## TRAINING OF A GAUSSIAN PROCESS

- To make predictions for a regression task by a Gaussian process, one simply needs to perform matrix computations.
- But for this to work out, we assume that the covariance functions is fully given, including all of its hyperparameters.
- A very nice property of GPs is that we can learn the numerical hyperparameters of a selected covariance function directly during GP training.

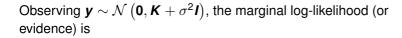


## TRAINING A GP VIA MAXIMUM LIKELIHOOD

Let us assume

$$y = f(\mathbf{x}) + \epsilon, \ \epsilon \sim \mathcal{N}(0, \sigma^2),$$

where  $f(\mathbf{x}) \sim \mathcal{GP}(\mathbf{0}, k(\mathbf{x}, \mathbf{x}'|\boldsymbol{\theta}))$ .



$$\log p(\mathbf{y} \mid \mathbf{X}, \boldsymbol{\theta}) = \log \left[ (2\pi)^{-n/2} |\mathbf{K}_{y}|^{-1/2} \exp \left( -\frac{1}{2} \mathbf{y}^{\top} \mathbf{K}_{y}^{-1} \mathbf{y} \right) \right]$$
$$= -\frac{1}{2} \mathbf{y}^{T} \mathbf{K}_{y}^{-1} \mathbf{y} - \frac{1}{2} \log |\mathbf{K}_{y}| - \frac{n}{2} \log 2\pi.$$

with  $K_y := K + \sigma^2 I$  and  $\theta$  denoting the hyperparameters (the parameters of the covariance function).



## TRAINING A GP: EXAMPLE

To visualize this, we consider a zero-mean Gaussian process with squared exponential kernel

$$k(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{1}{2\ell^2}\|\mathbf{x} - \mathbf{x}'\|^2\right),$$

- Recall, the model is smoother and less complex for higher length-scale  $\ell$ .
- We show how the
  - data fit  $-\frac{1}{2} \mathbf{y}^T \mathbf{K}_{y}^{-1} \mathbf{y}$ ,
  - the complexity penalty  $-\frac{1}{2} \log |\mathbf{K}_y|$ , and
  - ullet the overall value of the marginal likelihood  $\log p(m{y} \mid m{X}, m{ heta})$

behave for increasing value of  $\ell$ .



## TRAINING A GP VIA MAXIMUM LIKELIHOOD

To set the hyperparameters by maximizing the marginal likelihood, we seek the partial derivatives w.r.t. the hyperparameters

$$\frac{\partial}{\partial \theta_{j}} \log p(\mathbf{y} \mid \mathbf{X}, \boldsymbol{\theta}) = \frac{\partial}{\partial \theta_{j}} \left( -\frac{1}{2} \mathbf{y}^{\mathsf{T}} \mathbf{K}_{y}^{-1} \mathbf{y} - \frac{1}{2} \log |\mathbf{K}_{y}| - \frac{n}{2} \log 2\pi \right) 
= \frac{1}{2} \mathbf{y}^{\mathsf{T}} \mathbf{K}^{-1} \frac{\partial \mathbf{K}}{\partial \theta_{j}} \mathbf{K}^{-1} \mathbf{y} - \frac{1}{2} \operatorname{tr} \left( \mathbf{K}^{-1} \frac{\partial \mathbf{K}}{\partial \boldsymbol{\theta}} \right) 
= \frac{1}{2} \operatorname{tr} \left( (\mathbf{K}^{-1} \mathbf{y} \mathbf{y}^{\mathsf{T}} \mathbf{K}^{-1} - \mathbf{K}^{-1}) \frac{\partial \mathbf{K}}{\partial \theta_{j}} \right)$$

using 
$$\frac{\partial}{\partial \theta_i} \boldsymbol{K}^{-1} = -\boldsymbol{K}^{-1} \frac{\partial \boldsymbol{K}}{\partial \theta_i} \boldsymbol{K}^{-1}$$
 and  $\frac{\partial}{\partial \boldsymbol{\theta}} \log |\boldsymbol{K}| = \operatorname{tr} \big( \boldsymbol{K}^{-1} \frac{\partial \boldsymbol{K}}{\partial \boldsymbol{\theta}} \big).$ 

