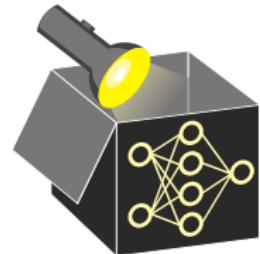
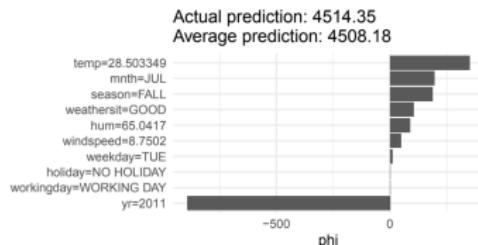


# Interpretable Machine Learning



## Shapley Shapley Values for Local Explanations

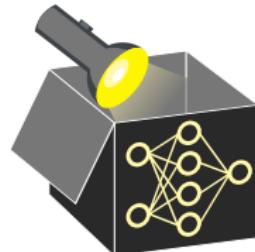
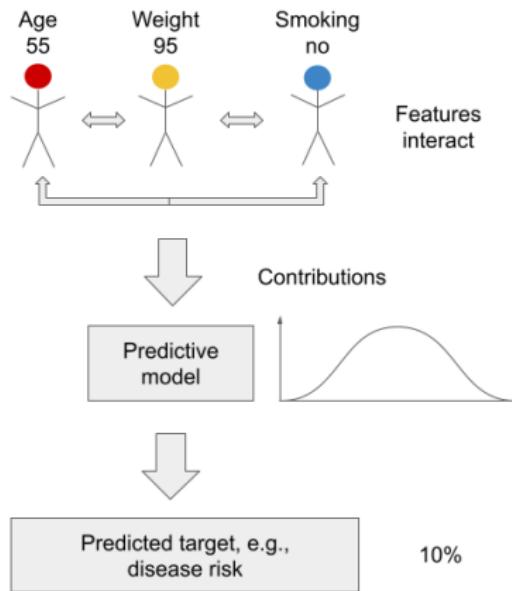


### Learning goals

- See model predictions as a cooperative game
- Transfer the Shapley value concept from game theory to machine learning

# FROM GAME THEORY TO MACHINE LEARNING

- Model prediction depends on feature interactions for a specific observation
- **Goal:** Decompose prediction into **individual feature contributions**
- **Idea:** Treat features as players jointly producing a prediction
- How to fairly assign credit to features?  
⇒ Shapley values

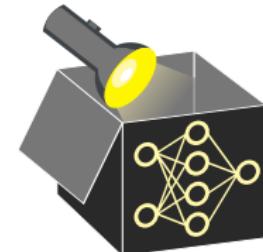


# FROM GAME THEORY TO MACHINE LEARNING

- **Game:** Predict  $\hat{f}(x_1, x_2, \dots, x_p)$  for a single observation  $\mathbf{x}$
- **Players:** Features  $x_j, j \in \{1, \dots, p\}$ , cooperate to produce a prediction
- **Value function:** Defines payout of coalition  $S \subseteq P$  for observation  $\mathbf{x}$  by

