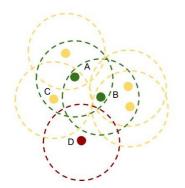
Interpretable Machine Learning

Local Explanations: Increasing Trust in Explanations





- Understand the aspects that undermine users' trust in an explanation
- Learn diagnostic tools that could increase trust



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- Failing in one of these → undermining users' trust in the explanations
 → undermining trust in the model



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- For local explanation methods, the following components could be out-of-distribution (OOD):
 - The data for LIME's surrogate model
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 - The data for LIME's surrogate model
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- Two very simple and intuitive approaches
 - Classifier for out-of-distribution
 - Clustering
- More complicated also possible, e.g., variational autoencoders
 - Daxberger 2020



OOD DETECTION: OOD-CLASSIFIER

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- Problem: we have only in-distribution data
- Idea: Hallucinate new (ood) data by randomly sampling data points
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- Problem: we have only in-distribution data
- Idea: Hallucinate new (ood) data by randomly sampling data points
- Learn a binary classifier to distinguish between the origins of the data
- Study whether an explanation approach can be fooled Slack 2020
 - Hide bias in the true (deployed) model, but use an unbiased model for all out-of-distribution samples
- → Important way to diagnose an explanation approach

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 ◆ Ester 1996
 (Density-Based Spatial Clustering of Applications with Noise)



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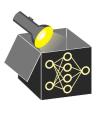
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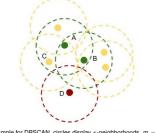


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- Noise points
 - Are not within $\mathcal{N}_{\epsilon}(\mathbf{x})$
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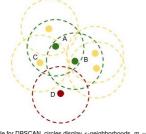




Example for DBSCAN, circles display ϵ -neighborhoods, m=4

 Green points A and B are core points and form one cluster since they lie in each others neighborhood, all yellow points are border points of this cluster



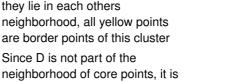


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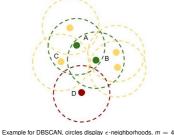
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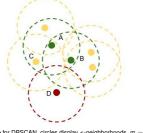




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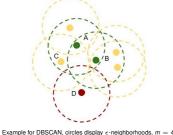




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Disadvantages:

- Depending on the distance metric $d(\cdot)$, DBSCAN could suffer from the "curse of dimensionality"
- ullet The choice of ϵ and m is not clear a-priori



ROBUSTNESS

- Differentiate between different kinds of uncertainty:
 - Explanation uncertainty: Change of explanation if we repeat the process, e.g., the explanation could differ depending on which subset of data we use for the expl. method and which hyperparams



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 - Process uncertainty: Change of explanation if the underlying model is changed
 - \leadsto are ML models non-robust, e.g., because they are trained on noisy data?
- We focus on explanation uncertainty
 - Even with the same model and same (or similar) data points, we can receive different explanations



• Objective: Similar explanations for similar inputs (in a neighborhood)

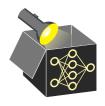


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- For LIME and SHAP, notion of stability based on locally Lipschitz continuity
 Jaakkola 2018

An explanation method $g:\mathcal{X} \to \mathbb{R}^m$ is locally Lipschitz if

- ullet for every $\mathbf{x}_0 \in \mathcal{X}$ there exist $\delta > \mathbf{0}$ and $\omega \in \mathbb{R}$
- ullet such that $||\mathbf{x}-\mathbf{x}_0||<\delta$ implies $||g(\mathbf{x})-g(\mathbf{x}_0)||<\omega||\mathbf{x}-\mathbf{x}_0||$

Note that, for LIME, *g* returns the *m* coefficients of the surrogate model



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- According to this, we can quantify the robustness of explanation models in terms of ω :
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- ullet ω is rarely known a-priori but it could be estimated as follows:

$$\hat{\omega}_X(\mathbf{x}) \in rg \max_{\mathbf{x}^{(i)} \in \mathcal{N}_e(\mathbf{x})} rac{||g(\mathbf{x}) - g(\mathbf{x}^{(i)})||_2}{d(\mathbf{x}, \mathbf{x}^{(i)})},$$

where $\mathcal{N}_{\epsilon}(\mathbf{x})$ is the ϵ -neighborhood of \mathbf{x}

