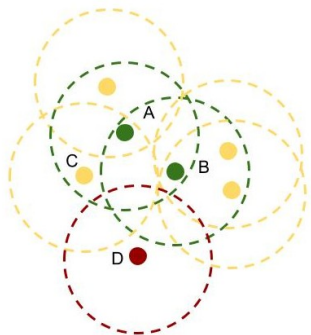
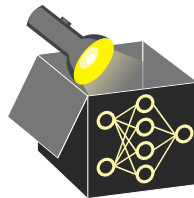


Interpretable Machine Learning

Increasing Trust in Explanations



Learning goals

- Understand the aspects that undermine users' trust in an explanation
- Learn diagnostic tools that could increase trust

MOTIVATION & IMPORTANT PROPERTIES

- Local explanations should not only make a model interpretable but also reveal if the model is trustworthy



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- **Trustworthy:** “How certain is this explanation?”
 - ① accurate insights into the inner workings of our model
 - Failure case: generation is based on inputs in areas where the model was trained with little or no training data (extrapolation)

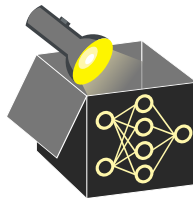


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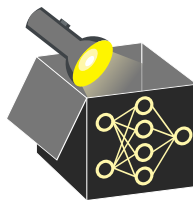
⇒ measure how robust an IML method is to small changes in the input data or parameters

⇒ Is an observation out-of-distribution?



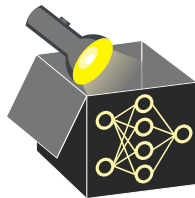
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- Failing in one of these ↪ undermining users' trust in the explanations
 - ↪ undermining trust in the model



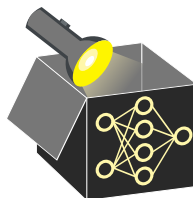
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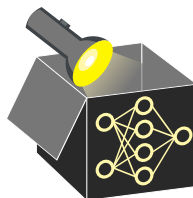
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- Two very simple and intuitive approaches
 - Classifier for out-of-distribution
 - Clustering
- More complicated also possible, e.g., variational autoencoders [Daxberger et al. 2020]

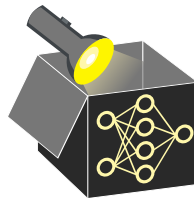


OUT-OF-DISTRIBUTION DETECTION: OOD-CLASSIFIER



- Problem: we have only in-distribution data
 - Idea: Hallucinate new (out-of-distribution) data by randomly sample data points
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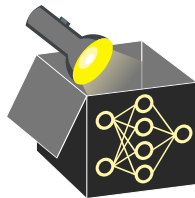
~> Learn a binary classifier to distinguish between the origins of the data

- Study whether an explanation approach can be fooled ▶ Dylan Slack et al. 2020
 - Hide bias in the true (deployed) model, but use an unbiased model for all out-of-distribution samples

~> Important way to diagnose an explanation approach

OUT-OF-DISTRIBUTION DETECTION: CLUSTERING VIA DBSCAN

- DBSCAN is a data clustering algorithm ► Martin Ester et al. 1996
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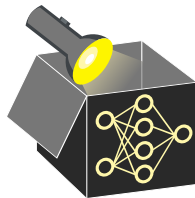


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$$\mathcal{N}_\epsilon(\mathbf{x}) = \{\mathbf{x}^{(i)} \in \mathcal{X} | d(\mathbf{x}, \mathbf{x}^{(i)}) \leq \epsilon\}.$$

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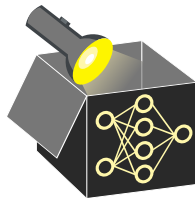
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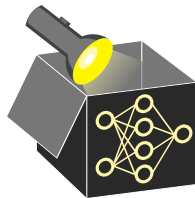
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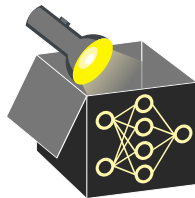
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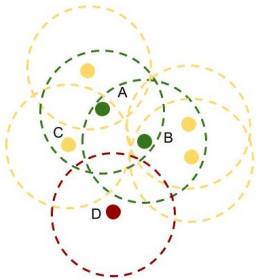
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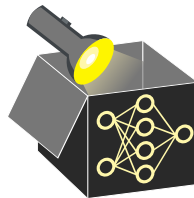


