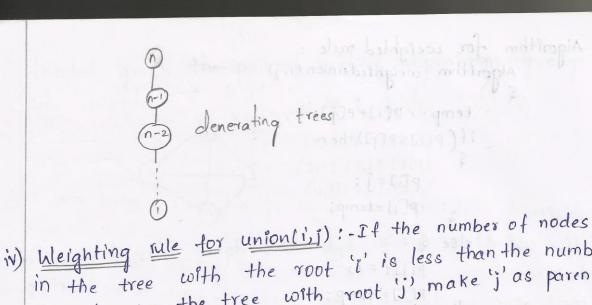
UNIT - 2 SEARCHING AND TRAVERSING TECHNIQUES DISJOINT SET OPERATION:
For n=10 the elements can be partioned into 3 disjoint sets: S, = { 1,7,8,9 } bondonun sin Sz= \$2,5/10} 32 de noitornessage quarro al Each set is represented as a tree where each set is link the nodes from children to the parent. Root node can be any element. The operations to be performed on this sets are i) <u>Disjoint</u> set union: - if s(i) and s(j) are two disjoint set then their union sivs; = all elements x such that x is in Si or Sj. i.e., S, US2 = \$1,2,5,7,8,9,104 ii) find (i) : Given the element 1, find set containing i i, e., determines the root of tree containing element i. The determination of i is done until we reach a node with parent value -1. 111) Data Representation And Array Representation of Sets: a) Data Representation will me more ment and seriame pointer

b) Array Representation [1] [2] [3] [4] [5] [6] [7] [87 [9] [07] In data representation the sets are represented in form of set table which contains two columns set name and the pointer which points to the tree representations of sets In array representation the set elements are numbered from 1 to n i,e., P[1:n] where n is max of n elements. The ith element of this away represents tree node that contains element i. ->* ALGORATHM FOR UNION AND FIND i) Algorithm for union i) Algorithm jui and simpleunion (i,j) Root noder can be any element. The operation of this sets are i) prejoint seil=(still); all elements Poles Algorithm simple Find (1) and the triops to out and a such that a is in ob (o < [1]7) sindy containing i i) find (i): Given the relement; [i]q=:i returning element; i)e, determines the root of; innutting we reach a note Sequence of union & Find operation intermentals of # union(1,2), union(2,3), union(3,4), union(4,5)____u(n-1,n) find (1), find (2) - - - find (n). (1) brit , (1) brit , (1) brit) The time taken for one union is constant. -) In order to perform (n-1) unions is O(n) obi Ques. The time taken to process n finds is O(n2) obj Ques. To improve the performance of union & find algorithm by avoiding the creation of degenerate trees, we make use of weighting rule for union (i,i).



in the tree with the root it is less than the number of nodes in the tree with root 'j', make 'j' as parent of 'i' otherwise i' as the parent of j'.

In order to implement the weighting rule, were need to know how many modes are three in each tree. We use a field called count in order to find the number of nodes in that tree.

Note: let T be a tree with m nodes created as a result of sequence of unions each performed using weight union. The height of a tree is not greater than log m+1

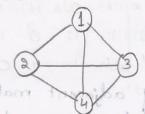
(1) (2) ---- (1) (1) (3) ---- (1) (1) (1) (1) (2) (3) union (1,3)

4) union (1,4)

