

# VV285 RC Final

## Final Exam Exercises

Last but not least...

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# Exercise 1

Calculate the directional derivative of the continuous function

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad f(x, y) = \sqrt[3]{x^2 y}$$

at  $(x, y) = (0, 0)$  in the direction of the vector  $h = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ .

# Solution 1

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From the definition , we need to calculate

$$\frac{d}{dt} f(x_0 + th)|_{t=0}$$

where  $x_0 = 0$  and  $h = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ .

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where  $x_0 = 0$  and  $h = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ . Hence, we have

$$f(x_0 + th) = f\left(t \cdot \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix}\right) = \sqrt[3]{\frac{t^2}{2} \cdot \frac{t}{\sqrt{2}}} = \frac{t}{\sqrt{2}}$$

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so that

$$\frac{d}{dt} f(x_0 + th) = \frac{d}{dt} \frac{t}{\sqrt{2}} = \frac{1}{\sqrt{2}}.$$



## Exercise 2

Let  $g : (0, \infty) \rightarrow \mathbb{R}$  be a differentiable function and let  $\|x\| = \sqrt{x_1^2 + x_2^2 + x_3^2}$  for  $x = (x_1, x_2, x_3) \in \mathbb{R}^3$ .

Prove that the vector field

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The set  $\mathbb{R}^3 \setminus \{0\}$  is simply connected, so it suffices to show that  $\text{rot}F = 0$ . Now

$$|(\text{rot}F)_i| = \left| \frac{\partial F_j}{\partial x_k} - \frac{\partial F_k}{\partial x_j} \right|$$

where  $(i, j, k)$  is any one of the permutation of  $\{1, 2, 3\}$ .

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Hence, the rotation of  $F$  vanishes everywhere on  $\mathbb{R}^3 \setminus \{0\}$ .



# Exercise 3

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through the surface

$$\mathcal{S} = \{x \in \mathbb{R}^3 : 4x_1^2 + 9x_2^2 + 6x_3^2 = 36\}$$

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where  $0 < \phi < 2\pi$  and  $0 < \theta < \pi$ . We have chosen the outward-pointing (positively oriented) normal vector.



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$$\begin{aligned} \int_{\partial B_\epsilon(0)} \langle F, d\vec{A} \rangle &= \int_0^{2\pi} \int_0^\pi \underbrace{\frac{1}{\|\varphi(\phi, \theta)^3\|}}_{=1/\epsilon^3} \langle \varphi(\phi, \theta), t_\phi \times t_\theta(\phi, \theta) \rangle d\theta d\phi \\ &= \int_0^{2\pi} \int_0^\pi \frac{\epsilon^3}{\epsilon^3} \left\langle \begin{pmatrix} \cos \phi \sin \theta \\ \sin \phi \sin \theta \\ \cos \theta \end{pmatrix}, \begin{pmatrix} \cos \phi \sin^2 \theta \\ \sin \phi \sin^2 \theta \\ \cos \theta \sin \theta \end{pmatrix} \right\rangle d\theta d\phi \\ &= \int_0^{2\pi} \int_0^\pi \sin \theta d\theta d\phi = 4\pi \end{aligned}$$



# Exercise 4

Let  $\Omega \subset \mathbb{R}^n$  be an open set and  $R \subset \Omega$  an admissible region. Let  $u : \Omega \rightarrow \mathbb{R}$  be a twice continuously differentiable function such that

$$\frac{\partial^2 u}{\partial x_1^2} + \cdots + \frac{\partial^2 u}{\partial x_n^2} = \lambda u \text{ on } \text{int}R \quad \text{and} \quad u|_{\partial R} = 0$$

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# Solution 4



Applying Green's first identity

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$$\lambda < 0.$$

