2016 EE214B Design Project - Part I

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1 Bias Calculations

1.1 Node Definitions

$$V_{C1} = V_{E2} = V_W$$

 $V_{B3} = V_{C2} = V_{B4} = V_X$
 $V_{E3} = V_Y$
 $V_{E4} = V_Z$
 $V_{B1} = V_{IN}$

1.2 Node Voltages and Device Currents

$$V_{IN} = V_{BE} = 0.8V \tag{1}$$

$$V_{B2} = 1.6V = V_W = 1.6 - V_{BE} = 0.8V$$
 (2)

Assuming Ib = 0

$$V_{IN} = V_Y = > V_Y = 0.8V$$
 (3)

$$V_X = V_Y + V_{BE} = V_X = 1.6V$$
 (4)

$$V_Z = V_X - V_{BE} = V_Z = 0.8V (5)$$

$$V_O = V_{CC} - IB4R_{C4} = V_O = 2.3V$$
 (6)

$$I_{C1} = I_{C2} = \frac{V_{CC} - V_{B3}}{R_{C2}} = 3.6mA \tag{7}$$

$$I_{C3} = I_{Bias3} = 4.5mA$$
 (8)

$$I_{C4} = I_{Bias4} = 2.0mA$$
 (9)

Parameter	Hand Calc	Spice Value	Percent Error%
V_{IN}	0.800V	0.801V	-0.12%
V_W	0.800V	0.798V	0.25%
V_X	1.600V	1.605V	-0.31%
V_Y	0.800V	0.804V	-0.49%
V_Z	0.800V	0.813V	-1.50%
V_O	2.300V	2.301V	-0.04%
gm_1	120.7mS	$120.7 \mathrm{mS}$	-0.03%
gm_2	120.3mS	120.3mS	-0.03%
gm_3	$152.3 \mathrm{mS}$	$152.3 \mathrm{mS}$	0.02%
gm_4	$70 \mathrm{mS}$	$70 \mathrm{mS}$	-0.04%
$r\pi_1$	$2.14 \mathrm{k}\Omega$	$1.875 \mathrm{k}\Omega$	14.3%
$r\pi_2$	$2.14 \mathrm{k}\Omega$	$1.883 \mathrm{k}\Omega$	13.64%
$r\pi_3$	$1.71 \mathrm{k}\Omega$	$1.502 \mathrm{k}\Omega$	13.84%
$r\pi_4$	$3.85 \mathrm{k}\Omega$	$3.515 \mathrm{k}\Omega$	9.5%

2 Calculations and plots for part I (c) through (f)

After applying two-port analysis for loop gain calculation:

$$a = (r_{\pi 1}||R_F) \cdot (-gm_1R_{C2}) \cdot \frac{gm_3R_F}{1 + gm_3R_F} = -5.486k\Omega$$
 (10)

$$f = \frac{-1}{R_E} = -4.5mS \tag{11}$$

$$t = af = 26.57 = 28.48dB \tag{12}$$

Mid-band transresistance of the overall amplifier:

$$A_{CL,MidBiand} = \frac{a}{1+t} \cdot \frac{-gm_4R_{C4}}{1+gm_4R_{E4}} = 724 = 57.2dB \tag{13}$$

Calculating node resistances and capacitances:

$$C_X = C_{\mu 2} + \frac{C_{\pi 3}}{1 + q m_3 R_F} + \frac{C_{\pi 4}}{1 + q m_4 R_{E4}} + C_{\mu 3} + C_{\mu 4} (1 + g m_4 R_{C4}) = 99 fF$$
(14)

$$R_X = R_{C2} ||r_{\pi 3}(1 + gm_3 R_F)||r_{\pi 4}(1 + gm_4 R_{E4}) = 241\Omega \approx R_{C2}$$
(15)

$$C_{IN} = C_D + C_{\pi 1} + C_{\mu 1} = 324fF \tag{16}$$

$$R_{IN} = r_{\pi 1} || R_F = 199\Omega \approx R_F \tag{17}$$

Calculation of most significant poles:

