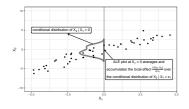
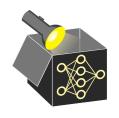
# **Interpretable Machine Learning**

# Accumulated Local Effect (ALE) plot





- PD plots and its extrapolation issue
- M plots and its omitted-variable bias
- Understand ALE plots



# ACCUMULATED LOCAL EFFECTS (ALE) Apley, Zhu (2020)

ALE plots use the idea of integrating partial derivatives. They do not suffer from the extrapolation issue of PD plots and the OVB issue of M plots when features are dependent.

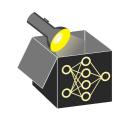


#### Concept of ALE plots is based on

• estimating local effects  $\frac{\partial \hat{f}(x_s, \mathbf{x}_{-s})}{\partial x_s}$  (via finite differences) evaluated at certain points  $(x_S = z_S, \mathbf{x}_{-S})$ 

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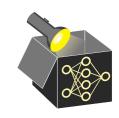


#### Concept of ALE plots is based on

- estimating local effects  $\frac{\partial \hat{t}(x_S, \mathbf{x}_{-S})}{\partial x_C}$  (via finite differences) evaluated at certain points  $(x_S = z_S, \mathbf{x}_{-S})$
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- **3** integrating averaged local effects up to a specific value  $x \sim \mathbb{P}(x_S)$ 
  - $\Rightarrow$  Accumulates local effects to estimate global main effect of  $x_S$
  - ⇒ Avoids OVB issue as other unwanted main effects were removed in (1)

#### FIRST ORDER ALE

- Let  $x_S$  be feature of interest with  $z_0 = \min(x_S)$  and  $\mathbf{x}_{-S}$  all other features (complement of S)
- Uncentered first order ALE  $\tilde{f}_{S,ALE}(x)$  at feature value  $x \sim \mathbb{P}(x_S)$  is defined as:

$$\tilde{f}_{S,ALE}(x) = \underbrace{\int_{z_0}^{x} \underbrace{\mathbb{E}_{\mathbf{x}_{-S}|x_S}}_{(2)} \left( \underbrace{\frac{\partial \hat{f}(x_S, \mathbf{x}_{-S})}{\partial x_S}}_{(1)} \middle| x_S = z_S \right) dz_S}_{(3)}$$



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 Subtract average of uncentered ALE curve (constant) to obtain centered ALE curve f<sub>S,ALE</sub>(x) with zero mean regarding marginal distribution of feature of interest x<sub>S</sub>:

$$f_{S,ALE}(x) = \tilde{f}_{S,ALE}(x) - \underbrace{\int_{-\infty}^{\infty} \tilde{f}_{S,ALE}(x_S) d\mathbb{P}(x_S)}_{:=constant}$$

#### **ALE ESTIMATION**

- Partial derivatives not useful for all models (e.g., tree-based methods)
- ullet Approximate them by finite differences of predictions within K intervals for  $\mathbf{x}_S$ :

 $\bullet$  Create K intervals for feature  $\mathbf{x}_S$ , e.g., using quantiles as interval bounds

$$x \in [\min(\mathbf{x}_{S}), \max(\mathbf{x}_{S})] \iff x \in [z_{0,S}, z_{1,S}]$$

$$\forall x \in ]z_{1,S}, z_{2,S}]$$

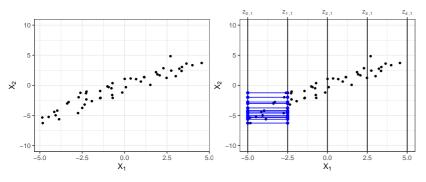
$$\dots$$

$$\forall x \in ]z_{K-1,S}, z_{K,S}]$$





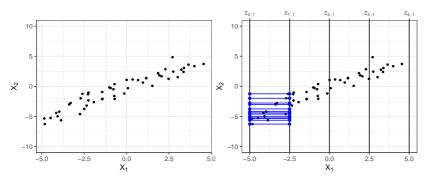
#### 2-D ILLUSTRATION

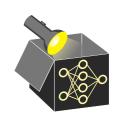




- Divide feature of interest into intervals (vertical lines)
- For all points within an interval, compute prediction difference when we replace feature value with upper/lower interval bound (blue points) while keeping other feature values unchanged
- These finite differences (approximate local effect) are accumulated & centered
   ⇒ ALE plot

