

Fall-2023 5304 LecN6 Notes

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Topics: PD; SPD; LDLT; Cholesky Factorization.

Math Tools: Inner Product, Eigenvalues and Eigencevectors, Properties of some special matrices

1 Positive Definite Matrices

Definition of PD

A real, square matrix is said to be PD if:
 $\langle Au, u \rangle > 0$ for all $u \neq 0$ and $u \in R^n$

1.1 Properties

1, A is nonsingular.

This can be proof by contradiction.

2, The eigenvalues of A are real and positive.

This can be proved by the definition of eigenvalues.

2 Pred: SPD, Semi-Definite, Neg definite, and Indefinite Matrices

2.1 Pred by the quadratic form

Pred steps:

1, transform the matrix to the quadratic form, method as below:

①含有 n 个变量 x_1, x_2, \dots, x_n 的二次齐次多项式 $f(x_1, x_2, \dots, x_n) = a_{11}x_1^2 + a_{22}x_2^2 + \dots + a_{nn}x_n^2 + 2a_{12}x_1x_2 + 2a_{13}x_1x_3 + \dots + 2a_{1n}x_1x_n + 2a_{23}x_2x_3 + \dots + 2a_{n-1}x_{n-1}x_n$ 称为二次型。

②二次型对应的矩阵为:

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

下标和原的下标一致。

例: $A = \begin{bmatrix} 9 & 6 \\ 6 & a \end{bmatrix}$

$$\begin{aligned} x^T A x &= a_{11}x_1^2 + a_{22}x_2^2 + a_{12}x_1x_2 + a_{21}x_1x_2 \\ &= 9x_1^2 + 6x_1x_2 + 6x_1x_2 + ax_2^2 \\ &= 9x_1^2 + 12x_1x_2 + ax_2^2 \end{aligned}$$

2, pred by this:

对于二次型函数^Q, $f(x) = x^T A x$:

- $f(x) > 0, x \neq 0, x \in \mathbb{R}$, 则 f 为正定二次型, A 为正定矩阵
- $f(x) \geq 0, x \neq 0, x \in \mathbb{R}$, 则 f 为半正定二次型, A 为半正定矩阵
- $f(x) < 0, x \neq 0, x \in \mathbb{R}$, 则 f 为负定二次型^Q, A 为负定矩阵
- $f(x) \leq 0, x \neq 0, x \in \mathbb{R}$, 则 f 为半负定二次型^Q, A 为半负定矩阵
- 以上皆不是, 就叫做不定^Q

Example

Example

$$A = \begin{bmatrix} 9 & 6 \\ 6 & a \end{bmatrix}$$

$$x^T A x = 9x_1^2 + 12x_1x_2 + ax_2^2 = (3x_1 + 2x_2)^2 + (a - 4)x_2^2$$

- A is positive definite for $a > 4$

$$x^T A x > 0 \quad \text{for all nonzero } x$$

- A is positive semidefinite but not positive definite for $a = 4$

$$x^T A x \geq 0 \quad \text{for all } x, \quad x^T A x = 0 \quad \text{for } x = (2, -3)$$

- A is not positive semidefinite for $a < 4$

$$x^T A x < 0 \quad \text{for } x = (2, -3)$$

2.2 Pred by leading principal minors

定理1: 正定性检验

设 A 是一个 $n \times n$ 对称矩阵。则:

目录

(a) A 是正定矩阵, 当且仅当 A 的 n 个顺序主子式(严格)为正。

(b) A 是负定矩阵^Q, 当且仅当 A 的 n 个顺序主子式以如下方式交替出现:

$$|A_1| < 0, |A_2| > 0, |A_3| < 0, \dots$$

即 k 阶顺序主子式的符号应该与 $(-1)^k$ 相同。

(c) 如果 A 的某个 k 阶顺序主子式非零, 但不符合上述两个符号模式中的任何一个, 则 A 是不定的。当 A 对偶数^Q k 有一个负 k 阶的顺序主子式, 或者当 A 对两个不同的奇数 k 和 ℓ 有一个负 k 阶的顺序主子式和一个正 ℓ 阶的顺序主子式时, 就会发生这种情况。

