Interpretable Machine Learning

Permutation Feature Importance (PFI)

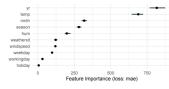
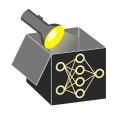


Figure: Bike Sharing Dataset

Learning goals

- Understand how PFI is computed
- Understanding strengths and weaknesses



MOTIVATION FOR PFI

- Goal: Assess how important feature(s) X_S are for predictive performance of a fixed trained model \hat{f} on a given dataset \mathcal{D}
- Idea: Estimate change in model performance when X_S is "made uninformative"



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- Question: Can we make X_S uninformative by removing it from the model? \rightarrow No, \hat{t} was trained with X_S and retraining without X_S gives a different model



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- Question: Can we make X_S uninformative by removing it from the model?
 → No, f̂ was trained with X_S and retraining without X_S gives a different model
- **Solution:** Simulate feature removal by replacing X_S with a perturbed version \tilde{X}_S that is independent of (X_{-S}, Y) but preserves distribution $\mathbb{P}(X_S)$ \rightsquigarrow Compare baseline predictions $\hat{f}(X)$ with perturbed predictions $\hat{f}(\tilde{X}_S, X_{-S})$

$$\mathsf{PFI}_S := \underbrace{\mathbb{E}\Big[L\big(\hat{f}(\tilde{X}_S, X_{-S}), Y\big)\Big]}_{\mathsf{risk after "destroying"} \, X_S} - \underbrace{\mathbb{E}\Big[L\big(\hat{f}(X), Y\big)\Big]}_{\mathsf{baseline risk}},$$

- How to perturb X_S ?
 - Add random noise: distorts $\mathbb{P}(X_S)$ (not used)
 - Permutation: preserves marginal $\mathbb{P}(X_S)$, breaks dependence with Y (used)



PERMUTATION FEATURE IMPORTANCE (PFI) Pereiman (2001)

Sample estimator (using independent test set $\mathcal{D} = \{(\mathbf{x}^{(i)}, \mathbf{y}^{(i)})\}_{i=1}^n$)

- Measure the error with feat. values x_S and with permuted feat. values \tilde{x}_S
- Repeat permutation (e.g., *m* times) and average difference of both errors:

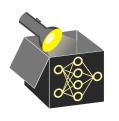
$$\widehat{\mathit{PFI}}_{\mathcal{S}} = \tfrac{1}{m} \sum_{k=1}^{m} \left[\mathcal{R}_{\mathsf{emp}}(\hat{f}, \tilde{\mathcal{D}}_{(k)}^{\mathcal{S}}) - \mathcal{R}_{\mathsf{emp}}(\hat{f}, \mathcal{D}) \right]$$

- $\mathcal{D}_{S}^{(k)}$: dataset where column(s) x_{S} are **permuted** once (in repetition k)
- $\mathcal{R}_{emp}(\hat{f}, \mathcal{D}) = \frac{1}{n} \sum_{(x,y) \in \mathcal{D}} L(\hat{f}(x), y)$: Measures performance of \hat{f} using \mathcal{D}
- Average over m permutations to reduce Monte-Carlo variance

Example of permuting feature x_S with $S = \{1\}$ and m = 6 permutations:

	\mathcal{D}				$ ilde{\mathcal{D}}_{(1}^{S}$)		$ ilde{\mathcal{D}}_{(2}^{S}$)		$ ilde{\mathcal{D}}_{(3)}^{S}$: 3)		$ ilde{\mathcal{D}}_{(4)}^{S}$	4)		$ ilde{\mathcal{D}}_{(5)}^{S}$)		$ ilde{\mathcal{D}}_{(6)}^{\mathcal{S}}$)
X ₁	X ₂	X 3	⇒	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3	$\mathbf{x}_{\mathcal{S}}$	X ₂	X 3
1	4	7	_	1	4	7	2	4	7	2	4	7	1	4	7	3	4	7	3	4	7
2	5	8		2	5	8	1	5	8	3	5	8	3	5	8	1	5	8	2	5	8
3	6	9		3	6	9	3	6	9	1	6	9	2	6	9	2	6	9	1	6	9

