

SUDONG LEE

[Google Scholar](#) ◇ [LinkedIn](#)

ORCID: [0000-0002-8928-6070](#)

EDUCATION

Ph.D. student in Robotics, Control, and Intelligent Systems (EDRS) <i>EPFL (Swiss Federal Institute of Technology in Lausanne)</i> <i>Advisor: Prof. Josie Hughes</i>	2023.04. - present <i>Lausanne, Switzerland.</i>
M.S. in Mechanical Engineering <i>Seoul National University</i> <i>Advisor: Prof. Yong-Lae Park</i> <i>Thesis: Modularized Robotic Skin Sensorized by Fiber Optic Force Sensing for Remote and Autonomous Robot Operation [Link]</i>	2019.03. - 2021.08. <i>Seoul, Korea.</i>
B.S. in Mechanical Engineering <i>Korea University</i>	2013.03. - 2019.02. <i>Seoul, Korea.</i>

RESEARCH EXPERIENCE

Computational Robot Design & Fabrication Laboratory (CREATE Lab) - <i>EPFL (École Polytechnique Fédérale de Lausanne)</i> Assistant-doctorant	<i>Lausanne, Switzerland.</i> 2023.04. - present
Soft Robotics Research Center (SRRC) - <i>Seoul National University</i> Research Associate Research Assistant Research topics: <ul style="list-style-type: none">· Fiber Jamming Actuator driven by Tendons to Enhance Adaptability· Robotic Skin using 3-DoFs Force Sensor for Dexterous and Safe Interaction	<i>Seoul, Korea.</i> 2022.09. - 2023.03. 2021.09. - 2022.08.
Soft Robotics and Bionics Laboratory (SRBL) - <i>Mechanical Engineering, Seoul National University</i> Graduate Student Researcher Research topics: <ul style="list-style-type: none">· Robotic Skin Sensorized by Fiber Optic Strain Sensors· Multi-modal Locomotion and Environmental Adaptability of Legged Robots· Soft Electronics and Sensors using Stretchable Materials and Sensing Mechanisms	<i>Seoul, Korea.</i> 2019.01. - 2021.08.

HONORS AND AWARDS

M.S. Thesis Presentation Award Mechanical Engineering, Seoul National University	2021.06.
Third Place Award for Locomotion Challenge IEEE International Conference on Soft Robotics 2019 (RoboSoft 2019) Team SRBL (Sudong Lee, G. Shin, J. Kim, M. Choi, Y. Baek, and Y.-L. Park)	2019.04.
Great Honor, Winter 2018 Graduation Korea University	2019. 02.
Semester High Honors Korea University	1 st Semester, 2013., 2 nd Semester, 2013., 1 st Semester, 2014., 2 nd Semester, 2014., 1 st Semester, 2015.,

SCHOLARSHIPS

Kwanjeong Fellowship
Kwanjeong Educational Foundation

1st Semester, 2019.,
2nd Semester, 2019.,
1st Semester, 2020.,
2nd Semester, 2020.

National Science and Engineering Scholarship
Korea Student Aid Foundation

1st Semester, 2015.,
2nd Semester, 2017.,
1st Semester, 2018.,
2nd Semester, 2018.

Academic Excellence Scholarship
Korea University

2nd Semester, 2014.

Best Honor Scholarship
Korea University

1st Semester, 2014.

