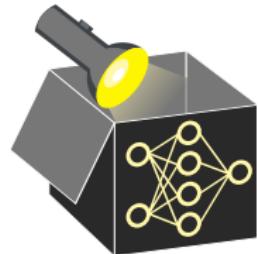
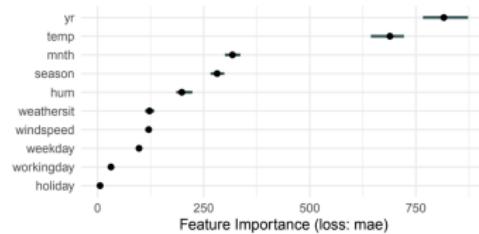


# Interpretable Machine Learning



## Feature Importance

### Permutation Feature Importance (PFI)



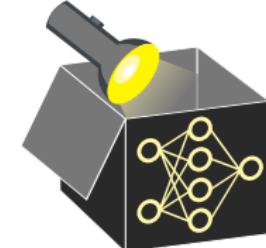
#### Learning goals

- Understand how PFI is computed
- Understanding strengths and weaknesses

Figure: Bike Sharing Dataset

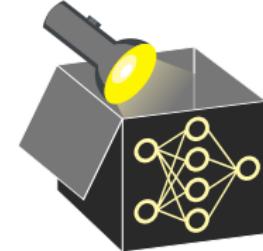
# MOTIVATION FOR PFI

- **Goal:** Assess how important feature(s)  $X_S$  are for predictive performance of a **fixed trained model**  $\hat{f}$  on a given dataset  $\mathcal{D}$
- **Idea:** Estimate performance change when  $X_S$  is "made uninformative"



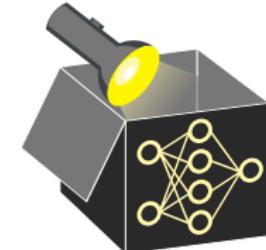
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~~ No,  $\hat{f}$  was trained with  $X_S$ ; retraining without  $X_S$  gives a different model



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  - ↪ No,  $\hat{f}$  was trained with  $X_S$ ; retraining without  $X_S$  gives a different model
- **Question:** Can we make  $X_S$  uninformative by removing it from model?
  - ↪ No,  $\hat{f}$  was trained with  $X_S$ ; retraining without  $X_S$  gives a different model
- **Solution:** Simulate feature removal by replacing  $X_S$  with a perturbed version  $\tilde{X}_S$  that is independent of  $(X_{-S}, Y)$  but preserves distrib.  $\mathbb{P}(X_S)$ 
  - ↪ Compare **baseline predictions**  $\hat{f}(X)$  with **perturbed predictions**  $\hat{f}(\tilde{X}_S, X_{-S})$



$$\text{PFI}_S := \underbrace{\mathbb{E}\left[L\left(\hat{f}(\tilde{X}_S, X_{-S}), Y\right)\right]}_{\text{risk after "destroying" } X_S} - \underbrace{\mathbb{E}\left[L\left(\hat{f}(X), Y\right)\right]}_{\text{baseline risk}},$$

- **How to perturb  $X_S$ ?**
  - Add random noise: distorts  $\mathbb{P}(X_S)$  (not used)
  - Permutation: preserves marginal  $\mathbb{P}(X_S)$ , breaks dependence with  $Y$  (used)

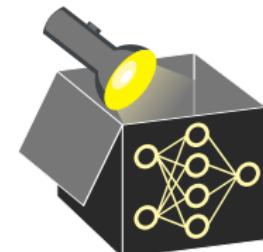
# PERMUTATION FEATURE IMPORTANCE (PFI)

▶ "Breiman" 2001

Sample estimator (using independent test set  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^n\}$ )

- Measure error **with feat. values  $x_S$**  and **with permuted feat. values  $\tilde{x}_S$**
- Repeat permutation (e.g.,  $m$  times) and average difference of both errors:

$$\widehat{PFI}_S = \frac{1}{m} \sum_{k=1}^m [\mathcal{R}_{\text{emp}}(\hat{f}, \tilde{\mathcal{D}}_{(k)}^S) - \mathcal{R}_{\text{emp}}(\hat{f}, \mathcal{D})]$$