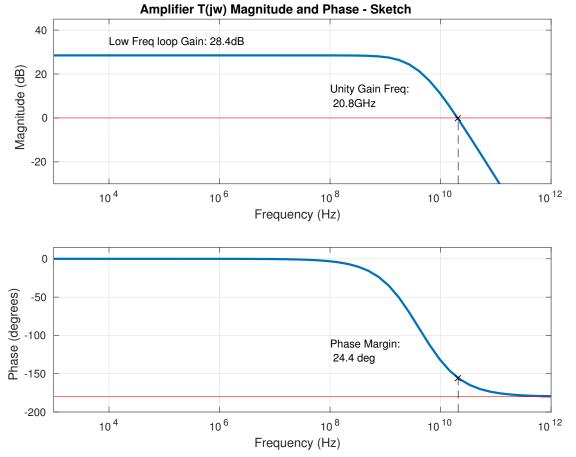
$$f_{IN} = \frac{1}{2\pi R_{IN} C_{IN}} = 2.46 GHz \tag{18}$$

$$f_X = \frac{1}{2\pi R_Y C_Y} = 6.63GHz \tag{19}$$

Calculation of $T(j\omega)$ Unity Gain Frequency and Phase Margin

$$f_u = \sqrt{T_0 * f_{IN} * f_X} = 20.8GHz \tag{20}$$

$$PM = 180^{\circ} - atan(\frac{f_u}{f_{IN}}) - atan(\frac{f_u}{f_X}) = 24.4^{\circ}$$
(21)



The low value of phase margin suggests that significant peaking will be observed.

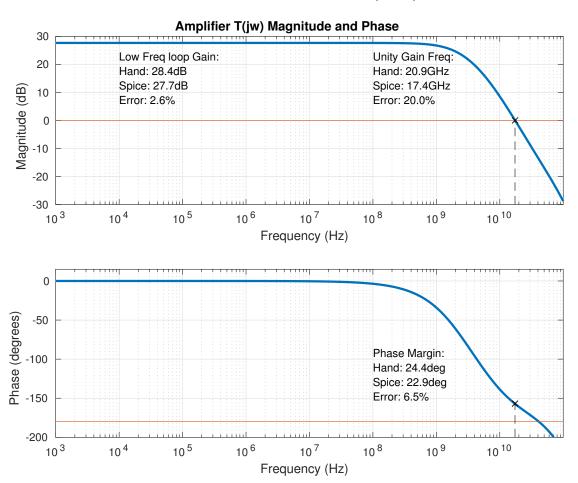
$$a(s) = (R_{IN}||\frac{1}{sC_{IN}}) \cdot gm_1 \cdot (R_X||\frac{1}{sC_X}) \cdot \frac{gm_3R_f}{1 + gm_3R_F}$$
(22)

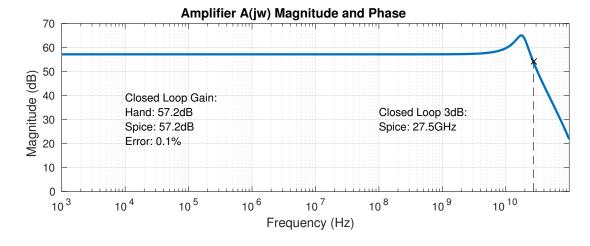
$$\frac{v_{E3}}{i_s} = \frac{a(s)}{1 + a(s)f} \tag{23}$$

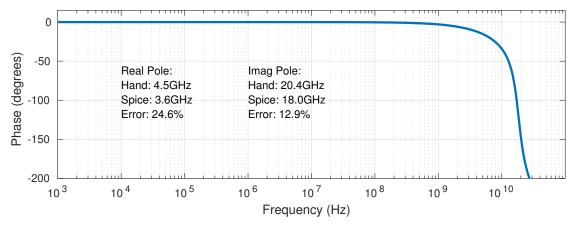
$$f_0 = \sqrt{(1+T_0) * f_{IN} * f_X} \approx f_u$$
 (24)

$$Q = \frac{\sqrt{(1+T_0)\omega_X\omega_{IN}}}{\omega_X + \omega_{IN}} = 2.29 \tag{25}$$

3 Bode Plots and PZ Outputs - Part I(g,h)







***** pole/zero analysis					
input = 0:is	output =	v(vo)			
<pre>poles (rad/sec)</pre>	poles (hertz)				
real	imag	real	imag		
-33.1562m	0.	-5.27698m	0.		
-22.9305g	113.319g	-3.64950g	18.0353g		
-22.9305g	-113.319g	-3.64950g	-18.0353g		
-473.782g	0.	-75.4048g	0.		
-1.12800t	0.	-179.526g	0.		
-1.18039t	0.	-187.865g	0.		
zeros (rad/sec)		zeros (hertz)			

zeros (rad/sec)		zeros (hertz)	
real	imag	real	imag
0.	0.	0.	0.
-1.10418t	0.	-175.736g	0.

