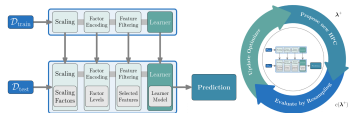


Introduction to Machine Learning

Hyperparameter Tuning Pipelines and AutoML

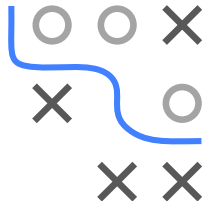
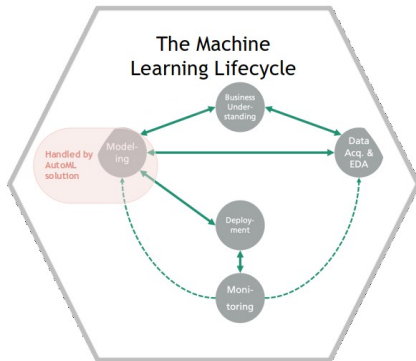


Learning goals

- Pipelines as connected steps of learnable operations
- Sequential pipeline
- Pipelines and DAGs

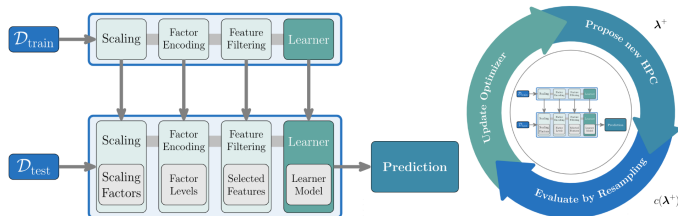
CASE FOR AUTOML

- More and more tasks are approached via data driven methods.
- Data scientists often rely on trial-and-error.
- The process is especially tedious for similar, recurring tasks.
- Not the entire machine learning lifecycle can be automated.



PIPELINES AND AUTOML

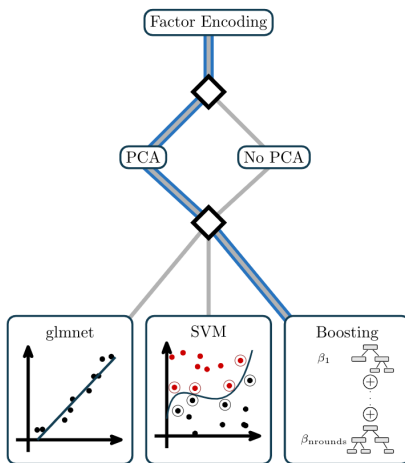
- ML typically has several data transformation steps before model fit
- If steps are in succession, data flows through sequential pipeline
- NB: Each node has a train and predict step and learns params
- And usually has HPs



Pipelines are required to embed full model building into CV to avoid overfitting and biased evaluation!

PIPELINES AND AUTOML

- Further flexibility by representing pipeline as DAG
- Single source accepts $\mathcal{D}_{\text{train}}$, single sink returns predictions
- Each node represents a preprocessing operation, a learner, a postprocessing operation or controls data flow
- Can be used to implement ensembles, operator selection, ...



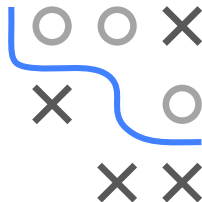
PIPELINES AND AUTOML

- HPs of pipeline are the joint set of all HPs of its contained nodes:

$$\tilde{\Lambda} = \tilde{\Lambda}_{\text{op},1} \times \cdots \times \tilde{\Lambda}_{\text{op},k} \times \tilde{\Lambda}_{\mathcal{I}}$$

- HP space of a DAG is more complex:
Depending on branching / selection
different nodes and HPs are active
→ **hierarchical search space**

| Search Space $\tilde{\Lambda}$ | | | |
|--------------------------------|------|-----------------------|--------|
| Name | Type | Bounds/Values | Trafo |
| encoding | C | one-hot, impact | |
| ◇ pca | C | PCA, no PCA | |
| ◇ learner | C | glmnet, SVM, Boosting | |
| if learner = glmnet | | | |
| s | R | $[-12, 12]$ | 2^x |
| alpha | R | $[0, 1]$ | – |
| if learner = SVM | | | |
| cost | R | $[-12, 12]$ | 2^x |
| gamma | R | $[-12, 12]$ | 2^x |
| if learner = Boosting | | | |
| eta | R | $[-4, 0]$ | 10^x |
| nrounds | I | $\{1, \dots, 5000\}$ | – |
| max_depth | I | $\{1, \dots, 20\}$ | – |



A graph that includes many preprocessing steps and learner types can be flexible enough to work on a large number of data sets

Combining such graph with an efficient tuner is key in AutoML

AUTOML – CHALLENGES

- Most efficient approach?
- How to integrate human a-priori knowledge?
- How can we best (computationally) transfer “experience” into AutoML? Warmstarts, learned search spaces, etc.
- Multi-Objective goals, including model interpretability
- AutoML as a process is too much of a black-box, hurts adoption.

