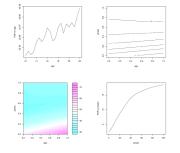
### **Interpretable Machine Learning**

# **Functional Decompositions Theory of Standard fANOVA**



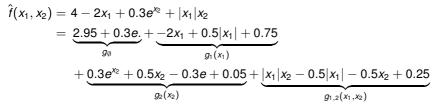
#### Learning goals

- Properties of classical fANOVA, reason for its popularity
- Equivalent definition of classical fANOVA
- Understand the role constraints play for any functional decomposition



### **EXAMPLE: FANOVA ALGORITHM**

- Remember: Functional decomposition in general not unique
- Standard fANOVA only one possible approach
- Example:



→ seems arbitrarily chosen?

 $\longleftrightarrow$  Show: Standard fANOVA fulfills specific desirable properties or constraints



#### CONSTRAINTS FOR STANDARD FANOVA ALGO.

#### **Theorem**

Features independent  $\implies$  The components defined by standard fANOVA fulfill the so-called vanishing conditions:

$$\mathbb{E}_{X_j}[g_S(\mathbf{x}_S)] = \int g_S(\mathbf{x}_S) d\mathbb{P}(x_j) = 0 \quad \text{for any } j \in S \text{ and } S \subseteq \{1, \dots, p\}$$



#### CONSTRAINTS FOR STANDARD FANOVA ALGO.

#### **Theorem**

Features independent  $\implies$  The components defined by standard fANOVA fulfill the so-called vanishing conditions:

$$\mathbb{E}_{X_j}\left[g_S(\mathbf{x}_S)\right] = \int g_S(\mathbf{x}_S) d\mathbb{P}(x_j) = 0 \quad \text{for any } j \in S \text{ and } S \subseteq \{1, \dots, p\}$$

#### Implications:

• For any component  $g_S$ , all its PD-functions are 0:

$$\mathbb{E}_{X_V}\left[g_S(\mathbf{x}_S)\right] = \int g_S(\mathbf{x}_S) d\mathbb{P}(\mathbf{x}_V) = 0 \quad \text{for any } V \subsetneq S \text{ and } S \subseteq \{1,\dots,p\}$$

 $\rightsquigarrow g_S$  contains no lower-order effects, but only pure interaction term (compare H-statistic)

#### CONSTRAINTS FOR STANDARD FANOVA ALGO.

#### **Theorem**

Features independent  $\implies$  The components defined by standard fANOVA fulfill the so-called vanishing conditions:

$$\mathbb{E}_{X_j}\left[g_{\mathcal{S}}(\mathbf{x}_{\mathcal{S}})\right] = \int g_{\mathcal{S}}(\mathbf{x}_{\mathcal{S}}) d\mathbb{P}(x_j) = 0 \quad \textit{for any } j \in \mathcal{S} \textit{ and } \mathcal{S} \subseteq \{1,\ldots,p\}$$

#### Implications:

• For any component  $g_S$ , all its PD-functions are 0:

$$\mathbb{E}_{X_V}\left[g_S(\mathbf{x}_S)\right] = \int g_S(\mathbf{x}_S) d\mathbb{P}(\mathbf{x}_V) = 0 \quad \text{for any } V \subsetneq S \text{ and } S \subseteq \{1, \dots, p\}$$

 $\rightsquigarrow$   $g_S$  contains no lower-order effects, but only pure interaction term (compare H-statistic)

• All components are orthogonal, i.e., mutually indep. and uncorrelated:

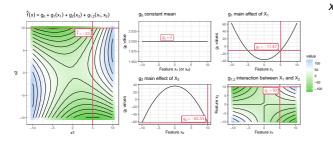
$$\forall V 
eq S: \quad \mathbb{E} \big[ g_V(\mathbf{x}_V) g_S(\mathbf{x}_S) \big] = 0$$

