FOR MICH - 2 Exam

Part - B.

Expecting: DAA: Part - B.

Set - I

What is an Optimal Binary search Trace (OBST) 9

A write an algorithm and time complexity for OBST. Construct an OBST with the following data:

Let n = 4: but az az az a4) = /do it int with

Let n=4; (a1, a2, a3, a4) = (d0, if, int, while).

P[1:4] = (3,3,1,1); 9(0:4] = (2,3,1,1).

The P'S and q'S have been multiplied by 16 for the convenience.

BD Describe the Travelling sales person problem.

Construct the optimal Tour of the following frollow Using travelling Salesperson.

A B C D = cities

RI-A I O 10 15 20

R2-B 2 5 0 9 10

R3-C 3 6 13 0 12

R4-D 4 8 8 9 0

Tates C1 C2 C3 C4

Land or

2 AA Descuss the basic nothed of backtracking affeithm. Also explain the following a) live node b) E-Node c) Answer node d) Answer Path e) Dead node of) Answer.

2BQ:- Discuss algorithm of Hamiltonian cycle and Grouph Coloring. Also draw the state Have tree for n = 4 and m = 3 graph Coloring problem.

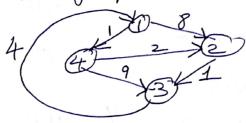
3AQ:- Define Branch and Bound.
Discuss L.C and FIFO(B/Bag)

3 BQ:- Describe FIFO Brand and Bound algorithm. Also Draw the portion of state Spor tree generated by FIFO-B&Bay for Knapsack instances. n=5,(P1,P2,...P5)=(10,15,6,8,4), $(W_1, W_2, \dots, W_5) = (4, 6, 3, 4, 2)$ and M = 12.

Backtracking: General method, applications-n-queen problem, sum of subsets problem. graph

4A9: Down the portion of state space tree generated by LCBB for the Knapsack instances n=4, (P1, P2...P5) = (10, 10, 12, 18) (W1, W2,... W5) = (2,4,6,9) and M=15. (02)

4BO: Doaw the following all Pairs Shortest Path Problem and find the shortest distance from each node to each other in the geaph.



5AQ: Differentiate N, NRHard and NP- complete problems

5BO!- state the cooks theorem. And Explain its importance.

Unit-5 Short Q.

- 1. NP-Hard, NP-complete, P-class, NP- class, deterministic and nondéterministic problems.
- L' délision problem and optimization problem, approximate solution, promising and non-proprising nodes.
 - Fromula for bounding function in Knaplack

 Problem > L.C, FIFO
 - 4. about travelling salesposson problem
- 5. time complexity and space complexity of
- Long Questions Extra 5th and
- 1. Connort Bookan formula B=(x, \xx2). (X3+X4X5).(X1X2+X3X4) into CNF.
- 2. Pseudo code description of B & B alg for Travelling Sales person Problem.

Expecting Set-2-for Mid-2. IAQ: - Explain the concepts of reliability design Problem. Design a three-stage system with derice types D1, D2, and D3. The losts are \$ 30, \$ 15 and \$20 respectively. Reliability is 0.9, 0.8 and 0.5. The total lost of the system must not be more than C = \$ 105.

B. AQ:-Explain the off KnapSack problem with an algorithm. Find an optimal solution for the 0/1 Knapsack instance for n=4, m=16, ferofits are (P1, P2, P3, P4) = (10, 6, 5, 1), weights are (w1, w2, w3, w4); W4=(9,6,73) Using Dynamic programming. BO: - write an algorithm (Floyd-Warshall algorithm) for all-pairs - shortest path Problem.

2Al: what is the sum-of-subsets problem I solve the following sum-of-subsets problem Using Brack tracking. Let n=6, m=30, and W[1:6] = (5, 10, 12, 13, 15, 18). (Draw the state space tree and the solution Using fixed - tuple sized format).

2BP:- Discuss in detail about 4-Queens fieldem with state space tree and solution trac. write an aborithm for N-Queen problem.

3Al!- Draw the Portion of state space true generated by FIFO-Brand of Bound for the Knapsack instances n=5, (P1, P2, ...P5) = (1915, 6, 8, 4) (W1, W2; iw5) = (4,634,2) and M=12.

3BD: Daw the Portion of State space tree generated by LCBB for the following Travelling Sales person Problem. 1 2 3 4 5 7

40!- Explain about stisfability problem with explane.

4BQ:- Describe FIFO Branch and Bound Algorithms. Explain NP-Hord and NP-Complete

50:- Explan P-class, NP-class problems. > P, NP-Hard, NP-Comple, Non-Determinite and deterministic problems.

5BO: - what is non-determinetic algorithm? Write the non-deterministic algorithm for Knapsack problem.

Short Questions:

I what is Dynamic programing; its applications.

2.0BST, Knapsæk Problem.

s features of Dynamic programing. 4. Principle of Optimality.

- > general procedure for Dynamic programming.
- > Define all Pair shortest Path Problem.
- > State time and space efficiency of OBST.
- Doaw backs of Dynamic Programing.

Unit-IV

- 1. hequirements needed for performing Backtracking
- 2. explicit and Implicit constraints.
- 3. State space tree Answer tree line node E node, dead node.
 - 4. factors influence the efficiency of the backtracking algorithm.
 - 5. Boanch and Bond method.
- 6. searching techniques commely used in Board and Bound
- State 8- Queens Poblem; 4 Queen.
- Sum of Subsets problem.
- m- Coloralistity decision problem. Chromatic number of graph.
- dynamic tres.