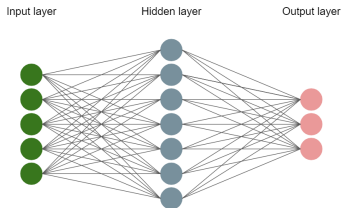


## Models & Parameters



- Understand that an ML model is simply a parametrized function
- Understand that the hypothesis space lists all admissible models
- Understand relationship between hypothesis and parameter space

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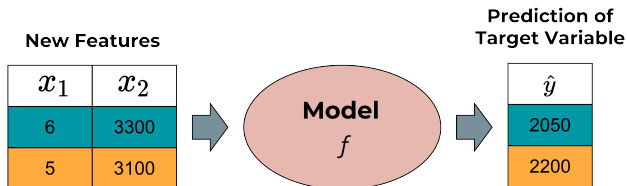
# WHAT IS A MODEL?

- A **model** (or **hypothesis**)

$$f : \mathcal{X} \rightarrow \mathbb{R}^g$$

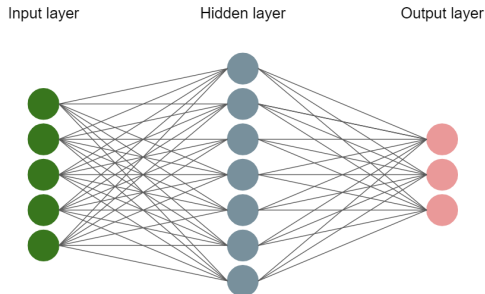
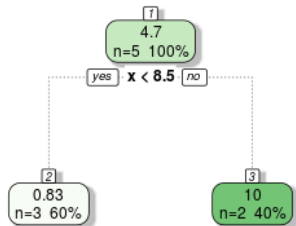
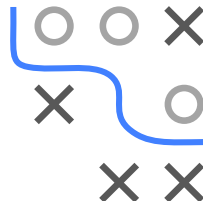
is a function that maps feature vectors to predicted target values

- In regression:  $g = 1$ ; in classification,  $g$  is the number of classes, and output vectors are scores or class probabilities



# WHAT IS A MODEL?

- $f$  is meant to capture intrinsic patterns of the data, the underlying assumption being that these hold true for *all* data drawn from  $\mathbb{P}_{xy}$
- Models can range from super simple (e.g., linear, tree stumps) to very complex (e.g., DL) with lots of choices



- ML requires **constraining**  $f$  to a certain type of functions

# HYPOTHESIS SPACES

- Without restrictions on the functional family, the task of finding a “good” model among all available models is impossible to solve
- We have to determine the class of our model *a priori*, thereby narrowing down the search space. We call this a **structural prior**.
- The set of functions defining a specific model class is called a **hypothesis space**  $\mathcal{H}$ :

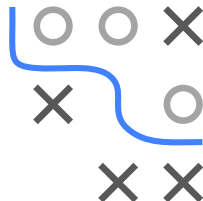
$$\mathcal{H} = \{f : f \text{ belongs to a certain functional family}\}$$



# PARAMETRIZATION

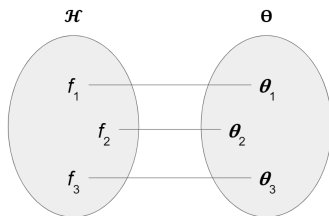
- All models within a hypothesis space share a common functional structure typically constructed as **parametrized family of functions**
- We collect all parameters in a **parameter vector**  $\theta = (\theta_1, \theta_2, \dots, \theta_d)$  from **parameter space**  $\Theta$
- They are our means of fixing a specific function from the family: once set our model is fully determined
- Therefore, we can re-write  $\mathcal{H}$  as:

$$\mathcal{H} = \{f_{\theta} : f_{\theta} \text{ belongs to a certain functional family} \\ \text{parameterized by } \theta\}$$

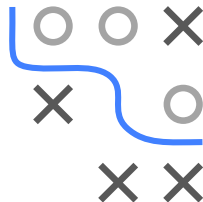


# PARAMETRIZATION

- Finding optimal model = finding optimal parameters
- This allows us to operationalize our search for the best model as a search for the optimal value on a  $d$ -dimensional parameter surface

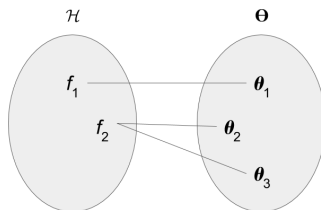
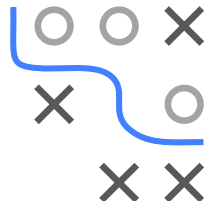


- $\theta$  might be scalar or very high-dimensional with thousands of parameters depending on the complexity of our model



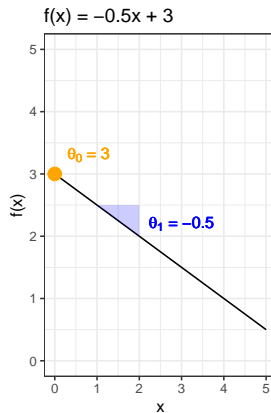
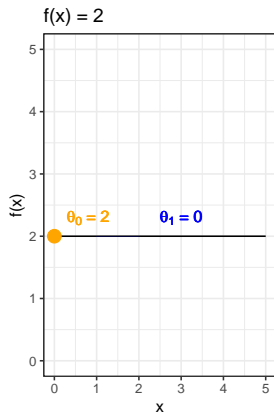
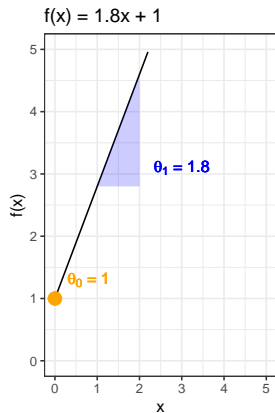
# PARAMETRIZATION