TREES OBTAINED USING THE WEIGHT RULE

```
Algorithm for weighted rule:
         Algorithm weighted union (i, j)
             temp: = P[i]+P[j];
             if (PCi]>PCj]) then
                  P[i]= [i]
  esbon to codming p[i] = temp;
                   anion(if): If the
 else &
                  Ptj?:= is took sat affect out sat all
        2 y jo trans of the parent of your to be good to
v) Collapsing rule: - If I is anode on path from i loits root-and
  P[i] $ root[i], then set P[j] to root [i]
         Algorithm collapsing Find (i)
             while (ptr] > 0) do
  of book soot grant of the find root
 while (i # r) do 11 collapse nodes from i to root r. II
    a tield called count in order +[i] Pho: 21he number of
                  P[i]i= Y;
Note: let T be a tree with m' nodless created as a result
sequence of unions each performentitional weight union the
              height of a tree is not greater than log m+1 &
  A graph G consists of two sets vand E. the set
   V is a finite nonempty set of vertices. The set E is a
   Set of pairs of vertices, these pairs are called Edges. The
   notation V(G), e(G) represent the set of vertices and edges.
   of graph G. GF(V,E) which represents a graph, in un-
                               REES (ONTAINED
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directed graph the pair of vertices represents any edge in



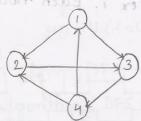
(1,2), (1,3)(114)(2,1)(2,3)(214)

(3,1) (3,2) (3,4)

(u,1)(u,2),(u,3)

a tield vertex and link.

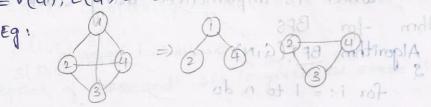
In at directed graph, each edge is represented by directed



The number of distinct unordered pairs with P(U,V) in addition U & V in graph with n vertices is n(n+1)/2 i.e., max. no. of edges in any n vertex, of undirected graph.

SUB GRAPH:
SUB GRAPH:
Subgraph of G is a su graph G' such that

V(G') = V(G), E(G') = E(G)



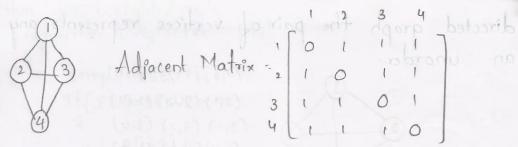
GRAPH REPRESENTATION

Adjacent matrix: let $G = (v, \varepsilon)$ be a graph with n vertices

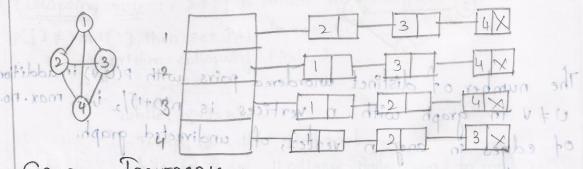
n > 1 the adjacent matrix of G is a 2-D n x n array if

the property that a[i,i] = 1 if and only if there is an

edge between 1 and j. a[i,i] = 0 if there is no edge.



91) Adjacent list: The n' rows of adjacent matrix are represented as n linked list. There is one list for each vertex. There is a node in list i represent the vertexes that are adjacent from vertex i. Each nodes have atleast a field vertex and link.



GRAPH TRAVERSALS:

There are two types of traversing graph.

i) BFS - which is implemented using queue data structure

(1) DFS - which is implemented using stack data structure.

- Algorithm for BFS Algorithm BFT (GIN) Breadth First Traversing

for i:= 1 to n do visited[i]=0;

CRAPH : REPRESENTATION ob not 1: = 1 to n do MOITATION Northers

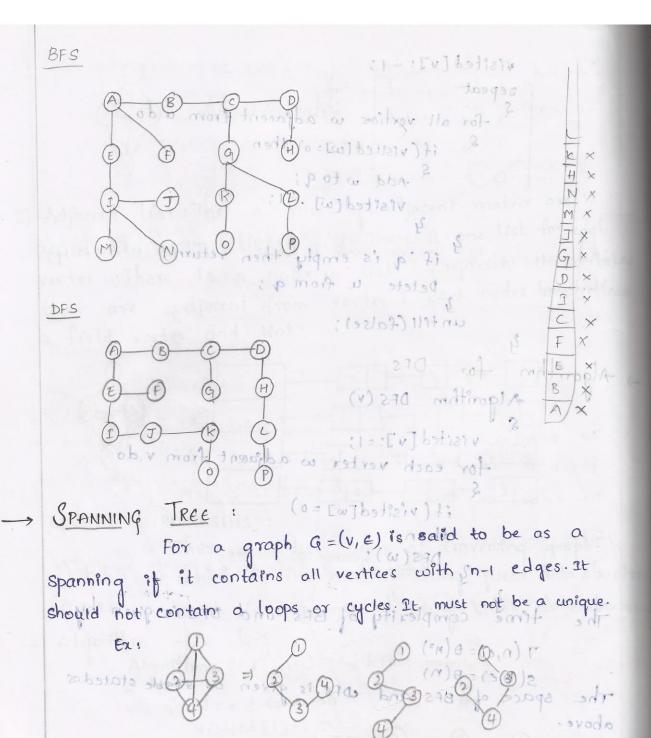
if (visited Til = 0) of to sint on the ofthe (

then si between the matrix of continue there is an all the adjacent matrix of continue the property the south first such property and the property and first the property and south prop