- $\mathcal{D}_S^{(k)}$ : dataset with column(s)  $x_S$  are **permuted** once (in repetition  $k$ )
- $\mathcal{R}_{\text{emp}}(\hat{f}, \mathcal{D}) = \frac{1}{n} \sum_{(x,y) \in \mathcal{D}} L(\hat{f}(x), y)$ : Measures performance of  $\hat{f}$  using  $\mathcal{D}$
- Average over  $m$  permutations to reduce Monte-Carlo variance

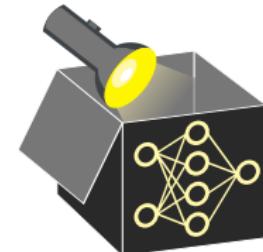
Example of permuting feature  $x_S$  with  $S = \{1\}$  and  $m = 6$  permutations:

$\mathcal{D}$	$\tilde{\mathcal{D}}_{(1)}^S$	$\tilde{\mathcal{D}}_{(2)}^S$	$\tilde{\mathcal{D}}_{(3)}^S$	$\tilde{\mathcal{D}}_{(4)}^S$	$\tilde{\mathcal{D}}_{(5)}^S$	$\tilde{\mathcal{D}}_{(6)}^S$
$\begin{array}{ c c c }\hline x_1 & x_2 & x_3 \\ \hline 1 & 4 & 7 \\ \hline 2 & 5 & 8 \\ \hline 3 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 1 & 4 & 7 \\ \hline 2 & 5 & 8 \\ \hline 3 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 2 & 4 & 7 \\ \hline 1 & 5 & 8 \\ \hline 3 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 2 & 4 & 7 \\ \hline 3 & 5 & 8 \\ \hline 1 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 1 & 4 & 7 \\ \hline 3 & 5 & 8 \\ \hline 2 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 3 & 4 & 7 \\ \hline 1 & 5 & 8 \\ \hline 2 & 6 & 9 \\ \hline\end{array}$	$\begin{array}{ c c c }\hline x_S & x_2 & x_3 \\ \hline 3 & 4 & 7 \\ \hline 2 & 5 & 8 \\ \hline 1 & 6 & 9 \\ \hline\end{array}$

Note:  $S$  refers to a subset of features, here  $|S| = 1$  to measure impact of permuting  $x_1$  on performance

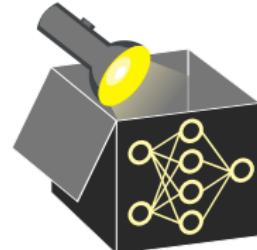
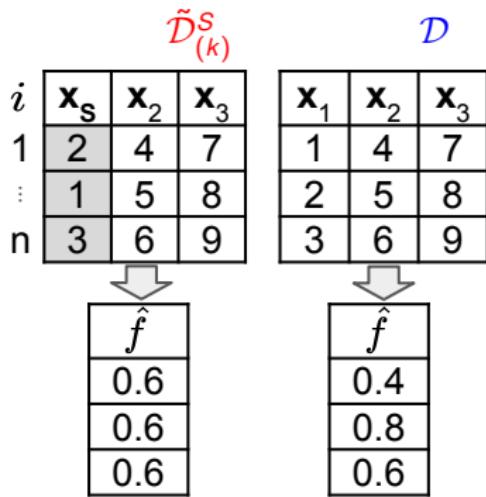
# PERMUTATION FEATURE IMPORTANCE

$i$	$\tilde{\mathcal{D}}_{(k)}^S$	$\mathcal{D}$	
	$x_s$	$x_2$	$x_3$
1	2	4	7
:	1	5	8
n	3	6	9



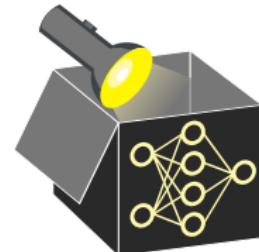
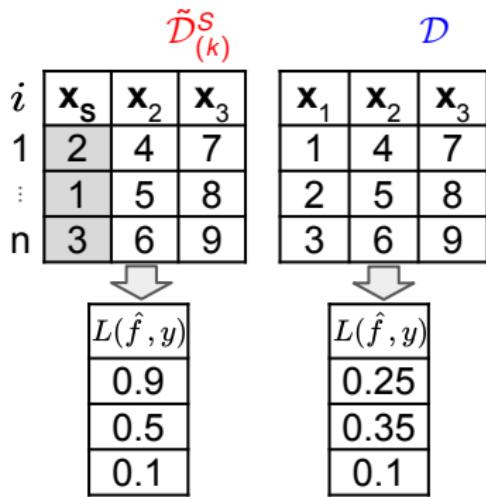
1. **Perturbation:** Sample feature values from the distribution of  $x_S$  ( $P(X_S)$ ).  
⇒ Randomly permute feature  $x_S$   
⇒ Replace  $x_S$  with permuted feat.  $\tilde{x}_S$  and create data  $\tilde{\mathcal{D}}^S$  containing  $\tilde{x}_S$

