

# **Deep Learning**

**Chapter 9: Autoencoders** 

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# LECTURE OUTLINE

**Autoencoders - Basic Principle** 

**Undercomplete Autoencoders** 

**Principal Component Analysis as Autoencoder** 

# **Autoencoders - Basic Principle**

# **AUTOENCODER (AE)-TASK AND STRUCTURE**

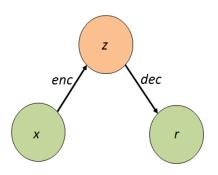
- Autoencoders (AEs) are a special kind of feedforward neural networks.
- Task: Learn a lossy compression of the data
- Autoencoders consist of two parts:
  - **encoder** function z = enc(x).
  - **decoder** that produces the reconstruction  $\hat{\mathbf{x}} = dec(\mathbf{z})$ .
- Loss function measures the quality of the reconstruction compared to the input:

$$L(\mathbf{x}, dec(enc(\mathbf{x})))$$

Goal: Learn good internal representations z (also called code).

# **AUTOENCODER (AE)- COMPUTATIONAL GRAPH**

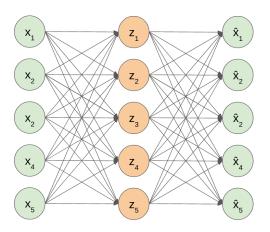
The general structure of an AE as a computational graph:



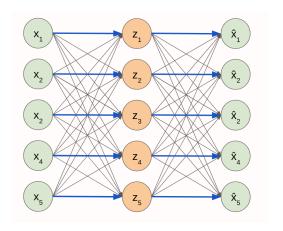
- An AE has two computational steps:
  - the encoder enc, mapping x to z.
  - the decoder dec, mapping z to x.

# **Undercomplete Autoencoders**

- A naive implementation of an autoencoder would simply learn the identity  $dec(enc(\mathbf{x})) = \mathbf{x}$ .
- This would not be useful.

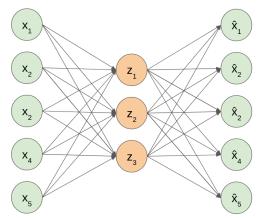


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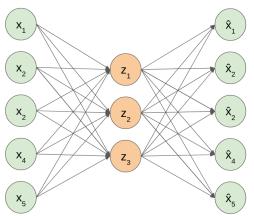


 Therefore we have a "bottleneck" layer: We restrict the architecture, such that

• Such an AE is called undercomplete.



- In other words: In an undercomplete AE, the hidden layer has fewer neurons than the input layer.
- $\rightarrow$  That will force the AE to
  - capture only the most salient features of the training data!
  - learn a "compressed" representation of the input.



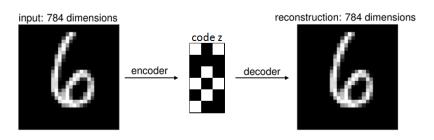
- Training an AE is done by minimizing the risk, where the loss function penalizes the reconstruction dec(enc(x)) for differing from x.
- The L2-loss

$$\|\mathbf{x} - dec(enc(\mathbf{x}))\|_2^2$$

is a typical choice, but other loss functions are possible as well.

 For optimization, the very same optimization techniques as for standard feed-forward nets are applied (SGD, RMSProp, ADAM....).

- Let us try to compress the MNIST data as good as possible.
- Therefore, we will fit a simple undercomplete autoencoder to learn the best possible representation
- We fit the autoencoder for different dimensions of the internal representation **z** (different "bottleneck" sizes).



**Figure:** Flow chart of our autoencoder: reconstruct the input with fixed dimensions  $dim(\mathbf{z}) \ll dim(\mathbf{x})$ .

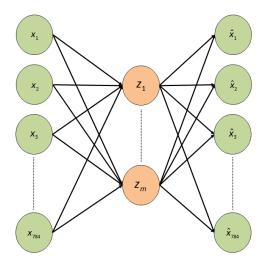
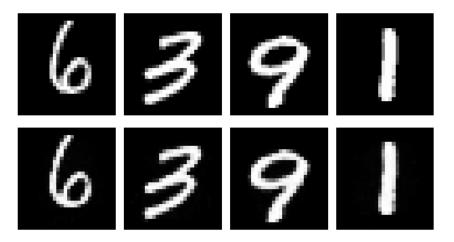
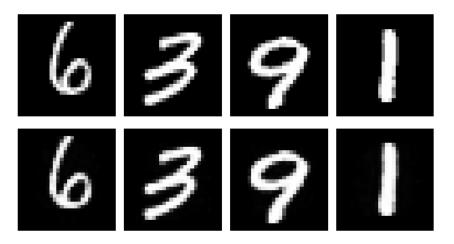


Figure: Architecture of the autoencoder.



