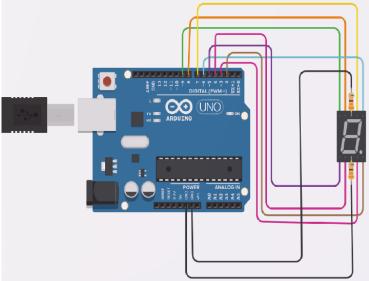
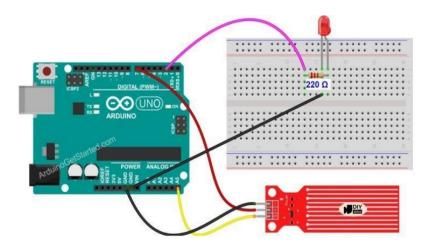


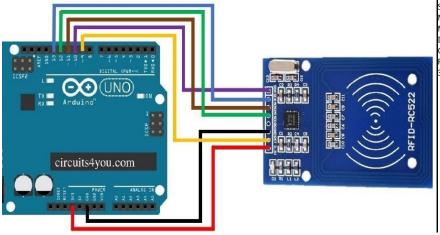
- ➤ G is connected to Pin 9
- > Fis connected to Pin 8
- > A is connected to Pin 7
- > B is connected to Pin 6
- > E is connected to Pin 5
- D is connected to Pin 4
- > C is connected to Pin 3
- > DP is connected to Pin 2
- > Centre Pins (COM) are Connected to GND.



```
void setup()
 pinMode(2, OUTPUT);
 pinMode(3, OUTPUT);
 pinMode(4, OUTPUT);
 pinMode(5, OUTPUT);
 pinMode(6, OUTPUT);
 pinMode(7, OUTPUT);
 pinMode(8, OUTPUT);
 pinMode(9, OUTPUT);
void loop()
 // to display ZERO
 digitalWrite(2, LOW);
 digitalWrite(3, HIGH);
 digitalWrite(4, HIGH);
 digitalWrite(5, HIGH);
 digitalWrite(6, HIGH);
 digitalWrite(7, HIGH);
 digitalWrite(8, HIGH);
 digitalWrite(9, LOW);
 delay(1000); // Wait for 1000 millisecond(s)
}
```



```
#define LED_PIN 2
#define water_sensor 7
#define SIGNAL_PIN A5
#define THRESHOLD 300
int value = 0;
void setup() {
 Serial.begin(9600);
 pinMode(LED_PIN, OUTPUT);
 pinMode(water_sensor, INPUT);
 pinMode(SIGNAL_PIN, INPUT);
 digitalWrite(LED_PIN, LOW);
}
void loop() {
 value = analogRead(SIGNAL_PIN);
 Serial.print("The water level is: ");
 Serial.println(value);
 if (value > THRESHOLD) {
  Serial.println("Water is detected");
  digitalWrite(LED_PIN, HIGH);
 } else {
  digitalWrite(LED_PIN, LOW);
 delay(1000);
```



SDA pin is connected to digital pin 10 of Arduino Uno SCK pin is connected to digital pin 13 of Arduino Uno MOSI pin is connected to digital pin 11 of Arduino Uno MISO pin is connected to digital pin 12 of Arduino Uno IRQ

GND is connected to GND of Arduino Uno RST is connected to digital pin 9 of Arduino Uno 3.3 V is connected to 3.3 Volts of Arduino Uno

```
#define RST_PIN 9
#define SS_PIN 10
MFRC522 mfrc522(SS_PIN, RST_PIN);
void setup() {
 Serial.begin(9600);
while (!Serial);
 SPI.begin();
 mfrc522.PCD_Init();
 delay(4);
 mfrc522.PCD_DumpVersionToSerial();
 Serial.println(F("Scan PICC to see UID, SAK, type, and data blocks"));
void loop() {
 if (!mfrc522.PICC_IsNewCardPresent()) {
  return;
 if (!mfrc522.PICC_ReadCardSerial()) {
  return;
 mfrc522.PICC\_DumpToSerial(\&(mfrc522.uid));
const int trigPin = 7;
const int echoPin = 8;
void setup() {
Serial.begin(9600);
pinMode(trigPin,OUTPUT);
pinMode(echoPin,INPUT);
void loop() {
long duration, inches, cm;
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
inches = microsecondsToInches(duration);
cm = microsecondsToCentimeters(duration);
// The data has to be fed in this format so that it will be stored in MySQL
Serial.print("{\"inches\":");
Serial.print(inches);
// The data has to be fed in this format so that it will be stored in MySQL
Serial.print(",\"cm\":");.
Serial.print(cm);
Serial.println("}")
delay(1000);
long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
var\ value = JSON.parse(JSON.stringify(msg.payload)); //converting\ string\ to
// JSON object
value = msg;
var sensor1 = msg.payload.inches; //adding value to the payload var sensor2 = msg.payload.cm; //adding value to the payload msg.payload = [sensor1, sensor2]; //adding value to the payload
msg.topic = 'INSERT INTO distance(inches,cm) values (?,?);'; //query to insert
return msg;
```