对于给定对称矩阵 A , 定理1的顺序主子式检验可能失败。一种原因是, A 的一些顺序主子式为零, 而非零的其他顺序主子式则符合定理1中 (a) 或 (b) 的符号模式。当这种情况发生时, 矩阵 A 是不定的, 它可能是半定, 也可能不是半定。在这种情况下, 为了检查半定性, 不再只检查 A 的 n 个顺序主子式, 而是必须检查 A 的每个主子式的符号, 使用下面的定理描述的检验。

定理2: 半定性检验

设 A 是一个 $n \times n$ 对称矩阵。则:

- A 是正半定的, 当且仅当 A 的每一个主子式都大于等于0
- A 是负半定的, 当且仅当 A 的每一个奇阶的主子式小于等于0, 每一个偶阶的主子式大于等于0

2.3 Conclusions

1, Semi-definite matrix may be nonsingular, not as positive definite one.

3 Gram matrix $X^T X$

Gram matrix is a special type of matrix to describe the inner product relationships between sets of vectors. Specifically, if there is a set of vectors $[v_1, v_2, \dots, v_n]$, then the elements G_{ij} of the Gram matrix G are the inner products of vectors v_i and v_j , that is, $G_{ij} = \langle v_i, v_j \rangle$. The Gram matrix is semi-positive definite, and it is positive definite when the set of vectors is linearly independent.

Gram matrix

recall the definition of *Gram matrix* of a matrix B (page 4.20):

$$A = B^T B$$

- every Gram matrix is positive semidefinite

$$x^T A x = x^T B^T B x = \|Bx\|^2 \geq 0 \quad \forall x$$

- a Gram matrix is positive definite if

$$x^T A x = x^T B^T B x = \|Bx\|^2 > 0 \quad \forall x \neq 0$$

in other words, B has linearly independent columns

4 Symmetric positive definite matrices, SPD

4.1 Definition of SPD

A square matrix is SPD **iff** it is **symmetric** and all its eigenvalues λ are **positive**, that is $\lambda > 0$.

Note:

- Don't forget the 2nd part of the definition, sometimes useful to think in this way.
- This is an iff relationship.

Properties

1, Diagonal entries of SPD is positive.

Proof starting from the definition: Known that A is SPD, then for all nonzero vector u , we have $\langle Au, u \rangle > 0$. Then, utilize identity matrix to extract an element of A. (MV Product, dot product view). Good enough.

2, SPD iff Each A_k is SPD

will fill this part later.

3, a conclusion

will fill this part later.

4, If A is SPD, then for any $n \times k$ matrix X of rank k, the matrix $X^T A X$ is SPD.

Memory:

$$\begin{matrix} & k < n \\ \left[\begin{matrix} X^T \end{matrix} \right] & \left[\begin{matrix} A \end{matrix} \right] & \left[\begin{matrix} X \end{matrix} \right] \\ k \times n & n \times n & n \times k \end{matrix}$$

Proof (will use the notation of the inner product and def of SPD):

Application: Covariance Matrices in Statistics

5 The LDL^T Factorization from LU

Theorem

Theorem. Let S be a positive-definite symmetric matrix. Then S has unique decompositions

$$S = LDL^T \quad \text{and} \quad S = L_1 L_1^T$$

where:

- L is lower-unitriangular,
- D is diagonal with positive diagonal entries, and
- L_1 is lower-triangular with positive diagonal entries.

For the LU Factorization, all we need is all A_k matrices for $k=1$ to $n-1$ have to be nonsingular. As A is SPD, implying that all A_k matrices from $k=1$ to n are nonsingular. Thus LU fac exists and is unique.

Inverse of a Diagonal Matrix is easy to compute:

Inverse of a Diagonal Matrix



$$D = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & 0 & 0 \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{bmatrix} \quad D^{-1} = \begin{bmatrix} 1/d_1 & 0 & \dots & 0 \\ 0 & 1/d_2 & 0 & 0 \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & 1/d_n \end{bmatrix}$$

Nice results because of symmetry

L is M

Proof that $A = LU = LDL^T$

Thus, a SPD matrix A could be written in this form: $A = LDL^T$ where L is a lower triangular matrix with 1s on the diagonal, and D is a diagonal matrix (of U).