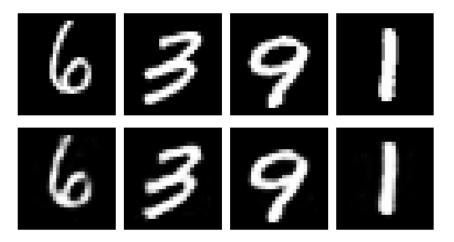
**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 784 = dim(x).



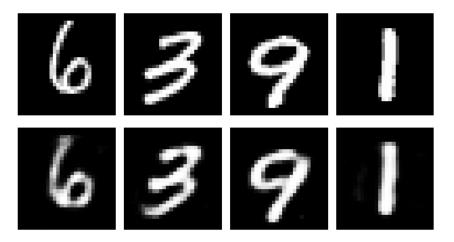
**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 256.



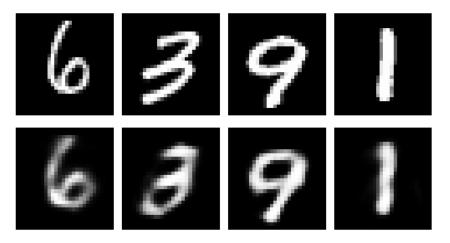
**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 64.



**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 32.



**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 16.



**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 8.



**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 4.



**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 2.

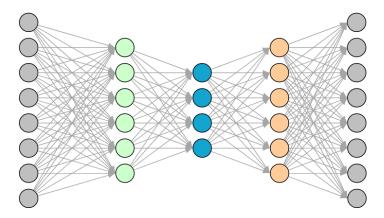


**Figure:** The top row shows the original digits, the bottom row the reconstructed ones.

• dim(z) = 1.

## **INCREASING THE CAPACTLY OF AES**

Increasing the number of layers adds capacity to autoencoders:

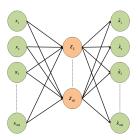


# Principal Component Analysis as Autoencoder

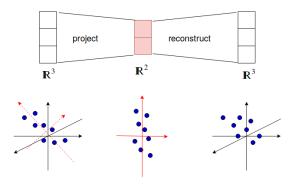
- Consider the same simple undercomplete autoencoder architecture as above, but this time with
  - linear encoder function enc(x), and
  - **linear** decoder function dec(z).

Further we use the L2-loss  $\|\mathbf{x} - dec(enc(\mathbf{x}))\|_2^2$  and assume that inputs are normalized to zero mean.

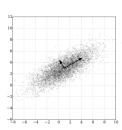
 In other words: We want to find the linear projection of the data with the minimal L2-reconstruction error.



• It can be shown that, given a  $\dim(z) = k$ , the optimal solution is an **orthogonal** linear transformation (i.e. a rotation of the coordinate system) given by the k singular vectors with largest singular values.



- This is an equivalent formulation to Principal Component
   Analysis (PCA), which uses an orthogonal transformation to convert a set of observations of possibly correlated variables into a set of values of linearly uncorrelated variables called principal components.
- The transformation is defined in such a way that the first principal component has the largest possible variance (that is, accounts for as much of the variability in the data as possible)



- The formulations are equivalent: "Find a linear projection into a k-dimensional space that ..."
  - "... minimizes the L2-reconstruction error" (AE-based formulation)
  - "... maximizes the variance of the projected datapoints" (statistical formulation).

 An AE with a non-linear decoder/encoder can be seen as a non-linear generalization of PCA.

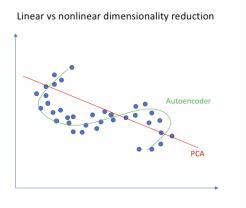


Figure: Credits: Jeremy Jordan "Introduction to autoencoders"

#### **REFERENCES**



Ian Goodfellow, Yoshua Bengio and Aaron Courville (2016)

#### Deep Learning

http://www.deeplearningbook.org/