Note: S refers to a subset of features, here |S| = 1 to measure impact of permuting x_1 on performance



		$ ilde{\mathcal{D}}_{0}$	S (k)	${\cal D}$					
i	xs	X ₂	\mathbf{x}_3	X ₁	X ₂	x ₃			
1	2	4	7	1	4	7			
:	1	5	8	2	5	8			
n	3	6	9	3	6	တ			



- **1. Perturbation:** Sample feature values from the distribution of x_S ($P(X_S)$).
 - \Rightarrow Randomly permute feature x_S
 - \Rightarrow Replace x_S with permuted feature \tilde{x}_S and create data $\tilde{\mathcal{D}}^S$ containing \tilde{x}_S

		$ ilde{\mathcal{D}}$	\mathcal{D}					
i	xs	\mathbf{x}_2	\mathbf{x}_3		X ₁	X ₂	X ₃	
1	2	4	7		1	4	7	
:	1	5	8		2	5	8	
n	3	6	9		3	6	9	
		$\frac{\hat{f}}{\hat{f}}$ 0.6 0.6 0.6				$\frac{\hat{f}}{\hat{f}}$ 0.4 0.8 0.6		



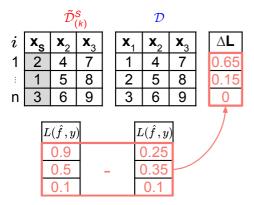
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 - \Rightarrow Randomly permute feature x_S
 - \Rightarrow Replace $x_{\mathcal{S}}$ with permuted feature $\tilde{x}_{\mathcal{S}}$ and create data $\tilde{\mathcal{D}}^{\mathcal{S}}$ containing $\tilde{x}_{\mathcal{S}}$
- 2. Prediction: Make predictions for both data, i.e., $\mathcal D$ and $\tilde{\mathcal D}^{\mathcal S}$

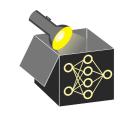
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1	2	4	7	1	4	7			
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n	3	6	9	3	6	9			
		(\hat{f}, y) 0.9 0.5)		0.25	-			
	L	0.1		0.1					



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• Compute the loss for each observation in both data sets





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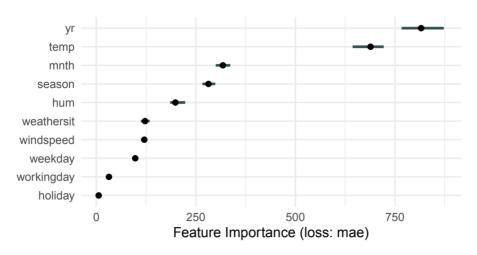
- Compute the loss for each observation in both data sets
- Take the difference of both losses ΔL for each observation
- \bullet Average this change in loss across all observations Note: Same as computing \mathcal{R}_{emp} on both data sets and taking difference

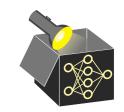


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- Compute the loss for each observation in both data sets
- Take the difference of both losses ΔL for each observation
- Average this change in loss across all observations
- Repeat perturbation and average over multiple repetitions

EXAMPLE: BIKE SHARING DATASET

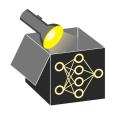




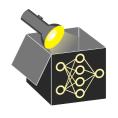
Interpretation:

- yr and temp are most important features using mean absolute error (MAE)
- Destroying information about yr by permuting it increases MAE of model by 816
- Error bars show 5% and 95% quantiles over multiple permutations

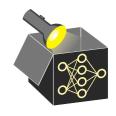
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- PFI automatically includes importance of interaction effects with other features
 - \Rightarrow Permuting x_i also destroys interactions with permuted feature
 - ⇒ PFI score contains importance of all interactions with permuted feature



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 - ⇒ PFI score contains importance of all interactions with permuted feature
- Interpretation of PFI depends on whether training or test data is used



COMMENTS ON PFI - EXTRAPOLATION

Example: Let $y = x_3 + \epsilon_y$, with $\epsilon_y \sim \mathcal{N}(0, 0.1)$.