# PERMUTATION FEATURE IMPORTANCE



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  - ⇒ Randomly permute feature  $x_S$
  - ⇒ Replace  $x_S$  with permuted feat.  $\tilde{x}_S$  and create data  $\tilde{\mathcal{D}}^S$  containing  $\tilde{x}_S$
- Prediction:** Make predictions for both data, i.e.,  $\mathcal{D}$  and  $\tilde{\mathcal{D}}^S$

# PERMUTATION FEATURE IMPORTANCE



### 3. Aggregation:

- Compute the loss for each observation in both data sets

# PERMUTATION FEATURE IMPORTANCE

$\tilde{\mathcal{D}}_{(k)}^s$        $\mathcal{D}$

$i$	$\mathbf{x}_s$	$\mathbf{x}_2$	$\mathbf{x}_3$	
1	2	4	7	
:	1	5	8	
n	3	6	9	

	$\mathbf{x}_1$	$\mathbf{x}_2$	$\mathbf{x}_3$	
	1	4	7	
	2	5	8	
	3	6	9	

	$\Delta L$
	0.65
	0.15
	0

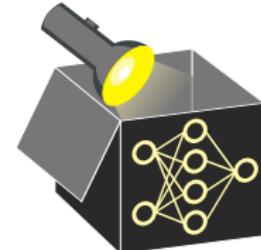
$L(\hat{f}, y)$
0.9
0.5
0.1

$L(\hat{f}, y)$
0.25
0.35
0.1

-

### 3. Aggregation:

- Compute the loss for each observation in both data sets
- Take the difference of both losses  $\Delta L$  for each observation

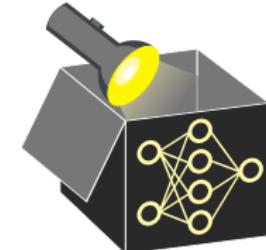


# PERMUTATION FEATURE IMPORTANCE

$$\mathcal{R}_{\text{emp}}(\hat{f}, \tilde{\mathcal{D}}_{(k)}^S) - \mathcal{R}_{\text{emp}}(\hat{f}, \mathcal{D})$$

$i$	$\mathbf{x}_S$	$\mathbf{x}_2$	$\mathbf{x}_3$	$\mathbf{x}_1$	$\mathbf{x}_2$	$\mathbf{x}_3$	$\Delta L$
1	2	4	7	1	4	7	0.65
:	1	5	8	2	5	8	0.15
n	3	6	9	3	6	9	0

$$= 0.267$$

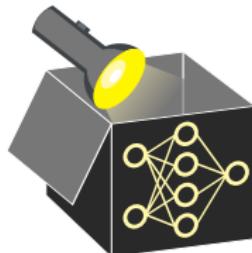


### 3. Aggregation:

- Compute the loss for each observation in both data sets
- Take the difference of both losses  $\Delta L$  for each observation
- Average this change in loss across all observations

Note: Same as computing  $\mathcal{R}_{\text{emp}}$  on both data sets and taking difference

# PERMUTATION FEATURE IMPORTANCE



$$\mathcal{R}_{\text{emp}}(\hat{f}, \tilde{\mathcal{D}}_{(k)}^S) - \mathcal{R}_{\text{emp}}(\hat{f}, \mathcal{D})$$

