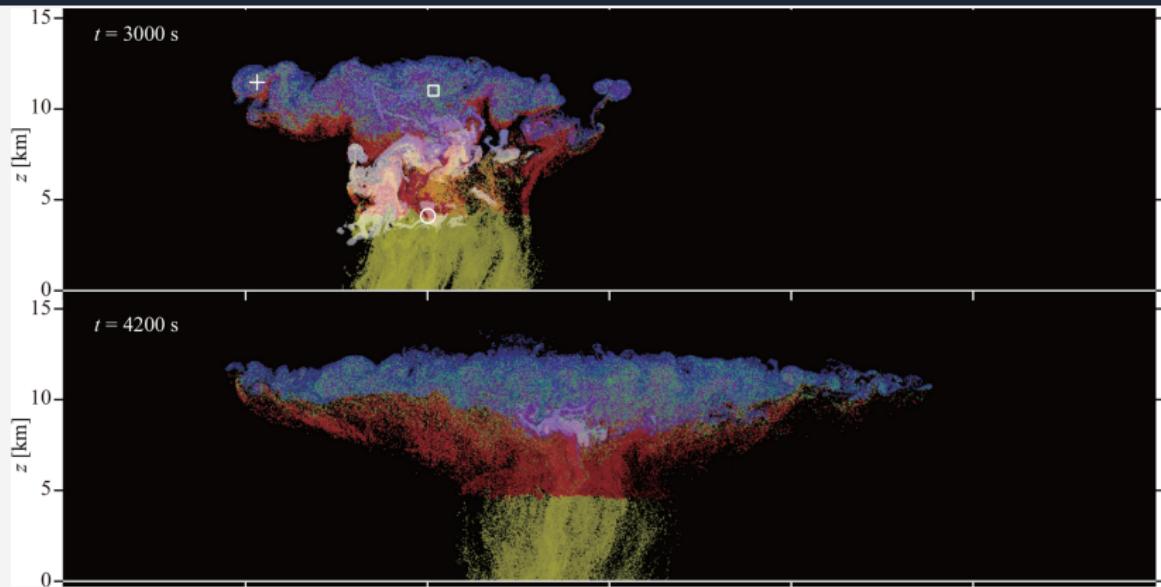


Figure 1. Typical realization of CTRL cloud spatial structures at $t = 2040, 2460, 3000, 4200$, and 5400 s. The mixing ratio of cloud water, rainwater, cloud ice, graupel, and snow aggregates are plotted in fading white, yellow, blue, red, and green, respectively. The symbols indicate examples of unrealistic predicted ice particles (Sects. 7.3 and 9.1). See also Movie 1 in the video supplement.

Super Droplet Method vs. SCE: differences

method type

mean-field, deterministic

Monte-Carlo, stochastic

considered pairs

all (i,j) pairs

random set of $n_{sd}/2$ non-overlapping pairs, probability up-scaled by $(n_{sd}^2 - n_{sd})/2$ to $n_{sd}/2$ ratio

computation complexity

$\mathcal{O}(n_{sd}^2)$

$\mathcal{O}(n_{sd})$

Super Droplet Method vs. SCE: differences

collisions triggered

every time step

by comparing probability with a random number

collisions

colliding a fraction of $\xi_{[i]}, \xi_{[j]}$

collide all of $\min\{\xi_{[i]}, \xi_{[j]}\}$
(all or nothing)

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besides c_i , each “particle” i carries other physicochemical attributes incl. position in space (x_i, y_i, z_i)

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in aerosol community: DeVille, Riemer & West 2011:

Weighted Flow Algorithms (WFA) for stochastic particle coagulation

super-particles as an alternative to bulk or bin μ -physics

Confronting the Challenge of Modeling Cloud and Precipitation Microphysics

Hugh Morrison , Marcus van Lier-Walqui, Ann M. Fridlind, Wojciech W. Grabowski, Jerry Y. Harrington, Corinna Hoose, Alexei Korolev, Matthew R. Kumjian, Jason A. Milbrandt, Hanna Pawlowska, Derek J. Posselt, Olivier P. Prat, Karly J. Reimel, Shin-Ichiro Shima, Bastiaan van Diedenhoven, Lulin Xue

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Journal of Advances in Modeling Earth Systems

10.1029/2019MS001689

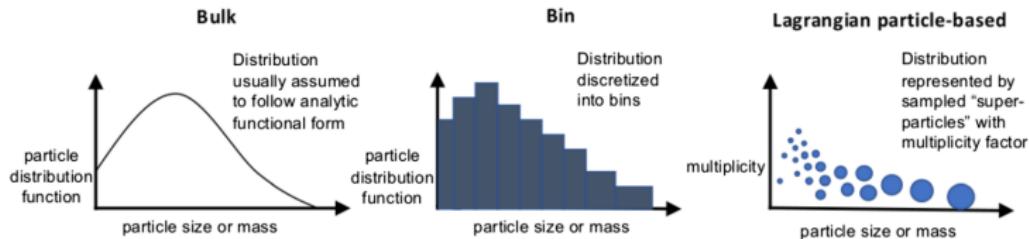


Figure 3. Representation of cloud and precipitation particle distributions in the three main types of microphysics schemes: Bulk (left), bin (center), and particle-based Lagrangian (right). The horizontal axes show particle diameter or mass, and the vertical axes show the number density distribution for the bulk and bin diagrams and “multiplicity” for the Lagrangian particle-based diagram, which is the actual number of particles that each super-particle represents. The size of the blue super-particles in this diagram represents the size or mass of a super-particle. Note that almost all current bulk schemes represent particle distributions using analytic functions, although some earlier schemes did not make any assumptions about the cloud particle distribution and only considered bulk cloud water content.

SDM

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Summer 2021 news

IPCC AR6 WGI: Chapter 7

Final Government Draft

Chapter 7

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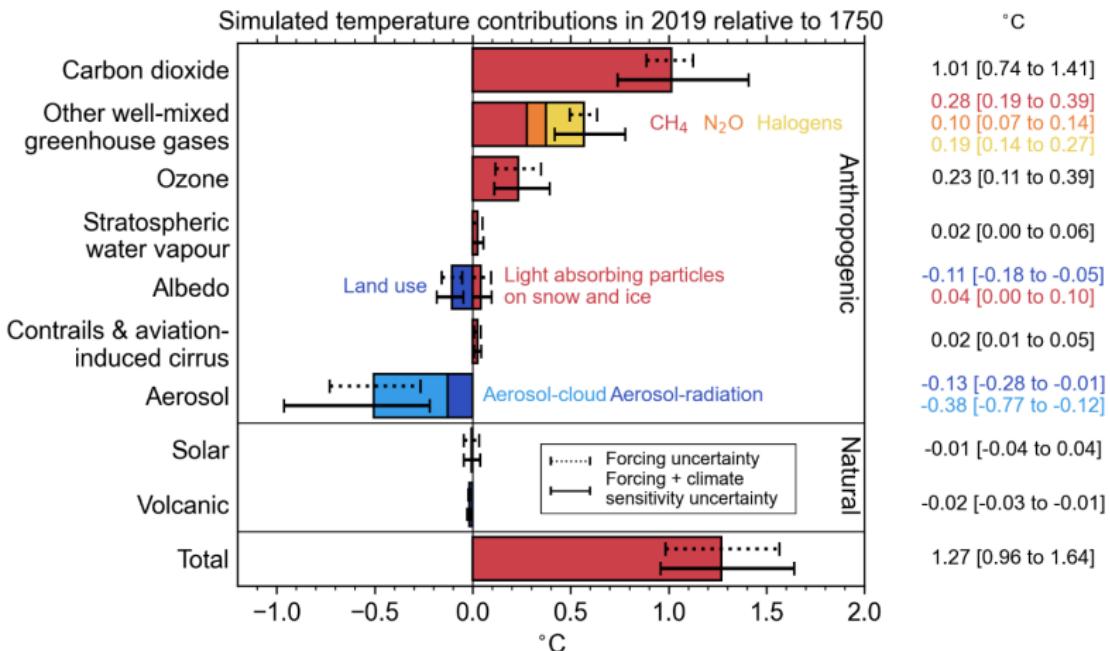


Figure 7.7: The contribution of forcing agents to 2019 temperature change relative to 1750 produced using the two-layer emulator (Supplementary Material 7.SM.2), constrained to assessed ranges for key climate metrics described in Cross-Chapter Box 7.1.



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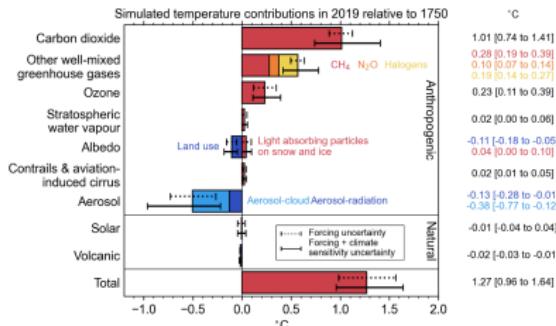


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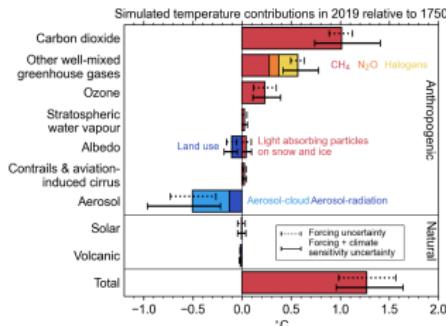


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AMS Statement on Software Preservation, Stewardship and Reuse



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A Professional Guidance Statement of the American Meteorological Society

Adopted by the AMS Council on 16 July 2021

Motivation

Software is an essential component in driving scientific and technical advances in the atmospheric and oceanic sciences, leading to broader societal benefits. Society now relies upon software tools to assist in planning for daily life, improving the efficiency of economic activities, and saving lives when faced with pending natural disasters such as hurricanes. Modern numerical weather prediction (NWP) and ocean circulation models, which provide the foundation for environmental prediction, are essentially software products arising from decades of scientific research. As computational capacity and the complexity of observational networks increase, stewardship of software resulting from research is imperative in many cases. In order to build upon and further the knowledge that has been characterized within current software tools, the community is now expected to produce and curate software that is equitably accessible and easier to be reused by others. Equitable access to software that was used to discover the most recent research findings avoids wasteful duplication of efforts and provides an opportunity for any researcher to more easily build upon the work of others.

PySDM: goals (stimulating overlap with PartMC!)