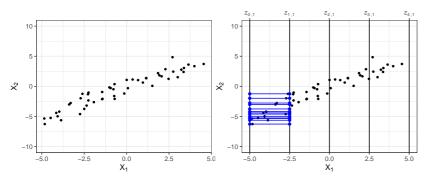
#### 2-D ILLUSTRATION





- For  $\mathbf{x}^{(i)} = (x_S^{(i)}, \mathbf{x}_{-S}^{(i)})$ , value  $x_S^{(i)}$  is located within k-th interval of  $\mathbf{x}_S$   $(x_S^{(i)} \in ]z_{k-1,S}, z_{k,S}]$ )
- ullet Replace  $x_{S}^{(i)}$  by upper/lower interval bound while all other feature values  $\mathbf{x}_{-S}^{(i)}$  are kept constant
- ullet Finite differences correspond to  $\hat{f}(z_{k,S},\mathbf{x}_{-S}^{(i)}) \hat{f}(z_{k-1,S},\mathbf{x}_{-S}^{(i)})$

#### 2-D ILLUSTRATION





- Estimate local effect of  $\mathbf{x}_S$  within each interval by averaging all observation-wise finite differences  $\hat{=}$  Approximation of inner integral that integrates over local effects w.r.t.  $\mathbb{P}(\mathbf{x}_{-S}|z_S)$ .

### **ALE ESTIMATION: FORMULA**

• Estimated uncentered first order ALE  $\hat{\tilde{f}}_{S,ALE}(x)$  at point x:

$$\hat{\tilde{f}}_{S,ALE}(x) = \sum_{k=1}^{k_S(x)} \frac{1}{n_S(k)} \sum_{i: \ x_S^{(i)} \in \ ]z_{k-1,S}, z_{k,S}]} \left[ \hat{f}(z_{k,S}, \mathbf{x}_{-S}^{(i)}) - \hat{f}(z_{k-1,S}, \mathbf{x}_{-S}^{(i)}) \right]$$



- $k_S(x)$  denotes the interval index a feature value  $x \in \mathbf{x}_S$  falls in
- $n_S(k)$  denotes the number of observations inside the k-th interval of  $\mathbf{x}_S$
- Subtract average of estimated uncentered ALE to obtain centered ALE estimate:

$$\hat{f}_{S,ALE}(x) = \hat{f}_{S,ALE}(x) - \frac{1}{n} \sum_{i=1}^{n} \hat{f}_{S,ALE}(x_S^{(i)})$$

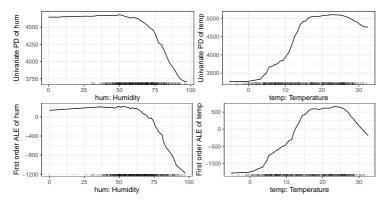
## **ALE ESTIMATION: ALGORITHM**

- Create K intervals for value range of  $\mathbf{x}_S$
- 2 Repeat for each interval:
  - Replace observation's feature value  $x_S^{(i)}$  with upper/lower interval bound for each observation inside k-th interval
  - Compute observation-wise finite difference inside k-th interval and average them to estimate interval-wise local effects
- Accumulate interval-wise local effects up to value of interest x to estimate uncentered ALE and then center it



### **BIKE SHARING DATASET: FIRST ORDER ALE**

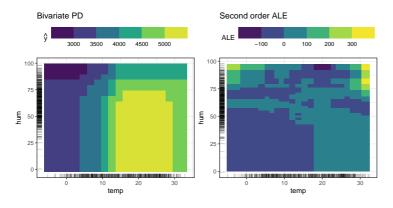
Shape of PD plot (left) often looks similar to (centered) first order ALE plot (right) but on different *y*-axis scale. In case of correlated features, ALE might be better due to PD's extrapolation issue.





### **BIKE SHARING DATASET: SECOND ORDER ALE**

Unlike bivariate PD plots, 2nd-order ALE plots only estimate pure interaction between two features (1st-order effects are not included).





# PD VS. ALE

PD:

$$f_{\mathcal{S},PD}(x_{\mathcal{S}}) = \mathbb{E}_{\mathbf{x}_{-\mathcal{S}}}\left(\hat{f}(x_{\mathcal{S}},\mathbf{x}_{-\mathcal{S}})\right)$$

ALE:

$$f_{S,ALE}(x) = \int_{z_0}^{x} \mathbb{E}_{\mathbf{x}_{-S}|\mathbf{x}_{S}} \left( \frac{\partial \hat{f}(x_{S}, \mathbf{x}_{-S})}{\partial x_{S}} \middle| x_{S} = z_{S} \right) dz_{S} - const$$



- ullet Recall: PD directly averages predictions over marginal distribution of  ${f x}_{-S}$
- Difference 1: ALE averages the
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   → isolates effect of feature S and removes main effect of other dependent features

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- Difference 3: ALE is centered so that  $\mathbb{E}_{x_S}(f_{S,ALE}(x)) = 0$