$$v(S) = \hat{f}_S(\mathbf{x}_S) - \hat{f}_{\emptyset}, \text{ where}$$

- $\hat{f}_S : \mathcal{X}_S \mapsto \mathcal{Y}$  is the PD function  $\hat{f}_S(\mathbf{x}_S) := \int \hat{f}(\mathbf{x}_S, X_{-S}) d\mathbb{P}_{X_{-S}}$   
~~~ "Removes" features in  $-S$  by marginalizing, keeping  $\hat{f}$  fixed
- Mean prediction  $\hat{f}_{\emptyset} := \mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$  is subtracted to ensure  $v(\emptyset) = 0$
- **Goal:** Distribute total payout  $v(P) = \hat{f}(\mathbf{x}) - \hat{f}_{\emptyset}$  fairly among features



# FROM GAME THEORY TO MACHINE LEARNING

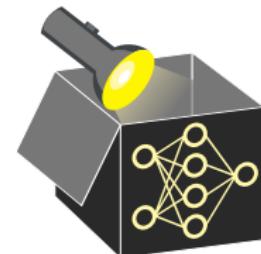
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- **Goal:** Distribute total payout  $v(P) = \hat{f}(\mathbf{x}) - \hat{f}_{\emptyset}$  fairly among features
- **Marginal contribution of feature  $j$  joining coalition  $S$**  ( $\hat{f}_{\emptyset}$  cancels):

$$\Delta(j, S) = v(S \cup \{j\}) - v(S) = \hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) - \hat{f}_S(\mathbf{x}_S)$$

- **Example (3 features):** Feature contributions for joining order  
 $x_1 \rightarrow x_2 \rightarrow x_3$  toward total payout  $v(P) = \hat{f}(\mathbf{x}) - \hat{f}_{\emptyset}$ , each step reflects a marginal contribution



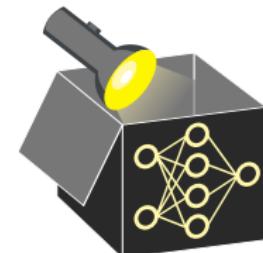
# SHAPLEY VALUE - DEFINITION

► "Shapley" 1953

► "Strumbelj et al." 2014

**Order definition:** Shapley value  $\phi_j(\mathbf{x})$  quantifies contribution of  $x_j$  via

$$\phi_j(\mathbf{x}) = \frac{1}{|P|!} \sum_{\tau \in \Pi} \underbrace{\hat{f}_{S_j^\tau \cup \{j\}}(\mathbf{x}_{S_j^\tau \cup \{j\}}) - \hat{f}_{S_j^\tau}(\mathbf{x}_{S_j^\tau})}_{\Delta(j, S_j^\tau) \text{ marginal contribution of feature } j}$$



- **Interpretation:**  $\phi_j(\mathbf{x})$  quantifies how much feature  $x_j$  contributes to the difference between  $\hat{f}(\mathbf{x})$  and the mean prediction  $\hat{f}_\emptyset$   
~~ Marginal contributions and Shapley values can be negative

- **Exact computation of  $\phi_j$ :** Using PD function

$$\hat{f}_S(\mathbf{x}_S) = \frac{1}{n} \sum_{i=1}^n \hat{f}(\mathbf{x}_S, \mathbf{x}_{-S}^{(i)}) \text{ yields}$$

$$\phi_j(\mathbf{x}) = \frac{1}{|P|!} \sum_{\tau \in \Pi} \frac{1}{n} \sum_{i=1}^n \hat{f}(\mathbf{x}_{S_j^\tau \cup \{j\}}, \mathbf{x}_{-\{S_j^\tau \cup \{j\}\}}^{(i)}) - \hat{f}(\mathbf{x}_{S_j^\tau}, \mathbf{x}_{-S_j^\tau}^{(i)})$$

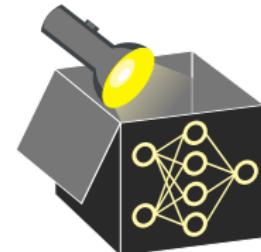
- ~~  $\hat{f}_S$  marginalizes over all features not in  $S$  using all obs.  $i = 1, \dots, n$
- ~~ Exact computation requires  $|P|! \cdot n$  marginal contribution terms

# ESTIMATION: A PRACTICAL PROBLEM

- **Exact computation is infeasible for many features:**

For  $|P| = 10$ , the number of permutations is  $10! \approx 3.6$  million

~~ Complexity grows factorially with feature count



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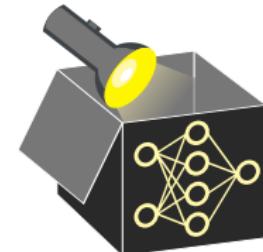