Develop an implementation of the SDM algorithm:

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- ▶ **curation**: open licensing (GPL), public versioned development (Github)
KPI: instant and anonymous execution on commodity environment

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Atmospheric Cloud Simulation Group @ Jagiellonian University

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Pythonic particle-based (super-droplet) warm-rain/aqueous-chemistry cloud microphysics package with box, parcel & 1D/2D prescribed-flow examples in Python, Julia and Matlab

● Python ⭐ 17 📂 14

[PyMPDATA](#)

Forked from piotrbartman/PyMPDATA

Numba-accelerated Pythonic implementation of MPDATA with examples in Python, Julia and Matlab

● Python ⭐ 5 📂 7

[numba-mpi](#)

Numba @njittable MPI wrappers tested on Linux, macOS and Windows

● Python 📂 2

[PySDM-examples](#)

PySDM usage examples (mostly reproducing results from literature) depicting how to use PySDM in Python, in particular from Jupyter notebooks

● Jupyter Notebook ⭐ 1 📂 4

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PySDM: backends, dynamics & environments

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- ▶ CPU (Numba/LLVM)
- ▶ GPU (ThrustRTC/CUDA)

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“dynamics”

- ▶ coalescence (SDM + dt-adaptivity)
- ▶ condensation (dt-adaptive,
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- ▶ displacement (incl. sedimentation)
- ▶ aqueous chemistry (Hoppel gap)
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“environments”

- ▶ Box
- ▶ Parcel
- ▶ PyMPDATA-based:
 - ▶ Kinematic1D
 - ▶ Kinematic2D
- ▶ PySDMachine.jl (planned)

PySDM: 2D kinematic Sc test (Morrison & Grabowski '07)

2D flow field

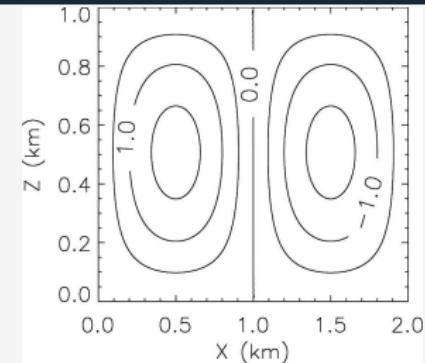
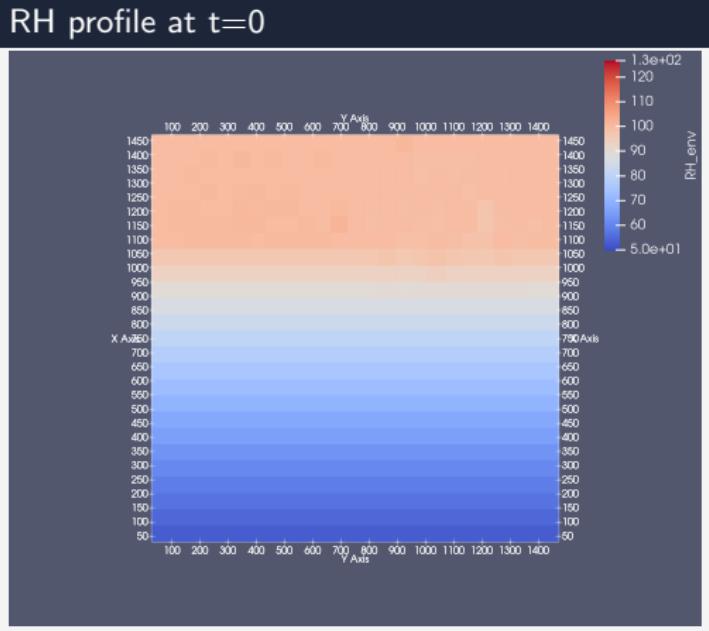
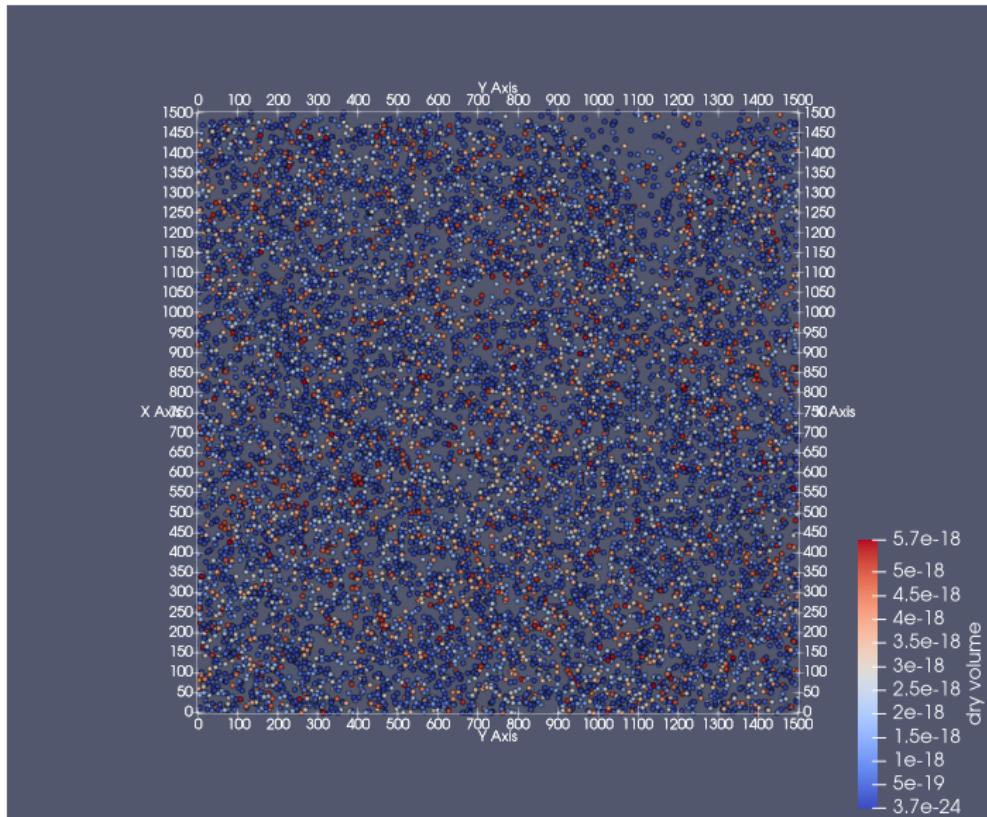


FIG. 1. Time-invariant vertical velocity for the stratocumulus case (contour interval is 0.5 m s^{-1}).

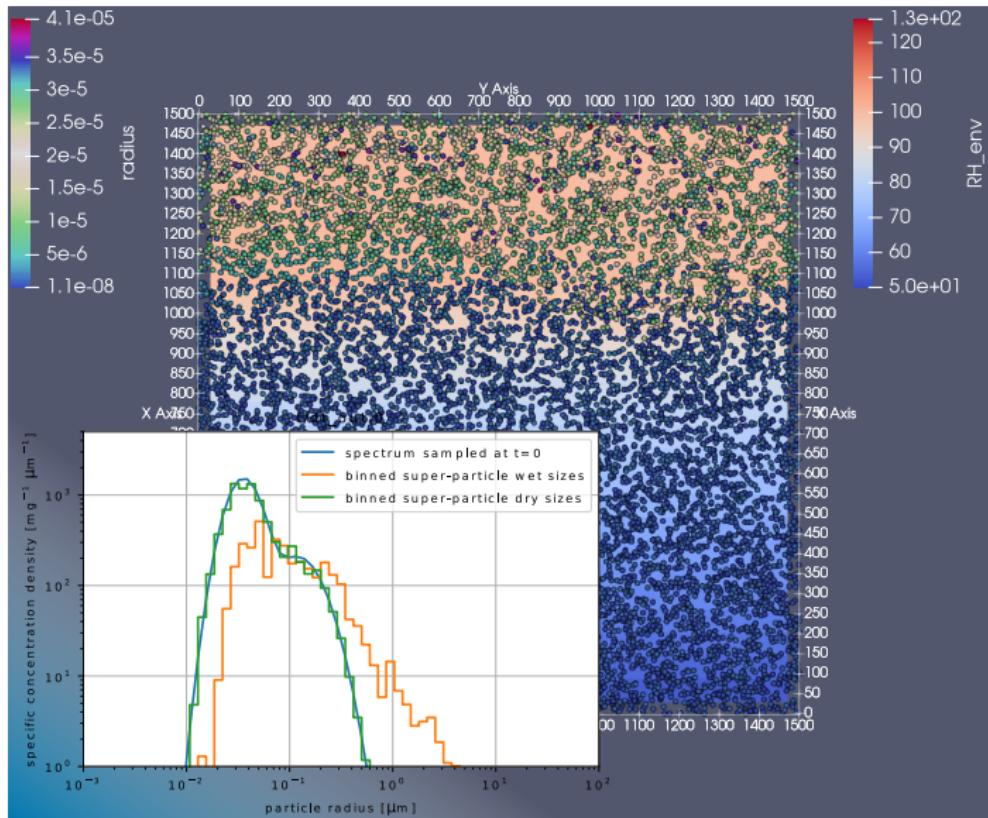
RH profile at $t=0$



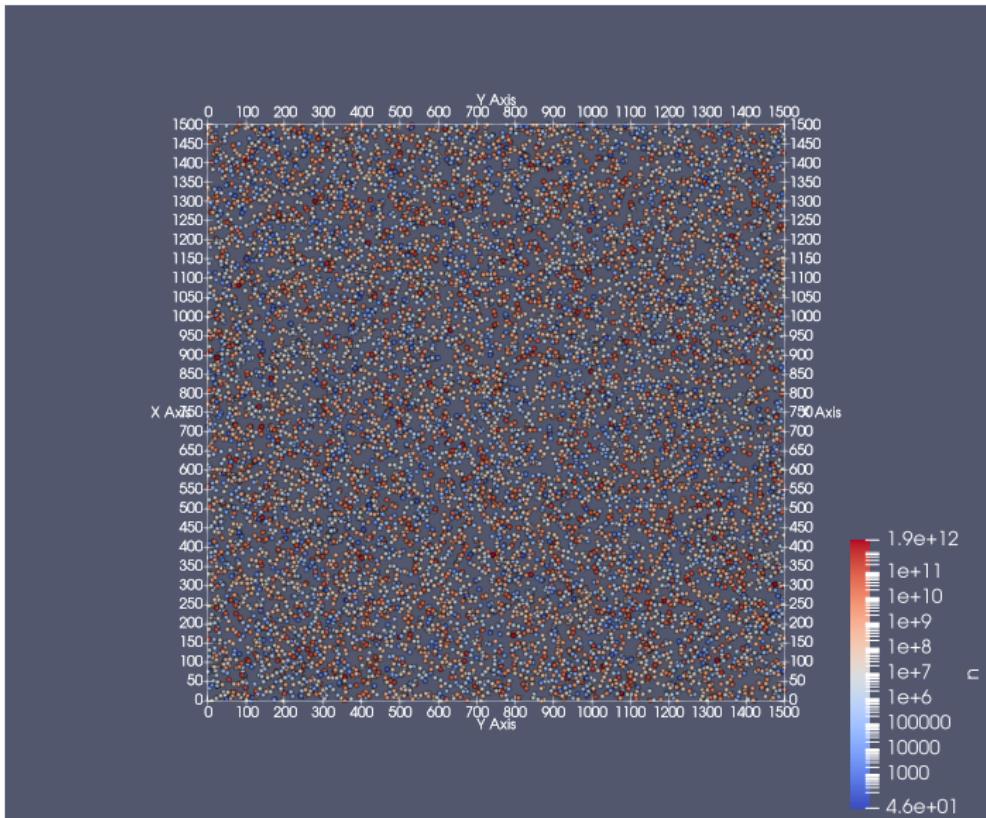
particle attribute initialisation: dry/wet volume



