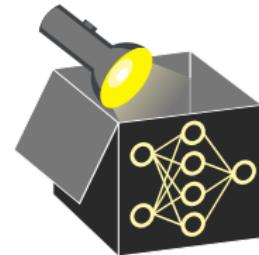
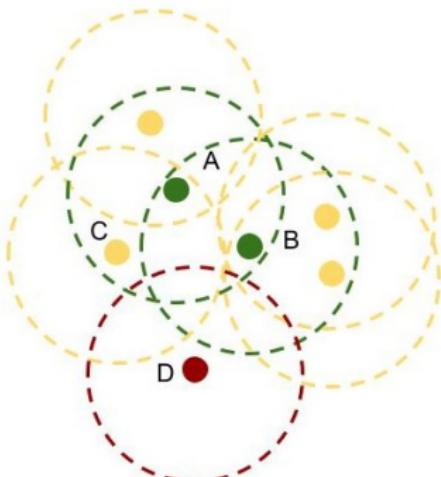


Interpretable Machine Learning



Local Explanations: Increasing Trust in Explanations

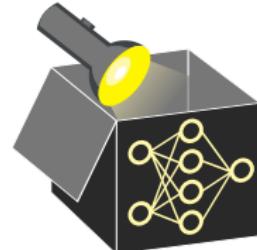


Learning goals

- Understand the aspects that undermine users' trust in an explanation
- Learn diagnostic tools that could increase trust

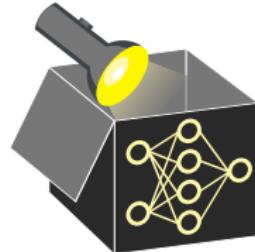
MOTIVATION & IMPORTANT PROPERTIES

- Local explanations should not only make a model interpretable but also reveal if the model is trustworthy



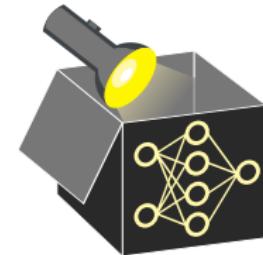
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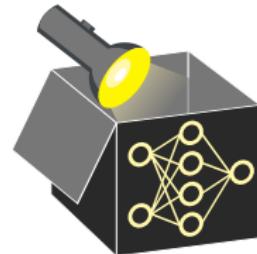
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 - ➊ accurate insights into the inner workings of our model
 - Failure case: generation is based on inputs in areas where the model was trained with little or no training data (extrapolation)



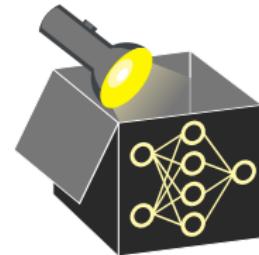
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 - ➋ robust (i.e. low variance)
 - Expectation: similar explanations for similar data points with similar predictions
 - However, multiple sources of uncertainty exist
 - ~~ measure how robust an IML method is to small changes in the input data or parameters
 - ~~ Is an observation out-of-distribution?



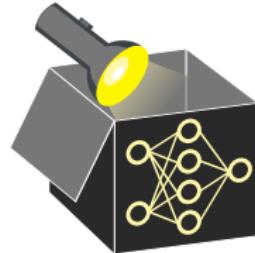
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- Failing in one of these ~~ undermining users' trust in the explanations
 - ~~ undermining trust in the model



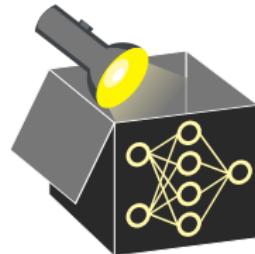
OUT-OF-DISTRIBUTION (OOD) DETECTION

- Models are unreliable in areas with little data support
~~ explanations from local explanation methods are unreliable

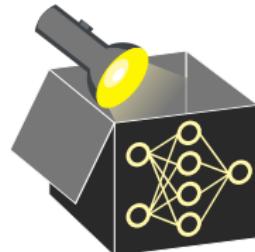


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- For local explanation methods, the following components could be out-of-distribution (OOD):
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 - Shapley value's permuted obs. to calculate the marginal contribs
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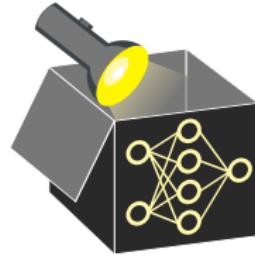
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- Two very simple and intuitive approaches
 - Classifier for out-of-distribution
 - Clustering
- More complicated also possible, e.g., variational autoencoders