	$i$	$\mathbf{x}_S$	$\mathbf{x}_2$	$\mathbf{x}_3$
1	1	2	4	7
	⋮	1	5	8
n	n	3	6	9

	$i$	$\mathbf{x}_1$	$\mathbf{x}_2$	$\mathbf{x}_3$
1	1	1	4	7
	⋮	2	5	8
n	n	3	6	9

	$\Delta L$
1	0.65
	0.15
n	0

$$= 0.267$$

$$\widehat{PFI}_S = \frac{1}{2} (0.267 + 0.4)$$

	$i$	$\mathbf{x}_S$	$\mathbf{x}_2$	$\mathbf{x}_3$
m	1	3	4	7
	⋮	2	5	8
n	n	1	6	9

	$i$	$\mathbf{x}_1$	$\mathbf{x}_2$	$\mathbf{x}_3$
m	1	1	4	7
	⋮	2	5	8
n	n	3	6	9

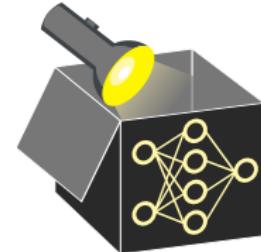
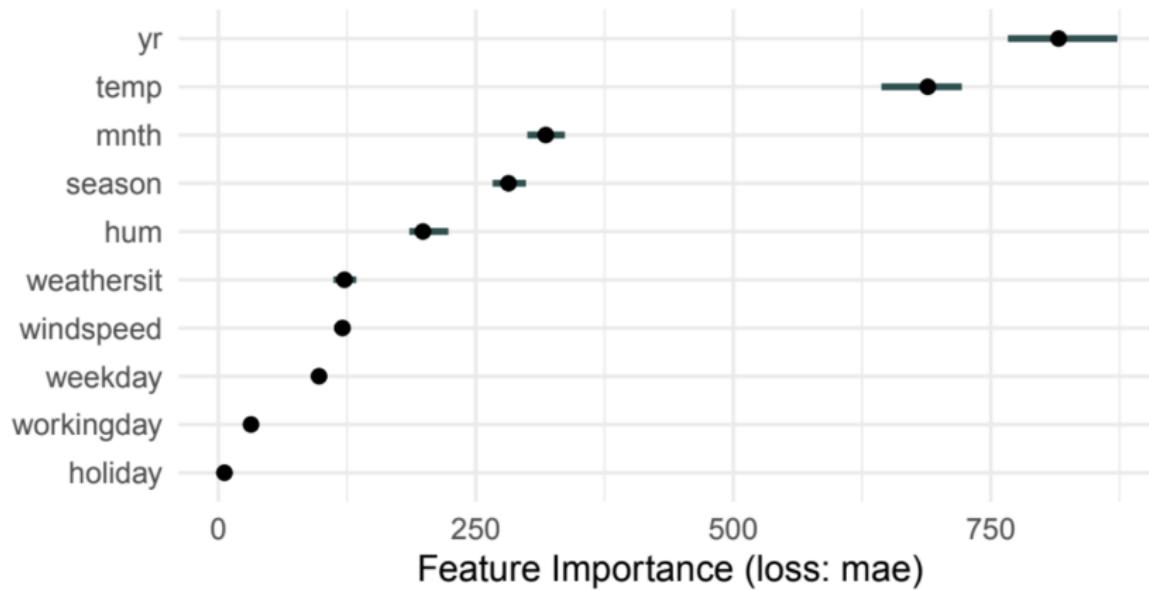
	$\Delta L$
m	0.85
	0
n	0.35

$$= 0.4$$

### 3. Aggregation:

- Compute the loss for each observation in both data sets
- Take the difference of both losses  $\Delta L$  for each observation
- Average this change in loss across all observations
- Repeat perturbation and average over multiple repetitions

# EXAMPLE: BIKE SHARING DATASET

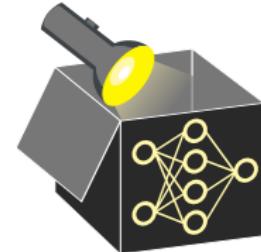


## Interpretation:

- yr and temp are most important feats using mean absolute error (MAE)
- Destroying info. about yr by permuting it increases MAE of model by 816
- Error bars show 5% and 95% quantiles over multiple permutations

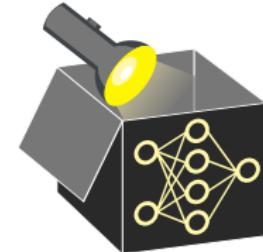
# COMMENTS ON PFI

- Interpretation: Increase in error when feature's information is destroyed



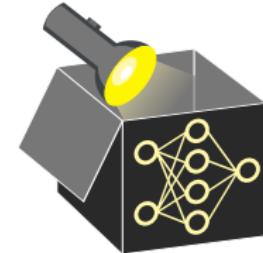
# COMMENTS ON PFI

- Interpretation: Increase in error when feature's information is destroyed
- Results can be unreliable due to random permutations  
⇒ Solution: Average results over multiple repetitions