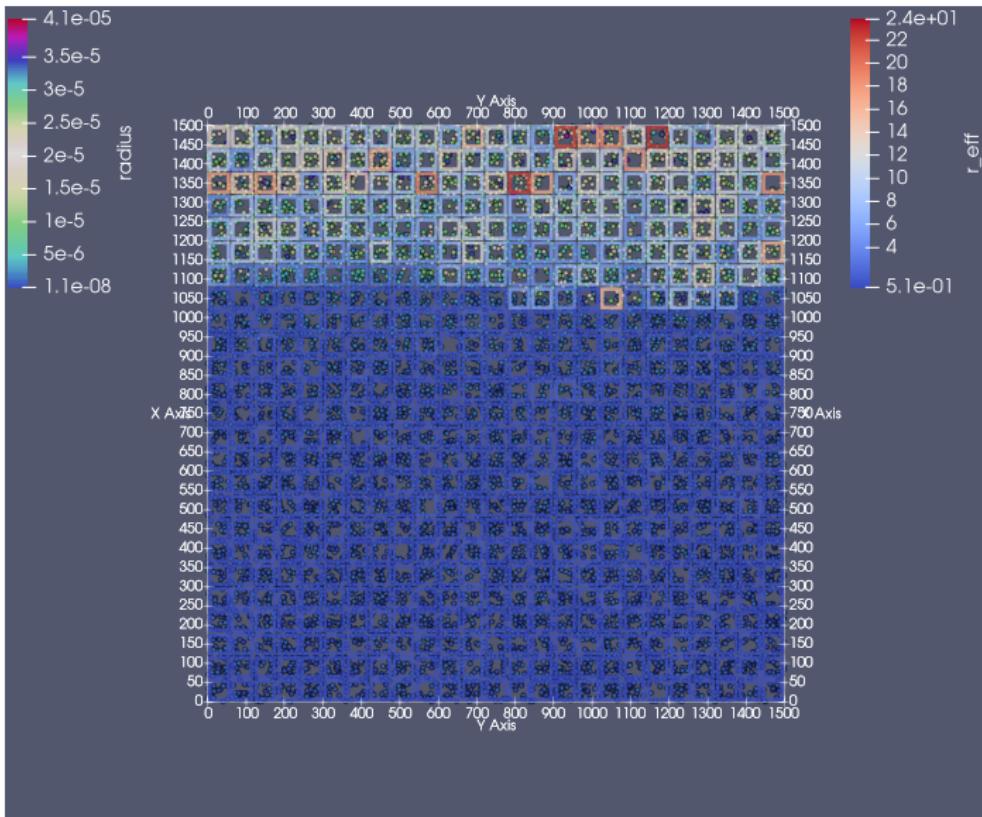
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particle attribute initialisation: multiplicity

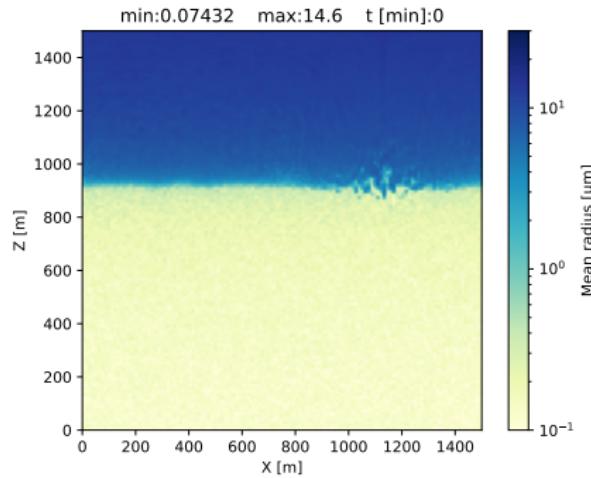
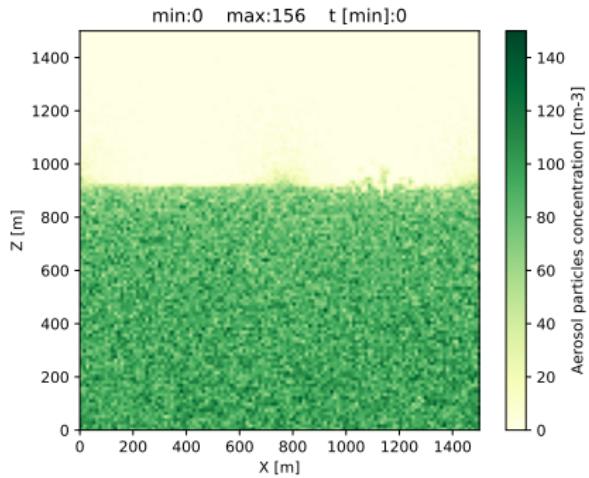


particle attribute evolution: droplet radius



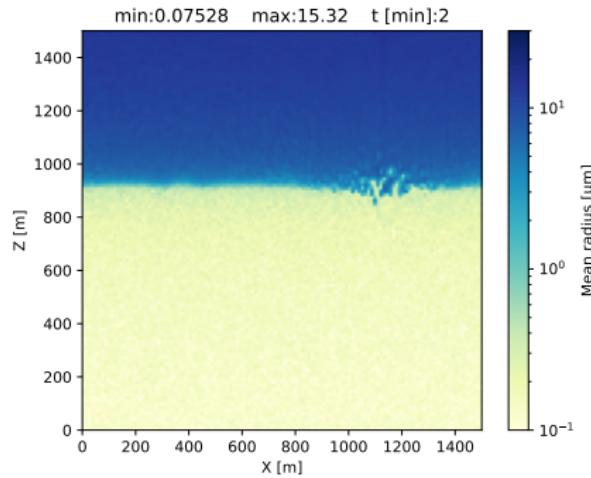
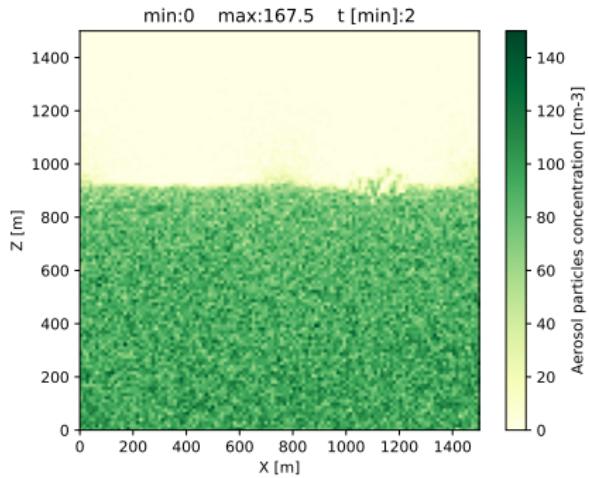
sample aerosol-cloud-precipitation interactions simulation

