For simplicity, let us consider functions with finite domains first.

Let $\mathcal{X} = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)}\}$ be a finite set of elements and \mathcal{H} the set of all functions from $\mathcal{X} \to \mathbb{R}$.

Remark: \mathcal{X} does not mean the training data here but means the "real" domain of the functions.

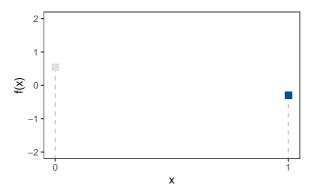
Since the domain of any $f(.) \in \mathcal{H}$ has only n elements, we can represent the function f(.) compactly as a n-dimensional vector

$$\mathbf{f} = \left[f\left(\mathbf{x}^{(1)}\right), \dots, f\left(\mathbf{x}^{(n)}\right) \right].$$

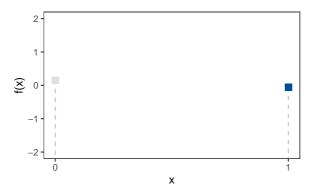




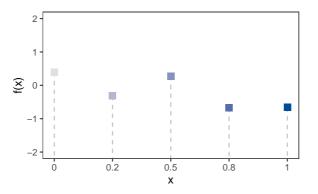




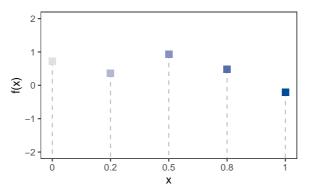




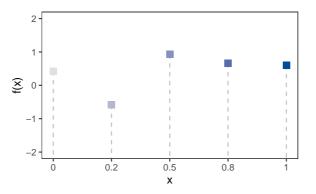




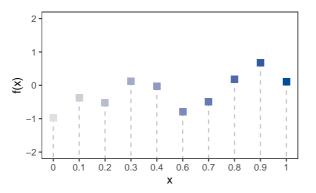




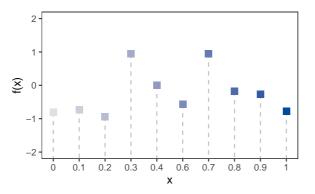




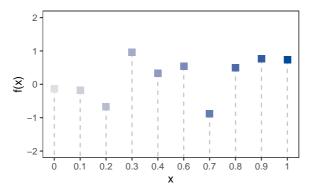














DISTRIBUTIONS ON DISCRETE FUNCTIONS

One natural way to specify a probability function on a discrete function $f \in \mathcal{H}$ is to use the vector representation

$$\mathbf{f} = \left[f\left(\mathbf{x}^{(1)}\right), f\left(\mathbf{x}^{(2)}\right), \dots, f\left(\mathbf{x}^{(n)}\right) \right]$$

of the function.

Let us see *f* as a *n*-dimensional random variable. We will further assume the following normal distribution:

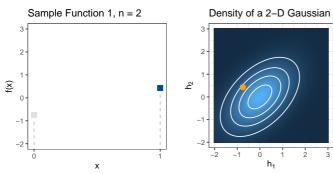
$$extbf{\emph{f}} \sim \mathcal{N}\left(extbf{\emph{m}}, extbf{\emph{K}}
ight).$$

Note: For now, we set m = 0 and take the covariance matrix K as given. We will see later how they are chosen / estimated.



Let $f: \mathcal{X} \to \mathbb{R}$. Sample functions by sampling from a two-dimensional normal variable.

$$\mathbf{f} = [f(1), f(2)] \sim \mathcal{N}(\mathbf{m}, \mathbf{K})$$

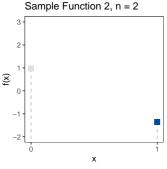


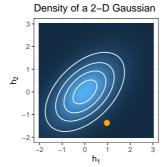
In this example,
$$m = (0,0)$$
 and $K = \begin{pmatrix} 1 & 0.5 \\ 0.5 & 1 \end{pmatrix}$.



