

BGN: 2191A

P6

Q8

- a. A stationary distribution is a probability distribution π over the possible values of a random variable X_t in a time series such that

$$\forall t \geq 0 \quad (X_t \sim \pi) \Rightarrow (X_{t+1} \sim \pi)$$

Let t arbitrary

Assume $E_t \sim \text{Normal}(0, \sigma^2)$

$$E_{t+1} = \lambda E_t + \text{Normal}(0, (1-\lambda^2)\sigma^2)$$

$$\therefore E_{t+1} \sim \lambda \text{Normal}(0, \sigma^2) + \text{Normal}(0, (1-\lambda^2)\sigma^2)$$

$$= \text{Normal}(0, (\lambda\sigma)^2) + \text{Normal}(0, (1-\lambda^2)\sigma^2)$$

$$= \text{Normal}(0+0, (\lambda\sigma)^2 + (1-\lambda^2)\sigma^2)$$

$$= \text{Normal}(0, (1-\lambda^2 + \lambda^2)\sigma^2)$$

$$= \text{Normal}(0, \sigma^2)$$

$$\sim E_t$$

b. "memorylessness" refers to the property that the distribution of E_{t+1} depends solely on the value of E_t , not any E_{t-i} for $i \geq 1$

$$\begin{aligned}
 \log(\text{lik}) &= \log \Pr(e_1, \dots, e_n | e_0) \\
 &= \log(\Pr(e_1 | e_0) \Pr(e_2 | e_1, e_0) \dots \Pr(e_n | e_{n-1}, \dots, e_0)) \\
 &= \log(\Pr(e_1 | e_0) \Pr(e_2 | e_1) \dots \Pr(e_n | e_{n-1})) \text{ by memorylessness} \\
 &= \sum_{i=1}^n \log \Pr(e_i | e_{i-1})
 \end{aligned}$$

c. $Y_{t+1} = \alpha + \beta \sin(2\pi\omega(t+1)) + \gamma(t+1) + E_{t+1}$

$$\begin{aligned}
 &= \alpha + \beta \sin(2\pi\omega(t+1)) + \gamma(t+1) + \lambda E_t + \text{Normal}(0, (1-\lambda^2)\sigma^2) \\
 &= \lambda\alpha - \lambda\alpha + \alpha + \beta \sin(2\pi\omega(t+1)) + \lambda\beta \sin(2\pi\omega t) - \lambda\beta \sin(2\pi\omega t) + \lambda\gamma t - \lambda\gamma t + \gamma(t+1) \\
 &\quad + \lambda E_t + \text{Normal}(0, (1-\lambda^2)\sigma^2) \\
 &= \lambda Y_t + \alpha(1-\lambda) + \beta(\sin(2\pi\omega(t+1)) - \lambda \sin(2\pi\omega t)) + \gamma(t+1 - \lambda t) + \text{Normal}(0, (1-\lambda^2)\sigma^2)
 \end{aligned}$$

$\therefore Y$ is memoryless

$$\begin{aligned}
 \therefore \log(\text{lik}) &= \log\left(\prod_{i=0}^t \Pr(y_{i+1} | y_i)\right) \\
 &= \sum_{i=0}^t \log \Pr(y_{i+1} | y_i)
 \end{aligned}$$

Q. A linear model is one in which the estimated vector is a linear combination of known feature vectors, with the parameters of the model being scalar multipliers.

from (c):

$$Y_{t+1} = \lambda Y_t + \alpha(1-\lambda) + \beta(\sin(2\pi\omega(t+1)) - \lambda\sin(2\pi\omega t)) + \gamma(t+1-\lambda t) + \text{Normal}(0, (1-\lambda^2)\sigma^2)$$

Let $\Delta_t = Y_{t+1} - \lambda Y_t$

Δ_t is the variable we will be modelling.

Let $f_1 = 1 - \lambda$

$$f_2 = \sin(2\pi\omega(t+1)) - \lambda\sin(2\pi\omega t)$$

$$f_3 = t+1 - \lambda t$$

be feature vectors

$$\Delta_t \approx \alpha f_1 + \beta f_2 + \gamma f_3$$