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Each permut.  $\tau$  defines a coal.  $S_j^\tau$  needing its own estimate of  $\hat{f}_{S_j^\tau}(\mathbf{x}_{S_j^\tau})$

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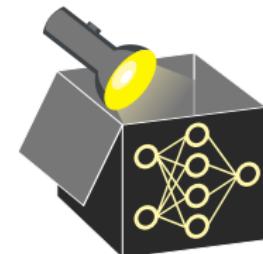
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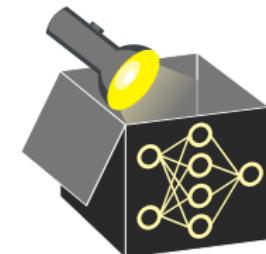
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- **Tradeoff: Accuracy vs. Efficiency**

Larger  $M$  improves Shapley approximation

~~ Higher cost, but better fidelity to the exact value

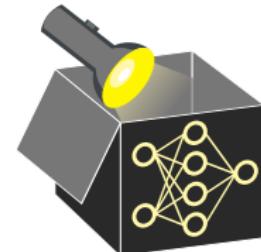


# APPROXIMATION ALGORITHM

► "Strumbelj et al." 2014

Estimate Shapley value  $\phi_j$  of observation  $\mathbf{x}$  for feature  $j$ :

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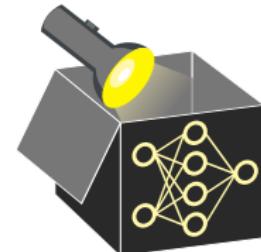


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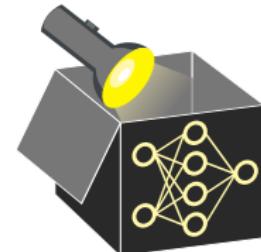


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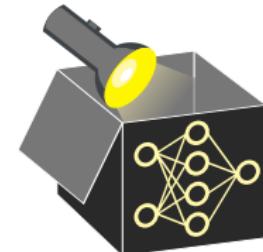


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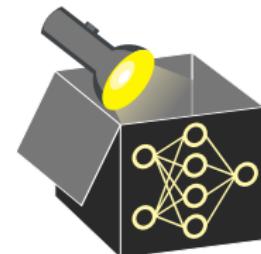
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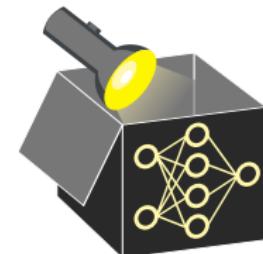
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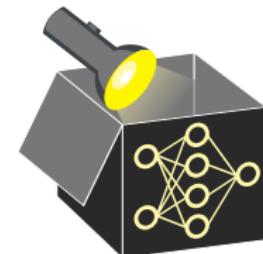
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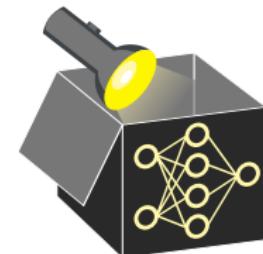
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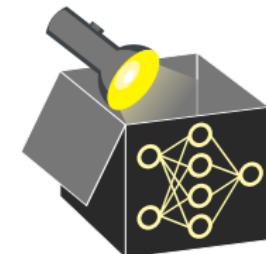
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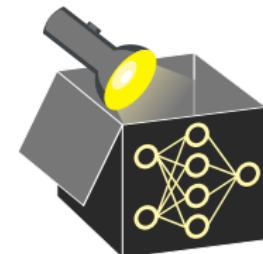
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► "Strumbelj et al." 2014

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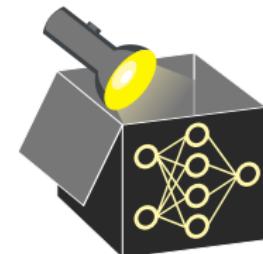
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- ⑦ Compute Shapley value  $\phi_j = \frac{1}{M} \sum_{m=1}^M \Delta(j, S_m)$

- ~~ Over  $M$  iterations, the PD functions  $\hat{f}_{S_m}(\mathbf{x}_{S_m})$  and  $\hat{f}_{S_m \cup \{j\}}(\mathbf{x}_{S_m \cup \{j\}})$  are approximated by  $\hat{f}(\mathbf{x}_{-j}^{(m)})$  and  $\hat{f}(\mathbf{x}_{+j}^{(m)})$ , where features not in the coalition (to be marginalized) are imputed with vals from random data points  $\mathbf{z}^{(m)}$



# SHAPLEY VALUE APPROX. - ILLUSTRATION

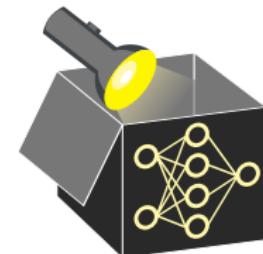
Definition

$\mathbf{x}$ : obs. of interest

$\mathbf{x}$  with feature values in  
 $\mathbf{x}_{S_m}$  (other are replaced)

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^M \left[ \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]$$

$\mathbf{x}$  with feature values in  
 $\mathbf{x}_{S_m \cup \{j\}}$



|                   | Temperature | Humidity | Windspeed                      | Year                      |
|-------------------|-------------|----------|--------------------------------|---------------------------|