6 The Cholesky Factorization GGT from LDLT

GGT, scope of application: SPD matrices (??? what about semi-definite matrix??).

Diagonal of D should be positive so that we can take a square root to D to reach the Cholesky.

Remark. Suppose that S has an LDL^T decomposition with

$$D = \begin{pmatrix} d_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & d_n \end{pmatrix}.$$

Then we define

$$\sqrt{D} = \begin{pmatrix} \sqrt{d_1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sqrt{d_n} \end{pmatrix},$$

so that $(\sqrt{D})^2 = D$, and we set $L_1 = L\sqrt{D}$. Then

$$L_1 L_1^T = L(\sqrt{D})(\sqrt{D})^T L^T = LDL^T = S,$$

so $L_1 L_1^T$ is the Cholesky decomposition of S .

Proof: Diagonal of D should be positive

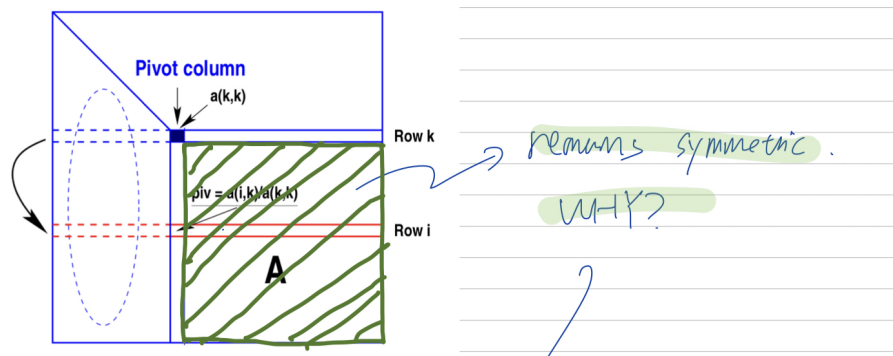
What can we say about G? G is lower triangular

The Cholesky: Any matrix that is SPD could be written as $A = GGT$ where G is a lower triangular matrix, and positive entries on diagonal.

7 Algos of LDLT and GGT

row-oriented LDLT

Idea: Adapted from Gaussian but just work on upper part of the matrix because of symmetry because the working matrix $A(k+1:n, k+1:n)$ in standard LU remains symmetric. See graph below:



Proof: $A(k+1:n, k+1:n)$ is symmetric (induction argument).

What is the cost(FLOPs) of this algo?

Cost of standard LU:

Suppose k 's index starting from 0, then in standard LU decomposition, when clearing the 1st col, each row replacement involves $n-1$ multiplications (scale piv row) and $n-1$ subtraction (update curr row), $2(n-1)$ flops in total. Hence, when k increase, problem size decrease, it takes $2(n-2)^2$ flops to clear the 2nd col etc.. Thus, we have:

$$(n-1) \cdot 2(n-1) + (n-2) \cdot 2(n-2) + \dots + 1$$

$$= 2 \left(\underbrace{(n-1)^2 + (n-2)^2 + \dots + 1}_{\text{平方和与立方和公式}} \right) = 2 \cdot \frac{n(n-1)(2n-1)}{6} \approx \frac{2}{3} n^3$$

平方和与立方和

平方和与立方和的求和公式如下:

$$\sum_{k=0}^n k^2 = \frac{n(n+1)(2n+1)}{6} \quad (\text{A.3})$$

$$\sum_{k=0}^n k^3 = \frac{n^2(n+1)^2}{4} \quad (\text{A.4})$$

Cost of LDLT (just half of LU): $\frac{1}{2} * \frac{2}{3} * n^3 = \frac{1}{3} * n^3$

Rank 1 update: You're updating the matrix by something like uv^T where u and

v are the same.

2, row GGT, outer product form

3, column-oriented LDLT