

Fall-2023 5304 LecN6 Notes

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Topics: PD; SPD; LDLT; Cholesky Factorization.

Math Tools: Inner Product, Eigenvalues and Eigenvectors, Properties of some special matrices

1 Positive Definite Matrices

Definition of PD

A real, square matrix is said to be PD if:
 $\langle Au, u \rangle > 0$ for all $u \neq 0$ and $u \in R^n$

1.1 Properties

1, A is nonsingular.

This can be proof by contradiction.

2, The eigenvalues of A are real and positive.

This can be proved by the definition of eigenvalues.

2 Symmetric positive definite matrices, SPD

2.1 Definition of SPD

A square matrix is SPD iff it is **symmetric** and all its eigenvalues λ are **positive**, that is $\lambda > 0$.

Note: Don't forget the 2nd part of the definition, sometimes useful to think in this way.

Properties

1, Diagonal entries of SPD is positive.

Proof starting from the definition: Known that A is SPD, then for all nonzero vector u , we have $\langle Au, u \rangle > 0$. Then, utilize identity matrix to extract an element of A. (MV Product, dot product view). Good enough.

2, Each A_k is SPD

will fill this part later.

3, a conclusion

will fill this part later.

4, If A is SPD, then for any $n \times k$ matrix X of rank k, the matrix $X^T A X$ is SPD.

Memory:

$$\begin{matrix} & k < n \\ \left[\begin{matrix} X^T \end{matrix} \right] & \left[\begin{matrix} A \end{matrix} \right] & \left[\begin{matrix} X \end{matrix} \right] \\ k \times n & n \times n & n \times k \end{matrix}$$

Proof (will use the notation of the inner product and def of SPD):

Application: Covariance Matrices in Statistics

3 Pred: SPD, Semi-Definite, Neg definite, and Indefinite Matrices

4 The LDL^T Factorization from LU

Theorem

Theorem. Let S be a positive-definite symmetric matrix. Then S has unique decompositions

$$S = LDL^T \quad \text{and} \quad S = L_1 L_1^T$$

where:

- L is lower-unitriangular,
- D is diagonal with positive diagonal entries, and
- L_1 is lower-triangular with positive diagonal entries.

For the LU Factorization, all we need is all A_k matrices for $k=1$ to $n-1$ have to be nonsingular. As A is SPD, implying that all A_k matrices from $k=1$ to n are nonsingular. Thus LU fac exists and is unique.

Inverse of a Diagonal Matrix is easy to compute:

Inverse of a Diagonal Matrix



$$D = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & 0 & 0 \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{bmatrix} \quad D^{-1} = \begin{bmatrix} 1/d_1 & 0 & \dots & 0 \\ 0 & 1/d_2 & 0 & 0 \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & 1/d_n \end{bmatrix}$$

Nice results because of symmetry

L is M

Proof that $A = LU = LDL^T$

Thus, a SPD matrix A could be written in this form: $A = LDL^T$ where L is a lower triangular matrix with 1s on the diagonal, and D is a diagonal matrix (of U).

5 The Cholesky Factorization GGT from LDLT

GGT, scope of application: SPD matrices (??? what about semi-definite matrix???).

Diagonal of D should be positive so that we can take a square root to D to reach the Cholesky.

Remark. Suppose that S has an LDL^T decomposition with

$$D = \begin{pmatrix} d_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & d_n \end{pmatrix}.$$

Then we define

$$\sqrt{D} = \begin{pmatrix} \sqrt{d_1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sqrt{d_n} \end{pmatrix},$$

so that $(\sqrt{D})^2 = D$, and we set $L_1 = L\sqrt{D}$. Then

$$L_1 L_1^T = L(\sqrt{D})(\sqrt{D})^T L^T = LDL^T = S,$$

so $L_1 L_1^T$ is the Cholesky decomposition of S .

Proof: Diagonal of D should be positive

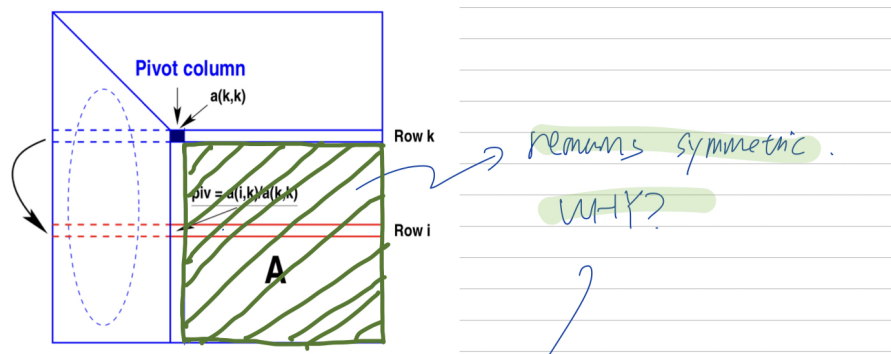
What can we say about G? G is lower triangular

The Cholesky: Any matrix that is SPD could be written as $A = GGT$ where G is a lower triangular matrix, and positive entries on diagonal.

6 Algos of LDLT and GGT

row-oriented LDLT

Idea: Adapted from Gaussian but just work on upper part of the matrix because of symmetry because the working matrix $A(k+1:n, k+1:n)$ in standard LU remains symmetric. See graph below:



Proof: $A(k+1:n, k+1:n)$ is symmetric (induction argument).

What is the cost(FLOPs) of this algo?

Cost of standard LU:

Suppose k 's index starting from 0, then in standard LU decomposition, when clearing the 1st col, each row replacement involves $n-1$ multiplications (scale piv row) and $n-1$ subtraction (update curr row), $2(n-1)$ flops in total. Hence, when k increase, problem size decrease, it takes $2(n-2)^2$ flops to clear the 2nd col etc.. Thus, we have:

$$(n-1) \cdot 2(n-1) + (n-2) \cdot 2(n-2) + \dots + 1$$

$$= 2 \left(\underbrace{(n-1)^2 + (n-2)^2 + \dots + 1}_{\text{平方和与立方和公式}} \right) = 2 \cdot \frac{n(n-1)(2n-1)}{6} \approx \frac{2}{3} n^3$$

平方和与立方和

平方和与立方和的求和公式如下:

$$\sum_{k=0}^n k^2 = \frac{n(n+1)(2n+1)}{6} \quad (\text{A.3})$$

$$\sum_{k=0}^n k^3 = \frac{n^2(n+1)^2}{4} \quad (\text{A.4})$$

Cost of LDLT (just half of LU): $\frac{1}{2} * \frac{2}{3} * n^3 = \frac{1}{3} * n^3$

Rank 1 update: You're updating the matrix by something like uv^T where u and

v are the same.

2, row GGT, outer product form

3, column-oriented LDLT