| $\mathbf{x}$      | 10.66       | 56       | 11                             | 2012                      |
| $\mathbf{x}_{+j}$ | 10.66       | 56       | random : $z_{windspeed}^{(m)}$ | 2012                      |
| $\mathbf{x}_{-j}$ | 10.66       | 56       | random : $z_{windspeed}^{(m)}$ | random : $z_{year}^{(m)}$ |

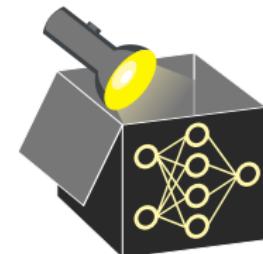
$j$

# SHAPLEY VALUE APPROX. - ILLUSTRATION

## Definition

Contribution of feature  $j$   
to coalition  $S_m$

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^M \underbrace{\left[ \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]}_{:= \Delta(j, S_m)}$$



- $\Delta(j, S_m) = \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)})$  is marginal contribution of feature  $j$  to coalition  $S_m$
- Here: Feature *year* contributes +700 bike rentals if it joins coalition  $S_m = \{\text{temp}, \text{hum}\}$

|                   | Temperature | Humidity | Windspeed                      | Year                      | Count                                                                                                                                                                                                                                                                                                  |
|-------------------|-------------|----------|--------------------------------|---------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\mathbf{x}$      | 10.66       | 56       | 11                             | 2012                      |                                                                                                                                                                                                                                                                                                        |
| $\mathbf{x}_{+j}$ | 10.66       | 56       | random : $z_{windspeed}^{(m)}$ | 2012                      | <div style="display: flex; align-items: center;"><div style="background-color: #80e680; padding: 5px; margin-right: 10px;">5600</div><div style="background-color: #ffd700; padding: 5px; border: 1px solid black; border-radius: 5px; width: 40px; height: 20px;"></div></div>                        |
| $\mathbf{x}_{-j}$ | 10.66       | 56       | random : $z_{windspeed}^{(m)}$ | random : $z_{year}^{(m)}$ | <div style="display: flex; align-items: center;"><div style="background-color: #80e680; padding: 5px; margin-right: 10px;">4900</div><div style="background-color: #ffd700; padding: 5px; border: 1px solid black; border-radius: 5px; width: 40px; height: 20px; text-align: center;">700</div></div> |

$j$

$\hat{f}$

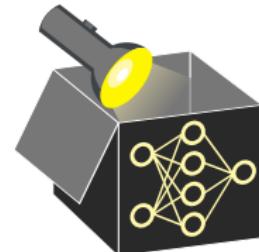
$\Delta(j, S_m)$   
marginal  
contribution

# SHAPLEY VALUE APPROX. - ILLUSTRATION

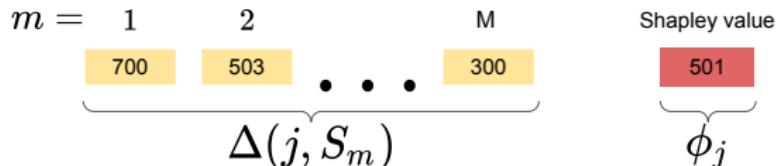
## Definition

average the contributions  
of feature  $j$

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^M \left[ \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]$$