- Some parameter vectors, for some model classes, encode the same function: the parameter-to-model mapping could be non-injective
- We call this a non-identifiable model
- This shall not concern us here



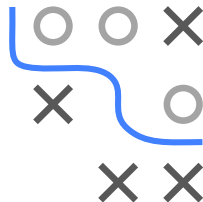
# EXAMPLE: UNIVARIATE LINEAR FUNCTIONS

$$\mathcal{H} = \{f : f(\mathbf{x}) = \theta_0 + \theta_1 x, \theta \in \mathbb{R}^2\}$$



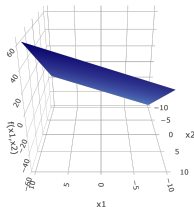


# EXAMPLE: BIVARIATE QUADRATIC FUNCTIONS

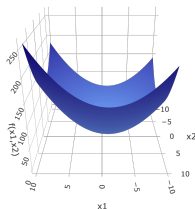


$$\mathcal{H} = \{f : f(\mathbf{x}) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2 + \theta_5 x_1 x_2, \theta \in \mathbb{R}^6\}$$

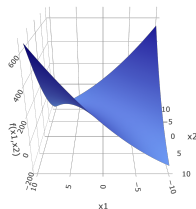
$$f(x) = 3 + 2x_1 + 4x_2$$



$$f(x) = 3 + 2x_1 + 4x_2 + 1x_1^2 + 1x_2^2$$



$$f(x) = 3 + 2x_1 + 4x_2 + 1x_1^2 + 1x_2^2 + 4x_1 x_2$$



# EXAMPLE: RBF NETWORK

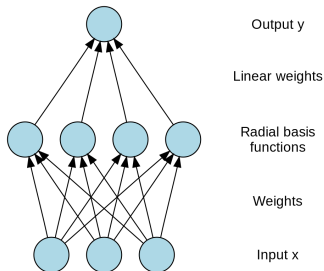
Radial basis function networks with Gaussian basis functions

$$\mathcal{H} = \left\{ f : f(\mathbf{x}) = \sum_{i=1}^k a_i \rho(\|\mathbf{x} - \mathbf{c}_i\|) \right\}$$

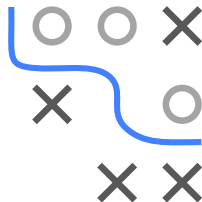
where

- $a_i$  is the weight of the  $i$ -th neuron
- $\mathbf{c}_i$  its center vector and
- $\rho(\|\mathbf{x} - \mathbf{c}_i\|) = \exp(-\beta\|\mathbf{x} - \mathbf{c}_i\|^2)$  is the  $i$ -th radial basis function with bandwidth  $\beta \in \mathbb{R}$

Usually number of centers  $k$  and bandwidth  $\beta$  need to be set in advance (so-called *hyperparameters*)

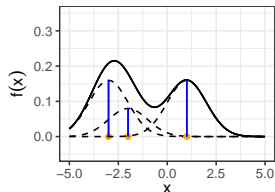


► [Click for source](#)



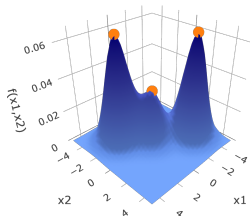
# EXAMPLE: RBF NETWORK

Exemplary setting



$$a_1 = 0.4, a_2 = 0.2, a_3 = 0.4$$

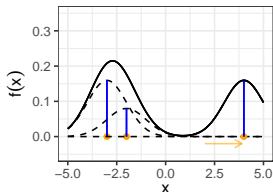
$$c_1 = -3, c_2 = -2, c_3 = 1$$



$$a_1 = 0.4, a_2 = 0.2, a_3 = 0.4$$

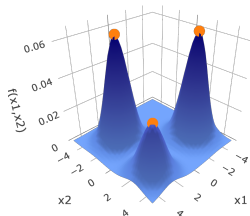
$$c_1 = (2, -2), c_2 = (0, 0), c_3 = (-3, 2)$$

Centers altered



$$a_1 = 0.4, a_2 = 0.2, a_3 = 0.4$$

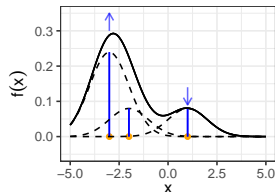
$$c_1 = -3, c_2 = -2, c_3 = 4$$



$$a_1 = 0.4, a_2 = 0.2, a_3 = 0.4$$

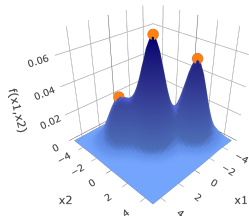
$$c_1 = (2, -2), c_2 = (3, 3), c_3 = (-3, 2)$$

Weights altered



$$a_1 = 0.6, a_2 = 0.2, a_3 = 0.2$$

$$c_1 = -3, c_2 = -2, c_3 = 1$$



$$a_1 = 0.2, a_2 = 0.45, a_3 = 0.35$$

$$c_1 = (2, -2), c_2 = (0, 0), c_3 = (-3, 2)$$

