Lab 4

Welcome to the fourth lab. In this lab, we will derive the backpropagation equations, code the training procedure, and test it on the XOR problem. Additionally, there will be a couple of theoretical questions about weight decay (or L2 regularization) that should give you some intuition on how it works.

Exercise 1

Derive the back-propagation algorithm. You might find the results of the second exercise of the previous lab a useful reference.

- Consider a neural network with L layers and a loss function \mathcal{L} composed of a generic error term $\mathcal{E}(\mathbf{y}^L, \hat{\mathbf{y}})$ and weight decay term $\mathcal{R}_{\lambda}(\mathbf{W})$. Call the output of the ℓ -th layer $\mathbf{y}^{\ell} = \phi_{\ell}(\mathbf{z}^{\ell})$ with $\mathbf{z}^{\ell} = \mathbf{W}^{\ell}\mathbf{y}^{\ell-1} + \mathbf{b}^{\ell}$ its pre-activation output. Finally, consider a vector $\delta^{\ell} = \nabla_{\mathbf{z}^{\ell}} \mathcal{L}(\mathbf{y}^{L}, \hat{\mathbf{y}})$ containing the gradient of the loss with respect to the pre-activation outputs of layer ℓ .
- Compute δ^L .
- Compute ∇_{Wℓ} L(y^L, ŷ) in terms of y^{ℓ-1} and δ^ℓ.
 Compute ∇_{bℓ} L(y^L, ŷ) in terms of y^{ℓ-1} and δ^ℓ.
- Compute $\delta^{\ell-1}$ from δ^{ℓ} .
- Use vectorized operations (i.e. operations with vectors and matrices): they will make your code in the next exercise *much* faster!
- Optional: Extend the vectorized operations to handle data in batches. Call \mathbf{Y}^{ℓ} and Δ^{ℓ} the matrices whose *i*-th rows contains the activations \mathbf{y}^{ℓ} and deltas δ^{ℓ} of the *i*-th training example in the batch.
- Hint: make sure that the results have the right shape. The deltas should be vectors, and the gradients should have the same shape as the respective parameters.

Exercise 2

In this exercise, we will code the backpropagation algorithm and apply it to a very simple example: the XOR problem. We will use reference classes to keep the code modular and organized.

- 1. Create a class that computes the binary cross entropy and its derivative.
- 2. Create a class that computes the ReLU activation and its derivative.
- 3. Create a class that computes the sigmoid activation and its derivative.
- 4. Create a class that computes the tanh activation and its derivative (which is $1 \tanh(x)^2$)
- 5. Create a class that performs one step of gradient descent.
- 6. Write a function for the forward pass and for backpropagation.
- 7. Create a neural network with a suitable architecture and train it on the XOR problem.
- 8. Visualize the weights and biases of the trained network. Can you explain how the network makes predictions?
- 9. Test different activation functions, learning rates, initializations, number of layers and their sizes.
- 10. Optional: implement the softmax activation, the categorical cross entropy loss function, and train a network on the MNIST dataset.

Hint: you can check that the gradients you compute are correct by comparing them with the "empirical" gradients obtained through the finite differences method.

Hint: If you do this exercise in a R script, you will be able to debug the code and see where things are not going according to plan.