PUBLICATIONS

Journal Papers

1. T. Kim, **Sudong Lee**, T. Hong, G. Shin, T. Kim, and Y.-L. Park, "Heterogeneous Sensing in a Multifunctional Soft Sensor for Human-Robot Interfaces," *Science Robotics*, Vol. 5, No. 49, eabc6878, 2020. (DOI: [10.1126/scirobotics.abc6878](https://doi.org/10.1126/scirobotics.abc6878))
2. G. Shin*, **Sudong Lee***, and Y.-L. Park, "Selective Patterning of Conductive Elastomers Embedded with Silver Powders and Carbon Nanotubes for Stretchable Electronics," *IEEE Robotics and Automation Letters*, vol. 7, no. 2, pp. 4983-4990, 2022. (DOI: [10.1109/LRA.2022.3153707](https://doi.org/10.1109/LRA.2022.3153707))
*: **These authors contributed equally to this work.**
3. Y. Lee, S. Lim, W. J. Song, **Sudong Lee**, S. J. Yoon, J.-M. Park, M.-G. Lee, Y.-L. Park, and J.-Y. Sun, "Triboresistive Touch Sensing: Grid-Free Touch Point Recognition Based on Monolayered Ionic Power Generators," *Advanced Materials*, vol. 34, no. 19, 2108586, 2022. (DOI: [10.1002/adma.202108586](https://doi.org/10.1002/adma.202108586))
4. T. Kim*, **Sudong Lee***, S. Chang, S. Hwang, and Y.-L. Park, "Environmental Adaptability of Legged Robots with Cutaneous Inflation and Sensation," *Advanced Intelligent Systems*, 2300172, 2023. (DOI: [10.1002/aisy.202300172](https://doi.org/10.1002/aisy.202300172))
*: **These authors contributed equally to this work.**
5. J. Kang*, **Sudong Lee***, and Y.-L. Park, "Soft Bending Actuator with Fiber-Jamming Variable Stiffness and Fiber-Optic Proprioception," *IEEE Robotics and Automation Letters*, 2023. (DOI: [10.1109/LRA.2023.3316075](https://doi.org/10.1109/LRA.2023.3316075))
*: **These authors contributed equally to this work.**
6. **Sudong Lee***, J. I. Kim*, Y. Baek, D. Chang, J. Lee, Y. S. Park, D. Lee, and Y.-L. Park, "Modularized Robotic Skin Sensorized by Fiber Optic Force Sensing for Remote and Autonomous Robot Operation." (Under review, Submitted to *IEEE Transactions on Robotics*.)
*: **These authors contributed equally to this work.**
7. D. Kim, **Sudong Lee**, T. H. Hong, and Y.-L. Park, "Robust Online Model Identification for Versatile Robot Control Based on Self-Attention Learning." (Under review, Submitted to *npj Robotics*.)

Conference Papers and Posters

1. G. Shin*, **Sudong Lee***, and Y.-L. Park, "Selective Patterning of Conductive Elastomers Embedded with Silver Powders and Carbon Nanotubes for Stretchable Electronics," *IEEE International Conference on Soft Robotics 2022 (Robosoft 2022)*.
*: **These authors contributed equally to this work.**

2. S. Koh*, **Sudong Lee***, and Y.-L. Park, "Multi-Functional Tactile Sensors using a Hybrid Structure of Soft and Rigid Layers for Adaptable Interactions of Robots," (*Submitted to IEEE International Conference on Robotics and Automation 2024 (ICRA 2024)*).

***: These authors contributed equally to this work.**

PATENTS

1. J. I. Kim, **Sudong Lee**, Y. Baek, and Y.-L. Park, "Modularized Robotic Skin," 2020.
(Korea Appl. No.: 1,020,200,148,802)
2. T. Kim, **Sudong Lee**, and Y.-L. Park, "Soft Sensor with Multi-Sensing Function," 2022.
(Korea Patent: 102,384,623)

TEACHING EXPERIENCE

M2794.001700_001: Mechanical Product Design
- Mechanical Engineering, Seoul National University
Teaching assistant, Instructor: Prof. Yong-Lae Park.

1st Semester, 2019.

ACADEMIC SERVICE

Reviewer - Journal Papers
IEEE Robotics and Automation Letters (RA-L)
Soft Robotics

Reviewer - Conference Paper
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

TECHNICAL STRENGTHS (SKILLS)

Programming Languages	C++, Python, Matlab
Embedded System	Arduino, AVR ATmega, Single-Board Computer (SBC)
Software for System and Robots	ROS, Pybullet
Machine Learning	Pytorch, TensorFlow
Design and Simulation	3D Computer-Aided Design (CAD), Finite Element Analysis (FEA) Software
Fabrication	3D Printing (Additive Manufacturing), Silicone Fabrication

OTHER EXPERIENCE

Republic of Korea Air Force (ROKAF, Military Service)
Staff Sergeant, Honorable discharge.

2015.08. - 2017.08.