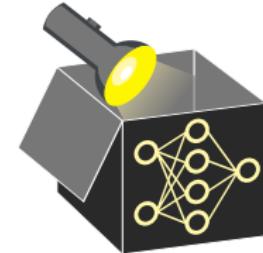
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- Interpretation: Increase in error when feature's information is destroyed
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⇒ Solution: Average results over multiple repetitions
- Permuting features despite correlation/dependence with other features can lead to unrealistic combinations of feature values  
~~ Extrapolation issue



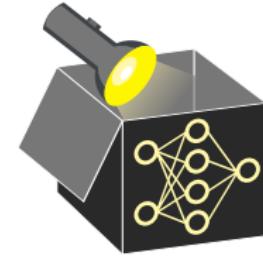
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~~ Extrapolation issue
- PFI automatically includes importance of interaction effects with other features  
⇒ Permuting  $x_j$  also destroys interactions with permuted feature  
⇒ PFI score contains importance of all interactions with permuted feature



# COMMENTS ON PFI

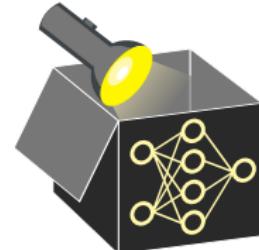
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~~ Extrapolation issue
- PFI automatically includes importance of interaction effects with other features  
⇒ Permuting  $x_j$  also destroys interactions with permuted feature  
⇒ PFI score contains importance of all interactions with permuted feature
- Interpretation of PFI depends on whether training or test data is used



# COMMENTS ON PFI - EXTRAPOLATION

**Example:** Let  $y = x_3 + \epsilon_y$ , with  $\epsilon_y \sim \mathcal{N}(0, 0.1)$ .

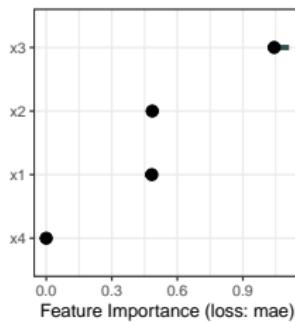
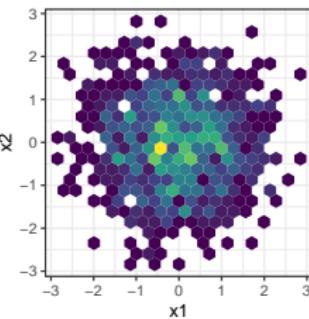
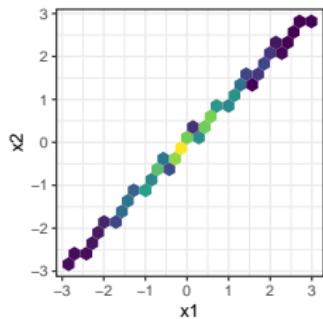
- $x_1 := \epsilon_1$ ,  $x_2 := x_1 + \epsilon_2$ ; highly correlated ( $\epsilon_1 \sim \mathcal{N}(0, 1)$ ,  $\epsilon_2 \sim \mathcal{N}(0, 0.01)$ )
- $x_3 := \epsilon_3$ ,  $x_4 := \epsilon_4$ , with  $\epsilon_3, \epsilon_4 \sim \mathcal{N}(0, 1)$ ; all noise terms  $\epsilon_j$  are indep.
- Fitting a linear model yields  $\hat{f}(\mathbf{x}) \approx 0.3x_1 - 0.3x_2 + x_3$