Note: all these functions should process the data in batches, i.e. matrices where every row is a different sample of the same batch.

```
loss_function = setRefClass( # base class for loss functions
 "loss_function",
```

```
methods = list(
    forward = function(y_true, y_pred) NA,
    backward = function(y_true, y_pred) NA
)
binary_crossentropy = setRefClass(
  "binary crossentropy",
  contains = "loss_function",
  methods = list(
   forward = function(y_true, y_pred) {
      # TODO compute the binary cross entropy loss
    backward = function(y_true, y_pred) {
      # TODO compute the gradient of the cross entropy loss
    }
  )
)
y_{true} = matrix(c(0, 0, 0, 1, 1, 0), ncol=3)
y_pred = matrix(c(0.2, 0.5, 0.3, 0.8, 0.1, 0.1), ncol=3)
loss = binary_crossentropy()
loss$forward(y_true, y_pred)
loss$backward(y_true, y_pred)
activation = setRefClass( # base class for activation functions
 "activation",
 methods = list(
   forward = function(x) NA,
    backward = function(x) NA
  )
)
relu = setRefClass(
  "relu",
  contains = "activation",
  methods = list(
    forward = function(x) {
     \# TODO compute the relu activation on x
   },
   backward = function(x) {
      # TODO compute the gradient of the relu activation
    }
  )
x = matrix(c(-0.1, 0.3, 0.7, 0.5, -1.0, 0.7), ncol=3)
act = relu()
act $forward(x)
act$backward(x)
```

```
sigmoid = setRefClass(
  "sigmoid",
  contains = "activation",
  methods = list(
    forward = function(x) {
      # TODO compute the sigmoid activation
    },
   backward = function(x) {
     # TODO compute the gradient of the sigmoid activation
    }
  )
)
x = matrix(c(2, 0, -2, 0.5, -0.25, 0.25), ncol=3)
act = sigmoid()
act$forward(x)
act$backward(x)
htan = setRefClass(
  "htan",
  contains = "activation",
  methods = list(
    forward = function(x) {
      # TODO compute the tanh activation
    },
    backward = function(x) {
      # TODO compute the gradient of the tanh activation
    }
  )
act = htan()
act$forward(x)
act$backward(x)
gradient_descent_optimizer = setRefClass(
  "gradient_descent_optimizer",
  fields = list(
    learning_rate = "numeric"
  methods = list(
    step = function(x, gradient) {
      \# TODO perform one step of gradient descent on x
    }
  )
)
opt = gradient_descent_optimizer(learning_rate = 0.1)
opt$step(10, 10)
dense_neural_network = setRefClass(
"dense_neural_network",
```

```
fields = list(
   weights = "list",
   biases = "list",
   activations = "list",
   loss = "loss_function",
   optimizer = "gradient_descent_optimizer"
  ),
  methods = list(
   predict = function(batch_x) {
     result = batch_x
      # TODO perform the forward pass to get the predictions
     result
   },
   train_on_batch = function(batch_x, batch_y, iter, lrate) {
      intermediate_activations = list(batch_x)
      # TODO perform the forward pass to get the predictions
      # and put the intermediate activations in the list
     batch_loss = loss$forward(
       batch y,
        intermediate_activations[[length(intermediate_activations)]]
      weight_gradients = list()
      bias_gradients = list()
      # TODO use backpropagation to compute the gradients,
      # accumulate them in the lists, then use the optimizer
      # to apply the gradients to the parameters
      batch_loss
   }
 )
)
# just an utility function to create networks
build_dense_neural_network = function(input_size, layers, loss, optimizer) {
  weights = list()
 biases = list()
 activations = list()
 last_layer_size = input_size
  for(i in 1:length(layers)) {
   if(class(layers[[i]]) == "numeric") {
      sd = sqrt(2 / (last_layer_size + layers[[i]]))
     vals = rnorm(n = last_layer_size * layers[[i]], mean = 0, sd = sd)
     vals = ifelse(vals > 2 * sd, 2 * sd, vals)
```

```
vals = ifelse(vals < -2 * sd, -2 * sd, vals)
      weights[[length(weights) + 1]] = matrix(
        vals, ncol = layers[[i]], nrow = last_layer_size
      biases[[length(biases) + 1]] = rep(0, layers[[i]])
      last_layer_size = layers[[i]]
    }
    else {
      activations[[length(activations) + 1]] = layers[[i]]
    }
  }
  dense_neural_network(
    weights = weights,
    biases = biases,
    activations = activations,
    loss = loss,
    optimizer = optimizer
}
data.x = matrix(c(
 -1, -1,
 -1, 1,
 1, -1,
 1, 1
), nrow = 4, ncol = 2, byrow = TRUE)
data.y = matrix(c(
 0, 1, 1, 0
), nrow = 4, ncol = 1)
network = build_dense_neural_network(
  input_size = 2,
 layers = list(2, htan(), 1, sigmoid()),
 loss = binary_crossentropy(),
  optimizer = gradient_descent_optimizer(learning_rate = 0.25)
losses = lapply(1:250, function(i) network$train_on_batch(data.x, data.y))
network$predict(data.x)
plot(1:length(losses), losses)
network$weights
network$biases
```

Exercise 3

This exercise should improve your understanding of weight decay (or L2 regularization).

- 1. Consider a quadratic error function $E(\mathbf{w}) = E_0 + \mathbf{b}^T \mathbf{w} + 1/2 \cdot \mathbf{w}^T \mathbf{H} \mathbf{w}$ and its regularized counterpart $E'(\mathbf{w}) = E(\mathbf{w}) + \tau/2 \cdot \mathbf{w}^T \mathbf{w}$, and let \mathbf{w}^* and $\tilde{\mathbf{w}}$ be the minimizers of E and E' respectively. We want to find a formula to express $\tilde{\mathbf{w}}$ as a function of \mathbf{w}^* , i.e. find the displacement introduced by weight decay.
 - Find the gradients of E and E'. Note that, at the global minimum, we have $\nabla E(\mathbf{w}^*) = \nabla E'(\hat{\mathbf{w}}) = 0$.
 - In the equality above, express \mathbf{w}^* and $\tilde{\mathbf{w}}$ as a linear combination of the eigenvectors of \mathbf{H} .
 - Through algebraic manipulation, obtain $\tilde{\mathbf{w}}_i$ as a function of \mathbf{w}_i^* .
 - Interpret this result geometrically.
- 2. Consider a linear network of the form $y = \mathbf{w}^T \mathbf{x}$ and the mean squared error as a loss function. Assume that every observation is corrupted with Gaussian noise $\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$. Compute the expectation of the gradient under ϵ and, show that adding gaussian noise to the inputs has the same effect of weight decay.