Computational grid: 128x128
Computational particles: 2^{21}



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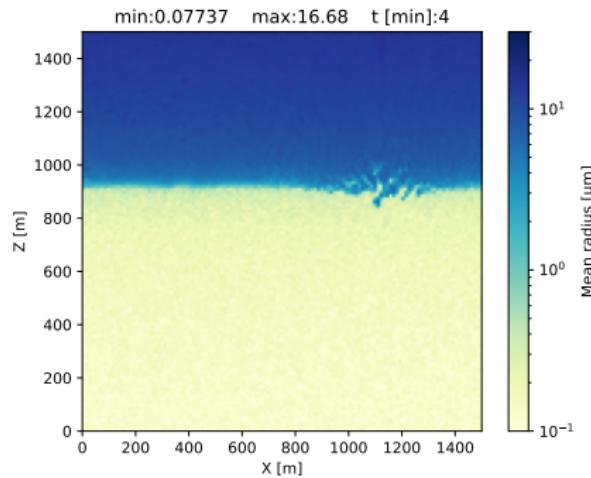
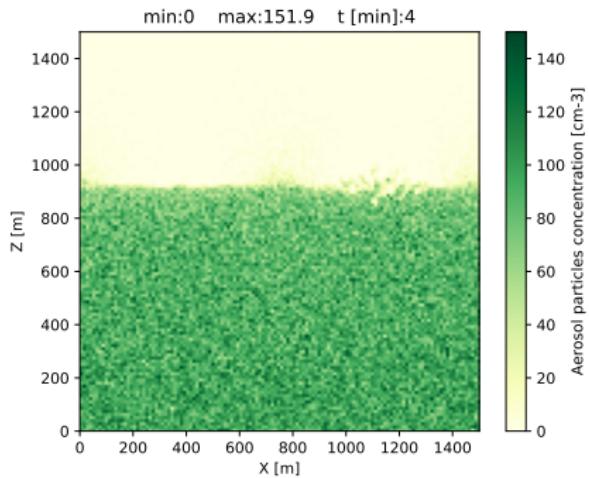
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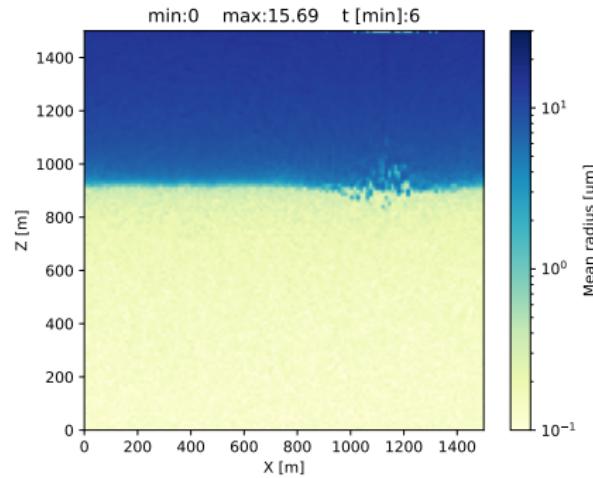
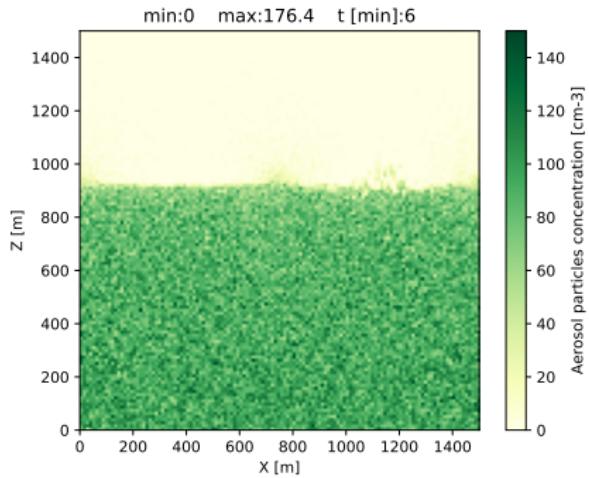
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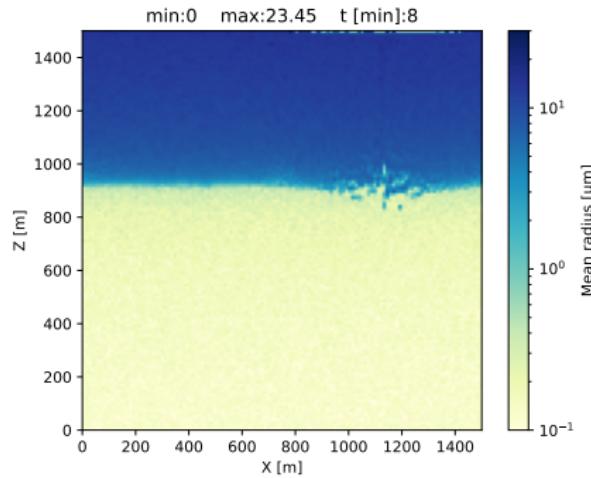
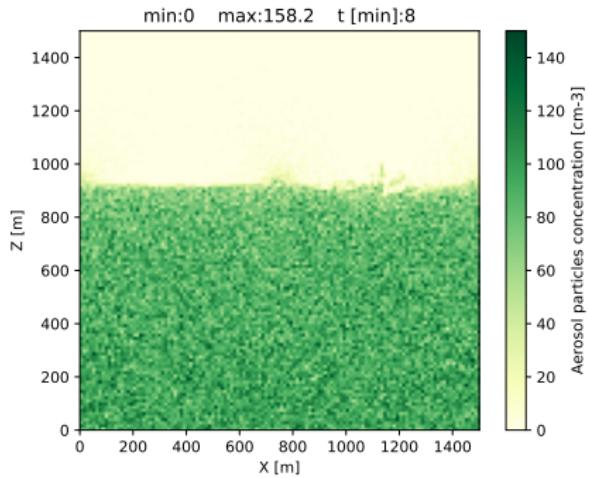
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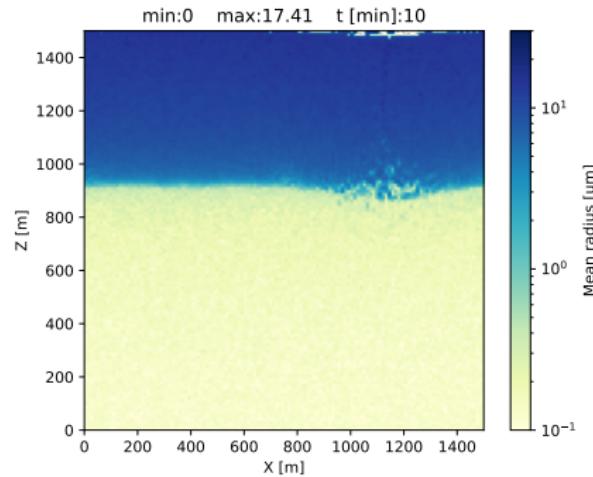
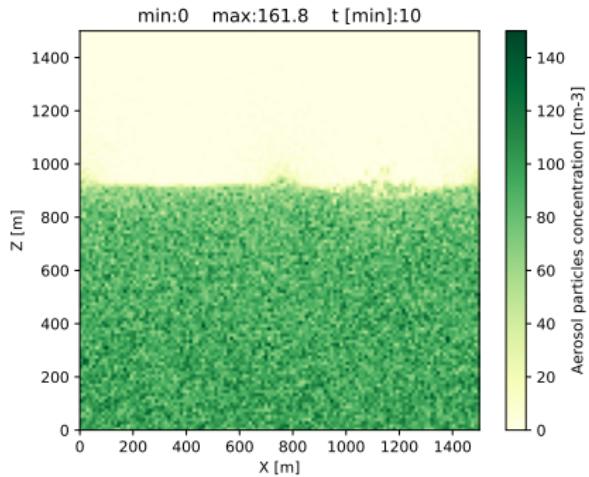
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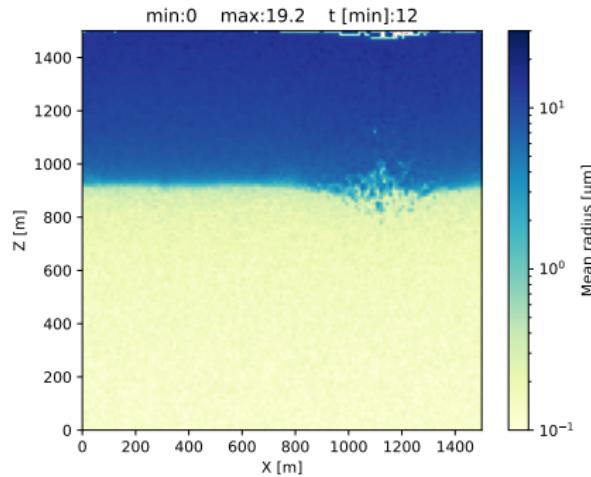
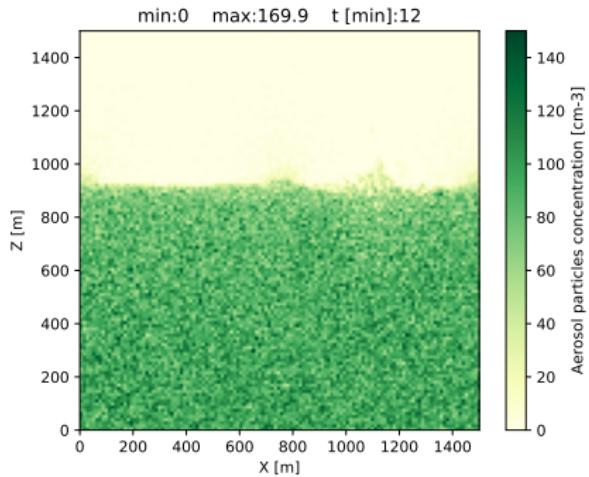
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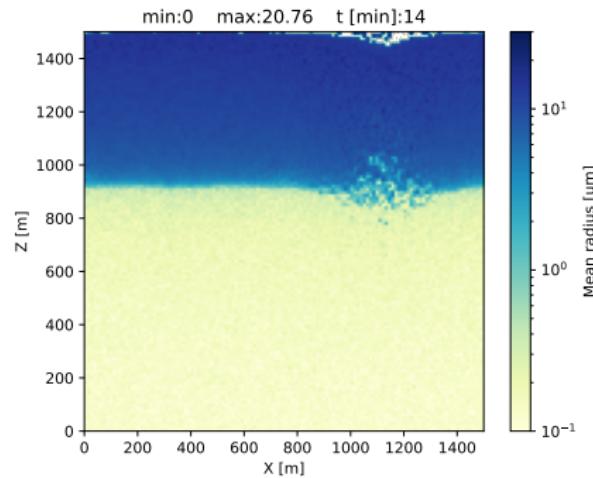
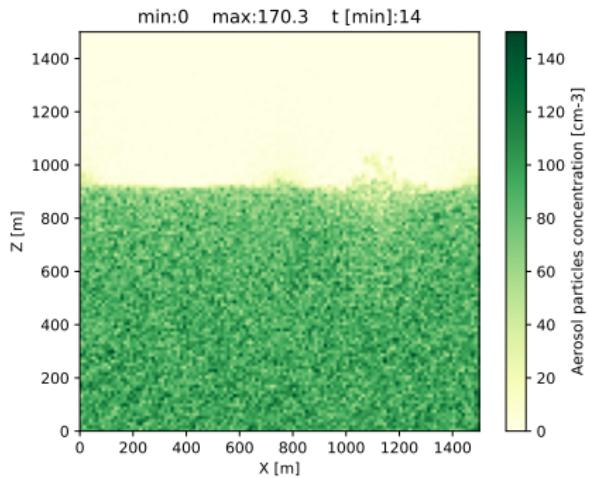
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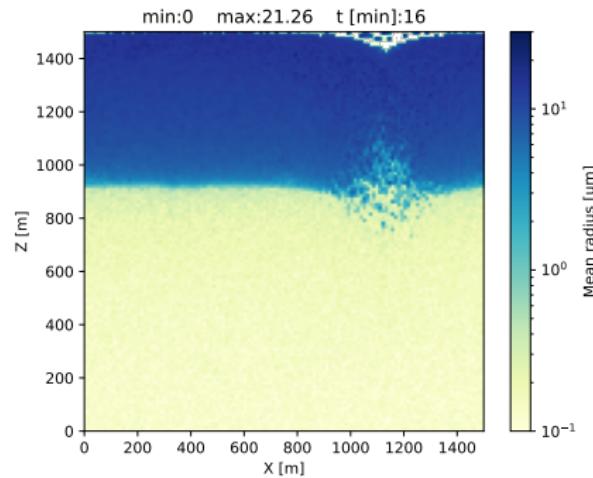
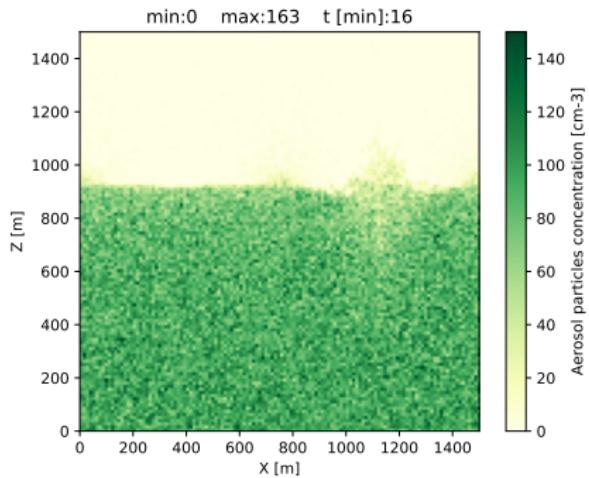
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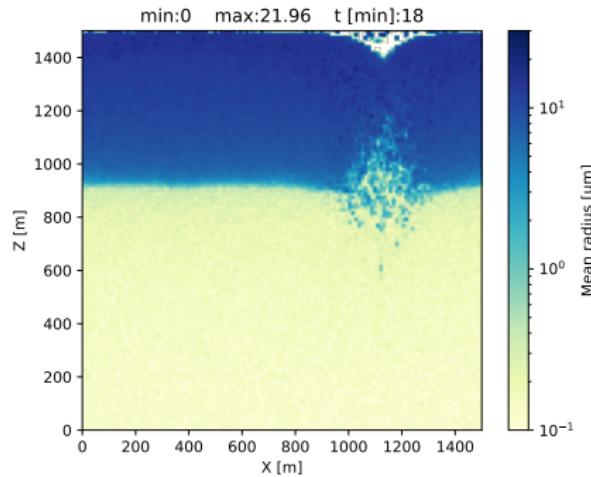
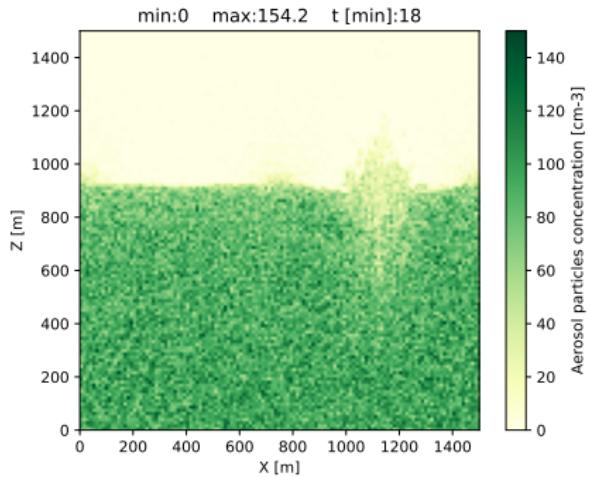
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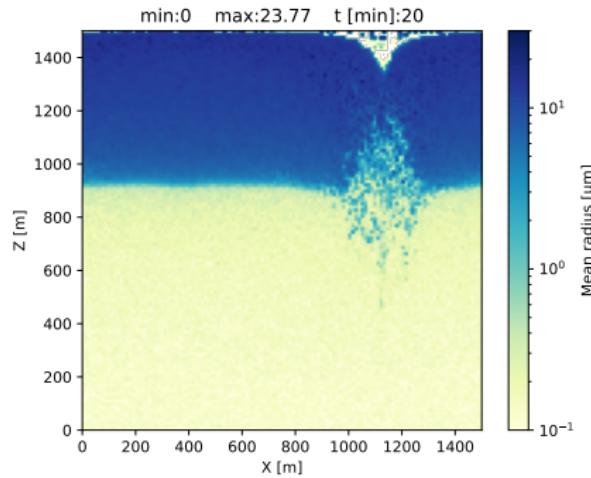
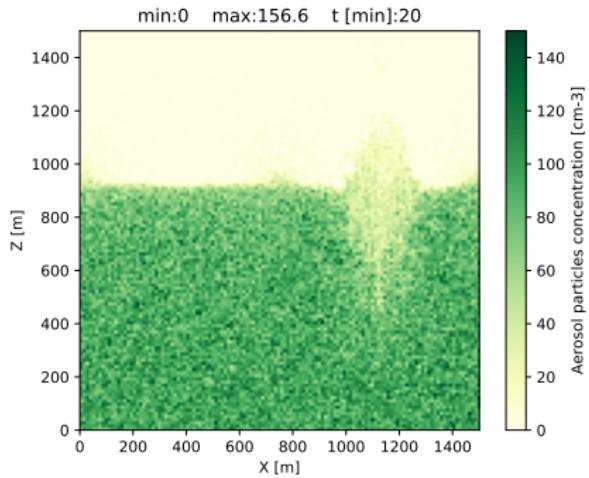
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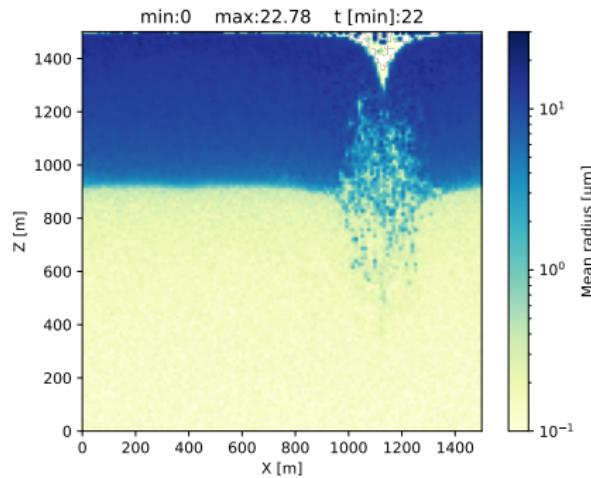
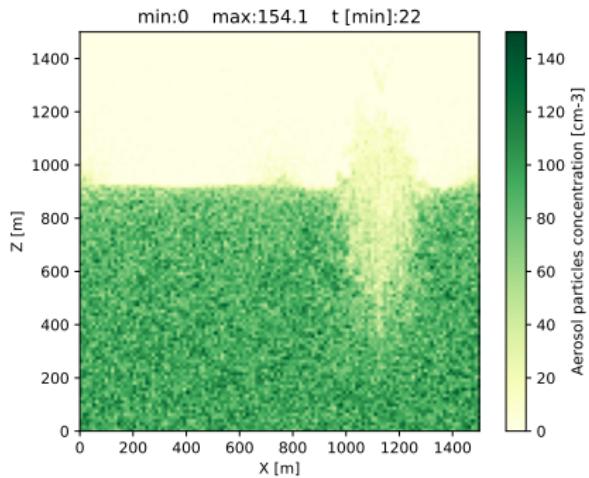
sample aerosol-cloud-precipitation interactions simulation

