

Complete this and submit it to Canvas by the posted due date: Friday, Feb. 1.

1. Let $M_{3 \times 3}$ denote the vector space of all 3×3 matrices with real entries. Let

$$W = \{\vec{m} \in M_{3 \times 3} \mid \text{all row and column sums of } \vec{m} \text{ are zero}\}.$$

Note that we are writing 3×3 matrices as vectors (they belong to the vector space $M_{3 \times 3}$).

1. Find a basis \mathcal{B} for $M_{3 \times 3}$. Make \mathcal{B} as simple as possible.

2. Find and n so that $M_{3 \times 3}$ is isomorphic to \mathbb{R}^n . (An isomorphism from $M_{3 \times 3}$ to \mathbb{R}^n is $T : M_{3 \times 3} \rightarrow \mathbb{R}^n$ defined by $T(\vec{m}) = [\vec{m}]_{\mathcal{B}}$.)

3. Let $V \subset \mathbb{R}^n$ be defined by

$$V = \{[\vec{w}]_{\mathcal{B}} \mid \vec{w} \in W\}$$

In other words, $V = T(W)$. Can you write V as the Null space of some matrix C ? Hint: think about the constraints that define W . What is the size of C ?

Bennet Sloan
Mth 342
2/1/19

1.) $W = \{ \vec{m} \in M_{3 \times 3} \mid \sum \text{row} = \sum \text{col} = 0 \}$

A basis for $M_{3 \times 3}$ would be 9 single entry matrices.

$$B = \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right\}$$

2.) $A \cdot \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \\ a_6 \\ a_7 \\ a_8 \\ a_9 \end{bmatrix}$ Given $M_{3 \times 3} \cong \mathbb{R}^n$
Therefore $T(\vec{m}) = [\vec{m}]_B$
So, $n = 9$ (bijective)

3.) $V = \{ [\vec{w}]_B \mid \vec{w} \in W \}$

If $V = T(W)$, then $[\vec{w}]_B = T(\vec{w})$

Let $\vec{m} = \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix}$ And $[\vec{m}]_B = \begin{bmatrix} x_{11} \\ x_{12} \\ x_{13} \\ x_{21} \\ x_{22} \\ x_{23} \\ x_{31} \\ x_{32} \\ x_{33} \end{bmatrix}$

There are 6 constraints:

$$\begin{array}{ll} x_{11} + x_{12} + x_{13} = 0 & x_{11} + x_{21} + x_{31} = 0 \\ x_{21} + x_{22} + x_{23} = 0 & x_{12} + x_{22} + x_{32} = 0 \\ x_{31} + x_{32} + x_{33} = 0 & x_{13} + x_{23} + x_{33} = 0 \end{array}$$

Therefore V is the nullspace of C ,

where C is defined by the 6 constraints:

$$\begin{array}{c}
 \begin{matrix} x_{11} & x_{12} & x_{13} & x_{21} & x_{22} & x_{23} & x_{31} & x_{32} & x_{33} \end{matrix} \\
 \begin{bmatrix}
 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\
 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\
 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\
 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 x_{11} \\
 x_{12} \\
 x_{13} \\
 x_{21} \\
 x_{22} \\
 x_{23} \\
 x_{31} \\
 x_{32} \\
 x_{33}
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0
 \end{bmatrix}
 \end{array}$$

$\underbrace{\hspace{15em}}_{C} \quad \underbrace{\hspace{5em}}_{[\vec{m}]_B}$

$(6 \times 9) \qquad (9 \times 1)$