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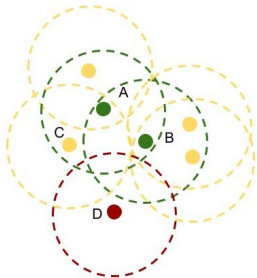


Example for DBSCAN, circles display ϵ -neighborhoods, $m = 4$

- Green points A and B are core points and form one cluster since they lie in each others neighborhood, all yellow points are border points of this cluster

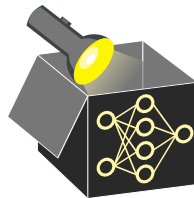


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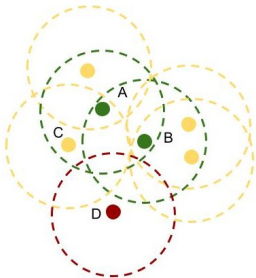


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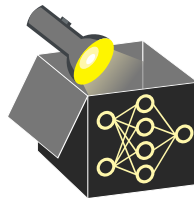


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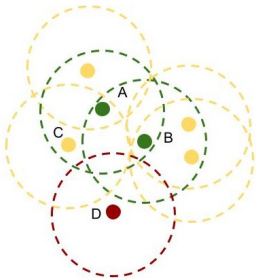


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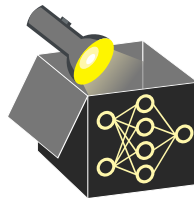


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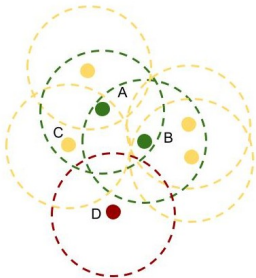


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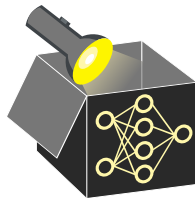


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- Disadvantages:

- Depending on the distance metric $d(\cdot)$, DBSCAN could suffer from the “curse of dimensionality”
- The choice of ϵ and m is not clear a-priori

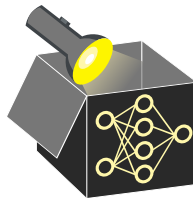
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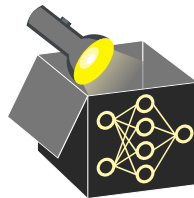
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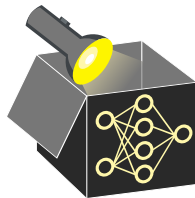


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 - ~> are ML models non-robust, e.g., because they are trained on noisy data?
- We focus on explanation uncertainty
 - Even with the same model and same (or similar) data points, we can receive different explanations

ROBUSTNESS MEASURE FOR LIME AND SHAP

- Objective: Similar explanations for similar inputs (in a neighborhood)



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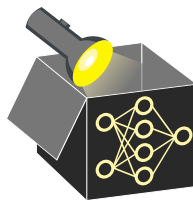
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- For LIME and SHAP, notion of stability based on **locally Lipschitz continuity**

► Alvarez-Melis and Jaakkola 2018 :

An explanation method $g : \mathcal{X} \rightarrow \mathbb{R}^m$ is locally Lipschitz if

- for every $\mathbf{x}_0 \in \mathcal{X}$ there exist $\delta > 0$ and $\omega \in \mathbb{R}$
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Note that, for LIME, g returns the m coefficients of the surrogate model



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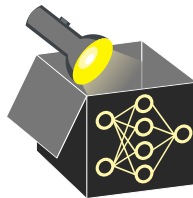
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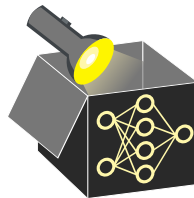
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- ω is rarely known a-priori but it could be estimated as follows:

$$\hat{\omega}_{\mathcal{X}}(\mathbf{x}) \in \arg \max_{\mathbf{x}^{(i)} \in \mathcal{N}_{\epsilon}(\mathbf{x})} \frac{\|g(\mathbf{x}) - g(\mathbf{x}^{(i)})\|_2}{d(\mathbf{x}, \mathbf{x}^{(i)})},$$

where $\mathcal{N}_{\epsilon}(\mathbf{x})$ is the ϵ -neighborhood of \mathbf{x}