Computational grid: 128x128
Computational particles: 2^{21}



sample aerosol-cloud-precipitation interactions simulation

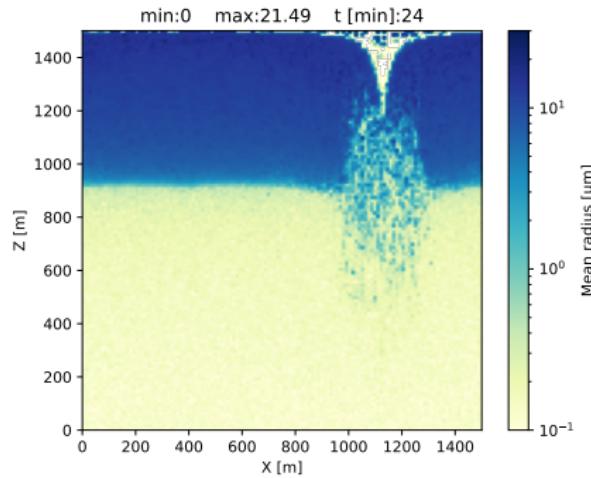
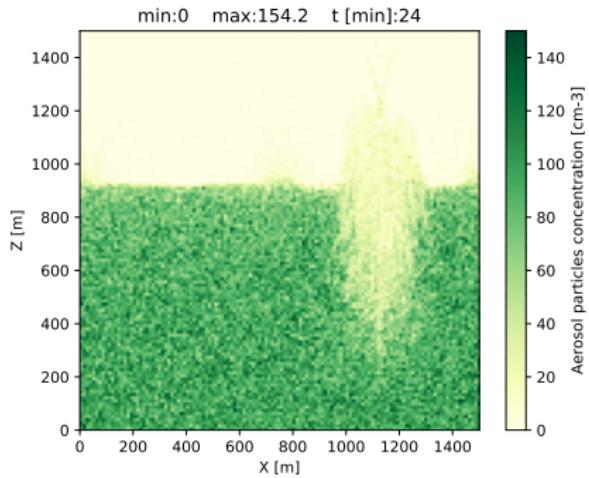
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Computational particles: 2^{21}



sample aerosol-cloud-precipitation interactions simulation

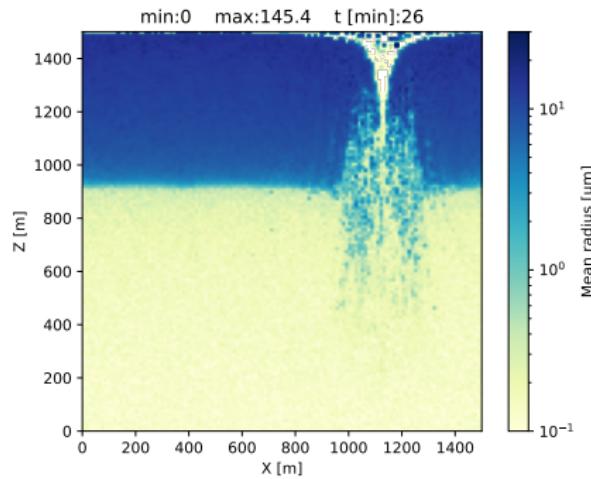
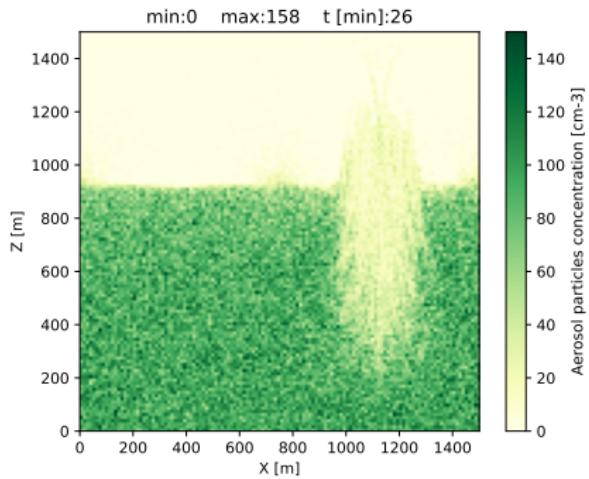
Computational grid: 128x128

Computational particles: 2^{21}



sample aerosol-cloud-precipitation interactions simulation

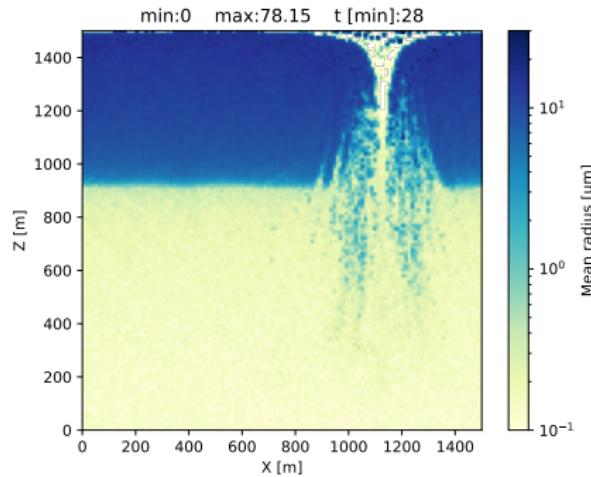
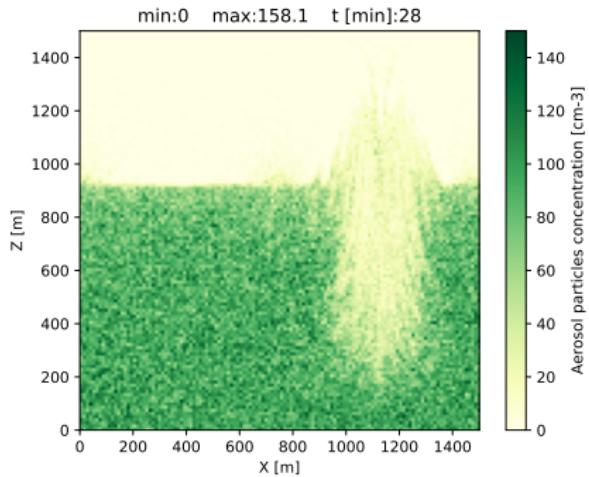
Computational grid: 128x128
Computational particles: 2^{21}