Let $f: \mathcal{X} \to \mathbb{R}$. Sample functions by sampling from a two-dimensional normal variable.

$$\mathbf{f} = [f(1), f(2)] \sim \mathcal{N}(\mathbf{m}, \mathbf{K})$$



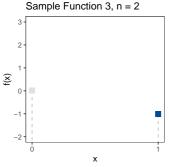


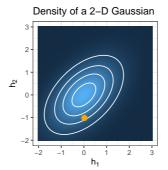
In this example, m = (0,0) and $K = \begin{pmatrix} 1 & 0.5 \\ 0.5 & 1 \end{pmatrix}$.



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$$\mathbf{f} = [f(1), f(2)] \sim \mathcal{N}(\mathbf{m}, \mathbf{K})$$



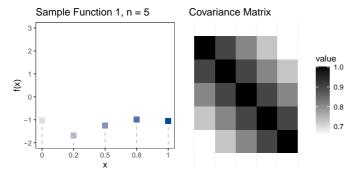


In this example, m = (0,0) and $K = \begin{pmatrix} 1 & 0.5 \\ 0.5 & 1 \end{pmatrix}$.



Let $f: \mathcal{X} \to \mathbb{R}$. Sample functions by sampling from a five-dimensional normal variable.

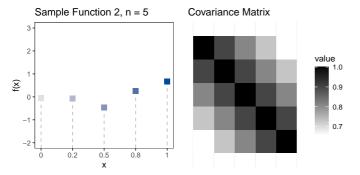
$$\textit{\textbf{f}} = [\textit{f}(1), \textit{f}(2), \textit{f}(3), \textit{f}(4), \textit{f}(5)] \sim \mathcal{N}(\textit{\textbf{m}}, \textit{\textbf{K}})$$





Let $f: \mathcal{X} \to \mathbb{R}$. Sample functions by sampling from a five-dimensional normal variable.

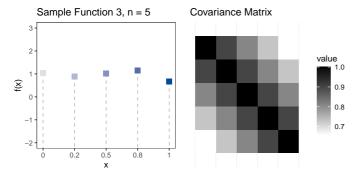
$$extbf{\emph{f}} = [f(1), f(2), f(3), f(4), f(5)] \sim \mathcal{N}(extbf{\emph{m}}, extbf{\emph{K}})$$





Let $f: \mathcal{X} \to \mathbb{R}$. Sample functions by sampling from a five-dimensional normal variable.

$$extbf{\emph{f}} = [f(1), f(2), f(3), f(4), f(5)] \sim \mathcal{N}(extbf{\emph{m}}, extbf{\emph{K}})$$



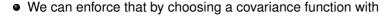


ROLE OF THE COVARIANCE FUNCTION

• "Meaningful" functions (on a numeric space \mathcal{X}) may be characterized by a spatial property:

If two points $\mathbf{x}^{(i)}$, $\mathbf{x}^{(j)}$ are close in \mathcal{X} -space, their function values $f(\mathbf{x}^{(i)})$, $f(\mathbf{x}^{(j)})$ should be close in \mathcal{Y} -space.

In other words: If they are close in \mathcal{X} -space, their functions values should be **correlated**!



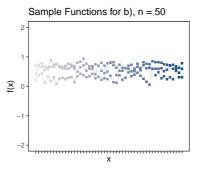
$$K_{ij}$$
 high, if $\mathbf{x}^{(i)}, \mathbf{x}^{(j)}$ close.



ROLE OF THE COVARIANCE FUNCTION

b) Correlation almost 1:
$$\mathbf{K} = \begin{pmatrix} 1 & 0.99 & \dots & 0.99 \\ 0.99 & 1 & \dots & 0.99 \\ 0.99 & 0.99 & \ddots & 0.99 \\ 0.99 & \dots & 0.99 & 1 \end{pmatrix}$$
.





Points are highly correlated. Functions become very smooth and flat.