Notes on Linear Systems

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We often face some linear algebra related problems in data science. Here are a collection of my notes.

1 General Cases

Usually, the problem will be reduced to solve a linear system:

$$Ax = b$$
, with $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$, (1)

where m is the number of linear equations and n is the number of variables. There are several cases:

- Case 1: A is full-ranked
 - Case 1.1: If A is square, then (1) has a unique solution $x = A^{-1}b$.
 - Case 1.2: If A is not square, then (1) is not solvable. Instead, we consider the least square problem

$$\hat{x} = \underset{x \in \mathbb{R}^n}{\arg \max} \|Ax - b\|_2. \tag{2}$$

In this case, the least square problem (2) has a unique solution and can be solved by solving the equivalent normal equation

$$A^T A \hat{x} = A^T b.$$

Since A is full-ranked, A^TA is invertible. So

$$\hat{x} = (A^T A)^{-1} A^T b.$$

• Case 2: A is not full-ranked. In this case, no matter A is square or not, we can find the solution to the least square problem by using the psudoinverse:

$$\hat{x} = A^+ b = \arg\max_{x \in \mathbb{R}^n} ||Ax - b||_2$$

where A^+ is defined using the SVD of A in the following way: If $A = U \begin{pmatrix} \Sigma_r & 0_{12} \\ 0_{21} & 0_{22} \end{pmatrix} V^T$, then $A^+ = V \begin{pmatrix} \Sigma_r^{-1} & 0_{21} \\ 0_{12} & 0_{22} \end{pmatrix} U^T$. Note that since A is not full-ranked, the least square problem have finite many solutions.