sample aerosol-cloud-precipitation interactions simulation

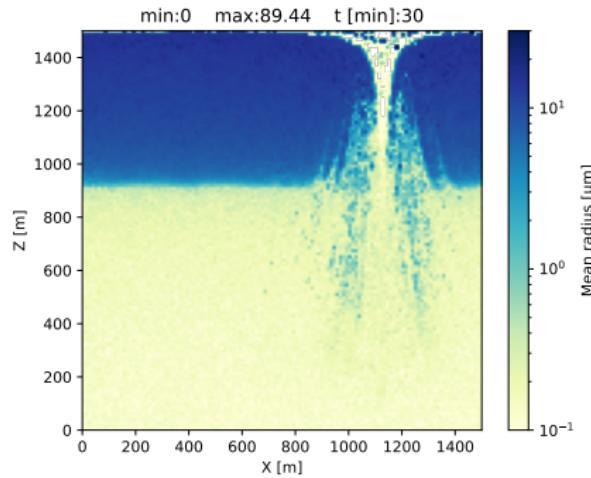
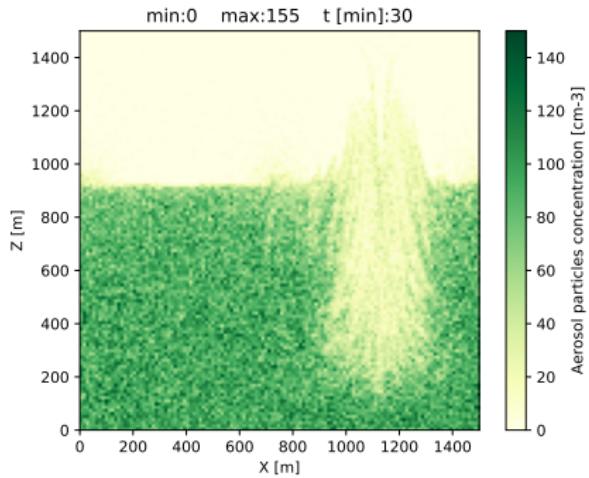
Computational grid: 128x128

Computational particles: 2^{21}



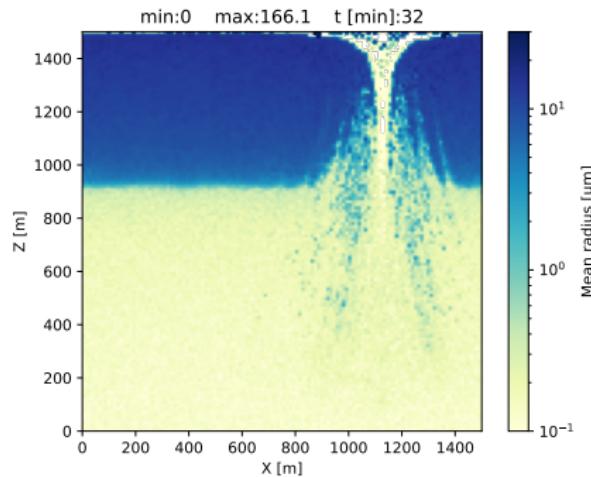
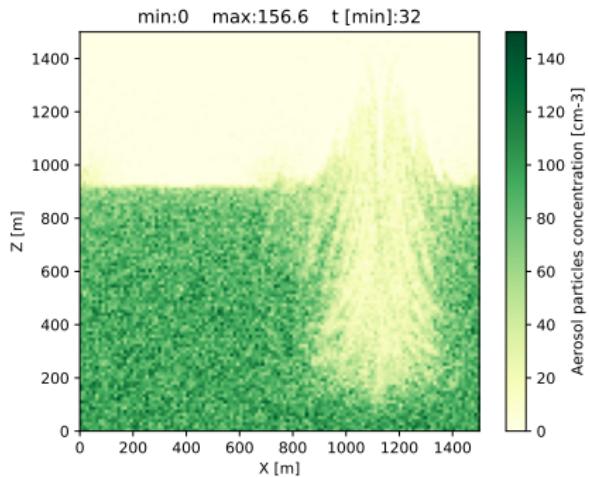
sample aerosol-cloud-precipitation interactions simulation

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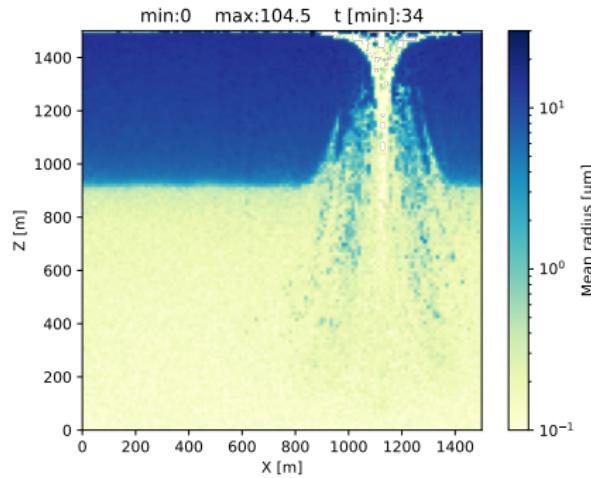
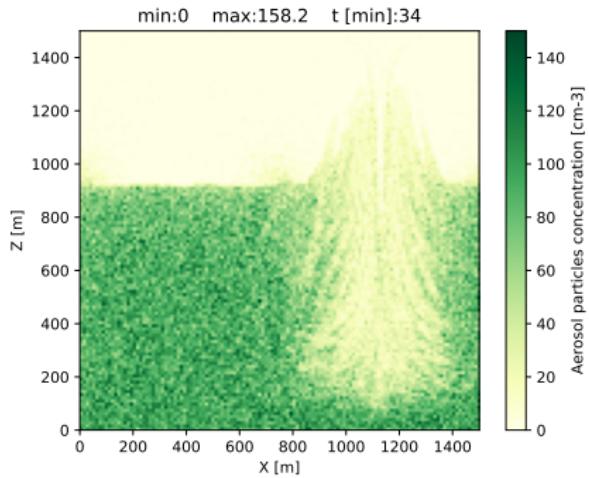
sample aerosol-cloud-precipitation interactions simulation

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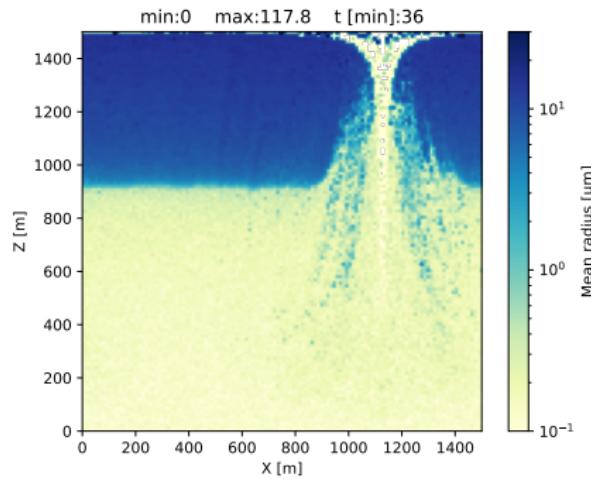
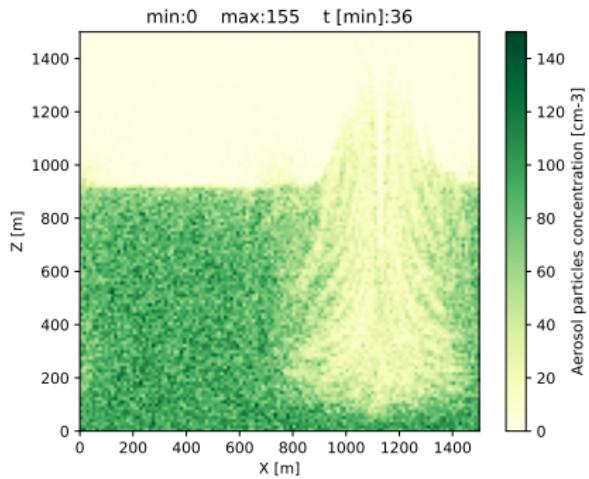
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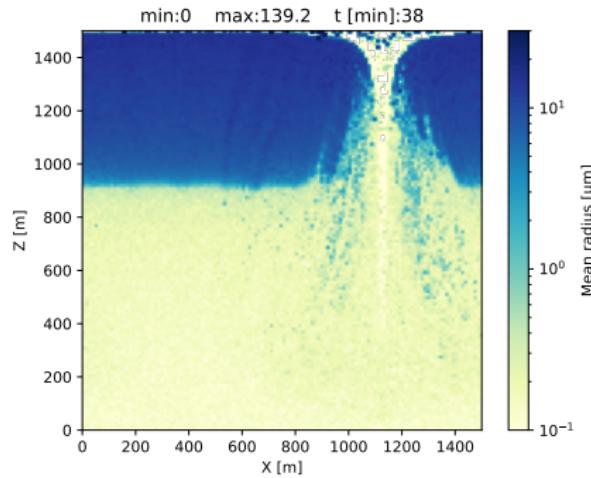
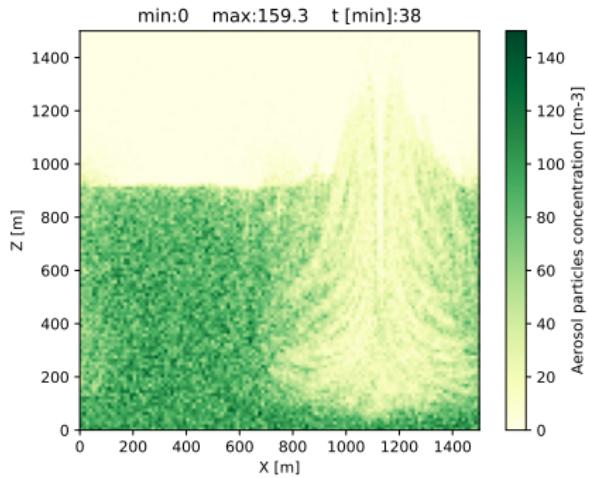
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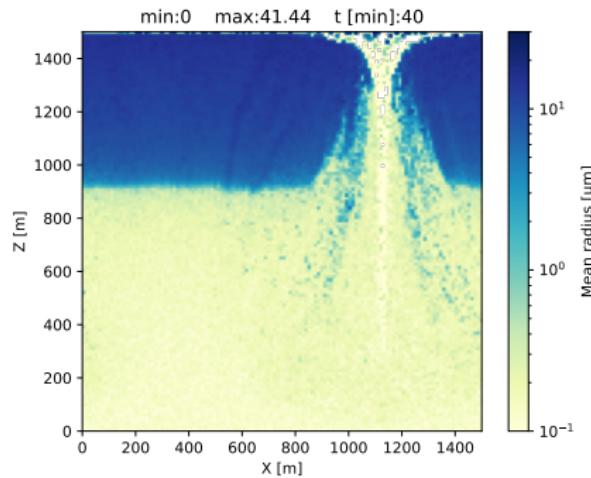
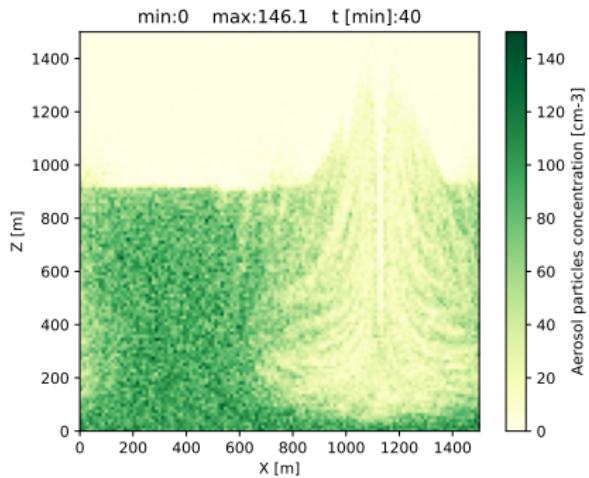
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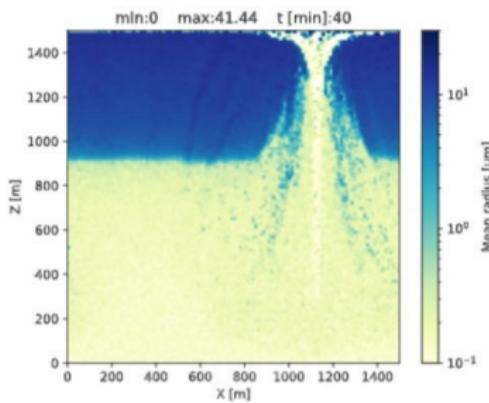
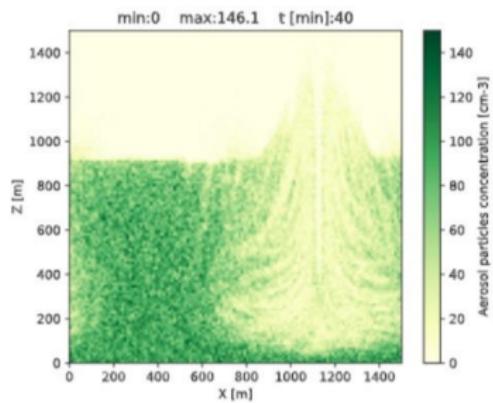