```
visited [v]: =1;
        repeat
           for all vertices w adjacent from u do
               if (visited two = 0) then
                 & Add w to q;
                 Visited[w] .=1;
              if 'q is empty then return;
                 Delete u from q;
              untill (false);
Algorithm for DFS
        Algorithm DFS (V)
             visited [v]:=1;
            for each verter w adjacent from v do
                if (visited[w] = 0)
   Spanning if it contains all vertices with sn-1 edges. It
       time complexity of BFs and DFs is given by
       T (n,e)= 0 (n2)
The space of BFS and DFS is given as stable statedos
 above.
                             Spanning trees can
```

ture

ure,



Spanning trees can also be implemented using DFA and BFA.

CONNECTED GRAPH:
Two vertices v and v are connected in undirected
graph if there is a path from u to v and v to u. A
connected component of undirected graph is a maximal

-> STRONGLY CONNECTED GRAPH : 200 bis pointing of

A directed graph G is said to be strongly connected if for every pair of distinct vertices u and v in G there is a directly path from u to v and v to u. A strongly connected component is a maximal subgraph that is strongly connected.

BICONNECTED Components:

**. A vertex V(G) is an articulation point if and only if the
**. A vertex V(G) is an articulation point if and only if the
deletion of B, together with deletion of all edges incident to V
leaves behind a graph that has atleast two connected components.

**. A biconnected graph is a Connected graph that has no
articulation points.

**. A biconnected component of connected graph G is a maximal
biconnected subgraph of G i.e., G contains noother subgraphs i.e.,
both connected & biconnected.

Note: i) Two biconnected components of same graph can
have atmost one verter in Common.

ii) No edge can be intolor more biconnected components.

Note: i) Two biconnected components of same graph can have atmost one verter in common.

ii) No edge can be intolor more biconnected components.

iii) The biconnected components of a connected, undirected graph iii) The biconnected components of a connected, undirected graph can be found by using depth. first spanning tree of G.

can be found by using depth. first spanning tree of G.

iv) A non tree edge U, v is an back edge with respect to a spanning tree T.

v) A non tree edge that is not back edge is called Cross Edge.

v) A non tree edge that is not back edge is called Cross Edge.

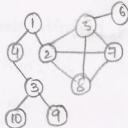
vi) No graph can have cross edges with respect to any depth-first spanning tree.

> FINDING THE ARTICULATION POINTS FOR GIVEN GRAPH:

The root of depth-first spanning tree is an articulation point if and only if it has alleast 2 children.

```
ii) u is an articulation point if and only if, u is either
  a spanning tree and has 2 or more childrens.
  Hi) u is not the root and u has a child w such that
  low(w) > fr (u) where dfn is depth first number.
  iv) L(v) = min { dfn[u], min { L[w] | w is child of u y, min { dfn[w]
                (u,w) is a back edge & }
   ALGORITHM FOR BICONNECTED COMPONENTS: hotomos
   Bi comp (u,v) : amechenis (v,v) Bicomp (u,v) and Algorithm, Bicomp (u,v) is an articulation point, and is an exticulation point.
   incident to v
            dfn[u]:=num; deletion redtepot de la modelete
leaves behind a graph that has attemunis: [u] seled components.
   4. A biconnected graph is a contemporarion that has no
          for each verter w adjacent from u do
   4. A biconnected component of connected graph & iz a maximal
   edgers dif((v+w)and(dfn[w] kdfn[w]) then
                 add (u, w) to the top of the stack.
    as doop if (dfn [w] = 0) then bets accord out (i : old
                  have atmost one verther ([w] ) then to soo troots
        bleenner & demponents
   gap Indorrior p bet repeat "new bicomponent"); opbo on (ii
     se spanning tree of G.
                          Delete an edge from top of stacks;
    o of largear dita spha let this edge be (x,y); sort non A (vi
                           write(x,y); ent pointes
dept - dtqbb par o' togget dia 2000 ((x,y)=(u,w)) or ((x,y)=(u,u))),
                Bicomp(w,u); llant w 13 unvisited
                 L[u]:=min[L[u],L[w]);
       FINDING THE ARTICULATION POINTS FOR SIVER GRAPH
 L[u]: =min[[[w]], dfn[w]));

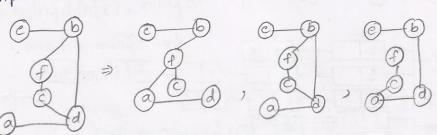
2,
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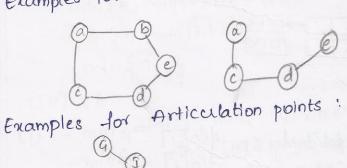
In order to find L[u] easily the vertices of depth-first spanning tree are visited in post order.

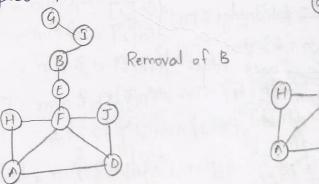
1 to 10 the 85 the decor never primately ent rol