• This implies variance decomposition used to define Sobol indices:  $Var[\hat{f}(\mathbf{x})] = \sum_{S \subset \{1,...,p\}} Var[g_S(\mathbf{x}_S)]$ 

#### **EXAMPLES REVISITED**

**Example:**  $\hat{f}(\mathbf{x}) = 2 + x_1^2 - x_2^2 + x_1 \cdot x_2$  (e.g., for  $x_1 = 5$  and  $x_2 = 10$  we have  $\hat{f}(\mathbf{x}) = -23$ )

• Computation of components using feature values  $x_1 = x_2 = (-10, -9, ..., 10)^{\top}$  gives:



For  $x_1 = 5$  and  $x_2 = 10$ :

- g<sub>∅</sub> = 2
- $g_1(x_1) = -9.67$
- $g_2(x_2) = -65.33$
- $g_{1,2}(x_1,x_2) = 50$

$$\Rightarrow \hat{f}(\mathbf{x}) = -23$$

- Vanishing condition means:
  - $g_1$  and  $g_2$  are mean-centered w.r.t. marginal distribution of  $x_1$  and  $x_2$
  - Integral of  $g_{1,2}$  over marginal distribution  $x_1$  (or  $x_2$ ) is always 0.



### **EXAMPLES REVISITED**

#### **Example**

$$\hat{f}(x_1, x_2) = 4 - 2x_1 + 0.3e^{x_2} + |x_1|x_2 
= \underbrace{2.95 + 0.3e}_{g_{\emptyset}} + \underbrace{-2x_1 + 0.5|x_1| + 0.75}_{g_1(x_1)} 
+ \underbrace{0.3e^{x_2} + 0.5x_2 - 0.3e + 0.05}_{g_2(x_2)} + \underbrace{|x_1|x_2 - 0.5|x_1| - 0.5x_2 + 0.25}_{g_{1,2}(x_1, x_2)}$$



- $\implies$  Main effect terms inside  $g_{1,2}$  are chosen exactly such that the one-dimensional PDPs of  $g_{1,2}$  vanish
- $\implies$  Same for constant terms inside  $g_1$  and  $g_2$ : Ensure centering

#### **EXAMPLES REVISITED**

#### **Example**

$$\hat{f}(x_1, x_2) = 4 - 2x_1 + 0.3e^{x_2} + |x_1|x_2$$

$$= \underbrace{2.95 + 0.3e}_{g_{\emptyset}} + \underbrace{-2x_1 + 0.5|x_1| + 0.75}_{g_1(x_1)}$$

$$+ \underbrace{0.3e^{x_2} + 0.5x_2 - 0.3e + 0.05}_{g_2(x_2)} + \underbrace{|x_1|x_2 - 0.5|x_1| - 0.5x_2 + 0.25}_{g_{1,2}(x_1, x_2)}$$



- $\implies$  Main effect terms inside  $g_{1,2}$  are chosen exactly such that the one-dimensional PDPs of  $g_{1,2}$  vanish
- $\implies$  Same for constant terms inside  $g_1$  and  $g_2$ : Ensure centering

#### **Example**

From in-class exercise:  $g(x_1, x_2) = \beta_{12} (x_1 - \mu_1)(x_2 - \mu_2)$ 

• So far: Definition of standard fANOVA implies vanishing conditions



- So far: Definition of standard fANOVA implies vanishing conditions



- So far: Definition of standard fANOVA implies vanishing conditions
- In other words: Vanishing conditions are equivalent characterization



- So far: Definition of standard fANOVA implies vanishing conditions
- In other words: Vanishing conditions are equivalent characterization
- In general: Functional decomp. can be defined by sets of constraints



- So far: Definition of standard fANOVA implies vanishing conditions
- In other words: Vanishing conditions are equivalent characterization
- In general: Functional decomp. can be defined by sets of constraints
- Many other methods to compute decompositions exist, each with their set of constraints