4 Calculations for Part I(i)

A feedback capacitor can be used to introduce a zero into the feedback loop in order to push the higher frequency pole out and flatten the response of the closed loop amplifier. The optimally flat response of the amplifier occurs when $Q = \sqrt{2}$. Hence:

$$\omega_0 = 1.09e11rad/s \tag{26}$$

$$\omega_Z = \frac{\omega_0}{\sqrt{2} - \frac{\omega_{P1} + \omega_{P2}}{\omega_0}} \tag{27}$$

$$C_F = \frac{1}{\omega_Z R_F} = 37fF \tag{28}$$

From this, the new closed loop bandwidth can be calculated as such:

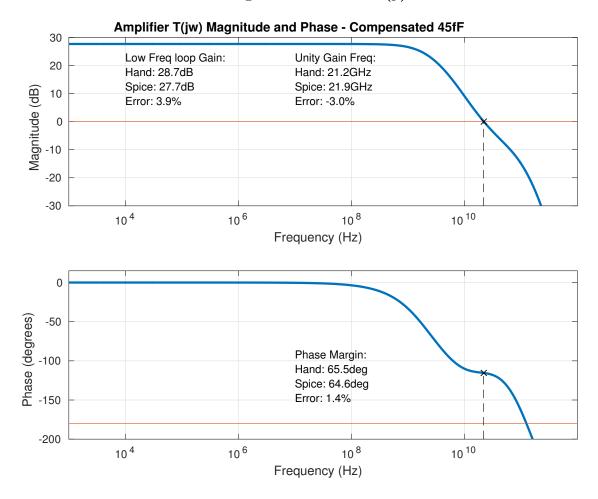
$$C_{in,C_F} = C_{in} + C_F \tag{29}$$

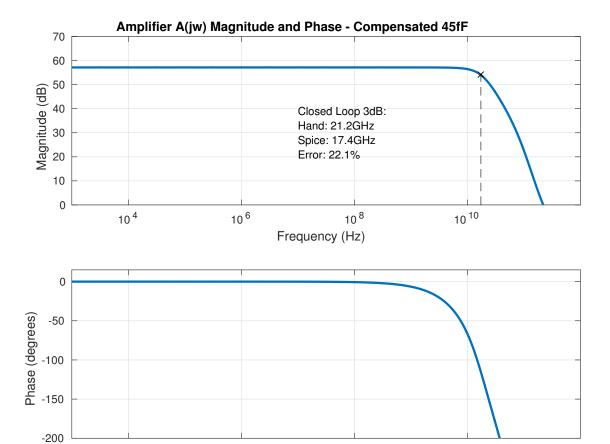
$$k = \frac{R_{in} * Q1_{gm} * R_x * A_{V3}}{R_F} \tag{30}$$

$$BW_{CL,C_F} = \frac{\sqrt{1+k}}{2\pi R_{in} C_{in} R_x C_x} = 19.2Ghz$$
 (31)

Value of C_F was tweaked from 37fF to 45fF in order to flatten the magnitude response. Approximately 0.1dB of peaking was observed in the response curve, and with 45fF it was completely flat.

5 Bode Plots and PZ Outputs - Part I(j)





10⁸

Frequency (Hz)

10 ¹⁰

10⁶

***** pole/zero analysis

104

poles (rad/sec)		poles (hertz)	
real	imag	real	imag
-33.1562m	0.	-5.27698m	0.
-86.5643g	75.6614g	-13.7771g	12.0419g
-86.5643g	-75.6614g	-13.7771g	-12.0419g
-385.396g	343.565g	-61.3377g	54.6800g
-385.396g	-343.565g	-61.3377g	-54.6800g
-1.11884t	0.	-178.069g	0.
-1.35144t	0.	-215.088g	0.
-1.90665t	0.	-303.452g	0.
zeros (rad/sec)		zeros (hertz)	
real	imag	real	imag
0.	0.	0.	0.
-1.09715t	0.	-174.617g	0.

6 Transient Response - Part I(m)