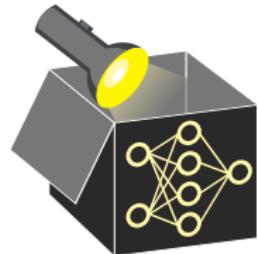
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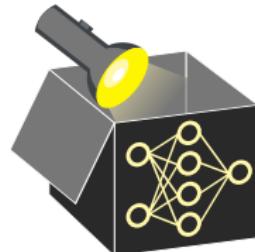
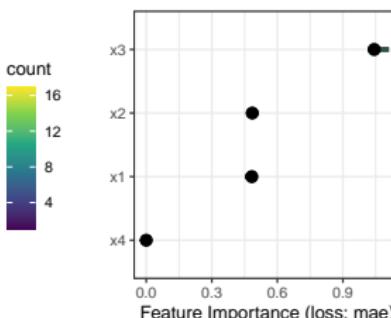
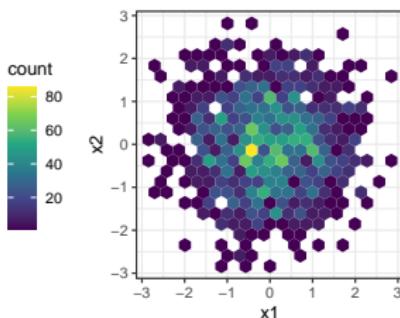
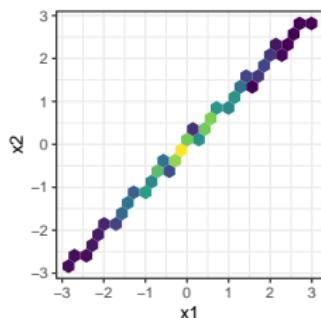
Hexbin plot of  $(x_1, x_2)$  before (left) and after (center) permuting  $x_1$ ;  
PFI scores (right).



# COMMENTS ON PFI - EXTRAPOLATION

**Example:** Let  $y = x_3 + \epsilon_y$ , with  $\epsilon_y \sim \mathcal{N}(0, 0.1)$ .

- $x_1 := \epsilon_1, x_2 := x_1 + \epsilon_2$ ; highly correlated ( $\epsilon_1 \sim \mathcal{N}(0, 1), \epsilon_2 \sim \mathcal{N}(0, 0.01)$ )
- $x_3 := \epsilon_3, x_4 := \epsilon_4$ , with  $\epsilon_3, \epsilon_4 \sim \mathcal{N}(0, 1)$ ; all noise terms  $\epsilon_j$  are indep.
- Fitting a linear model yields  $\hat{f}(\mathbf{x}) \approx 0.3x_1 - 0.3x_2 + x_3$



Hexbin plot of  $(x_1, x_2)$  before (left) and after (center) permuting  $x_1$ ;  
PFI scores (right).

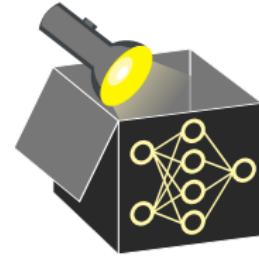
- ⇒  $x_1, x_2$  cancel in  $\hat{f}$  since  $x_1 \approx x_2$ , hence  $0.3x_1 - 0.3x_2 \approx 0$   
~~ should be irrelevant
- ⇒ Permuting  $x_1$  breaks joint structure ~~ unrealistic inputs
- ⇒  $PFI > 0$  due to extrapolation (PFI evaluates model on unrealistic inputs)  
~~  $x_1, x_2$  are misleadingly considered relevant

# COMMENTS ON PFI - INTERACTIONS

**Example:** Let  $x_1, \dots, x_4$  be independently and uniformly sampled from  $\{-1, 1\}$  and

$$y := x_1 x_2 + x_3 + \epsilon_Y \text{ with } \epsilon_Y \sim N(0, 1)$$

Fitting a LM yields  $\hat{f}(x) \approx x_1 x_2 + x_3$ .



# COMMENTS ON PFI - INTERACTIONS

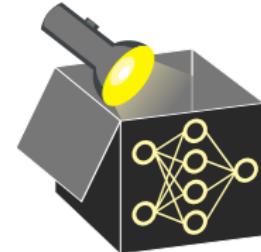
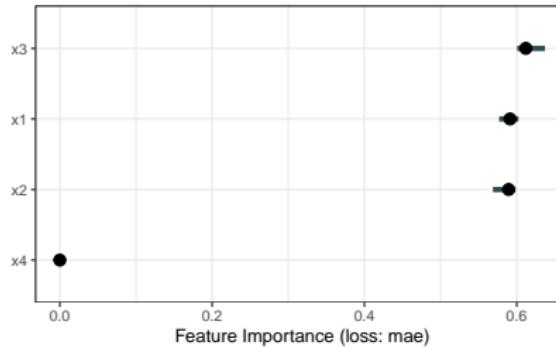
**Example:** Let  $x_1, \dots, x_4$  be independently and uniformly sampled from  $\{-1, 1\}$  and

$$y := x_1 x_2 + x_3 + \epsilon_Y \text{ with } \epsilon_Y \sim N(0, 1)$$

Fitting a LM yields  $\hat{f}(x) \approx x_1 x_2 + x_3$ .

