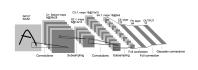
# **Deep Learning**

## **Modern Architectures - I**



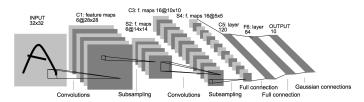
#### Learning goals

- LeNet
- AlexNet
- VGG
- Network in Network

## LeNet

#### LENET ARCHITECTURE

- Pioneering work on CNNs by Yann Lecun in 1998.
- Applied on the MNIST dataset for automated handwritten digit recognition.
- Consists of convolutional, "subsampling" and dense layers.
- Complexity and depth of the net was mainly restricted by limited computational power back in the days.



**Figure:** LeNet architecture: two conv layers with subsampling, followed by dense layers and a 'Gaussian connections' layer.

#### LENET ARCHITECTURE

- A neuron in a subsampling layer looks at a 2 × 2 region of a feature map, sums the four values, multiplies it by a trainable coefficient, adds a trainable bias and then applies a sigmoid activation.
- A stride of 2 ensures that the size of the feature map reduces by about a half.
- The 'Gaussian connections' layer has a neuron for each possible class.
- The output of each neuron in this layer is the (squared) Euclidean distance between the activations from the previous layer and the weights of the neuron.

## **AlexNet**

#### **ALEXNET**

- AlexNet, which employed an 8-layer CNN, won the ImageNet Large Scale Visual Recognition (LSVR) Challenge 2012 by a phenomenally large margin.
- The network trained in parallel on two small GPUs, using two streams of convolutions which are partly interconnected.
- The architectures of AlexNet and LeNet are very similar, but there are also significant differences:
  - First, AlexNet is deeper than the comparatively small LeNet5.
    AlexNet consists of eight layers: five convolutional layers, two fully-connected hidden layers, and one fully-connected output layer.
  - Second, AlexNet used the ReLU instead of the sigmoid as its activation function.

#### **ALEXNET**



Figure: From LeNet (left) to AlexNet (right).

# **VGG**

#### **VGG BLOCKS**

- The block composed of convolutions with 3 × 3 kernels with padding of 1 (keeping height and width) and 2 × 2 max pooling with stride of 2 (halving the resolution after each block).
- The use of blocks leads to very compact representations of the network definition.
- It allows for efficient design of complex networks.

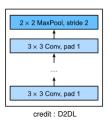


Figure: VGG block.

#### **VGG NETWORK**

- Architecture introduced by Simonyan and Zisserman, 2014 as "Very Deep Convolutional Network".
- A deeper variant of the AlexNet.
- Basic idea is to have small filters and Deeper networks
- Mainly uses many cnn layers with a small kernel size  $3 \times 3$ .
- Stack of three  $3 \times 3$  cnn (stride 1) layers has same effective receptive field as one  $7 \times 7$  conv layer.
- Performed very well in the ImageNet Challenge in 2014.
- Exists in a small version (VGG16) with a total of 16 layers (13 cnn layers and 3 fc layers) and 5 VGG blocks while a larger version (VGG19) with 19 layers (16 cnn layers and 3 fc layers) and 6 VGG blocks.

#### **VGG NETWORK**

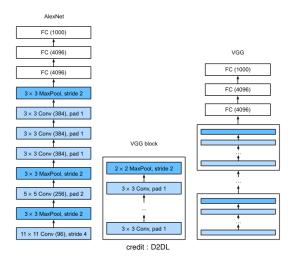


Figure: From AlexNet to VGG that is designed from building blocks.

# **Network in Network (NiN)**

#### **NIN BLOCKS**

- The idea behind NiN is to apply a fully-connected layer at each pixel location (for each height and width). If we tie the weights across each spatial location, we could think of this as a 1 × 1 convolutional layer.
- The NiN block consists of one convolutional layer followed by two 1 × 1 convolutional layers that act as per-pixel fully-connected layers with ReLU activations.
- The convolution window shape of the first layer is typically set by the user. The subsequent window shapes are fixed to  $1 \times 1$ .

## **NIN BLOCKS**

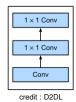


Figure: NiN block.

## **NETWORK IN NETWORK (NIN)**

- NiN uses blocks consisting of a convolutional layer and multiple 1 × 1 convolutional layers. This can be used within the convolutional stack to allow for more per-pixel nonlinearity.
- NiN removes the fully-connected layers and replaces them with global average pooling (i.e., summing over all locations) after reducing the number of channels to the desired number of outputs (e.g., 10 for Fashion-MNIST).
- Removing the fully-connected layers reduces overfitting. NiN has dramatically fewer parameters.
- The NiN design influenced many subsequent CNN designs.

## **NETWORK IN NETWORK (NIN)**

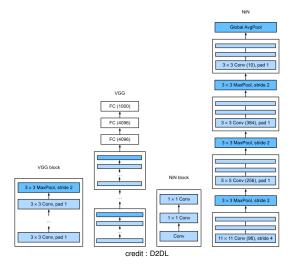


Figure: Comparing architectures of VGG and NiN, and their blocks.

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