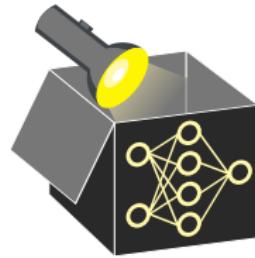
▶ "Daxberger et al." 2020

OOD DETECTION: OOD-CLASSIFIER



- Problem: we have only in-distribution data
- Idea: Hallucinate new (ood) data by randomly sampling data points
- ~~> Learn a binary classifier to distinguish between the origins of the data

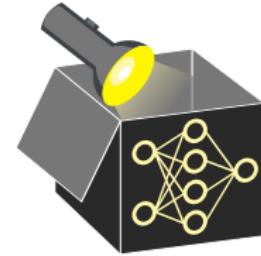
OOD DETECTION: OOD-CLASSIFIER



- Problem: we have only in-distribution data
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- ~~> Learn a binary classifier to distinguish between the origins of the data
- Study whether an explanation approach can be fooled ▶ "Dylan Slack et al." 2020
 - Hide bias in the true (deployed) model, but use an unbiased model for all out-of-distribution samples
- ~~> Important way to diagnose an explanation approach

OOD DETECTION: CLUSTERING VIA DBSCAN

- DBSCAN is a data clustering algorithm
▶ "Martin Ester et al." 1996
(Density-Based Spatial Clustering of Applications with Noise)

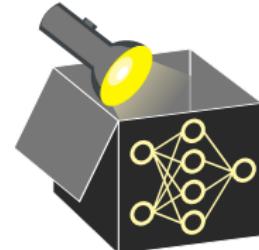


OOD DETECTION: CLUSTERING VIA DBSCAN

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- For this method, we define an ϵ -neighborhood:
Given a dataset $X = \{\mathbf{x}^{(i)}\}_{i=1}^n$, an ϵ -neighborhood for $\mathbf{x} \in \mathcal{X}$ is defined as

$$\mathcal{N}_\epsilon(\mathbf{x}) = \{\mathbf{x}^{(i)} \in \mathcal{X} \mid d(\mathbf{x}, \mathbf{x}^{(i)}) \leq \epsilon\}.$$

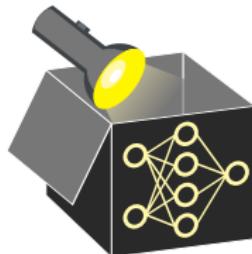
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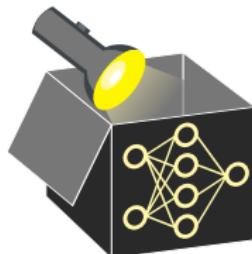
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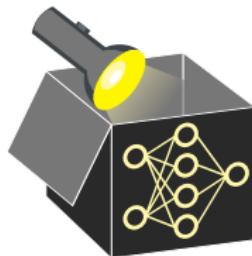
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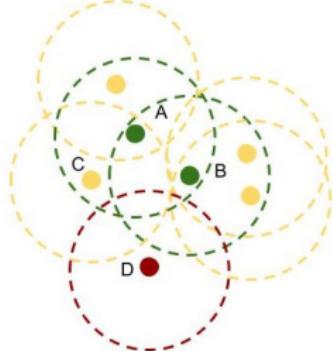
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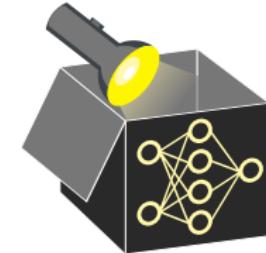
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- Noise points
 - Are not within $\mathcal{N}_\epsilon(\mathbf{x})$
 - Not part of any cluster

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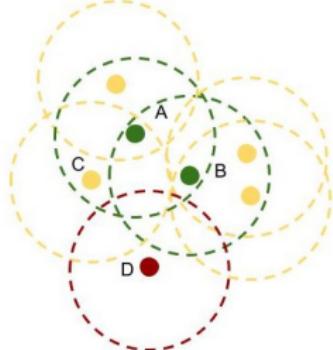


- Green points A and B are core points and form one cluster since they lie in each others neighborhood, all yellow points are border points of this cluster



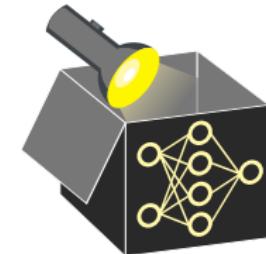
Example for DBSCAN, circles display ϵ -neighborhoods, $m = 4$

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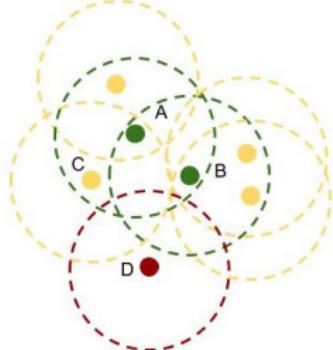