sample aerosol-cloud-precipitation interactions simulation

Computational grid: 128x128
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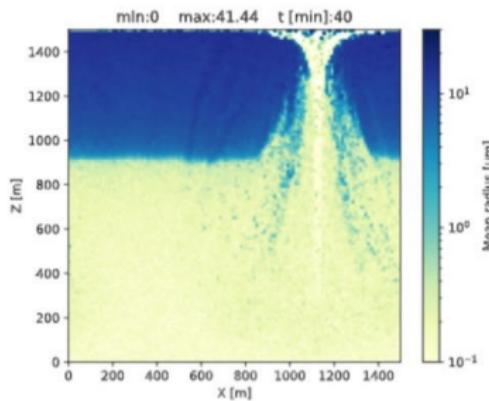
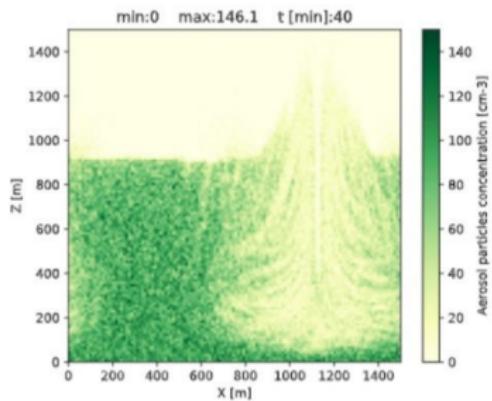


PySDM:



PySDM: Pythonic

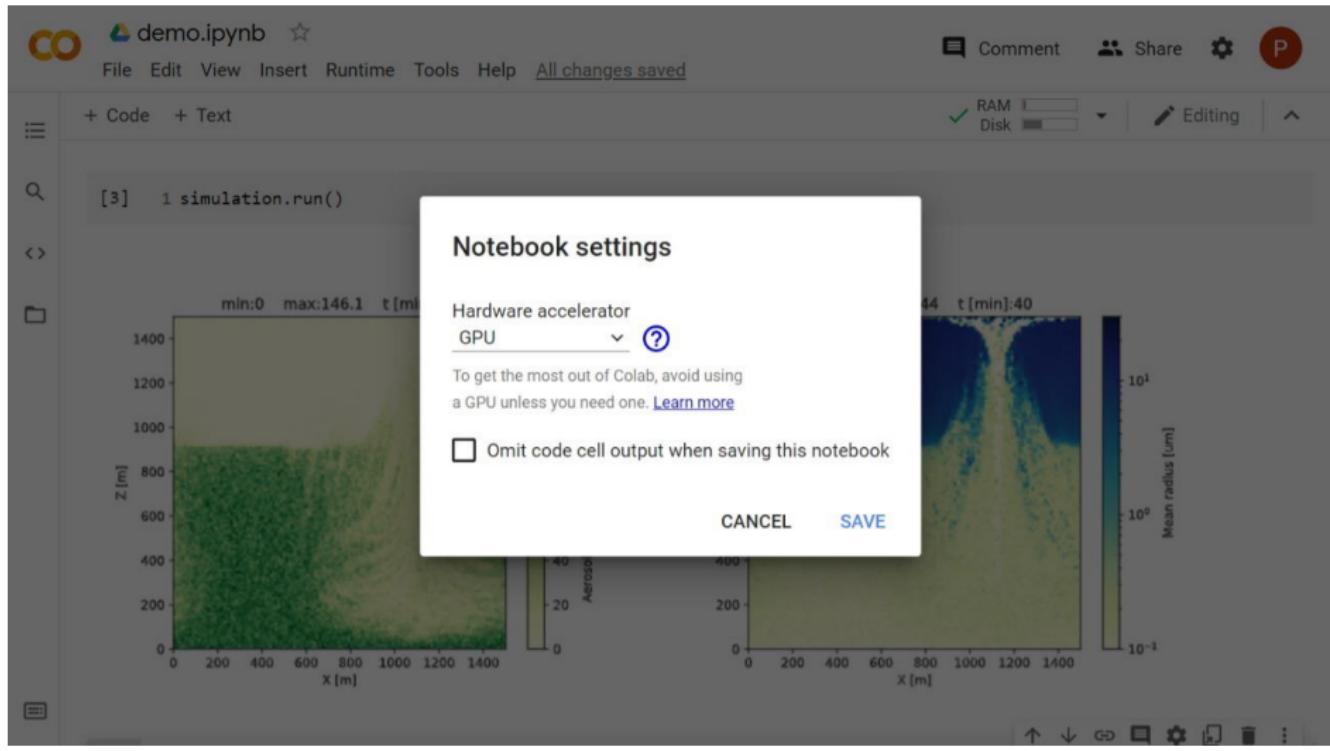
```
[3] 1 simulation.run()
```



PySDM: Pythonic, Jupyter-friendly



PySDM: Pythonic, Jupyter-friendly, GPU-enabled



Plan of the talk

PySDM: context

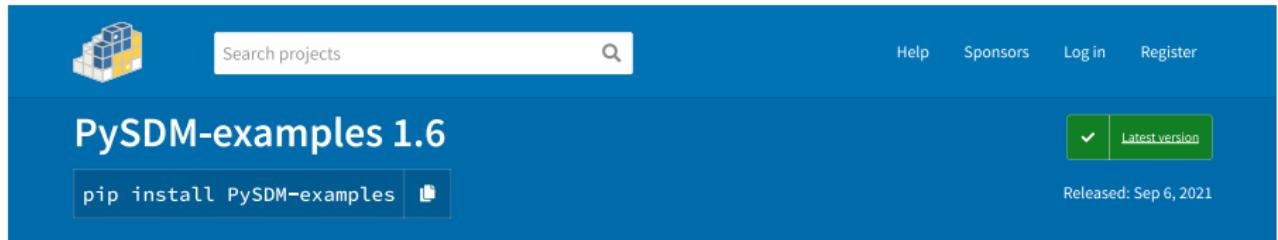
PySDM: statement of need & goals

PySDM: tour of the features

PySDM: demo (role play: reviewer)

PySDM: technological stack

PySDM-examples: pypi.org/p/PySDM-examples



The screenshot shows the PySDM-examples project page on PyPI. At the top, there's a search bar with "Search projects" and a magnifying glass icon. To the right are links for "Help", "Sponsors", "Log in", and "Register". Below the search bar is a logo of a 3D cube made of smaller cubes, followed by the project name "PySDM-examples 1.6". To the right of the name is a dropdown menu with "Latest version" selected. Below the project name is a button with "pip install PySDM-examples" and a pip icon. To the right of the button is the release date "Released: Sep 6, 2021".

Navigation

Project description

[Release history](#)

[Download files](#)

Project links

[Homepage](#)

Statistics

View statistics for this project via [Libraries.io](#), or by using [our public dataset on Google BigQuery](#).

Meta

License: [GPL-3.0](#)

Project description

This repository stores example files for `PySDM` depicting usage of `PySDM` from Python via Jupyter. For information on the `PySDM` package itself and examples of usage from Julia and Matlab, see [PySDM README.md](#) file.

Please use the [PySDM issue-tracking](#) and [discussion](#) infrastructure for `PySDM-examples` as well.

0D box-model coalescence-only examples:

- [Shima et al. 2009](#) (Box model, coalescence only, test case employing Golovin analytical solution):
 - Fig. 2: [Launch binder](#) [Open in Colab](#)
- [Berry 1967](#) (Box model, coalescence only, test cases for realistic kernels):
 - Figs. 5, 8 & 10: [Launch binder](#) [Open in Colab](#)

0D parcel-model condensation only examples:

- [Arabas & Shima 2017](#) (monodisperse size spectrum activation/deactivation test case):
 - Fig. 5: [Launch binder](#) [Open in Colab](#)
- [Yang et al. 2018](#) (polydisperse size spectrum activation/deactivation test case):
 - Fig. 2: [Launch binder](#) [Open in Colab](#)
- [Lowe et al. 2019](#) (externally mixed polydisperse size spectrum with surface-active organics case):
 - Fig. 1: [Launch binder](#) [Open in Colab](#)
 - Fig. 2: [Launch binder](#) [Open in Colab](#)



<https://doi.org/10.1038/s41467-019-12982-0>

OPEN

Key drivers of cloud response to surface-active organics

S.J. Lowe^{1,2}, D.G. Partridge^{1,3}, J.F. Davies⁴, K.R. Wilson⁵, D. Topping⁶ & I. Riipinen^{1,2,7*}

Aerosol-cloud interactions constitute the largest source of uncertainty in global radiative forcing estimates, hampering our understanding of climate evolution. Recent empirical evidence suggests surface tension depression by organic aerosol to significantly influence the formation of cloud droplets, and hence cloud optical properties. In climate models, however, surface tension of water is generally assumed when predicting cloud droplet concentrations. Here we show that the sensitivity of cloud microphysics, optical properties and shortwave radiative effects to the surface phase are dictated by an interplay between the aerosol particle size distribution, composition, water availability and atmospheric dynamics. We demonstrate that accounting for the surface phase becomes essential in clean environments in which ultrafine particle sources are present. Through detailed sensitivity analysis, quantitative constraints on the key drivers - aerosol particle number concentrations, organic fraction and fixed updraft velocity - are derived for instances of significant cloud microphysical susceptibilities to the surface phase.

