DECISION TREES TO PREDICT COLOMBIAN STUDENT'S SUCCESS ON SABER PRO BASED ON SABER 11 RESULTS

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ABSTRACT

The purpose of this report is to find a connection between the scores of Colombian bachelor students in Pruebas Saber 11 and Pruebas Saber Pro; as well as, socio-economic details regarding their personal and familiar lifestyle. Through this relationship, it will be possible to predict the results on the Pruebas Saber Pro resulting in scores above or below average.

Resulting predictions from the use of the decision tree can help solve the deficiency in education found in Colombia. It can help find a correlation between socio-economic conditions and results in Pruebas Saber Pro; allowing a hint and suggestions towards the most vulnerable stratum to destine more funds directly.

1.INTRODUCTION:

Education and technology are two areas that have been left behind in comparison with other countries in the region. Using decision trees to predict student results in the Pruebas Saber Pro, allows improvement in Colombian education. It helps distribute resources in the education area of society.

The information from each student that will be used includes the specific results on every area of the Pruebas Saber 11, information about their lifestyle, where they live, as well as parent occupations. The data includes more than 30 different factors that help the prediction on their success be as accurate as possible.

2.PROBLEM:

The problem consists in predicting if a student taking the Pruebas Saber Pro will have a score below or above the average using information from their lifestyle and their results on the Pruebas Saber 11 with the implementation of a decision tree.

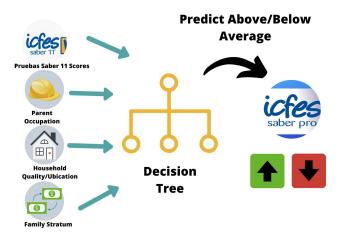


Figure 1. Visual representation of the problem [6][3]

3.POSSIBLE SOLUTIONS:

3.1. ID3

The iterative dichotomiser is a type of decision tree created by Ross Quinlan. It is considered to be one of the simplest but yet very efficient type of decision tree. It works by taking all of the attributes and sorting them by highest information gain. It tests the attribute with the highest information gain and then continues down a bunch of branches in a certain order until it gets to a final result. The algorithm works mostly with categorical attributes and is not the fastest since it has to check one attribute at a time, some others can check multiple attributes at the same time. [5]

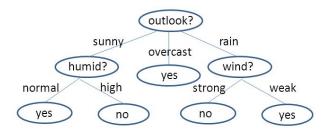


Figure 2: ID3 decision type tree [2]

3.2. C4.5

C4.5 is an algorithm that works as an extension to ID3 developed and created by Ross Quinlan. It is used for classification and works more effectively than ID3 because it works with continuous and discrete variables. It forms numerous reduced trees that are easier to understand and divides the problem multiple times. C4.5 is practical to use making its understanding easier while being able to use categorical and continuous values;however, it is not recommended for small sets.[5]

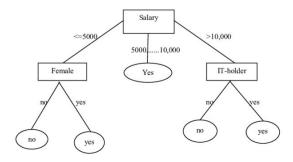


Figure 3: C4.5 decision type tree [1]

3.3. Random Forest

Random Forest is a type of decision tree created by Leo Breiman, consisting of numerous simple trees that return a response given certain predictor values declared at the start. It works for both classification and regression values and problems. This type of tree is one of the most accurate learning algorithms that gives an estimate of the most valuable variables classified. As a disadvantage, it is not easily interpreted by humans.[5]

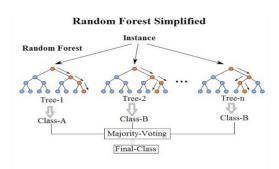


Figure 4: Random Forest decision type tree

```
To generate c classifiers:
    for i = 1 to c do
        Randomly sample the training data D with replacement to produce Di
Create a root node, Ni containing Di
         Call BuildTree(Ni)
    end for
    BuildTree(N):
if N contains instances of only one class then
        return
    else
    Randomly select x% of the possible splitting features in N
    Select the feature F with the highest information gain to split on
    Create f child nodes of N,N1,NF, where F has f possible values(F1,\underline{Ff}) for i = 1 to f do
        Set the content of Ni to Di, where Di is all intansces in N that match
         Call BuildTree(Ni)
    end for
end
```

Figure 5: Random Forest PseudoCode[7]

3.4. CART

CART, also known as Classification and Regression trees, is a type of decision tree that includes both classification and regression trees. One particular attribute about CART trees is that it only does binary separation, meaning every decision can only take two possible routes.[5]

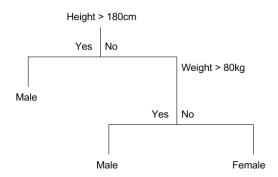


Figure 6: CART decision type tree [4]

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