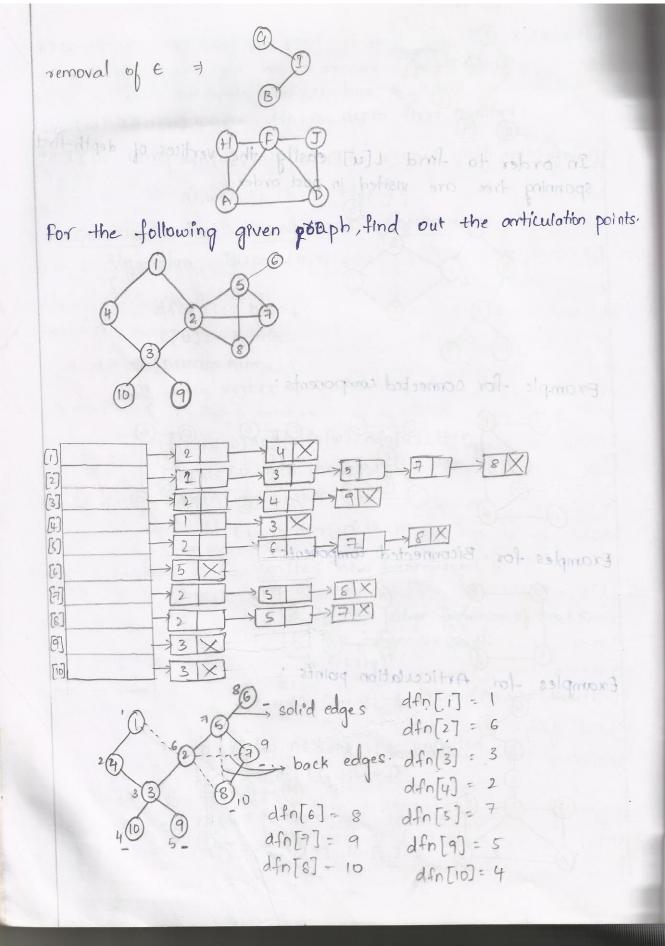
Example for connected components:



Examples for Biconnected Components:







```
L[10] = min{dfn[10], -, -}
     = min Sy 4
  4[10] = My
= mings&
49=5 fistain, chain Ding sexchains
L[6] = min &dfn[6], -, -}
    = min $ 8 4
                  cli] = ming, mingig, mingeg
  LT67=8
                    faisseine isum =
[7] = min {dfn[7], L[8]}
(B) = minfdfn[e], minfdfn[2], dfn[5]/ [1]
    * min $10, min $6,744 & [2] 3 min $6 [2] 3
    = min sio,63 / sigaim & Dologaim & gainr =
 L[8]=6
[[7]=min{dfn[7], min{[1]8], min{dfn[2]364
   = min{ 9, min{6}, min {63} } 3 3 3 mm 20 + } aim=
   = min { 9, min (6,6)}
    = min 59,64
L[7] = 6
L[1] = \min \{ dfn[1], \min \{ L[4], \min \{ dfn[2] \} \} \}
    = mingt, mingL[4]g, ming6g
                                   La theolegy
    = min &1, min &L[4] }, min &63 = [w]
L[4] = min {dfn[4], min {dfn[3]}, min {L[3]}
     = min {2} + min {[3], min & dfn[3] / dfn[1] }
L[3] = min {dfn[3], min{L[9], L[10] }, min{dfn[9], dfn[10]}
     = min & dfn[3], min & 41 5 4, min & 4, 5 4 6
```

cints.

```
= min { 3, 4 }
                                                                                                                                                 U107 = 1017J
         L[3]=3
     [[4] = min {2, min{3}, min{3}}
                          = min § 2, min § 3 4 4
                          = ming 2/3 & K[X] & min & 2, min & 3,1 }
       ([4) = min $ 2,13
                                                                                                         (10) = min {dfn[0],= ,- }
        LTy) = A1
                                                                                                                                               = min 8 8 4
      LTI] = min SI, min SI g, min S6 g
                              = min \1, min \1,6\3 \ \{[3] 1, [6] ab \} ain = [6] 1
                               emin Si 13 jezindeta Ezida Ezida Ezi i Pinim = Ezi
            LT17=1
         L[2]=min&dfn(2), min&L[5] g, min&dfn[i])
                               = ming 6, mingets] , mingig g
        2[5] = min Sdfn(5), min { et 6], [ta] 3, min { dfn[8] }
                             = min & 7; & po, min & c, 83; min & cold
                               = min {7,6,10} {(did) aira, p } aira =
           L[5] = 6
L[2] = \min_{s \in [6,6,1]} \{n_{s}^{(s)}, \min_{s \in [1]} \{n_{s}^{
            L[5] = 6
              [[2]=1 [w] > dfn[u]. [[v] skaim , skaim.
             Vertex 4: PEIJ Retain ( E) of b & aim = [4] 1.
[10] Nertends Faint [10] of dfo[3] aim, [2] of p? nim. [2] 1
                                                     $65 hours of the Built of the Built =
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L[9] > dfn[3] Vertex 2 L[5] -> dfn[2] and of L[6] >dfn[5] 100 to 1 L[7] >, dfn[5] Print root = data. More towards 756 L[8] > dfn [7] 2 4 4 ale 2 is an articulation point. is not an articulation point. NON RECURSINE BINARY TREE TRAVERSAL: The binary tree traversals are divided into three types. EFFICIENT >In order The Recursion algorithm of inorder is given as follows void Inorder (Node *root)