- Compute marginal contribution of feature  $j$  towards the prediction across all randomly drawn feature coalitions  $S_1, \dots, S_m$
- Average all  $M$  marginal contributions of feature  $j$
- Shapley value  $\phi_j$  is the payout of feature  $j$ , i.e., how much feature  $j$  contributed to the overall prediction in bicycle counts of a specific obs.  $\mathbf{x}$

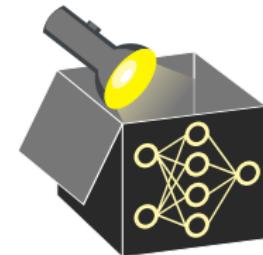


# REVISITED: AXIOMS FOR FAIR ATTRIBUTIONS

We adapt the classic Shapley axioms to the setting of model predictions:

- **Efficiency:** Sum of Shapley values adds up to the centered prediction:

$$\sum_{j=1}^p \phi_j(\mathbf{x}) = \hat{f}(\mathbf{x}) - \mathbb{E}_{\mathbf{x}}[\hat{f}(\mathbf{x})]$$



~~ All predictive contribution is fully distributed among features

- **Symmetry:** Identical contributors receive equal value:

$$\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_{S \cup \{k\}}(\mathbf{x}_{S \cup \{k\}}) \quad \forall S \subseteq P \setminus \{j, k\} \Rightarrow \phi_j = \phi_k$$

~~ Interaction effects are shared equitably

- **Dummy (Null Player):** Irrelevant features receive zero attribution:

$$\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_S(\mathbf{x}_S) \quad \forall S \subseteq P \Rightarrow \phi_j = 0$$

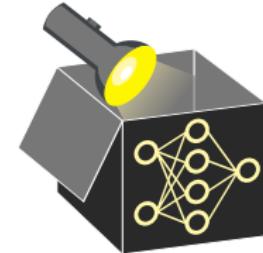
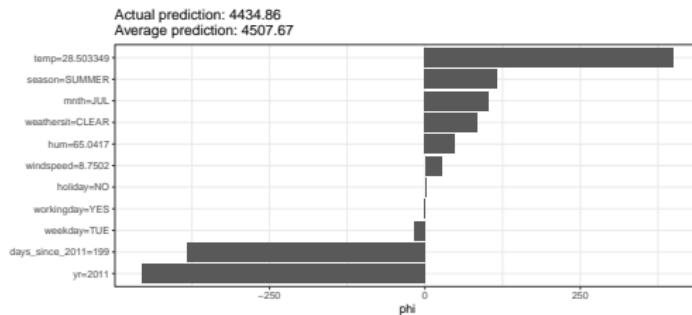
~~ Shapley value is zero for unused features (e.g., trees or LASSO)

- **Additivity:** Attributions are additive across models:

$$\phi_j(v_1 + v_2) = \phi_j(v_1) + \phi_j(v_2)$$

~~ Enables combining Shapley values for model ensembles

# BIKE SHARING DATASET

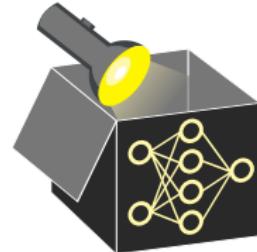


- Shapley decomposition for a single prediction in bike sharing dataset
- Model pred.:  $\hat{f}(\mathbf{x}^{(200)}) = \mathbf{4434.86}$  vs. dataset avg.:  $\mathbb{E}_{\mathbf{x}}[\hat{f}(\mathbf{x})] = \mathbf{4507.67}$
- Total feature attribution:  $\sum_j \phi_j = \mathbf{-72.81}$ 
  - ~~ Explain downward shift from mean prediction
- Temperature (with value  $28.5^{\circ}\text{C}$ ) – strongest positive contributor: +400
- $\text{yr} = 2011$  and  $\text{days\_since\_2011} = 199$  strongly reduce prediction
  - ~~ Model captures lower bike demand in 2011 compared to 2012

# ADVANTAGES AND DISADVANTAGES

## Advantages:

- **Strong theoretical foundation** from cooperative game theory
- **Fair attribution:** Prediction is additively distributed across features
  - ~~ Easy to interpret for users
- **Contrastive explanations:** Quantify each feature's role in deviating from the average prediction



## Disadvantages:

- **Comput. cost:** Exact computation scales factorially with feature count
  - ~~ Without sampling, all  $2^p$  coalitions (or  $p!$  permuts) must be evaluated
- **Issue with correlated features:** Shapley values may evaluate the model on feature combinations that do not occur in the real data