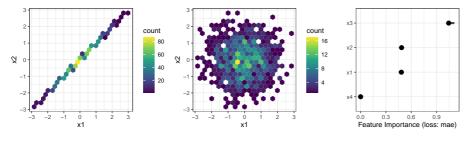
- $x_1 := \epsilon_1, x_2 := x_1 + \epsilon_2$ are highly correlated $(\epsilon_1 \sim \mathcal{N}(0, 1), \epsilon_2 \sim \mathcal{N}(0, 0.01))$
- $x_3 := \epsilon_3$, $x_4 := \epsilon_4$, with $\epsilon_3, \epsilon_4 \sim \mathcal{N}(0,1)$ and all noise terms ϵ_j are independent
- ullet Fitting a linear model yields $\hat{f}(\mathbf{x}) \approx 0.3x_1 0.3x_2 + x_3$



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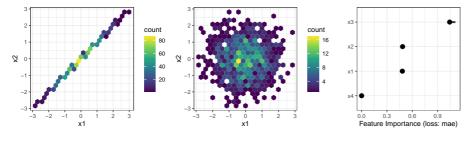
Hexbin plot of (x_1, x_2) before (left) and after (center) permuting x_1 ; PFI scores (right).



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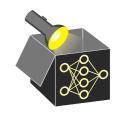
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- $\Rightarrow x_1, x_2$ cancel in \hat{f} since $x_1 \approx x_2$, hence $0.3x_1 0.3x_2 \approx 0 \rightsquigarrow$ should be irrelevant
- \Rightarrow Permuting x_1 breaks joint structure \rightsquigarrow unrealistic inputs
- \Rightarrow *PFI* > 0 due to extrapolation (PFI evaluates model on unrealistic inputs) $\rightsquigarrow x_1, x_2$ are misleadingly considered relevant



COMMENTS ON PFI - INTERACTIONS

Example: Let x_1, \ldots, x_4 be independently and uniformly sampled from $\{-1, 1\}$ and

$$y := x_1x_2 + x_3 + \epsilon_Y \text{ with } \epsilon_Y \sim N(0,1)$$

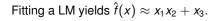
Fitting a LM yields $\hat{f}(x) \approx x_1 x_2 + x_3$.



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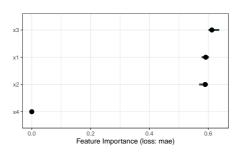
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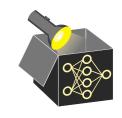
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Although x_3 alone contributes as much to the prediction as x_1 and x_2 jointly, all three are considered equally relevant.

 \Rightarrow PFI does not fairly attribute the performance to the individual features.

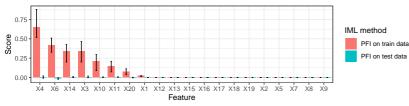




COMMENTS ON PFI - TRAIN VS. TEST DATA

Example:

- x_1, \ldots, x_{20}, y are independently sampled from $\mathcal{U}(-10, 10)$
- Train set: n = 50 (intentionally small) and large test set
- Model: xgboost with default settings (overfits strongly)





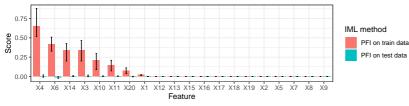
- PFI on train data highlights features that the model overfitted to.
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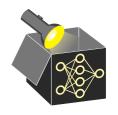
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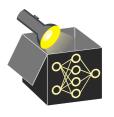
Why? $PFI \neq 0$ if permuting a feature breaks a dependency the model relies on. Model overfits due to spurious feature-target dependencies in train that vanish on test. \Rightarrow To identify features that help the model to generalize, compute PFI on test data.



IMPLICATIONS OF PFI

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 ⇒ PFI_j = 0
- \odot model requires access to x_j to achieve it's prediction performance?
 - As the extrapolation example demonstrates, such insight is not possible