Although  $x_3$  alone contributes as much to the prediction as  $x_1$  and  $x_2$  jointly, all three are considered equally relevant.

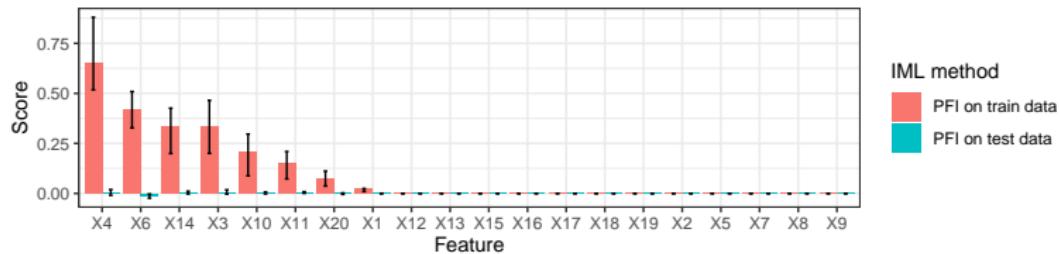
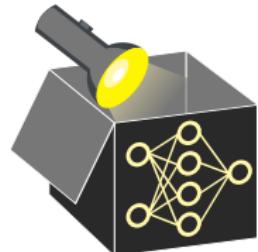
⇒ PFI does not fairly attribute the performance to the individual features.



# COMMENTS ON PFI - TRAIN VS. TEST DATA

## Example:

- $x_1, \dots, x_{20}, y$  are independently sampled from  $\mathcal{U}(-10, 10)$
- Train set:  $n = 50$  (intentionally small) and large test set
- Model: xgboost with default settings (overfits strongly)



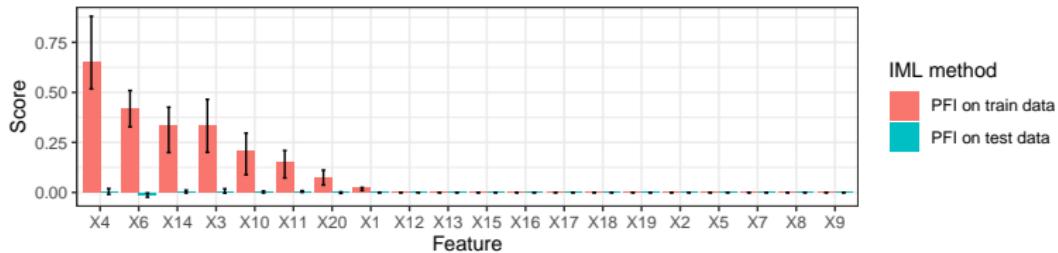
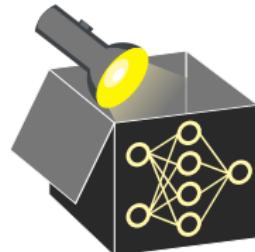
## Observation:

- PFI on train data highlights features that the model overfitted to.
- PFI on test data detects no relevant features.

# COMMENTS ON PFI - TRAIN VS. TEST DATA

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- PFI on train data highlights features that the model overfitted to.
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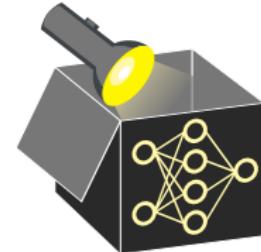
**Why?**  $PFI \neq 0$  if permuting a feature breaks a dependency the model relies on. Model overfits due to spurious feature-target dependencies in train that vanish on test.

⇒ To find features that help the model to generalize, compute PFI on test data.

# IMPLICATIONS OF PFI

Can we get insight into whether the ...

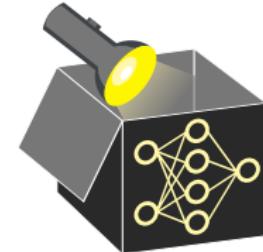
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  - $x_j$  is not exploited by model (regardless of its usefulness for  $y$ )  
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- ➌ model requires access to  $x_j$  to achieve its prediction performance?
  - As shown by the extrapolation example, such insight is not possible