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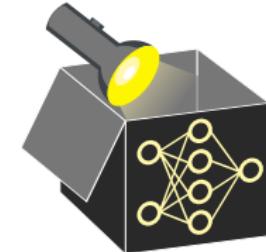


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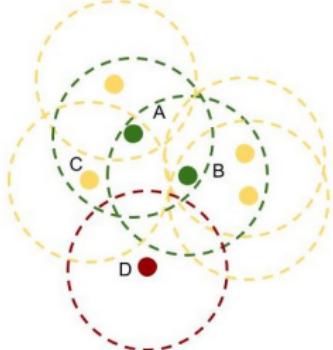


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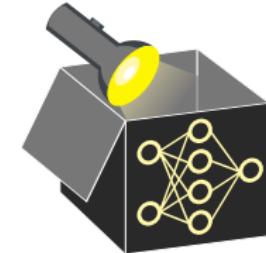


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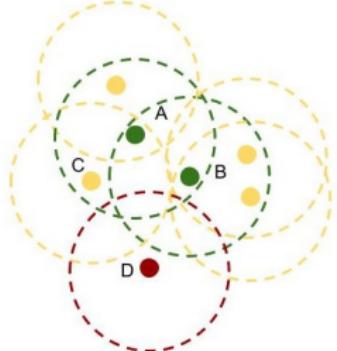


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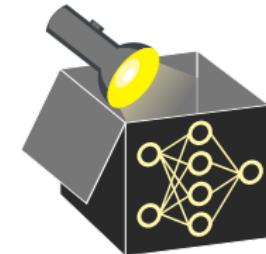


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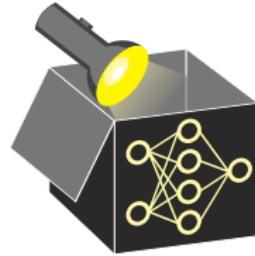
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- Disadvantages:

- Depending on the distance metric $d(\cdot)$, DBSCAN could suffer from the “curse of dimensionality”
- The choice of ϵ and m is not clear a-priori

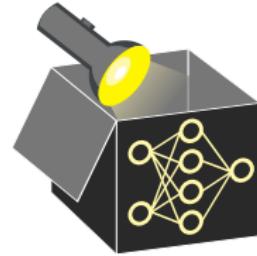


ROBUSTNESS



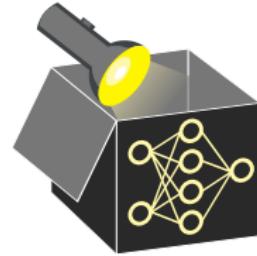
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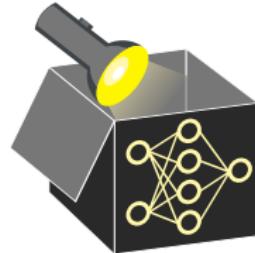
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- We focus on explanation uncertainty
 - Even with the same model and same (or similar) data points, we can receive different explanations

ROBUSTNESS MEASURE FOR LIME AND SHAP

- Objective: Similar explanations for similar inputs (in a neighborhood)



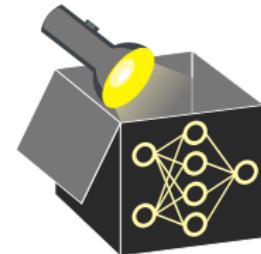
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An explanation method $g : \mathcal{X} \rightarrow \mathbb{R}^m$ is locally Lipschitz if

- for every $\mathbf{x}_0 \in \mathcal{X}$ there exist $\delta > 0$ and $\omega \in \mathbb{R}$
- such that $\|\mathbf{x} - \mathbf{x}_0\| < \delta$ implies $\|g(\mathbf{x}) - g(\mathbf{x}_0)\| < \omega \|\mathbf{x} - \mathbf{x}_0\|$

Note that, for LIME, g returns the m coefficients of the surrogate model



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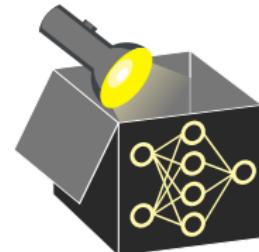
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- According to this, we can quantify the robustness of explanation models in terms of ω :
 - ~> The closer ω is to 0, the more robust our explanation method is
- ω is rarely known a-priori but it could be estimated as follows:

$$\hat{\omega}_X(\mathbf{x}) \in \arg \max_{\mathbf{x}^{(i)} \in \mathcal{N}_\epsilon(\mathbf{x})} \frac{\|g(\mathbf{x}) - g(\mathbf{x}^{(i)})\|_2}{d(\mathbf{x}, \mathbf{x}^{(i)})},$$

where $\mathcal{N}_\epsilon(\mathbf{x})$ is the ϵ -neighborhood of \mathbf{x}