PySDM-examples: Lowe et al. 2019

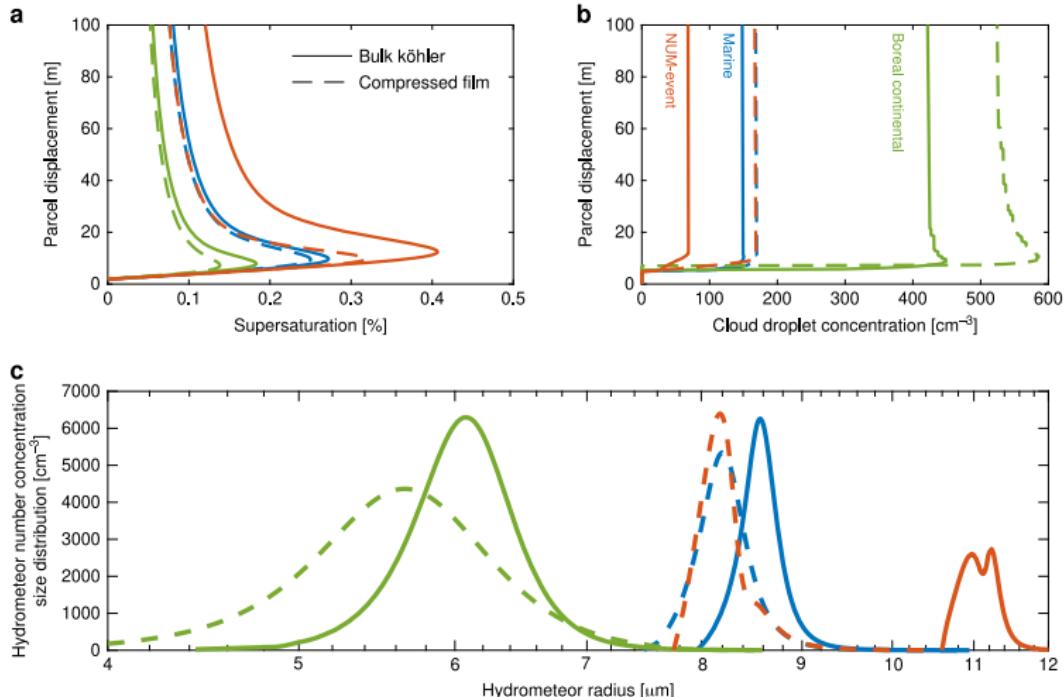


Fig. 2 Simulated microphysics of cloud events on marine (MA, blue), boreal (HYY, green) and NUM-event (NE, orange) aerosol populations. Cloud-formation event simulations using bulk Köhler BK (solid lines) and approximate compressed film CF (dotted lines) models of cloud droplet activation with initial temperature $T = 280$ K, pressure $P = 98,000$ Pa, supersaturation $s = -0.1\%$ and fixed updraft velocity $w = 0.32 \text{ ms}^{-1}$. Simulated (a) ambient parcel supersaturation and (b) cloud droplet number concentration during parcel ascent. c Simulated droplet size distribution at a parcel displacement 200 m above initialisation

PySDM-examples: Lowe et al. 2019

example contributed by Clare Singer et al.
(<https://claresinger.github.io/>)

The screenshot shows a Jupyter Notebook interface with two plots generated from the provided Python code.

Code:

```
[4]: figsize = (15, 5)
pylab.rc('font', size=14)
fig, axes = pylab.subplots(1, 2, figsize=figsize, sharey=True)

for idx, var in enumerate(['S_max', 'n_c_cm3']):
    for key in output.keys():
        Y = np.asarray(output[key][var])
        axes[idx].plot(output[key][var], Y, label=key,
                      color=output[key]['color'],
                      linestyle='-' if key.endswith('-bulk') else '--')
    axes[idx].set_yscale(0, 100)

    axes[idx].set_ylabel('Displacement [m]')
    if var == 'S_max':
        axes[idx].set_xlabel('Supersaturation [%]')
        axes[idx].set_xlim(0, 0.5)
    elif var == 'n_c_cm3':
        axes[idx].set_xlabel('Cloud droplet concentration (cm$^{-3}$)')
        axes[idx].set_xlim(0, 600)
    else:
        assert False

for ax in axes:
    ax.grid()
axes[0].legend()
```

Plots:

- Left Plot:** Displacement [m] vs Supersaturation [%]. The y-axis ranges from 0 to 100 m, and the x-axis ranges from 0.0 to 0.5%. It shows curves for different aerosol types:
 - AerosolMarine-bulk (blue solid)
 - AerosolMarine-film (blue dashed)
 - AerosolBoreal-bulk (green solid)
 - AerosolBoreal-film (green dashed)
 - AerosolNascent-bulk (orange solid)
 - AerosolNascent-film (orange dashed)The curves generally decrease as supersaturation increases, with marine aerosols showing higher displacement than boreal and nascent aerosols at higher supersaturations.
- Right Plot:** Displacement [m] vs Cloud droplet concentration [cm⁻³]. The y-axis ranges from 0 to 600 m, and the x-axis ranges from 0 to 600 cm⁻³. It shows the same six aerosol types. The curves show a sharp increase in displacement as concentration increases, with the transition occurring at different concentrations for each aerosol type.

Plan of the talk

PySDM: context

PySDM: statement of need & goals

PySDM: tour of the features

PySDM: demo (role play: reviewer)

PySDM: technological stack

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- ▶ Python python.org
- ▶ Numba (JIT, multi-threading)
numba.pydata.org
- ▶ ThrustRTC (GPU-resident backend)
pypi.org/project/ThrustRTC



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pypi.org/project/ThrustRTC
- ▶ GitHub & GitHub Actions github.com
- ▶ codecov codecov.io
- ▶ AppVeyor appveyor.com



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- ▶ GitHub & GitHub Actions github.com
- ▶ codecov codecov.io
- ▶ AppVeyor appveyor.com

- ▶ Jupyter jupyter.org
- ▶ Binder mybinder.org
- ▶ Colab colab.research.google.com



PySDM backend architecture overview



[International Conference on Computational Science](#)

... ICCS 2021: [Computational Science – ICCS 2021](#) pp 16–30 | [Cite as](#)

On the Design of Monte-Carlo Particle Coagulation Solver Interface: A CPU/GPU Super-Droplet Method Case Study with PySDM

Authors

[Authors and affiliations](#)

Piotr Bartman  , Sylwester Arabas

Conference paper

First Online: 09 June 2021



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Downloads

Part of the [Lecture Notes in Computer Science](#) book series (LNCS, volume 12743)

PySDM: GPU backend internals

```
1 _kernel = ThrustRTC.For(
2     ['perm_cell_start', 'perm_cell_id', 'pair_flag', 'length'], "i", ''
3     pair_flag[i] =
4         i < length - 1 &&
5         perm_cell_id[i] == perm_cell_id[i+1] &&
6         (i - perm_cell_start[perm_cell_id[i]]) % 2 == 0
7     );
8   ''
9
10 def flag_pairs(pair_flag, cell_start, cell_id, cell_idx):
11     perm_cell_id = ThrustRTC.DVPermutation(cell_id.data, cell_id.idx.data)
12     perm_cell_start = ThrustRTC.DVPermutation(cell_start.data, cell_idx.data)
13     d_length = ThrustRTC.DVInt64(len(cell_id))
14     _kernel.launch_n(len(cell_id),
15                     [perm_cell_start, perm_cell_id, cell_idx.data,
16                      pair_flag.indicator.data, d_length])
```

PySDM: CPU/multi-threaded backend internals

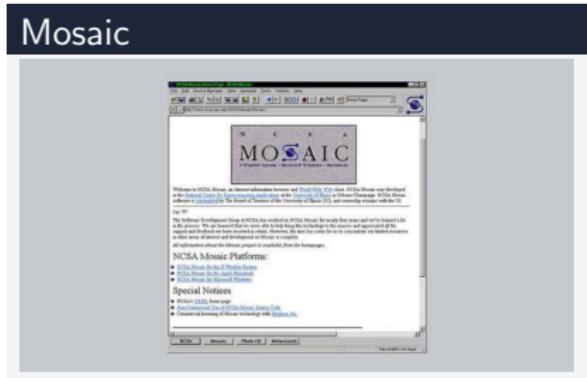
```
1 @numba.njit(parallel=True, error_model='numpy')
2 def _update_attributes(length, n, attributes, idx, gamma):
3     for i in prange(length//2):
4         j = idx[2*i]
5         k = idx[2*i + 1]
6         if n[j] < n[k]:
7             j, k = k, j
8         g = min(int(gamma[i]), int(n[j] / n[k]))
9         if g == 0:
10             continue
11         new_n = n[j] - g * n[k]
12         if new_n > 0:
13             n[j] = new_n
14             for attr in range(0, len(attributes)):
15                 attributes[attr, k] += g * attributes[attr, j]
16         else: # new_n == 0
17             n[j] = n[k] // 2
18             n[k] = n[k] - n[j]
19             for attr in range(0, len(attributes)):
20                 attributes[attr, j] = attributes[attr, j] * g \
21                             + attributes[attr, k]
22                 attributes[attr, k] = attributes[attr, j]
23
24 def update_attributes(n, intensive, attributes, gamma):
25     _update_attributes(len(n.idx),
26                       n.data, intensive.data, attributes.data,      # in/out
27                       n.idx.data, gamma.data)                         # in
```

UIUC-originated breakthroughs

MRI



Mosaic



LED



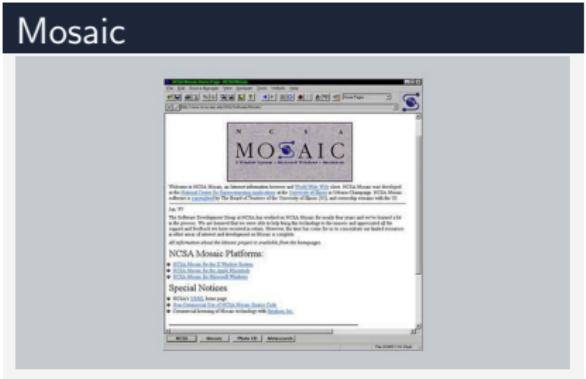
graphics from <https://illinois.edu>, <https://llvm.org>

UIUC-originated breakthroughs

MRI



Mosaic



LED



Instantwhip?

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UIUC-originated breakthroughs

MRI



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LLVM!



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Thank you for your attention!

<https://arxiv.org/abs/2103.17238> (**Bartman et al. 2021, arXiv/JOSS**)

https://doi.org/10.1007/978-3-030-77964-1_2 (**Bartman & Arabas 2021, LNCS**)

[&](https://pypi.org/p/PySDM) <https://pypi.org/p/PySDM-examples>