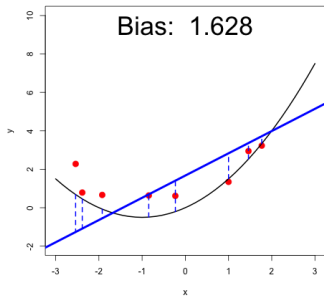


Introduction to Machine Learning

Advanced Risk Minimization

Bias-Variance Decomposition (Deep-Dive)



Learning goals

- Understand how to decompose the generalization error of a learner into
 - Bias of the learner
 - Variance of the learner
 - Inherent noise in the data

BIAS-VARIANCE DECOMPOSITION

Let us take a closer look at the generalization error of a learning algorithm \mathcal{I}_L . This is the expected error of an induced model $\hat{f}_{\mathcal{D}_n}$, on training sets of size n , when applied to a fresh, random test observation.

$$GE_n(\mathcal{I}_L) = \mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_{xy}^n, (\mathbf{x}, y) \sim \mathbb{P}_{xy}} \left(L(y, \hat{f}_{\mathcal{D}_n}(\mathbf{x})) \right) = \mathbb{E}_{\mathcal{D}_n, xy} \left(L(y, \hat{f}_{\mathcal{D}_n}(\mathbf{x})) \right)$$

We therefore need to take the expectation over all training sets of size n , as well as the independent test observation.

We assume that the data is generated by

$$y = f_{\text{true}}(\mathbf{x}) + \epsilon,$$

with zero-mean homoskedastic error $\epsilon \sim (0, \sigma^2)$ independent of \mathbf{x} .



BIAS-VARIANCE DECOMPOSITION / 2

By plugging in the $L2$ loss $L(y, f(\mathbf{x})) = (y - f(\mathbf{x}))^2$ we get

$$\begin{aligned} GE_n(\mathcal{I}_L) &= \mathbb{E}_{\mathcal{D}_n, xy} \left(L \left(y, \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) \right) = \mathbb{E}_{\mathcal{D}_n, xy} \left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)^2 \right) \\ &\stackrel{\text{LIE}}{=} \underbrace{\mathbb{E}_{xy} \left[\mathbb{E}_{\mathcal{D}_n} \left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)^2 \mid \mathbf{x}, y \right) \right]}_{(*)} \end{aligned}$$

Let us consider the error $(*)$ conditioned on one fixed test observation (\mathbf{x}, y) first. (We omit the $|\mathbf{x}, y$ for better readability for now.)

$$\begin{aligned} (*) &= \mathbb{E}_{\mathcal{D}_n} \left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)^2 \right) \\ &= \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(y^2 \right)}_{=y^2} + \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})^2 \right)}_{(1)} - 2 \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(y \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)}_{(2)} \end{aligned}$$

by using the linearity of the expectation.



BIAS-VARIANCE DECOMPOSITION / 3

$$(*) = \mathbb{E}_{\mathcal{D}_n} \left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)^2 \right) = y^2 + \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})^2 \right)}_{(1)} - 2 \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(y \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)}_{(2)} =$$

Using that $\mathbb{E}(z^2) = \text{Var}(z) + \mathbb{E}^2(z)$, we see that

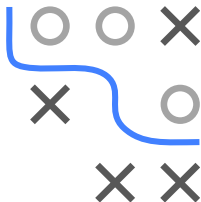
$$= y^2 + \text{Var}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) + \mathbb{E}_{\mathcal{D}_n}^2 \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) - 2y \mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)$$

Plug in the definition of y

$$= f_{\text{true}}(\mathbf{x})^2 + 2\epsilon f_{\text{true}}(\mathbf{x}) + \epsilon^2 + \text{Var}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) + \mathbb{E}_{\mathcal{D}_n}^2 \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) - 2(f_{\text{true}}(\mathbf{x}) + \epsilon) \mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)$$

Reorder terms and use the binomial formula

$$= \epsilon^2 + \text{Var}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) + \left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) \right)^2 + 2\epsilon \left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right) \right)$$



BIAS-VARIANCE DECOMPOSITION / 4

$$(*) = \epsilon^2 + \text{Var}_{\mathcal{D}_n}(\hat{f}_{\mathcal{D}_n}(\mathbf{x})) + \left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}(\hat{f}_{\mathcal{D}_n}(\mathbf{x}))\right)^2 + 2\epsilon \left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}(\hat{f}_{\mathcal{D}_n}(\mathbf{x}))\right)$$

Let us come back to the generalization error by taking the expectation over all fresh test observations $(\mathbf{x}, y) \sim \mathbb{P}_{xy}$:

$$\begin{aligned} GE_n(\mathcal{I}_L) &= \underbrace{\sigma^2}_{\text{Variance of the data}} + \underbrace{\mathbb{E}_{xy} \left[\text{Var}_{\mathcal{D}_n}(\hat{f}_{\mathcal{D}_n}(\mathbf{x}) \mid \mathbf{x}, y) \right]}_{\text{Variance of learner at } (\mathbf{x}, y)} \\ &+ \underbrace{\mathbb{E}_{xy} \left[\left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}(\hat{f}_{\mathcal{D}_n}(\mathbf{x})) \right)^2 \mid \mathbf{x}, y \right]}_{\text{Squared bias of learner at } (\mathbf{x}, y)} + \underbrace{0}_{\text{As } \epsilon \text{ is zero-mean and independent}} \end{aligned}$$

